## Probabilistic Temporal Logics

### Acknowledgement

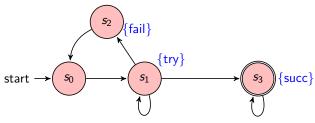
These notes are based on the fourth Dave Parker's lecture series, published on the PRISM web site: see "further reading" at the end of lecture 1.

### Temporal Logics

By these we mean formal languages for reasoning about the behaviour of systems over time.

- ► They extend formal *propositional logic* with operators expressing temporal properties such as always(...), eventually(...)
- We need them to express formally a system model, and system properties against which the system can be tested with a software model checker such as SPIN, UPPAAL or PRISM
- ► Temporal logics have formal semantics based on *labelled (state)* transition systems.

### **LTS**



A labelled transition system is a tuple  $(S, s_{ini}, \rightarrow, L)$  consisting of

- ▶ *S*,a set of locations or *states*
- $s_{ini} \in S$ , a particular *initial* state
- ▶  $\rightarrow \in S \times S$ , a transition relation. We write  $s \rightarrow s'$  rather than ' $(s, s') \in \rightarrow$ '.
- ▶  $L: S \rightarrow 2^{AP}$  is a function labelling each state s with a set of *atomic propositions*, possible empty.
- ▶ Drawn as a graph, with states as vertices and transitions as edges.

A DTMC, minus propabilities! Indeed, a DTMC has an underlying LTS in which  $s \to s'$  iff P(s,s') > 0. This example is derived from a the simple communication protocol DTMC we have seen previously.

### Paths in a LTS - notation

- ▶ A path is a sequence  $\omega = (s_0 s_1 s_2...)$  where  $\forall i \geq 0, s_i \rightarrow s_{i+1}$ 
  - ▶ a finite path is a finite sequence  $(s_0s_1s_2...s_n)$  where for  $0 \le i < n, s_i \to s_{i+1}$
- $\triangleright$   $\omega(i)$  denotes state no i:  $s_i$  in the examples above.
- $\blacktriangleright \ \omega[...i] \triangleq (s_0 s_1 s_2 ... s_i)$  a (finite) *prefix* of  $\omega$
- $\bullet$   $\omega[i...] \triangleq (s_{i+1}s_{i+2}...)$  a suffix of  $\omega$
- ▶ (As in DTMCs)  $Paths(s) \triangleq$  the set of all paths starting from s.

# Computation Tree Logic - CTL

Two types of propositional formulae are defined (in terms of each other):

- ▶ State formula:  $\varphi ::= true \mid \alpha \mid \varphi \land \varphi \mid \neg \varphi \mid \forall \psi \mid \exists \psi$
- ▶ Path formula:  $\psi ::= \bigcirc \varphi \mid \Box \varphi \mid \Diamond \varphi \mid \varphi \ \mathcal{U} \ \varphi$ 
  - here,  $\alpha$  denotes an atomic proposition,  $\varphi$  a state formula and  $\psi$  a path formula
- A 'CTL formula' is a state formula. A path formula is always inside scope of a ∀ or a ∃, making a state formula.

#### Alternative notation

- $\blacktriangleright X\varphi \text{ for } \bigcirc \varphi;$
- $\blacktriangleright F\varphi \text{ for } \Diamond \varphi;$
- $G\varphi$  for  $\Box \varphi$ ;
- ▶ A rather than  $\forall$ , E rather than  $\exists$

### CTL Semantics in a LTS

 $arphi, arphi_1, arphi_2$  denote a *state* formula;  $\psi$  denotes a *path* formula ...

State formula semantics:  $s \models \varphi$  means " $\varphi$  is true in/of state s"

- ▶  $s \models true$  always
- ▶  $s \models \alpha$  iff  $\alpha \in L(s)$
- ▶  $s \vDash \varphi_1 \land \varphi_2$  iff  $s \vDash \varphi_1$  and  $s \vDash \varphi_2$
- s ⊨ ¬ $\varphi$  iff s  $\nvDash \varphi$
- ▶  $s \models \forall \psi$  iff  $\omega \models \psi$  for all  $\omega \in Paths(s)$
- ▶  $s \models \exists \psi$  iff  $\omega \models \psi$  for some  $\omega \in Paths(s)$

Path formula semantics:  $\omega \vDash \psi$  means " $\psi$  is true of path  $\omega$ "

- $\triangleright \ \omega \vDash \bigcirc \varphi \ \text{iff} \ \omega(1) \vDash \varphi$
- $\omega \vDash \Box \varphi$  iff for all  $k \ge 0, \omega(k) \vDash \varphi$
- $\omega \vDash \Diamond \varphi$  iff for some  $k \ge 0, \omega(k) \vDash \varphi$
- $\blacktriangleright \ \omega \vDash \varphi_1 \mathcal{U} \varphi_2$  iff for some  $k \ge 0, \omega(k) \vDash \varphi_2$  and for all  $i < k, \omega(i) \vDash \varphi_1$

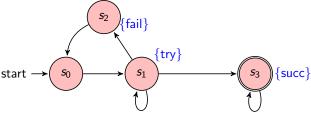
# CTL Semantics (ctd)

#### Thus,

- ▶  $s \models \exists \Diamond \varphi$  means *some* path from s has a state on it where  $\varphi$  is true;
- ▶  $s \models \exists \Box \varphi$  means on *some* path from s, at every state from s on,  $\varphi$  is true;
- ▶  $s \models \exists (\varphi_1 \mathcal{U} \varphi_2)$  means on *some* path from s, there is a state where  $\varphi_2$  is true and at previous states back to s,  $\varphi_1$  is true;
- ▶  $s \models \forall \Diamond \varphi$  means *every* path from s has a state on it where  $\varphi$  is true;
- ▶  $s \vDash \forall \Box \varphi$  means on *every* path from s, at every state from s on,  $\varphi$  is true;
- ▶  $s \models \forall (\varphi_1 \mathcal{U} \varphi_2)$  means on *every* path from s, there is a state where  $\varphi_2$  is true and at previous states back to s,  $\varphi_1$  is true;

## CTL Semantics Examples

(Referring to the LTS on slide 3)



Paths satisfying path formulae -

- $\omega = (s_1 s_2...)$  then  $\omega \models \bigcirc succ;$
- $ightharpoonup (s_0s_1s_1s_3...) \vDash \neg fail \ \mathcal{U} \ succ$

States satisfying CTL (state) formulae -

- ▶  $s_1 \models try \land \neg fail$ ;
- ▶  $s_1 \models \exists \bigcirc succ \text{ and } s_1, s_3 \models \forall \bigcirc succ;$
- ▶  $s_0 \vDash \exists (\neg fail \ \mathcal{U} \ succ) \ \mathsf{but} \ s_0 \nvDash \forall (\neg fail \ \mathcal{U} \ succ).$

## Common CTL formula examples

- ▶  $\forall \Box (\neg crit_1 \land crit_2)$ : mutual exclusion between critical sections 1, 2
- ▶ ∀□ ∃◊ init: in every run, it is always possible to return to the initial state
- ∀□(request ⇒ ∀◊ response): every request is always eventually responded to
  - → denotes implication see below.
- ▶  $\forall \Box \ \forall \Diamond crit_1 \land \forall \Box \ \forall \Diamond crit_2$ : processes 1, 2 both get access to critical section infinitely often

The 'usual' form for CTL formulae has a path quantifier  $\forall$  or  $\exists$  followed by a temporal operator  $\bigcirc$  or  $\square$  or  $\lozenge$  or  $(-\mathcal{U}-)$ . A path formula always appears inside the scope of a quantifier.

## Equivalences and derived operators

- false ≜ ¬true
- disjuction:  $\varphi_1 \vee \varphi_2 \triangleq \neg (\neg \varphi_1 \wedge \neg \varphi_2)$
- ▶ implication:  $\varphi_1 \Rightarrow \varphi_2 \triangleq \neg \varphi_1 \lor \varphi_2$  [or alternatively  $\neg (\varphi_1 \land \neg \varphi_2)$ ]
- $\forall \psi \equiv \neg \exists \neg \psi$  and similarly  $\exists \psi \equiv \neg \forall \neg \psi$
- $\triangleright \ \Diamond \varphi \equiv true \ \mathcal{U} \ \varphi$
- ▶  $\Box \varphi \equiv \neg \Diamond \neg \varphi$  and similarly  $\Diamond \varphi \equiv \neg \Box \neg \varphi$

Some more temporal operators making path formulae -

- weak-until:  $\varphi_1 \mathcal{W} \varphi_2 \triangleq (\varphi_1 \mathcal{U} \varphi_2) \vee \Box \varphi_1$  [alternatively  $\varphi_1 \mathcal{U}(\varphi_2 \vee \Box \varphi_1)$ ]:  $\varphi_1$  holds along the path until  $\varphi_2$  becomes true but this need never happen
- ▶ Thus  $\varphi_1 \mathcal{U} \varphi_2 \equiv (\varphi_1 \mathcal{W} \varphi_2) \wedge \Diamond \varphi_2$
- ► Release:  $\varphi_1 \mathcal{R} \varphi_2 \triangleq \varphi_2 \mathcal{W}(\varphi_1 \wedge \varphi_2)$ :  $\varphi_2$  holds along the path until (and including) the state where  $\varphi_1$  first becomes true.

## Probabilistic Computation Tree Logic - PCTL

A development of CTL: the path quantifiers  $\forall$ ,  $\exists$  are replaced by a 'probabilistic quantifer'  $\mathbb{P}(...)$ . For example,

- ▶ state formula 'send  $\Rightarrow \mathbb{P}_{\geq 0.95}(\lozenge^{\leq 10} deliver)$ '
- expresses that 'if message sent, then with probability at least 0.95, it is delivered with 10 steps'.

Again, two types of propositional formula:

- State formula:  $\varphi ::= true \mid \alpha \mid \varphi \wedge \varphi \mid \neg \varphi \mid \mathbb{P}_{\sim p} \psi$
- ▶ Path formula:  $\psi ::= \bigcirc \varphi \mid \varphi \ \mathcal{U}^{\leq k} \ \varphi \mid \varphi \ \mathcal{U} \ \varphi$ 
  - $\alpha$  denotes an atomic proposition,  $\varphi$  a state formula and  $\psi$  a path formula;  $\sim$  is one of  $<,>,\leq,\geq$ ;  $p\in[0,1]$ , a probability bound; k is a positive integer.
  - Also  $\mathcal{W}, \mathcal{R}$  derived from  $\mathcal{U}$  as in CTL, and bounded versions  $\mathcal{W}^{\leq k}, \mathcal{R}^{\leq k}$
- ▶ A 'PCTL formula' is a state formula. A path formula is always inside scope of a  $\mathbb{P}$ , making a state formula.

### PCTL Semantics in a DTMC

 $arphi, arphi_1, arphi_2$  denote a  $\mathit{state}$  formula;  $\psi$  denotes a  $\mathit{path}$  formula ...

State formula semantics:  $s \models \varphi$  means " $\varphi$  is true in/of state s"

- ▶  $s \models true$  always
- ▶  $s \models \alpha \text{ iff } \alpha \in L(s)$
- ▶  $s \vDash \varphi_1 \land \varphi_2$  iff  $s \vDash \varphi_1$  and  $s \vDash \varphi_2$
- s ⊨ ¬ $\varphi$  iff s  $\nvDash \varphi$
- ▶  $s \vDash \mathbb{P}_{\sim p} \psi$  iff  $Prob(s, \psi) \sim p$ 
  - ▶ where  $Prob(s, \psi) \triangleq Pr_s(\{\omega \in Paths(s) | \omega \models \psi\})$

Path formula semantics:  $\omega \vDash \psi$  means " $\psi$  is true of path  $\omega$ "

- $\triangleright \ \omega \vDash \bigcirc \varphi \ \text{iff} \ \omega(1) \vDash \varphi$
- $\blacktriangleright \ \omega \vDash \varphi_1 \ \mathcal{U} \ \varphi_2 \ \text{iff for some} \ j \geq 0, \omega(j) \vDash \varphi_2 \ \text{and for all} \ i < j, \omega(i) \vDash \varphi_1$
- $\omega \vDash \varphi_1 \ \mathcal{U}^{\leq k} \ \varphi_2$  iff for some  $j, 0 \leq j \leq k, \ \omega(j) \vDash \varphi_2$  and for all  $i < j, \ \omega(i) \vDash \varphi_1$
- ▶ Exercise: work out the semantics for  $\omega \models \varphi_1 \ \mathcal{W}^{\leq k} \ \varphi_2$  and for  $\omega \models \varphi_1 \ \mathcal{R}^{\leq k} \ \varphi_2$



# PCTL Semantics - commentary

- ▶ All bar  $\mathbb{P}_{\sim p}$  and  $\mathcal{U}^{\leq k}$  have essentially the same sematics (and same intuitive meaning) as in CTL
- ▶ The extra Markov chain structure is needed for interpreting  $\mathbb{P}_{\sim p}$ .
  - ▶ Recall definition of  $Pr_s(\Pi)$  for a 'measurable' set  $\Pi$  of paths out of a state s of the DTMC.
  - Set Π is built by countible union and complementation from cylinder sets and we assign it a probability by adding up the probabilities of the cylinder sets.
  - ▶  $Pr_s(\{\omega \in Paths(s) | \omega \models \psi\})$  is the probability of the set of paths out of s satisfying path formula  $\psi$ . (This is always 'measurable').
  - ▶ Thus, for instance,  $s \models \mathbb{P}_{>0.25} \ \psi$  iff the probability that  $\psi$  is true for outgoing paths from s is > 0.25.
  - ▶  $s \models \mathbb{P}_{>0.25} \bigcirc fail$  iff the probability is > 0.25 that fail will be the case pm the next state of outgoing paths from s.
- ▶  $\varphi_1 \ \mathcal{U}^{\leq k} \ \varphi_2$  is a 'bounded' version of  $\varphi_1 \ \mathcal{U} \ \varphi_2$ : at state s, it says ' $\varphi_2$  will hold within k steps (of s) and in the meantime,  $\varphi_1$  holds'. In fact this is definable in CTL, not just PCTL.

# Logical equivalences in PCTL

The propositional equivalences noted above for CTL obtain here also; eg

- ¬false ≡ true
- disjuction:  $\varphi_1 \vee \varphi_2 \equiv \neg(\neg \varphi_1 \wedge \neg \varphi_2)$
- implication:  $\varphi_1 \Rightarrow \varphi_2 \equiv \neg \varphi_1 \lor \varphi_2$

Negation works with probabilities as you would expect; eg

- $\qquad \neg \mathbb{P}_{>p}(\varphi_1 \mathcal{U} \varphi_2) \equiv \mathbb{P}_{<p}(\varphi_1 \mathcal{U} \varphi_2)$
- Check the sematics of this!
- ▶ How about bounded U?

## Logical equivalences in PCTL; Reachability; Invariance

#### More bounded temporal operators ...

- $\triangleright \lozenge^{\leq k}$ ,  $\square^{\leq k}$  are defined with semantics analogous to  $\mathcal{U}^{\leq k}$
- ... or they can be derived: eg  $\lozenge^{\leq k} \varphi \triangleq true \ \mathcal{U}^{\leq k} \ \varphi$
- ▶ Defining  $\Box^{\leq k} \varphi \triangleq \neg \lozenge^{\leq k} \neg \varphi$  requires the ability to negate a path formula; some textbook define this, some don't.
- $ightharpoonup \mathcal{W}^{\leq k}$  and  $\mathcal{R}^{\leq k}$  derived from  $\mathcal{U}^{\leq k}, \square^{\leq k}$  similarly to slide 10

#### Probabilistic reachability, bounded reachability...

- $ightharpoonup \mathbb{P}_{\sim p} \lozenge \varphi$ : the probability of reaching a state satisfying  $\varphi$
- ▶  $\mathbb{P}_{\sim p} \lozenge^{\leq k} \varphi$ : the probability of reaching a state satisfying  $\varphi$  in k steps

#### Probabilistic (bounded) invariance ...

- ▶  $\mathbb{P}_{\sim p}\Box \varphi$ : the probability of  $\varphi$  remaining always true
- $ightharpoonup \mathbb{P}_{\sim p} \square^{\leq k} \varphi$ : the probability of  $\varphi$  remaining true for k steps

### **Examples**

- ▶  $\mathbb{P}_{<0.05}$   $\Diamond$ (numFaults/total > 0.1) with probability less than 0.05, the fault rate is over 10%.
- ▶  $\mathbb{P}_{\geq 0.8}$   $\lozenge^{\leq 15}$  (numReplies == n) with probability at least 0.8, the sender has received n replies within 15 clock ticks.
- ▶  $\mathbb{P}_{<0.4}$  (¬ $fail_A \mathcal{U} fail_B$ ) with probability under 0.4, component B fails before A.
- ▶  $\neg oprtnl \Rightarrow \mathbb{P}_{\geq 1} \lozenge \mathbb{P}_{>0.99} \square^{\leq 100}$  oprtnl if the system is not operational, then almost surely, it eventually reaches a state where it has a better than 0.99 chance of staying operational for 100 ticks.

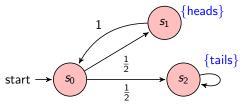
### Qualitative vs quantitative properties

 $\mathbb{P}$  is a kind of quantitative analogue of  $\forall$ ,  $\exists$  of CTL.

- ▶  $\mathbb{P}_{\sim p} \ \psi$  is *qual*itative when p = 0 or 1, *quant*itative when 0 .
- ▶  $\mathbb{P}_{>0}$   $\Diamond \varphi$  is semantically equivalent to (CTL)  $\exists \Diamond \varphi$ 
  - lacktriangle "There is a finite path to a state where  $\varphi$  holds"
  - Exercise: check this!
- ▶  $\mathbb{P}_{\geq 1} \lozenge \varphi$  is similar to but weaker than  $\forall \lozenge \varphi$ 
  - "A state where  $\varphi$  holds is 'almost surely' reached"
  - whereas  $\forall \Diamond \varphi$  says "A state where  $\varphi$  holds is reached"
  - For example ...

### Qualitative vs quantitative properties - example

Toss a coin repeatedly until "tails"



Must "tails" always eventually be thrown?

- ► CTL: ∀◊tails
- ▶ False: path  $s_0s_1s_0s_1s_0s_1...$  is a counterexample

#### But

- ▶ PCTL:  $\mathbb{P}_{>1} \lozenge tails$  is true
- ▶ ... because path  $s_0s_1s_0s_1s_0s_1$ ... has probability 0.

### Quantitative properties

When testing a PCTL formula  $\mathbb{P}_{\sim p} \ \psi$ , we might have no idea how to choose the bound, p.

- $\blacktriangleright$  If this  $\mathbb P$  is the outmost one in the formula, PRISM allows the form  $\mathbb P_{=^7}\ \psi$
- ightharpoonup PRISM returns the probability of  $\psi$
- Eg:  $\mathbb{P}_{=?}$  [ $\Diamond$ (err/tot > 0.1)]

### PRISM notation

Read the chapter on Property Specification in the PRISM manual.

- ▶ PRISM supports the  $\mathbb{P}$  operator in its inequality form (slide 11) as well as  $\mathbb{P}_{=?}$  [...] as above.
- ▶ In fact, PRISM supports CTL as well as PCTL: remember CTL (state) formulae are true/false at a state, as is a formula of the form  $\mathbb{P}_{\sim p}$  [...].
  - ▶ The CTL path quantifiers  $\forall$ ,  $\exists$  are denoted A, E in PRISM.
- ▶ Atomic formulae in PRISM are expressed in terms of state variables.
- ➤ A state is determined by a tuple of values of the state variables. Thus, state formulae are essentially predicates on these tuples.
- ▶ "Path properties" are path formulae in the sense of these slides. PRISM uses the notation X for  $\bigcirc$ ; and U, W for the "until" operators we have denoted U, W. F, G are used rather than  $\lozenge, \square$ .
  - $\mathbb{P}_{=?}[F\varphi]$  for  $\mathbb{P}_{=?}[\Diamond\varphi]$
  - Arr  $\mathbb{P} > 0.5 [XG^{\leq 4}\varphi]$  for  $\mathbb{P}_{>0.5} [\bigcirc \square^{\leq 4}\varphi]$

#### Rewards

PRISM provides an enhancement of basic probabilistic automaton modelling:

- A rewards section may be declared, in which a numerical "reward" can be assigned to each state
  - guarded by a predicate on state variables
  - may be a function of the state variables
- ... and/or to each transition, similarly.

A total reward accumulates as the model runs along a path. PRISM offers an operator  $\mathbb R$  to query the *expected value* of reward ...

- ▶  $R \sim p[\theta]$  where  $\sim$  is one of  $<, \le, >, \ge$ , p is a bound,  $\theta$  a "reward property"
  - true in a state of a model if "the expected reward on associated with θ of the model when starting from that state" is p
- $ightharpoonup R = ?[\theta], Rmin = ?[\theta], Rmax = ?[\theta]$ 
  - ▶ Reports the actual expected reward value.
- Details in the Property Specification chapter of the manual



### Other temporal logics?

Linear Time Logic (LTL, used by SPIN) is in some ways more expressive than CTL and its probabilistic version PCTL.

- LTL has only path formulae -
- $\psi ::= true \mid \alpha \mid \psi \wedge \psi \mid \neg \psi \mid \bigcirc \psi \mid \psi \ \mathcal{U} \ \psi$ 
  - $\alpha$  denotes an atomic proposition,  $\psi$  a path formula.
- ▶ Semantics: for any path  $\omega$ ,
  - ▶  $\omega \models true$  always
  - $\omega \vDash \alpha$  iff  $\alpha \in L(\omega(0))$
  - $\omega \vDash \psi_1 \wedge \psi_2$  iff  $\omega \vDash \psi_1$  and  $\omega \vDash \psi_2$
  - $\qquad \qquad \omega \vDash \neg \psi \text{ iff } \omega \nvDash \psi$
  - $\omega \vDash \bigcirc \psi$  iff  $\omega[1...] \vDash \psi$
  - $\omega \vDash \psi_1 \mathcal{U} \psi_2$  iff

for some n>0,  $\omega[n...] \vDash \psi_2$  and for all  $0 \le k < n$ ,  $\omega[k...] \vDash \psi_1$ 

- ▶ Derived operators as in CTL: eg propositional ∨, ⇒ and
  - $\blacktriangleright \ \Diamond \psi \triangleq \mathsf{true} \ \mathcal{U} \ \psi$
- An LTS satisfies a (path) formula iff all paths from its initial state satisfy it.

## Other temporal logics?

LTL has a simpler time model (linear rather than branching) than (P)CTL but in some ways is more expressive.

- ▶ The LTL formula  $\Diamond(reqst \land \bigcirc ack)$ : "Eventually there is a request followed immediately by an acknowledgement"
- ... cannot be expressed in CTL
- ▶ PCTL is essentially limited to properties than can be put in the form "B can reached via states in C [within k steps] (where B, C are sets of states).
- ▶ In (P)CTL, every temporal operator has to be within immendiate scope of a quantifer, but in LTL, temporal operators can be combined:  $\Box \Diamond \psi$  and so forth.

## Other temporal logics?

One idea is to add probabilities to LTL: taking cue from PCTL:

▶  $Prob(s, \psi) \triangleq Pr_s(\{\omega \in Paths(s) | \omega \models \psi\})$ 

One can then express in 'LTL+probability',

- ▶ Repeated reachability:  $Prob(s, \Box \Diamond action)$ 
  - the probability that the action occurs infinitely often
- ▶ Persistence:  $Prob(s, \Diamond \Box steadyState)$ 
  - the probability that the algorithm eventually reaches a steady state

### PCTL\*

#### An extension of PCTL with elements of LTL

- Maintains distict state and path formulae;
- State formula:  $\varphi ::= true \mid \alpha \mid \varphi \wedge \varphi \mid \neg \varphi \mid \mathbb{P}_{\sim p} \psi$
- ▶ Path formula:  $\psi ::= \varphi \mid \psi \land \psi \mid \neg \psi \mid \psi \ \mathcal{U}^{\leq k} \ \psi \mid \psi \ \mathcal{U} \ \psi$ 
  - $\alpha$  denotes an atomic proposition,  $\varphi$  a state formula and  $\psi$  a path formula;
- allows conjuction and negation (hence all boolean combinations) of path formulae; and a state formula is a path formula
- ► A PCTL\* formula is a state formula (so path formulae have to be quantified)
- ▶ Example:  $\mathbb{P}_{>0.1}[\Box \Diamond critSect_1] \land \mathbb{P}_{>0.1}[\Box \Diamond critSect_2]$