

Probability Basics in Computer Science

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Definitions

Experiments and Events

An event is a set of possible results in an experiment execution. For example, taking a card from a deck or rolling a dice. We can denote all possible results with Ω and an event with uppercase letter such that $A \subseteq \Omega$ or $A \in 2^\Omega$, then A is a subset of Ω .

Probability

Is an indicator that describes the frequency of an event in one universal set of possibilities. Daily, we express that indicator as a percentage value or value between 0 and 1. Then we can define the probability as:

$$p : 2^\Omega \mapsto [0, 1]$$

Definitions

- So, when Ω is a discrete and finite set, then:

$$p(A) = \frac{\#A}{\#\Omega}$$

- We name this as uniform distribution or counting distribution.
- However, counting elements in A and Ω isn't always trivial. Maybe we need to use operations like factorial, combinations, permutations, etcetera.

Examples

- Key pressing random letter of the english keyboard such that the letter be a vowel.
 - Let $A = \{a, e, i, o, u\}$ and $\Omega = \{a, \dots, z\}$, then $p(A) = \frac{5}{26}$.
- Rolling a dice such that the result be greater than 2.
 - Let $A = \{3, 4, 5, 6\}$ and $\Omega = \{1, 2, 3, 4, 5, 6\}$, then $p(A) = \frac{2}{3}$.
- Taking a card from a deck such that getting a red card.
 - Let
 $A = \{A♥, 2♥, \dots, 10♥, J♥, Q♥, K♥, A♦, 2♦, \dots, 10♦, J♦, Q♦, K♦\}$
and $\Omega =$
 $\left\{ \begin{array}{ll} A♥, 2♥, \dots, 10♥, J♥, Q♥, K♥, & A♦, 2♦, \dots, 10♦, J♦, Q♦, K♦, \\ A♠, 2♠, \dots, 10♠, J♠, Q♠, K♠, & A♣, 2♣, \dots, 10♣, J♣, Q♣, K♣ \end{array} \right\}$
then $p(A) = \frac{1}{2}$.

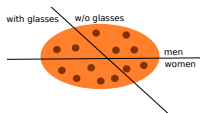
Properties and relations

Let A and B events in Ω , then

- $p(\Omega) = 1$ and $p(\emptyset) = 0$.
- $p(A \cap B)$ means the probability of a value that is in both sets, A and B .
- $p(A \cup B) = p(A) - p(A \cap B) + p(B)$ represents the probability of a value that is at least in one set, A or B .
- $p(A^c) = p(\Omega \setminus A) = 1 - p(A)$ is the probability of a value that isn't in A .
- If $A \cap B = \emptyset$ then $p(A \cup B) = p(A) + p(B)$.

Conditional probability

- Starting with following example: we have a set tokens whose represent the people whose are showing in the figure. So, closing our eyes we take a random token then the probability to take a woman is $\frac{\# \text{women}}{\# \text{people}} = \frac{7}{13}$.



- However, if someone tells us that (before we open our eyes) the chosen person wears glasses, then the probability will be conditioned to the fact that person wears glasses, then will be $\frac{\# \text{women with glasses}}{\# \text{people with glasses}} = \frac{5}{7}$.

Conditional probability

- This probability is denoted as $p(A|B)$, where
 - A is the event of taking a women.
 - B represents the event of taking a person who wears glasses.
- In general way, if $p(B) > 0$ then $p(A|B)$ is defined as:

$$p(A|B) = \frac{p(A \cap B)}{p(B)} = \frac{5/13}{7/13} = \frac{5}{7}$$

- Two events A and B are independents iff

$$p(A|B) = p(A)$$

or well

$$p(A \cap B) = p(A)p(B)$$

Probability in \mathbb{R}^n and random variables

- Let region $\Omega \subset \mathbb{R}^n$, then the probability of $A \subset \Omega$ will be:

$$p(A) = \frac{1}{c} \int_A f(\mathbf{x}) d\mathbf{x}$$

where:

- $\mathbf{x} \in A$ is the value of a random variable named $\mathbf{X} \in \mathbb{R}^n$ and $c = \int_{\Omega} f(\mathbf{x}) d\mathbf{x}$ is known as normalization factor. Random variables are denoted with uppercase letter and their values with lowercase letters.
- $f: \Omega \mapsto \mathbb{R}$ is a function known as probability density or simply density and for all $\mathbf{x} \in \Omega$ we have $f(\mathbf{x}) \geq 0$.
- $p(A)$ is known as probability distribution, cumulative distribution or simply distribution and is denoted with uppercase letter, frequently as F .

Probability in \mathbb{R}^n and random variables

- So, random variable can be discrete or continuous.
- We can denote the probability of a event where $\mathbf{X} = \mathbf{x}$ as $p(\mathbf{X} = \mathbf{x})$.
- Sometimes (always), the probability notation is very nasty. Beware!
- There are many probability distributions:
 - Uniform (discrete and continuous): $X \sim \mathcal{U}(a, b)$
 - Bernoulli (discrete): $X \sim \text{Be}(p)$
 - Binomial (discrete): $X \sim B(n; p)$
 - Geometric (discrete): $X \sim \text{Geom}(k; p)$
 - Poisson (discrete): $X \sim \text{Pois}(\lambda)$
 - Normal (continuous): $X \sim \mathcal{N}(\mu; \sigma^2)$
 - Chi-squared (continuous): $X \sim \chi^2(q)$
 - ...

Centrality

Let $X \in \mathbb{R}$ a random variable, then:

Expectation, expected value simply mean

Is the mean of the data based on their frequency:

$$\mathbb{E}X = \begin{cases} \sum_{x \in \Omega} x p(X=x) & X \text{ is discrete} \\ \frac{1}{c} \int_{\Omega} x f(x) dx & X \text{ is continuous} \end{cases}$$

Mode

Is most frequent value, then in the discrete case is $\arg \max_{x \in \Omega} p(X=x)$ and in the for continuos random variable is x such that $\frac{df}{dx} = 0$ and $\frac{d^2f}{dx^2} < 0$.

Centrality

Median

Is the value separating the higher half of a data sample, a population, or a probability distribution, from the lower half.

Function composition

The mean for composition functions is defined as following:

$$\mathbb{E}[g(X)] = \begin{cases} \sum_{x \in \Omega} g(x) p(X=x) & X \text{ is discrete} \\ \frac{1}{c} \int_{\Omega} g(x) f(x) dx & X \text{ is continuous} \end{cases}$$

Dispersion

Let $X \in \mathbb{R}$ a random variable, then:

Variance

Is the mean square distance between the mean point and the data.

$$\text{var}(X) = \mathbb{E}[X^2] - [\mathbb{E}X]^2$$

Entropy

Is the expected value of the information provided by a random variable X , we mean:

$$\mathbb{H}(X) = \mathbb{E}[\mathbb{I}(X)] = \mathbb{E}[-\log p(X)]$$

Linear median

```
function median( $\mathbf{x} \in \mathbb{R}^n$ )begin
```

```
    Parameters:  $k \in [n]$ 
```

```
     $p \leftarrow \text{random}(n);$ 
```

```
    Split  $\mathbf{x}$  into subarrays  $\mathbf{l}$  and  $\mathbf{g}$  by comparing each element to  
     $p$ -th element. While we are at it, count the number  $K$  of  
    elements going in to  $\mathbf{l}$ .
```

```
    if  $K = k - 1$  then:
```

```
        | return  $x_p$ ;
```

```
    else if  $K > k - 1$  then:
```

```
        | return median( $\mathbf{l}, k$ );
```

```
    else:
```

```
        | return median( $\mathbf{g}, k - K - 1$ );
```

```
    end
```

```
end
```

More applications

- Skip lists
- Random trees
- Random graphs
- Complexity analysis
- Page rank
- Simulation
- Visualizations
- Communications

References I

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