

Analysis of the SVD

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Definition 1. Eigenspace, $E(\lambda, T)$

Suppose $T \in L(V)$ and $\lambda \in \mathbf{F}$. The **eigenspace** of T corresponding to λ , denoted $E(\lambda, T)$, is defined by

$$E(\lambda, T) = \text{null}(T - \lambda I) \quad (1)$$

Remark 1. Since $\lambda I(0) = \lambda * I(0) = \lambda * 0 = 0$ and also $T(0) = 0$, we must have that the vector 0 is always in $\text{null}(T - \lambda I)$, since then $T(0) - \lambda I(0) = 0 - 0 = 0$. If $v \neq 0$, then we have that v is in $\text{null}(T - \lambda I)$ if and only if v is an eigenvector of T with eigenvalue λ .

Remark 2. If S is any linear map $\in \mathcal{L}(V, W)$, then $\text{null}(S)$ is a subspace of V . Thus, $\text{null}(T - \lambda I)$ is a vector space. This is the same thing as saying that $E(\lambda, T)$ is a vector space. Thus $\dim E(\lambda, T)$ may exist, if $E(\lambda, T)$ is finite-dimensional.

Definition 2. adjoint, T^*

Suppose $T \in \mathcal{L}(V, W)$. The **adjoint** of T is the function $T^* : W \rightarrow V$ such that $\langle Tv, w \rangle = \langle v, T^*w \rangle$ for every $v \in V$ and $w \in W$.

Definition 3. singular values

Suppose $T \in \mathcal{L}(V)$. The **singular values** of T are the eigenvalues of $\sqrt{T^*T}$, with each eigenvalue λ repeated $\dim E(\lambda, \sqrt{T^*T})$ times.

Now we will define the Singular Value Decomposition (SVD) of a linear map, T .

Theorem 1. Singular Value Decomposition

Suppose $T \in \mathcal{L}(V)$ has singular values s_1, \dots, s_n . Then there exist orthonormal bases e_1, \dots, e_n and f_1, \dots, f_n of V such that

$$Tv = s_1 \langle v, e_1 \rangle f_1 + \dots + s_n \langle v, e_n \rangle f_n \quad (2)$$

for every $v \in V$.

Now we will also define the Singular Value Decomposition (SVD) of an $n \times p$ matrix X . Any matrix X can be broken down into the form

$$X = U\Sigma W^T, \quad (3)$$

Where Σ is an $n \times p$ matrix whose entries on the main diagonal are all positive numbers, and whose entries off of the main diagonal are all 0. The entries on the main diagonal are called the singular values of X .

U is an $n \times n$ square matrix, the columns of which are orthogonal unit vectors of length n called the left singular values of X .

W is a $p \times p$ square matrix, the columns of which are orthogonal unit vectors of length p called the right singular values of X .

Now we will show a connection between the SVD from Theorem 1 and the SVD of a matrix.

Let $W = (e_1, \dots, e_n)$, $U = (f_1, \dots, f_n)$, where e_1, \dots, e_n and f_1, \dots, f_n are both from Theorem 1. Also let

$$\Sigma = \begin{pmatrix} s_1 & & \\ & \ddots & \\ & & s_n \end{pmatrix} \quad (4)$$

where s_1, \dots, s_n are the singular values from Theorem 1.

Now also let v be any vector in V , where the V comes again from Theorem 1.

Then we have that $v = \langle v, e_1 \rangle e_1 + \dots + \langle v, e_n \rangle e_n$.

To see this, note that we have $v = a_1 e_1 + \dots + a_n e_n$, for some $a_1, \dots, a_n \in \mathbf{F}$, since e_1, \dots, e_n is a basis of V .

If we take the inner product of both sides of the equation above with e_1 , we obtain $\langle v, e_1 \rangle = \langle a_1 e_1 + \dots + a_n e_n, e_1 \rangle$

By the Additivity in the First Slot property of inner products, the RHS is equal to: $\langle a_1 e_1, e_1 \rangle + \dots + \langle a_n e_n, e_1 \rangle$

Then by the Homogeneity in the First Slot property of inner products, this is equal to: $a_1 \langle e_1, e_1 \rangle + \dots + a_n \langle e_n, e_1 \rangle$

Since e_1, \dots, e_n is orthonormal, $\langle e_j, e_1 \rangle$ is equal to 1 if $e_j = e_1$. On the other hand, if $j \neq 1$, then $\langle e_j, e_1 \rangle$ is equal to 0. Thus, the RHS is equal to a_1 .

So, we have that $\langle v, e_1 \rangle = a_1$

Similarly, we have that $\langle v, e_2 \rangle = a_2$, and so on.

Thus, $v = a_1 e_1 + \dots + a_n e_n = \langle v, e_1 \rangle e_1 + \dots + \langle v, e_n \rangle e_n$.

So if we right-multiply the matrix W^T by the vector v , we obtain:

$$W^T v = \begin{pmatrix} e_1 \\ \vdots \\ e_n \end{pmatrix} (\langle v, e_1 \rangle e_1 + \dots + \langle v, e_n \rangle e_n) = \begin{pmatrix} \langle v, e_1 \rangle \\ \vdots \\ \langle v, e_n \rangle \end{pmatrix}$$

But then, if we right-multiply the matrix Σ by $W^T v$, we obtain $\Sigma W^T v =$

$$\begin{pmatrix} s_1 & & \\ & \ddots & \\ & & s_n \end{pmatrix} \begin{pmatrix} \langle v, e_1 \rangle \\ \vdots \\ \langle v, e_n \rangle \end{pmatrix} = \begin{pmatrix} s_1 \langle v, e_1 \rangle \\ \vdots \\ s_n \langle v, e_n \rangle \end{pmatrix}$$

But then, $U \Sigma W^T v =$

$$(f_1, \dots, f_n) \begin{pmatrix} s_1 \langle v, e_1 \rangle \\ \vdots \\ s_n \langle v, e_n \rangle \end{pmatrix} = s_1 \langle v, e_1 \rangle f_1 + \dots + s_n \langle v, e_n \rangle f_n,$$

which matches what the Tv from Theorem 1 equals.

References

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- [3] Wikipedia