

# Embedded Systems Specification and Design

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- Recap of Propositional Logic
- Linear-time Temporal Logic (LTL)
- Specifying properties with LTL
- LTL specification patterns
- LTL, ProMela and SPIN

# Propositional Logic: Recap

## Definition (Proposition, Propositional Variable)

A **proposition** is a statement that is either true or false.

A **propositional variable** is a variable that has one of two possible values: true and false. Propositional variables are used to represent propositions.

- Propositions

- “It rained in Newcastle on 17th October 2008”.
- “Mike Ashley is an excellent football club chairman”
- `n <= 1, len(buffer) == MAX_BUF_SIZE`

- Propositional variables

- rain, ashley,  $p$ ,  $q$ , ...

- Not propositions

- “Pass the salt”
- “Does Joe Kinnear know what he’s doing?”

# Propositional Logic: Recap

## Definition (Logical Connective)

Compound propositions can be formed from simpler propositions using **logical connectives**, whose meaning can be given by a **truth table**.

$p$	$q$	$\neg p$	$p \vee q$	$p \wedge q$	$p \Rightarrow q$	$p \Leftrightarrow q$
false	false	true	false	false	true	true
false	true	true	true	false	true	false
true	false	false	true	false	false	false
true	true	false	true	true	true	true

# Propositions and Transition Systems

- Modify our view of LTS with the idea that each state provides a valuation for a set of propositional variables. Ignore labels.

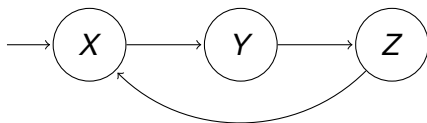
## Definition (Transition System)

A **transition system** is a tuple  $(S, s^0, \longrightarrow, Prop, \mathcal{P})$ , where

- $S$  is the set of states
- $s^0 \in S$  is the initial state
- $\longrightarrow \subseteq S \times S$  is the transition relation
- $Prop$  is the set of propositions
- $\mathcal{P} : S \rightarrow 2^{Prop}$  labels states with true propositions

# Propositions and Transition Systems

Consider the transition system  $TE$  given by



with  $Prop = \{m\_is\_2, m\_is\_3, m\_is\_4, n\_is\_0, n\_is\_2, n\_is\_4\}$  and  $\mathcal{P} = \{X \mapsto \{m\_is\_2, n\_is\_0\}, Y \mapsto \{m\_is\_3, n\_is\_2\}, Z \mapsto \{m\_is\_4, n\_is\_4\}\}$

- *TE* may arise from the Promela model given by

```
active proctype P() {  
    bool m_is_2 = true, m_is_3, m_is_4;  
    bool n_is_0 = true, n_is_2, n_is_4;  
  
    do  
        :: m_is_2 ->  
            d_step{m_is_2 = false; m_is_3 = true;  
                n_is_0 = false; n_is_2 = true}  
        :: m_is_3 ->  
            d_step{m_is_3 = false; m_is_4 = true;  
                n_is_2 = false; n_is_4 = true}  
        :: m_is_4 ->  
            d_step{m_is_4 = false; m_is_2 = true;  
                n_is_4 = false; n_is_0 = true}  
    od  
}
```

# Propositions and Transition Systems

- or more naturally from

```
active proctype P() {  
    byte m = 2;  
    byte n = 0;  
  
    do  
        :: (n >= m) -> d_step{m = 2; n = 0}  
        :: else      -> d_step{m = m + 1; n = n + 2}  
    od  
}
```

- so we will usually assume that the elements of *Prop* are simple propositions involving program variables.



## Definition (Trace)

Given a transition system  $T$ , a **trace** of  $T$  is a (possibly infinite) sequence of states  $s_0, s_1, s_2, \dots$  such that for  $i > 0$ ,  $s_{i-1} \longrightarrow s_i$ .

## Example

$s_0, s_1, s_2, s_3, s_4, s_5, s_6, s_7, \dots$  is a trace of the transition system  $TE$  where

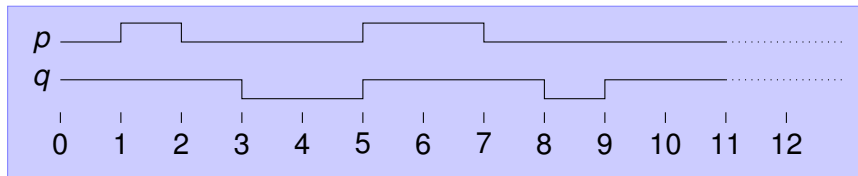
$$s_i = X, \quad \text{if } i \bmod 3 = 0$$

$$s_i = Y, \quad \text{if } i \bmod 3 = 1$$

$$s_i = Z, \quad \text{if } i \bmod 3 = 2$$

# Timing diagrams

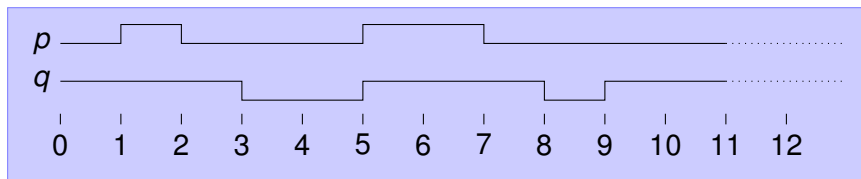
- Propositions are associated with the states in a trace.
- So they can change their truth value over time.
- Timing diagrams can be useful to show this change.



- Each propositional variable's value is shown as a line of the timing diagram.
- Line high – proposition is true.
- Line low – proposition is false.

# State formulas

- Now we can start to make formal statements about what happens in a trace.
- State formulas are the simplest statements about traces. They are propositional formulas constructed from *Prop* and the logical connectives; e.g. *n\_is\_4*, *m\_is\_3*  $\wedge$  *n\_is\_2*, *p*  $\Rightarrow$  *q*, etc.
- For a trace *s* and state formula *f*, we can ask whether *f* is true at some state *s<sub>i</sub>* in *s*, if it is we write *s<sub>i</sub>*  $\models$  *f*



For

which *i* do we have (a) *s<sub>i</sub>*  $\models$  *p*  $\wedge$  *q*, (b) *s<sub>i</sub>*  $\models$  *p*  $\vee$  *q*, and  
(c) *s<sub>i</sub>*  $\models$  *p*  $\Rightarrow$  *q*?

How can we say something about traces as they evolve over time?

- $\Box$  – **Always**:  $\Box\phi$  is true at moment  $i$  if  $\phi$  is true from moment  $i$  onwards
- $\Diamond$  – **Eventually**:  $\Diamond\phi$  is true at moment  $i$  if  $\phi$  is eventually true at  $i$  or some time later
- $\mathcal{U}$  – **Strong Until**:  $\phi \mathcal{U} \psi$  is true at moment  $i$  if  $\psi$  is eventually true and  $\phi$  is true until then.
- $\mathcal{W}$  – **Weak Until**: Like strong until except we don't require that  $\psi$  is eventually true

# Always ( $\Box\phi$ )

## Definition (Always)

$s_i \models \Box\phi$  iff  $\forall j \geq i \bullet s_j \models \phi$

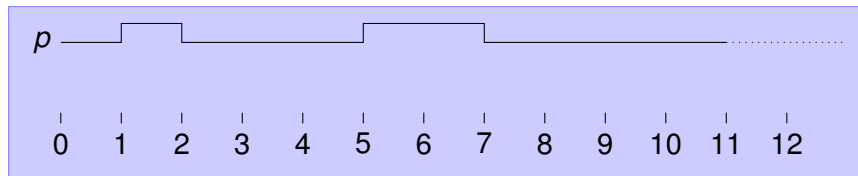


- $s_3 \models \Box p$
- $s_0 \not\models \Box p$

# Eventually ( $\Diamond\phi$ )

## Definition (Eventually)

$s_i \models \Diamond\phi$  iff  $\exists j \geq i \bullet s_j \models \phi$

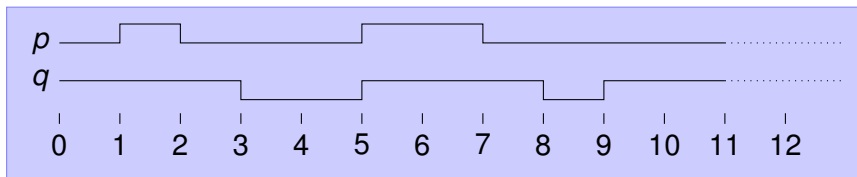


- $s_0 \models \Diamond p$
- $s_6 \models \Diamond p$
- $s_7 \not\models \Diamond p$

# Exercises

- Which of the following claims are true of the trace shown in the diagram below?

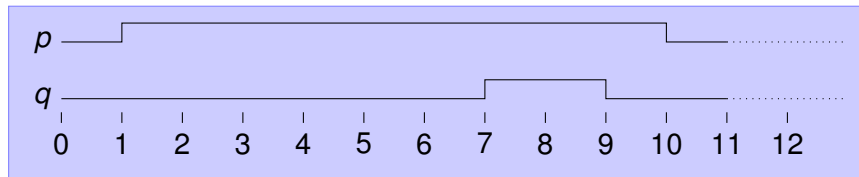
- 1  $s_9 \models \Box q$
- 2  $s_9 \models \Box \neg p$
- 3  $s_0 \models \Box q$
- 4  $s_0 \models \Box (p \Rightarrow q)$
- 5  $s_9 \models \Diamond p$
- 6  $s_0 \models \Diamond q$
- 7  $s_0 \models \Diamond \neg (p \Rightarrow q)$



# Strong Until ( $\phi \mathcal{U} \psi$ )

## Definition (Strong Until)

$s_i \models \phi \mathcal{U} \psi$  iff  $\exists k \geq i \bullet s_k \models \psi \wedge \forall j \mid i \leq j < k \bullet s_j \models \phi$



- $s_2 \models p \mathcal{U} q$
- $s_7 \models p \mathcal{U} q$
- $s_0 \not\models p \mathcal{U} q$
- $s_9 \not\models p \mathcal{U} q$



# Weak Until ( $\phi \mathcal{W} \psi$ )

- Define **weak until** in the style of the other definitions.
- Define **weak until** using the other temporal connectives.

# Classifying temporal properties

- **Safety** – “Nothing bad happens”

$\Box \neg (\text{in\_cs1} \wedge \text{in\_cs2})$

- **Liveness** – “Something good happens”

$\Box (\text{request} \Rightarrow \Diamond \text{receive})$

- **Fairness** – “Computation is fair”

$\Box \Diamond \text{coffee\_ordered} \Rightarrow \Box \Diamond \text{coffee\_delivered}$

# Specification Patterns

- It is easier to write specifications using temporal logic rather than automata.
- But it is still not easy.
- Specification **patterns** can help – just as design patterns can help in programming.
- Alavi, H. et al., [SPEC Patterns](#), 2005

# Main specification patterns for LTL

- **Invariance** ( $\Box \neg P$ )

$\Box \neg (\text{systemState} == \text{DANGEROUS})$

$\Box \neg ((\text{crossing} == \text{OCCUPIED}) \wedge (\text{gate} == \text{OPEN}))$

- **Bounded Response** ( $\Box(P \Rightarrow \Diamond Q)$ )

$\Box(\text{waitingForService} \Rightarrow \Diamond \text{serviceReceived})$

$\Box(\text{facingObstacle} \Rightarrow \Diamond(\text{distanceFromObstacle} \geq 5))$

- Nearly all of the specifications that you write will be either an *invariance* property or a *bounded response* property.
- Much more practice in writing LTL specifications to come in the lab sessions.

# Acknowledgements

These slides are based on material in Barland, I.; Vardi, M.; Greiner, J. *Model Checking Concurrent Programs*, Connexions Web site. <http://cnx.org/content/col10294/1.3/>, Oct 27, 2005.