

1 Definition of metrics

1.1 Distance metric

The essential features of the distance metric for swarms, presented in (Eliot et al. 2018), can be summarised as follows:

$$\psi_d(S) = \mu_d(S) \pm \sigma_d(S)$$

where $\mu_d(S)$ is the mean distance over all agents $b \in S$, between b and its cohesion neighbours, given by:

$$\mu_d(S) = \frac{\sum_{b \in S} \sum_{b' \in n_c(b)} \|\vec{bb'}\|}{\sum_{b \in S} |n_c(b)|}$$

and $\sigma_d(S)$ is the standard deviation from the mean:

$$\sigma_d(S) = \sqrt{\frac{\sum_{b \in S} \sum_{b' \in n_c(b)} \left(\|\vec{bb'}\| - \mu_d(S) \right)^2}{\sum_{b \in S} |n_c(b)|}}$$

1.2 Cohesion/repulsion metric

The essential features of the cohesion/repulsion metric for swarms, adapted from (Eliot et al. 2018), can be summarised as follows:

$$\psi_p(S) = \mu_p(S) \pm \sigma_p(S)$$

where $\mu_p(S)$ is the mean of the adjusted magnitude values of the weighted cohesion/repulsion vectors of all agents, induced by their cohesion/repulsion neighbours. For each cohesion/repulsion vector, a positive value is derived from the magnitude of the vector if the cohesion component of the vector dominates, but a negative value is derived if the repulsion component dominates.

We define some helper functions, v_{cr} and P , to aid the specifications of μ_p and σ_p :

$$v_{cr}(b) = k_c v_c(b) + k_r v_r(b)$$

$$P(b) = \begin{cases} \|v_{cr}(b)\| & k_c v_c(b) > k_r v_r(b) \\ -\|v_{cr}(b)\| & \text{otherwise} \end{cases}$$

$v_{cr}(b)$ gives the weighted cohesion/repulsion vector for b and $P(b)$ gives the value derived from the magnitude of this vector. Now we can define the mean and standard deviation.

$$\mu_p(S) = \frac{\sum_{b \in S} P(b)}{D}$$

and $\sigma_p(S)$ is the standard deviation from the mean:

$$\sigma_p(S) = \sqrt{\frac{\sum_{b \in S} (P(b) - \mu_p(S))^2}{D}}$$

We still need to consider the definition of the denominator, D , here. (Eliot et al. 2018) defines D like this:

$$D = \sum_{b \in S} |n_c(b)| + |n_r(b)|$$

This seems to me to be over-counting agents. Remember that each agent $b \in S$ has at most one cohesion/repulsion vector as defined above. This has been scaled already by the reciprocal of the number of its cohesion and repulsion neighbours (see the definitions of $v_c(b)$ and $v_r(b)$ earlier). In calculating $\mu_p(S)$ and $\sigma_p(S)$, we should be dividing by at most $|S|$ but the value of D , as defined above, may be as big as $2(|S|^2 - |S|)$, clearly too big!. It might be argued that even $|S|$ may be too big, since S may include agents that are isolated and not participating in the cohesion/repulsion structure of the swarm and, therefore, should not be counted. In this case, we could define D as

$$D = \left| \bigcup_{b \in S} (n_c(b) \cup n_r(b)) \right|$$

I think it's reasonable to consider that the cohesion/repulsion structure is a property of the whole swarm S , whether or not it contains isolated agents, and, in the following, I take D to be

$$D = |S|$$

2 Implementation of metrics

2.1 Distance metric

```
@jit(nopython=True, fastmath=True)
def mu_sigma_d(mag, ecb):
    n_agents = mag.shape[0]
    msum = 0; msum_sq = 0; nsum = 0
    for i in prange(n_agents):
        for j in range(i):
            if mag[j, i] <= ecb[j, i]:
                msum += mag[j, i]
                msum_sq += mag[j, i] **2
                nsum += 1
            if mag[i, j] <= ecb[i, j]:
                msum += mag[i, j]
                msum_sq += mag[i, j] **2
                nsum += 1
```

```

mu_d = msum / nsum
mu_d_sq = msum_sq / nsum
var_d = mu_d_sq - mu_d ** 2
sigma_d = np.sqrt(var_d)
return mu_d, sigma_d

```

2.2 Cohesion/repulsion metric

```

def mu_sigma_p(b):
    vcr_x = b[COH_X] + b[REP_X] # the weighted cohesion/
    vcr_y = b[COH_Y] + b[REP_Y] # the magnitude of the w
    vcr_mag = np.hypot(vcr_x, vcr_y) # the magnitude of the c
    vc_mag = np.hypot(b[COH_X], b[COH_Y]) # the magnitude of the r
    vr_mag = np.hypot(b[REP_X], b[REP_Y]) # the implementation of l
    P = np.where(vc_mag > vr_mag, vcr_mag, -vcr_mag) # the total number of ag
    n_agents = b.shape[1] # the mean
    mu_p = np.sum(P) / n_agents # the standard deviation
    sigma_p = np.sqrt(np.sum((P - mu_p) ** 2) / n_agents)
    return mu_p, sigma_p

```