### Static single assignment form (1)

Static single assignment form (SSA) is an intermediate representation where

- ► Each definition defines a unique name
- ► Each use refers to a single definition

# Static single assignment form (2)

### Example (1)

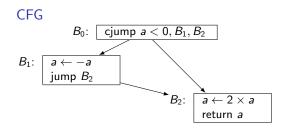
#### TACL code

if (a < 0) a = -a; a = 2 \* a; ^ a

#### Alternate IR

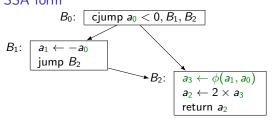
cjump  $a < 0, l_1, l_2$ 

 $l_1: a \leftarrow -a$   $l_2: a \leftarrow 2 \times a$ return a

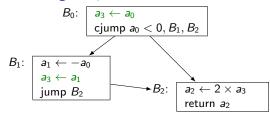


# Static single assignment form (3)

Example (1, cont.) SSA form



#### Removing the $\phi$ -function



### Static single assignment form (4)

 $\phi\text{-functions}$  reconcile different values for a name coming along different edges

A  $\phi$ -function  $a = \phi(a, \dots, a)$  in node m selects the correct value for a according to the CFG edge traversed to reach m

 $\phi\text{-functions}$  are a device for encoding data-flow information and are not meant to be implemented

All  $\phi$ -functions in a block are considered as being evaluated simultaneously

 $\phi$ -functions are only needed for global names (i.e., names that are not local to a basic block)

#### **Dominance**

A control flow graph (CFG) node m dominates node n if every path from the root to n passes through m

 $\triangleright$  m is a dominator of n

Node m strictly dominates n if m is a dominator of n and  $m \neq n$ 

m is a strict dominator of n

Node n is in the dominance frontier (DF) of m if

- m dominates a predecessor of n, and
- m does not strictly dominate n

### Static single assignment form (5)

A join point is a CFG node that has multiple predecessors

 $\phi\text{-functions}$  are only needed at join points

A node  $n \in DF(m)$  is a join point in the CFG since

- a. There is a path in the graph from m to n
- b. There is a path from the root of the graph to n that does not go through m (otherwise, m would strictly dominate n)
- c. In the path from m to n, n is the first node not strictly dominated by m

#### Inserting $\phi$ -functions

If node m defines a, every node in DF(m) needs a  $\phi$ -function for a

### Static single assignment form (6)

#### Translating into SSA

- 1. Building the CFG
- 2. Computation of the dominance frontiers
- 3. Insertion of  $\phi$ -functions
  - ightharpoonup Adding a  $\phi$ -function for a to a node makes that node define a
- 4. Numbering the definitions
- 5. Renaming uses

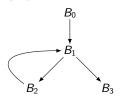
# Static single assignment form (7)

### Example (2)

#### TACL code

r = 1; while (n > 0) [ r = r \* n; n = n - 1;

### CFG



#### Alternate IR

 $r \leftarrow 1$   $\mid B_0$   $l_0$ : cjump  $n > 0, l_1, l_2 \mid B_1$   $l_1$ :  $r \leftarrow r \times n$   $\mid B_2$  j = 0 j = 0 $l_2$ : return  $r \mid B_3$ 

#### Dominance

	Dominates	DF
$B_0$	$B_0, B_1, B_2, B_3$	_
$B_1$	$B_0, B_1, B_2, B_3$ $B_1, B_2, B_3$	$B_1$
$B_2$	$B_2$	$B_1$
$B_3$	$B_3$	_

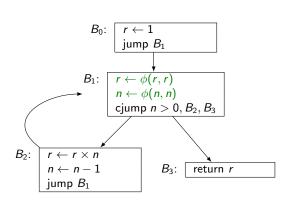
### Static single assignment form (8)

Example (2, cont.)

#### Inserting $\phi$ -functions

 $DF(B_0) = \emptyset$ , so  $B_0$  does not cause the insertion of any  $\phi$ -function

Since  $B_1$  does not define any name, it will not imply the insertion of any  $\phi$ -function



 $B_2$  defines names r and n and  $\phi$ -functions for both names are needed in all nodes in  $DF(B_2) = \{B_1\}$ 

 $B_1$  now defines r and n, but  $DF(B_1) = \{B_1\}$  and, since  $B_1$  already has the corresponding  $\phi$ -functions, no further  $\phi$ -function is needed

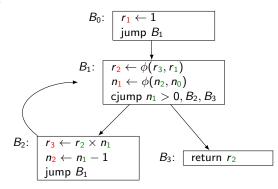
# Static single assignment form (9)

Example (2, cont. 2)

### Numbering definitions

Once  $\phi$ -functions have been inserted, all name definitions are numbered so all define a different name

Each name's definition 0 is available at the start node



Every use of a name is then renamed to reflect the definition that reaches it

### Static single assignment form (10)

SSA form incorporates both control-flow and data-flow information

The fact that each use refers to a single definition, makes it straightforward to implement copy-propagation and constant-propagation, and to recognise duplicate expressions

#### Translating out of SSA form

After program transformation and optimisation, the remaining  $\phi$ -functions must be removed for code generation

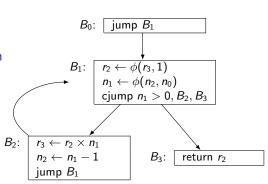
To remove each  $a_i \leftarrow \phi(e_1, \dots, e_k)$ , a definition  $a_i \leftarrow e_j$  is inserted at the end of the block where edge j starts, for every  $j \in \{1, \dots, k\}$ 

# Static single assignment form (11)

Example (2, cont. 3)

Code after constant--propagation and useless-code elimination

Once  $r_1$ 's definition is propagated,  $r_1 \leftarrow 1$  becomes useless code

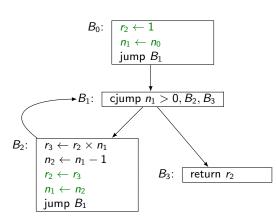


# Static single assignment form (12)

Example (2, cont. 4)

### Removing $\phi$ -functions

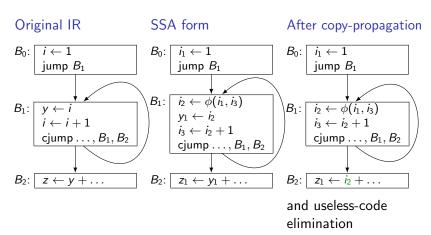
Since  $B_1$  is the only block with a  $\phi$ -function, definitions for  $r_2$  and  $n_1$  are inserted in its predecessors  $B_0$  and  $B_2$ 



### Static single assignment form (13)

### The lost-copy problem (1)

Following the previous rule when translating out of SSA form may sometimes lead to incorrect code



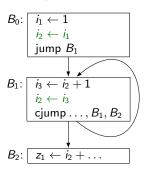
# Static single assignment form (14)

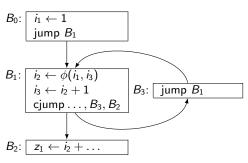
### The lost-copy problem (2)

This may be avoided by inserting a dummy node in edges that start from a node from where at least one other edge starts and arrive at a node where at least one other edge arrives

This is called edge splitting

#### After $\phi$ -function removal Edge splitting



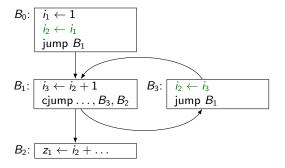


Now  $z_1$  gets the wrong value

# Static single assignment form (15)

### The lost-copy problem (3)

#### After $\phi$ -function removal again



Now  $z_1$  gets the correct value