

Seminar 4 problem Sheet

1. Consider the following process set:

Process	Priority	Release Time	Execution Pattern
A	3	2	ERRE
B	2	5	EEEE
C	1	0	ERRRRRE

(An alternative way of representing the above information is as follows

$A = \{1P(R)2V(R)1\}$ released at time 2

$B = \{5\}$ released at time 5

$C = \{1P(R)5V(R)1\}$ released at time 0

where $P(R)$ represents the lock operation on resource R and $V(R)$ the unlock operation. Each number in the brackets is the execution time for each piece of the task.}

where E represents the process executing without the resource and R the process executing with the resource.

- Draw the time line for the process set.
- Re-draw the time line when priority inheritance is used.
- Calculate the blocking time for each process.

The Completion Time Theorem still holds but with the following modification, we now calculate the response time using

$$R_i = C_i + B_i + I_i$$

where C_i is the worst case cpu requirement, B_i is the time lost due to blocking, and I_i is the interference due to higher priority processes.

- Test the schedulability of the task set.

An alternative approach to controlling priority inversion is to implement a policy that a process may not be pre-empted while in its critical section.

- Draw a time line showing how the above process set would execute under this policy.

2. Consider the following process set:

Process	Priority	CPU Time	Release Time	Resource Q (after, for)
A	3	5	6	2,2
B	2	7	2	2,4
C	1	6	0	1,4

- Draw a time line for the above process set using simple priority pre-emption.
- Assume the deadlines for each process are 14,17 and 18 respectively do the processes make their deadlines?
- Suppose process C only requires resource Q for 2.5 units of time. Redraw the time line.
- Do the processes still make their deadlines?
- Re-work each scenario using
 - basic priority inheritance;
 - Using the Ceiling Priority Protocol;
 - Using the Immediate Ceiling Priority Protocol;

3. Consider the following process set:

Process	Priority	CPU Time	Release Time	Resource Q After,For	Resource R After,For
A	4	5	4	1,2	3,1
B	3	6	2	3,2	1,2
C	2	3	2	1,2	
D	1	6	0	1,4	

(
 $A = \{1P(Q)2V(Q)P(R)1V(R)1\}$ released at time 4; priority 4 (high)
 $B = \{1P(R)2V(R)P(Q)2V(Q)1\}$ released at time 2; priority 3
 $C = \{1P(Q)2V(Q)\}$ released at time 2; priority 2
 $D = \{1P(Q)4V(Q)1\}$ released at time 0; priority 1 (low)
)

Draw time-lines for the above for

- A simple priority system;
- Using basic priority inheritance;
- Using the Ceiling Priority Protocol;
- Using the Immediate Ceiling Priority Protocol;

Calculate the blocking times for each process under basic priority inheritance and under CPP.

4. Consider the following process set:

A = {1P(Q)1V(Q)1} release time 7; priority 5 (high)

B = {1P(R)1V(R)1} release time 5; priority 4

C = {2} release time 4 ; priority 3

D = {1P(Q)2P(R)1.5V(R)0.5V(Q)1} release time 2 ; priority 2

E = {1P(R)4V(R)1} release time 0; priority 1 (low)

Draw a time line to show the behaviour of this set when the scheduler uses priority inheritance.

Assuming that the scheduler implements the Ceiling Priority Protocol what are the ceiling priorities of Q and of R? Draw a time line showing the behaviour of the system under the Ceiling Priority Protocol. Draw a graph showing the values of the priority ceiling for the system during the time the process set runs.

Re-work the problem using the Immediate Ceiling Priority Protocol.

Calculate the blocking times for each process under basic priority inheritance and under CPP.