

QuecPython GPS User Guide

LTE Standard Module Series

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Quectel Wireless Solutions Co., Ltd.

Building 5, Shanghai Business Park Phase III (Area B), No.1016 Tianlin Road, Minhang District, Shanghai 200233, China

Tel: +86 21 5108 6236

Email: info@quectel.com

Or our local office. For more information, please visit: <http://www.quectel.com/support/sales.htm>.

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About the Document

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1 Introduction

This document takes EC100Y-CN as an example to introduce how to use the GPS module and antenna with GPS function.

2 GPS Overview

The system that uses GPS positioning satellites to perform positioning and navigation on a global scale in real time is called Global Satellite Positioning System, or GPS. NEMA-0183 is a standard protocol that GPS receivers should comply with, and it is also the most widely used protocol on GPS receivers. Most common GPS receivers, GPS data processing software, and navigation software all comply with or are at least compatible with this protocol.

GPS has been widely used in many industries such as transportation, surveying and mapping. All the application fields of GPS are based on positioning, mainly including: motion navigation, track recording, geodetic survey, surrounding information query, etc.

3 GPS Module Usage Process

3.1. Preparation

Step1: First, prepare the EC100Y-CN EVB and the L80-R GPS module, and connect the L80-R GPS module to the EVB. It should be in an outdoor environment to facilitate receiving GPS signals. As shown below:

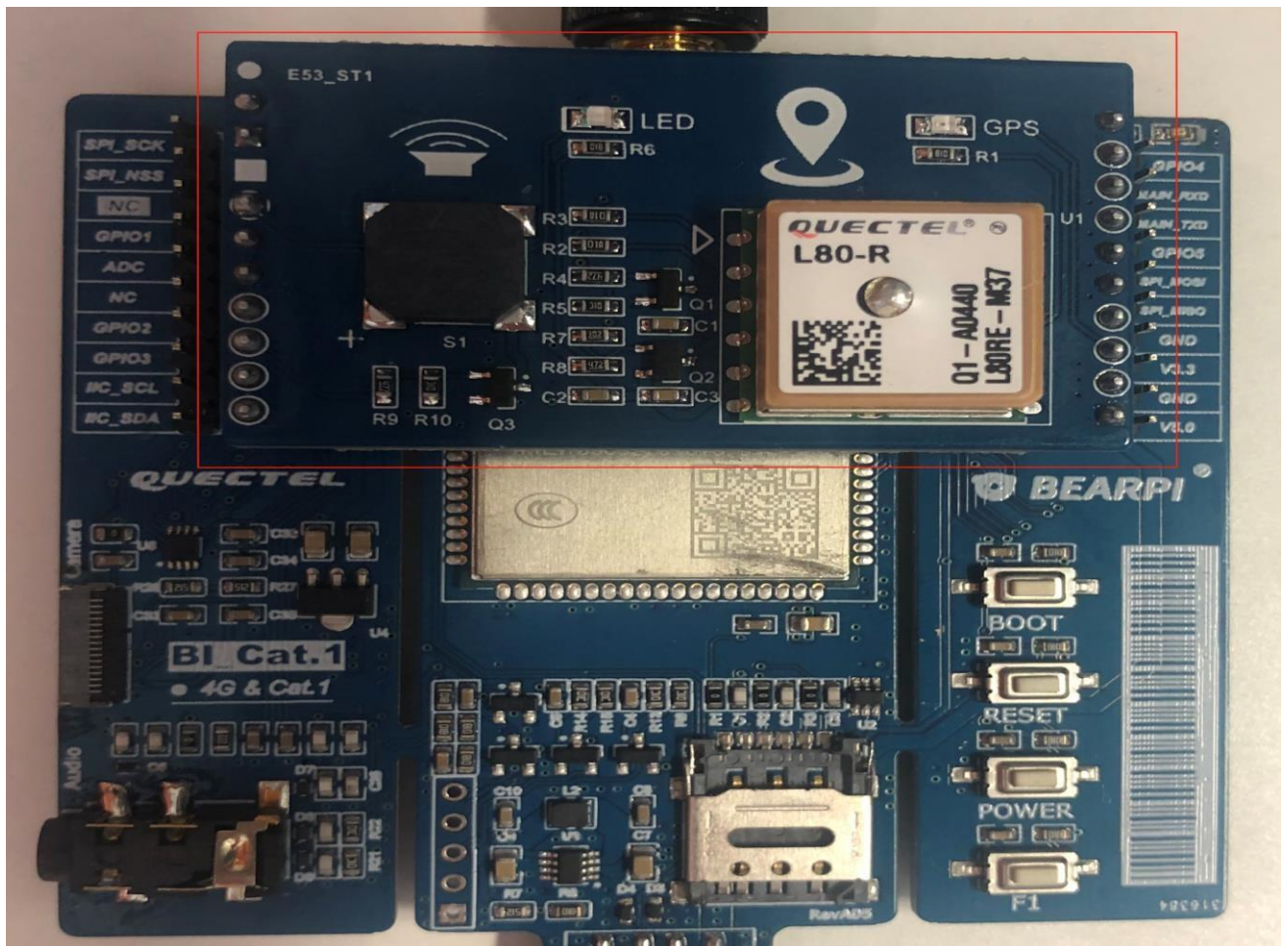


Figure 1: Connect GPS Module to EVB

The functions of the L80-R GPS module are shown below:

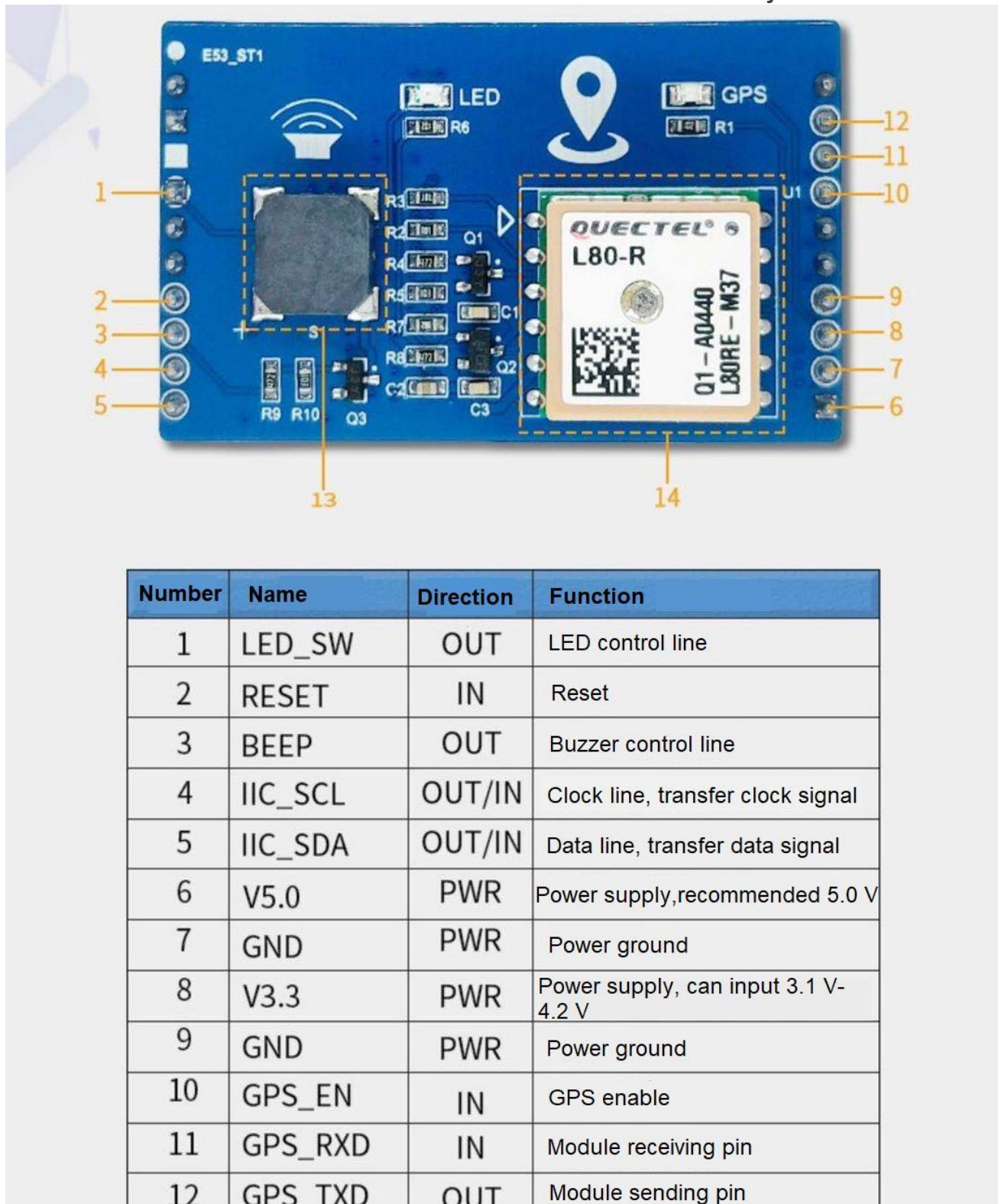


Figure 2: L80-R GPS Module Function

Step2: Connect the EVB through xshell tool and enter the interactive page. From the module function above, it can be seen that the serial port on the EVB corresponding to the *GPS_EN* pin is GPIO5, so the GPS function is enabled via GPIO5. The execution code is as follows:

```
>>> from machine import *
>>>
>>>
>>> gpio5 = Pin(Pin.GPIO5,Pin.OUT,Pin.PULL_DISABLE,1)
>>>
>>> gpio5.write(0)
0
>>>
```

Step3: After executing the above code, you can see that the GPS indicator light of the module is always on. Similarly, you can also set the voltage of GPIO1 to light up the LED.

3.2. Data Processing

Step1: After the GPS function of the module is enabled, the GPS data is sent to the EVB via the *GPS_TXD* serial port of the module, and the data is output via the data transmission function of the UART serial port of EC100Y-CN QuecPython machine module. The code is shown in the figure below:

```
>>>
>>> from machine import UART
>>> uart1 = UART(UART.UART2,9600,8,0,1,0)
>>> uart1.any()
8192
>>> uart1.read(1024)
b'$GPGGA,000102.262,,,,,0,0,,M,M,,*4D\r\n$GPGLL,,,,,000102.262,V,N*7F\r\n$GPGSA,A,1,,,,,,,,,,,,,*1E\r\n$G
00103.262,V,N*7E\r\n$GPGSA,A,1,,,,,,,,,,,,,*1E\r\n$GPGSV,1,1,00*79\r\n$GPRMC,000103.262,V,,,,,0.00,0.00,0.00,060
GSV,1,1,00*79\r\n$GPRMC,000104.262,V,,,,,0.00,0.00,0.00,060180,,N*41\r\n$GPVTG,0.00,T,,M,0.00,N,0.00,K,N*32\r\n$
80,,N*40\r\n$GPVTG,0.00,T,,M,0.00,N,0.00,K,N*32\r\n$GPGGA,000106.262,,,,,0,0,,M,M,,*49\r\n$GPGLL,,,,,00010
GGA,00'
>>> █
```

For detailed API interface description of machine module, please refer to *Quectel QuecPython Class Library API Description*.

Step2: Then, process the data format defined by the received NMEA-0183 protocol. The sentence to be processed is \$GNGGA. For example:

```
$GNGGA,092204.999,4250.5589,S,14718.5084,E,1,04,24.4,19.7,M,,,,,0000*1F
```

Field 0: \$GPGGA, sentence ID, indicating that the sentence is Global Positioning System Fix Data

Field 1: UTC time, hhmmss.sss, in hour, minute and second format

Field 2: Latitude, ddmm.mmmm, in degrees and minutes format (if the leading digit is insufficient, add 0)

Field 3: Latitude N (north latitude) or S (south latitude)

Field 4: Longitude, dddmm.mmmm, in degrees and minutes format (if the leading digit is insufficient, add

0)

Field 5: Longitude E (East longitude) or W (West longitude)

Field 6: GPS status, 0 indicates not positioned, 1 indicates non-differential positioning, 2 indicates differential positioning, 3 indicates invalid PPS, 6 indicates under estimation

Field 7: The number of satellites in use (00-12) (If the leading digit is insufficient, add 0)

Field 8: HDOP level precision factor (0.5-99.9)

Field 9: Altitude (-9999.9-99999.9)

Field 10: The height of the earth ellipsoid relative to the geoid

Field 11: Differential time (the seconds number since the last received differential signal, if it is not differential positioning, it is blank)

Field 12: Differential station ID number (0000-1023) (If the leading digit is insufficient, add 0, if it is not differential positioning, it is blank)

Field 13: Check value

Step3: Finally, run the following code to obtain the time, latitude and longitude in the GPS information. By continuously obtaining the time, latitude and longitude, the location can be tracked in real time. For detailed operation methods, please refer to *Quectel_QuecPython_Basic Operation Instructions*.

```
from machine import UART
import utime
import modem
import _thread
uart = UART(2, 115200, 8, 0, 1, 0)

def gngga():
    while True:
        #Get current RTC time
        time = utime.localtime() #Get
        device IMEI imei =
        modem.getDevImei() if
        uart.any() > 0:
            buf = uart.read(uart.any())
        buf = str(buf, "utf8") try :
            gngga1 = buf.split("$GNGGA,")[1].split("\r\n")[0].split(",")
        #UTC time, hhmmss.sss, in hour, minute and second format time_gps
        = gngga1[0]
        #Latitude, ddmm.mmmm, in degrees and minutes format (if the leading digit is insufficient, add
        0)
        _latitude = float(gngga1[1])
        #Longitude, dddmm.mmmm, in degrees and minutes format (if the leading digit is
        insufficient, add 0)
```

```

        _longitude = float(gngga1[3])
        #UTC time conversion
        _Clock = int(time[0:2])
        _Minute = time[2:4]
        _Second = time[4:6]
        _Clock = _Clock + 8
        #Prevent more than 24 hours
    if (_Clock >= 24):
        _Clock = _Clock % 24
        #Finally get the time
        Effect_time = str(_clock) + ':' + _Minute + ':' + _Second
        #Finally get the latitude
        Effect_latitude = int(_latitude / 100) + ((_latitude % 100) / 60)
        #Finally get the longitude
        Effect_longitude = int(_longitude / 100) + ((_longitude % 100) / 60)
    print( 'current time:',time)          print( 'GPS time:',Effect_time)
    print('Equipment IMET ',imei)         print(gngga1[2],"",str(Effect_latitude ))
    print(gngga1[4],"",str(Effect_longitude ))

        utime.sleep(2)          except:
        print('Incorrect data format or data corruption')
    continue def run():
        _thread.start_new_thread(gngga, ())

run()

```

4 Terms and Abbreviations

Table 1: Terms and Abbreviations

Abbreviation	Description
API	Application Programming Interface

GPS	Global Positioning System
GPIO	General-Purpose Input/Output
GGA	Global Positioning System Fix Data
HDOP	Horizontal Dilution of Precision
LED	Light Emitting Diode
