

Embedded Systems Specification and Design

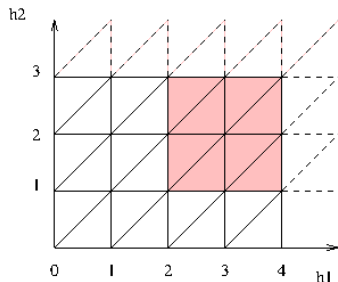
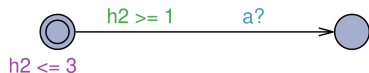
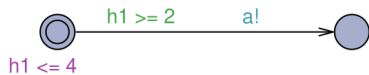
Model-based Design and Verification

David Kendall

State space of timed automaton is infinite ?!!

- Introduction of real-valued clock variables to FSM makes its state space infinite
- How can we exhaustively explore infinite state space?
 - ▶ We can't
- How can we exhaustively explore state space of timed automaton?
 - ▶ Find an equivalent finite representation of its state space
- This is the key idea that makes model-checking of timed automata possible
- Finite representations
 - ▶ Region graph
 - ▶ Zone (simulation) graph

Zones and their representation

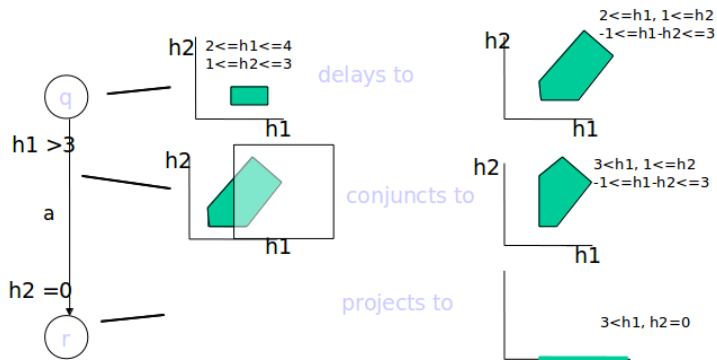


M	h_0	h_1	h_2
h_0	$(0, \leq)$	$(-2, \leq)$	$(-1, \leq)$
h_1	$(4, \leq)$	$(0, \leq)$	$(\infty, <)$
h_2	$(3, \leq)$	$(\infty, <)$	$(0, \leq)$

M'	h_0	h_1	h_2
h_0	$(0, \leq)$	$(-2, \leq)$	$(-1, \leq)$
h_1	$(4, \leq)$	$(0, \leq)$	$(3, \leq)$
h_2	$(3, \leq)$	$(1, \leq)$	$(0, \leq)$

DIFFERENCE BOUND MATRICES

Operations on zones



Thus $(q, 2 \leq h_1 \leq 4, 1 \leq h_2 \leq 3) = a \Rightarrow (r, 3 < h_1, h_2 = 0)$

Symbolic states and transitions

Symbolic state

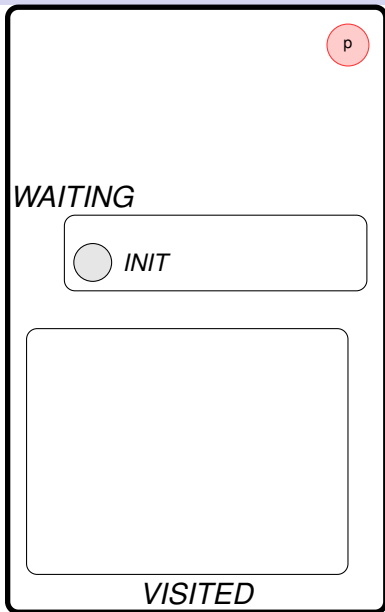
A **symbolic state**, $s = (\ell, \zeta)$, consists of:

- a *location vector*, ℓ , and
- a *zone*, ζ

Symbolic transition

If the edges of a network of timed automata justify a transition from location vector ℓ to location vector ℓ' and the delays to, conjuncts and projects operations transform the zone ζ to ζ' , then for $s = (\ell, \zeta)$ and $s' = (\ell', \zeta')$, we say there is a *symbolic transition* from s to s' and write $s \Rightarrow s'$

Forward reachability



$INIT \leftarrow (\ell^0, \mathbf{0}_C)$

$WAITING \leftarrow \{INIT\}$

$VISITED \leftarrow \emptyset$

while $WAITING \neq \emptyset$ **do**

 choose some $s = (\ell, \zeta)$ in $WAITING$

if s satisfies p **then**

return true

else

$NEW \leftarrow \{s' \mid s \Rightarrow s' \wedge s' \notin VISITED\}$

$WAITING \leftarrow WAITING \cup NEW \setminus \{s\}$

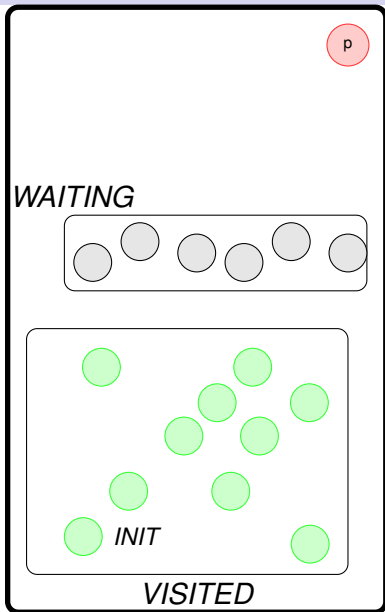
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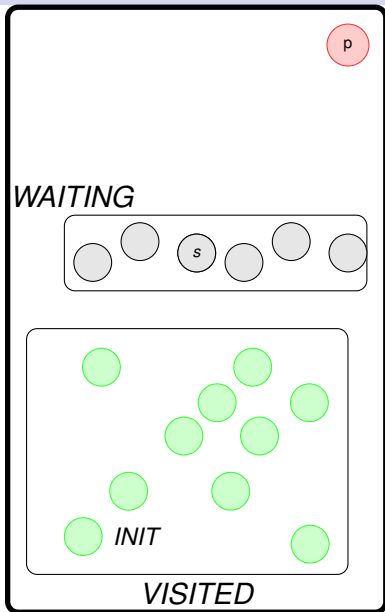
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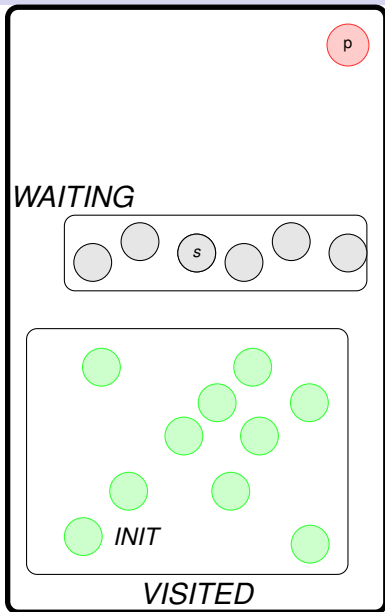
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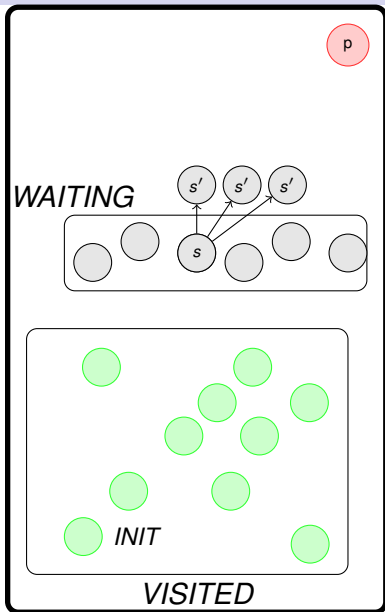
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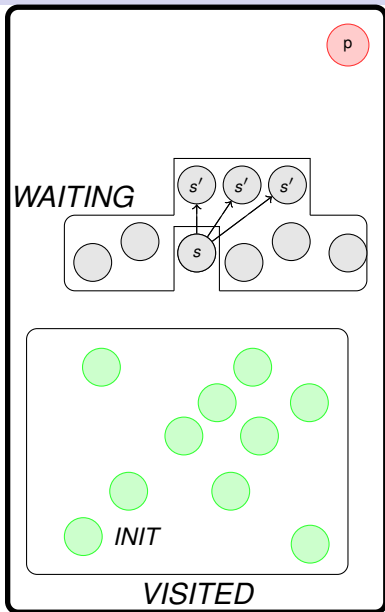
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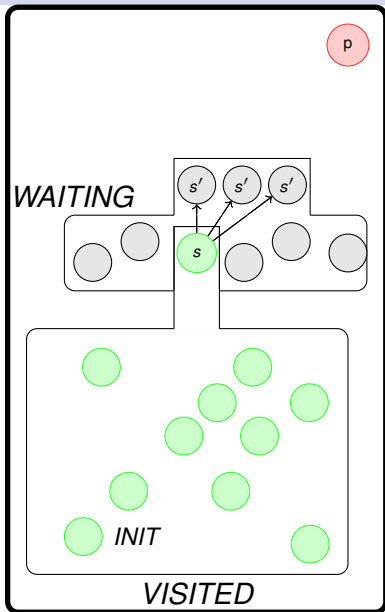
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Forward reachability



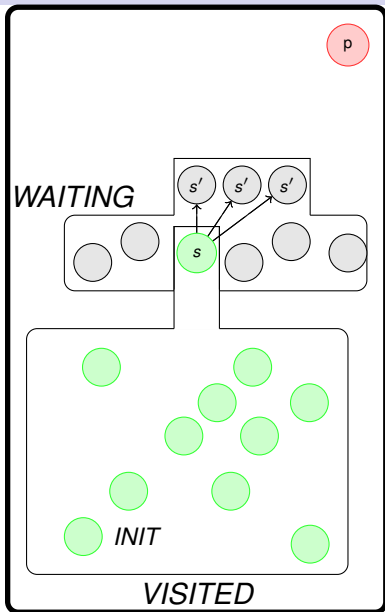
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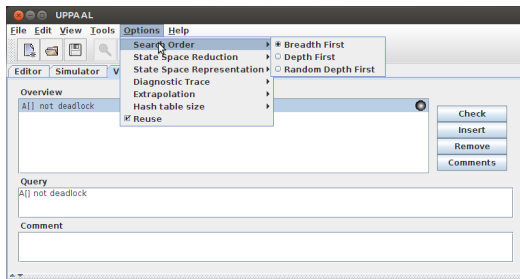
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Search order



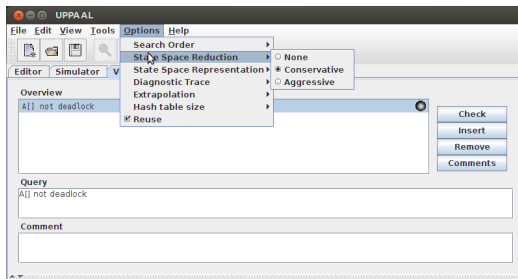
Breadth First:

- Search state space in breadth-first order
- Good for complete search and shortest/fastest trace

Depth First:

- Search state space in depth-first order
- Better than breadth-first if counter-example expected

State space reduction

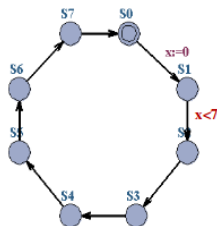


- Inclusion abstraction
- Active-clock reduction
- ...

Inclusion abstraction

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```

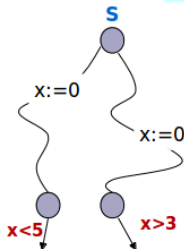

Active clock reduction



x is only **active** in location **S1**

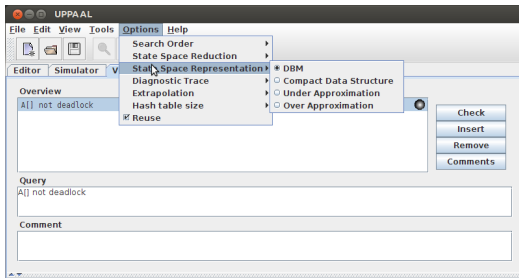
Definition

x is **inactive** at **S** if on all path from **S**, x is always reset before being tested.



- Inactive clocks need not be stored
- \Rightarrow smaller DBMs
- \Rightarrow smaller state space

State space representation



Under-approximation

- Uses **bit-state hashing**
- Does not guarantee to explore all states
- So, if verifier claims that some state is unreachable, it may be wrong
- Useful mainly for discovering bugs, not for proving their absence

Over-approximation

- Uses **convex hull abstraction**
- May explore too many states
- So, if verifier claims that some state is reachable, it may be wrong
- Can prove absence of bugs but when it fails you need to ask if it's a genuine failure or a failure caused by the abstraction

State space explosion summary

- Infinite number of states can be represented finitely by using symbolic representation, e.g. *zones*
- State space explosion
 - ▶ State space may be finite but often still too large to handle with current computing power
- Attacks on state space explosion
 - ▶ Store fewer states
 - ▶ Store smaller states

And finally...

Much recent research has pushed model-based development using timed automata into new areas

- Priced timed automata
 - ▶ Reason about resource usage, e.g. energy
- Timed games
 - ▶ Controller synthesis
- Probabilistic timed automata
 - ▶ Reason about probabilistic systems, e.g. Bluetooth
- Statistical model-checking
 - ▶ Don't explore full state space, but use statistical techniques to calculate confidence in results based on partial exploration