PhD Corrections

1.1 Introduction

1.2 Bibliography

(PJ & KS) Dates in references are appearing twice	References 6, 7, 9, 10, 11, 12, 14, 15, 16, 18, 20, 24, 25, 28, 33, 37, 41, 47, 50, 52, 54, 55, 56, 58, 59, 61, 65, 67, 69, 71, 74, 76, 77, 78, 79, 82, 86, 90, 93, 94, 96, 98, 100, 113, 118, 126, 127, 130, 137, 139, 140, 141, 142, 146, 147, 150, 151, 152, 154, 155, 156, 157, 158, 161
(KS) No dates	References 21, 60, 70, 75, 92, 135 ?
(KS) References with no publisher	References 27, 30, 36, 42, 44, 48, 49, 51, 52, 53, 57, 60, 63, 68, 73, 81, 83, 84, 87, 88, 89, 101, 103, 108, 109, 115, 132, 149 ?
(KS) References with capitalised Author	References 88, 149
(KS) References requiring page numbers	Reference 117 ?

1.3 Abstract

1.4 Introduction

1.5 Methods Techniques Tools

(PJ) Citations sections 2.1, 2.7	Separate references Split references from Barnes and Bennet appropriately
(PJ) Typo	Section 2.3 interction interaction
(PJ) Incorrect reference	Figure 2.6 shows the Equation 2.5 shows

	Cardinality notation changed to use .
(PJ) Formulae 2.1, 2.3, 2.4 - Formula notation	$nbr(b) \stackrel{\Delta}{=} \{b' \in S : bb' <= C_b\}$ $R(b) = \{b' \in S : bb' <= R_b\}$ $v_r(b) = -\frac{1}{ R(b) } \left(\sum_{b' \in R(b)} \left(1 - \frac{ bb' }{R_b} \right) bb' \right)$ $\{o \in O : bo <= O_b\}$
(PJ) Section 2.6 - Sentence restruc- ture	moves an obstacles moves it may enter an obstacle's
(PJ) Section 2.8 - Special case reference error	Special case of Equation 2.7 Special case of Equation 2.8
(PJ) Spelling	Section 2.11 amp Figure 2.12 Stabalise Stabilise
(PJ) Expand Conclusion	No mention of current work Added small discussion of current work
(PJ) Explain ^	Section 2.6 uses unexplained notation Moved ^ explanation from section 2.9 to 2.6
(PJ) No equation	Section 2.9 uses inline formulae for movement. Equation broken out and referenced.

1.6 Magnitude Metric

(PJ) Table 4.2 - ; 3.2 Explain Labels	Log, Id, N.Id Labels expanded in text
(PJ) Section 4.2 - ; 3.2 Sentence error	vectorTable 4.4 vector. Table 4.4
(PJ) Section 4.3 - ; 3.3 Punctuation	= 0) The = 0). The
(PJ) Diagram 4.7 -¿ 3.7 Label error	bot agent

(KS) Equations	
4(3).2, 4(3).3,	
4(3).4, 4(3).6,	
4(3).7, 4(3).8	
and inline equa-	
tions cardinality	
notation changed	

1.7 Swarm Type

1.8 Perimeter Coordination

(PJ) Fig 28, 29	Needs to indicate starting point
	Added "Start Point" and arrows to graphs

1.9 Flood Filling

1.10 Future Work