

# Embedded systems engineering

## Distributed real-time systems

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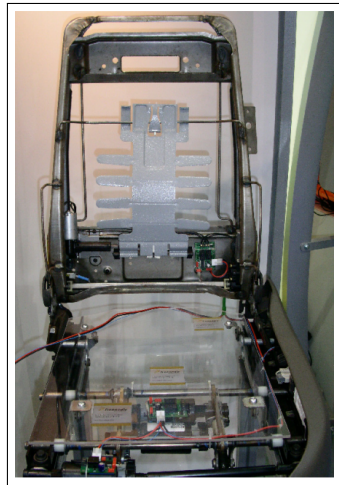
# Introduction

- ...to embedded systems
  - which are *distributed* and *real-time*
- ...to engineering
- ...to embedded systems engineering
- ...to the module

# Embedded systems are everywhere

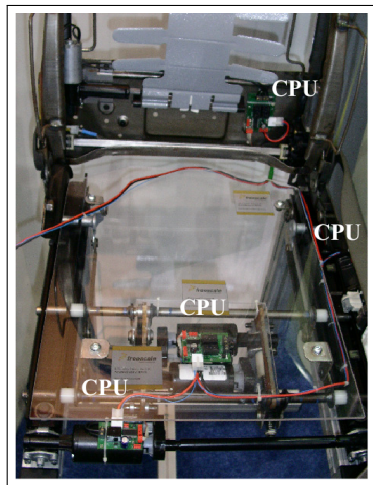
How many CPUs in a car seat?

- Photo from Convergence 2004
  - automotive electronics show



# How many CPUs in a car seat?

- Low speed LIN network to connect seat motion control nodes
- This is a distributed embedded system
- CPUs
  - Front-back motion
  - Seat tilt motion
  - Lumbar support
  - Control button interface



# How many CPUs in a car?

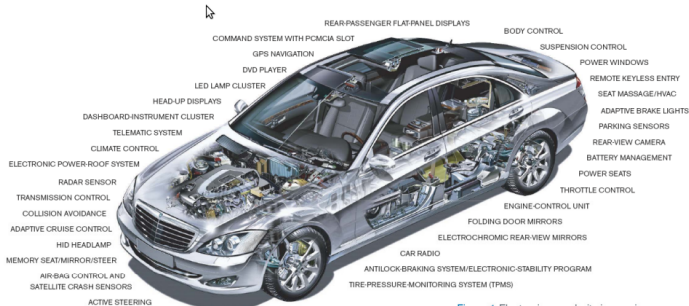
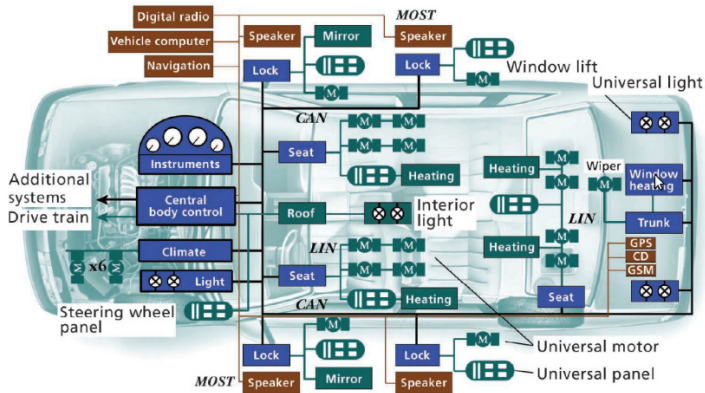


Figure 1 Electronic complexity in cars is increasing. New Mercedes S-Class cars employ at least 70 networked ECUs (electronic control units); 10 years ago, most cars had three ECUs (photo courtesy of DaimlerChrysler; source: Gartner Research, November 2005).

# Car as a distributed embedded system



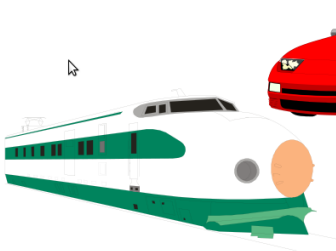
CAN Controller area network  
 GPS Global Positioning System  
 GSM Global System for Mobile Communications  
 LIN Local interconnect network  
 MOST Media-oriented systems transport

[Leen02]

# Embedded systems



Embedded Systems - Computers Monitoring/Controlling their environment



# Embedded systems characteristics

- **concurrent** – composed of multi-tasking and/or distributed processes
- **communicating** – specialized processes communicate in order to achieve some overall system function
- **real-time** – timing requirements are established by the environment
- **resource-constrained** – limited resources: processing, memory, peripherals, power, . . .



# Engineering

The American Engineers' Council for Professional Development defines “engineering” as:

*[T]he creative application of scientific principles to design or develop structures, machines, apparatus, or manufacturing processes, or works utilizing them singly or in combination; or to construct or operate the same with full cognizance of their design; or to forecast their behavior under specific operating conditions; all as respects an intended function, economics of operation and safety to life and property.*

# Embedded systems engineering

Application of scientific principles to

- the design of embedded systems
- the construction of embedded systems with “full cognizance” of their design
- the forecasting of the behaviour of embedded systems under specific operating conditions

“all as respects an intended function, economics of operation and safety to life and property”

# Embedded systems engineering

Application of scientific principles to design, construction and analysis of systems that are

- concurrent,
- communicating,
- real-time and
- resource-constrained

# Concurrency

- arises when multiple processes (tasks) share a single processor
- allocation of the processor to a different task can be
  - **event-triggered**
    - response to **any** of many possible **interrupts**: periodic timer overflow, the arrival of a message on a CAN bus, the pressing of a switch, the completion of an A/D conversion, ...
  - **time-triggered**
    - response to **one** source of **interrupt** only: usually a periodic timer
- managing and reasoning about concurrency is a major challenge for the embedded systems engineer

# Communication

- Computing nodes that communicate with each other form a **distributed system**
- Economic and safe allocation of resources in a distributed system requires a **predictable** communication network
- Predictable communication networks include
  - CAN, TTCAN
  - TTEthernet

# Real-time

- A **real-time system** is a system where the total correctness of an operation depends not just on the **logical correctness** of the result but also on its **temporal correctness** i.e. the time at which it is produced.
- A **deadline** specifies the time by which an operation must complete and deliver its result.
- A **hard real-time system** is a system that is considered useless if an operation misses a single deadline.
- A **soft real-time system** tries to meet its deadlines but can tolerate an occasional missed deadline, perhaps giving reduced service quality.

# Introduction to the module

- View the [module home page](#)

# Summary of the structure

- Uni-processor solutions
  - Time-triggered
  - Event-triggered
- Distributed solutions
  - Networks for embedded systems
    - Focus on Controller Area Network (CAN)
  - Analysing networked embedded systems
    - Distributed Response Time Analysis
- Other topics
  - C programming for embedded systems
  - Methods, tools, standards



# Acknowledgements

- Philip Koopman

[http://www.ece.cmu.edu/ece649/lectures/01\\_intro.pdf](http://www.ece.cmu.edu/ece649/lectures/01_intro.pdf)