



Marburg
University

Lecture Computer Vision Chapter 1 – Introduction

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Image Representation - Introduction

- Representation at pixel level does not represent well visual content
- Task: Find appropriate representations for
 - color
 - shape
 - texture
 - objects
 - regions

Spatial Resolution (German: „Ortsauflösung“)

↑
 N
↓



768*384



48*24



192*96



12*6

Source: K. Tönnies, Lecture material „Grundlagen der Bildverarbeitung“, 2005

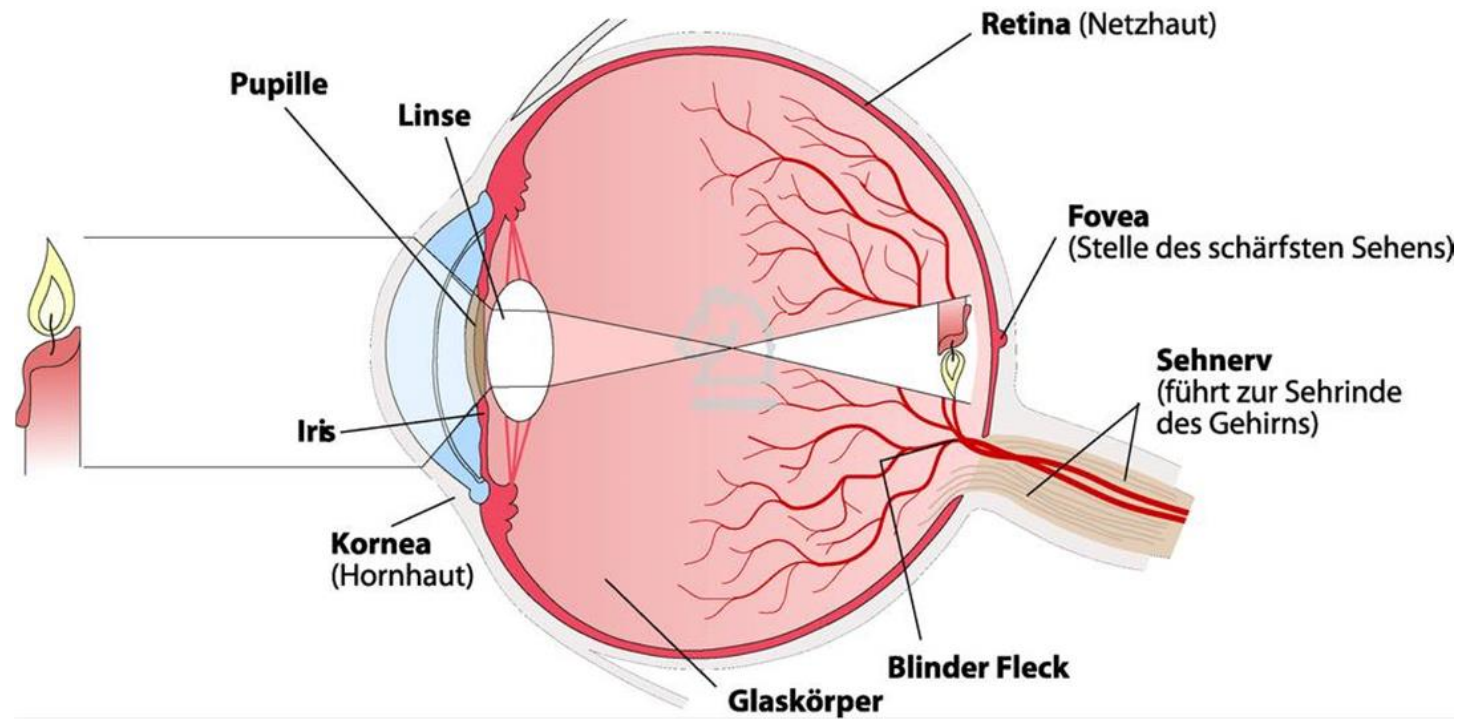
Resolution of Luminance



Source: K. Tönnies, Lecture material
„Grundlagen der Bildverarbeitung“,
2005

Reduction of contrast (number of grey levels) has less impact on image perception / scene recognition than reducing spatial resolution

Human Eye



Source: Prof. Schwaninger,
<http://www.casra.ch/en/about-us/team/teaching/101002-grundlagen-der-allgemeinen-psychologie-wahrnehmungspsychologie.html>

Today's Film Recommendation
from TIB AV-Portal (av.tib.eu)

„Die Umkehrbrille und das aufrechte Sehen“

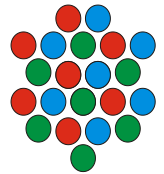
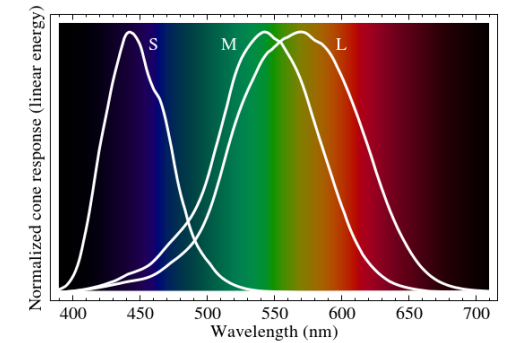
Stummfilm, 1950



<https://av.tib.eu/media/10429?1086>

Color perception

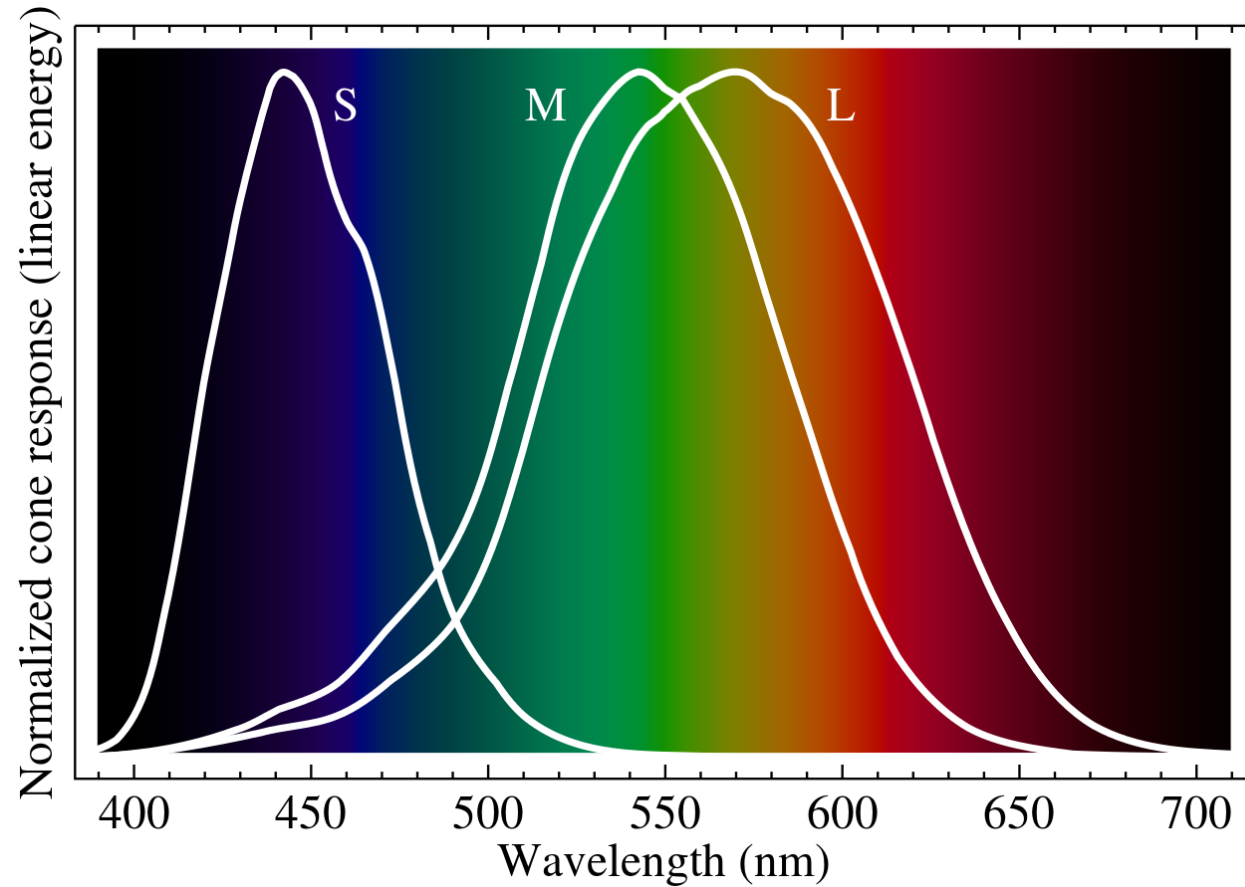
1. Color perception relies on three cell types of cones (“Zapfen”)
 - Their sensitivity with respect to wavelength differs significantly
 - All “visible” wave lengths approximated by 3 basis waves (spectra)
 - Color can be represented via an additive red-green-blue signal
2. Brightness is perceived via rods (“Stäbchen”)



Source of image (public domain)

https://en.wikipedia.org/wiki/Color_vision#/media/File:Cone-fundamentals-with-srgb-spectrum.svg

Color Response of Cone Cells

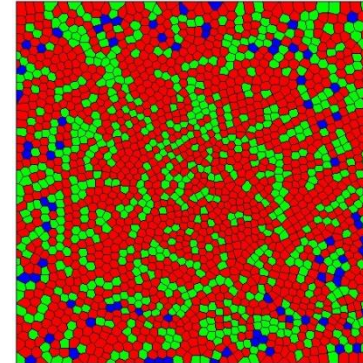


Source of image (public domain)

https://en.wikipedia.org/wiki/Color_vision#/media/File:Cone-fundamentals-with-srgb-spectrum.svg

Human Perception: „Resolution“ of Luminance and Color

1. Cone cells („Zapfen“):
 - ~6 millions
 - Active only for day light
 - Broader than rod cells
2. Rod cells („Stäbchen“)
 - ~120 millions (!):
 - „Resolution“
 - Always active, even for low light intensity
 - can even measure low number of photons



Source of image (top): <http://www.allpsych.uni-giessen.de/karl/html/heidelberg/heidelberg.html>

Source of image (bottom): <http://www.zum.de/Faecher/Materialien/beck/12/bs12-36.htm>

Modelling Color

Different Color Spaces

1. RGB: Red, Green, Blue
2. HSB/HSV/HLS
 - Hue
 - Saturation
 - Brightness (or Value, or Lightness)
3. YC_bC_r (YUV in analog world)
 - Y: Luminance
 - C_b : Blue difference level
 - C_r : Red difference level
4. There are many other color spaces...

Modelling Color with RGB Color Space

RGB color cube: Red, Green, Blue

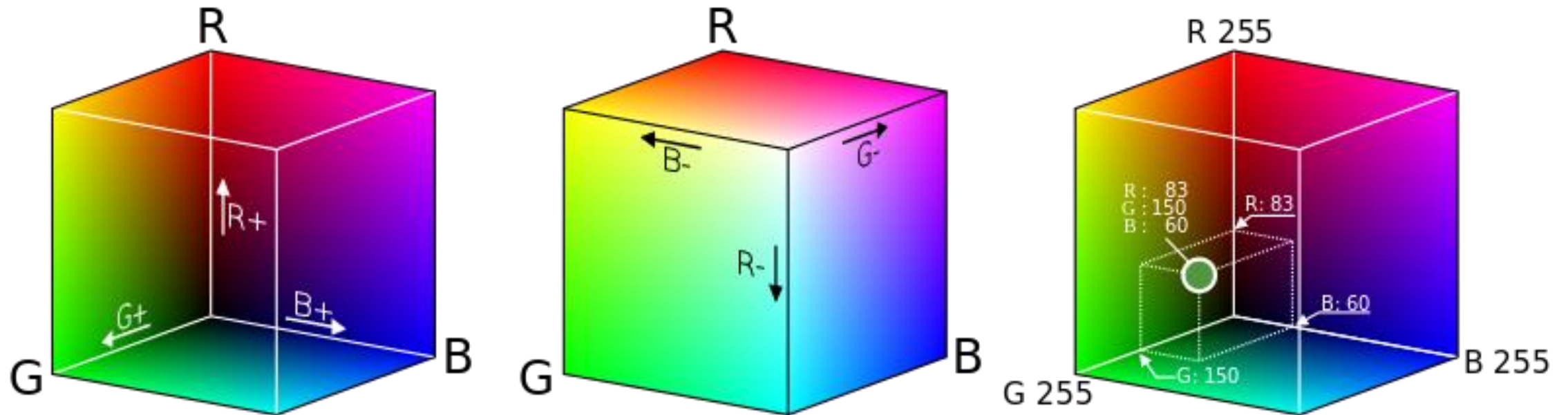
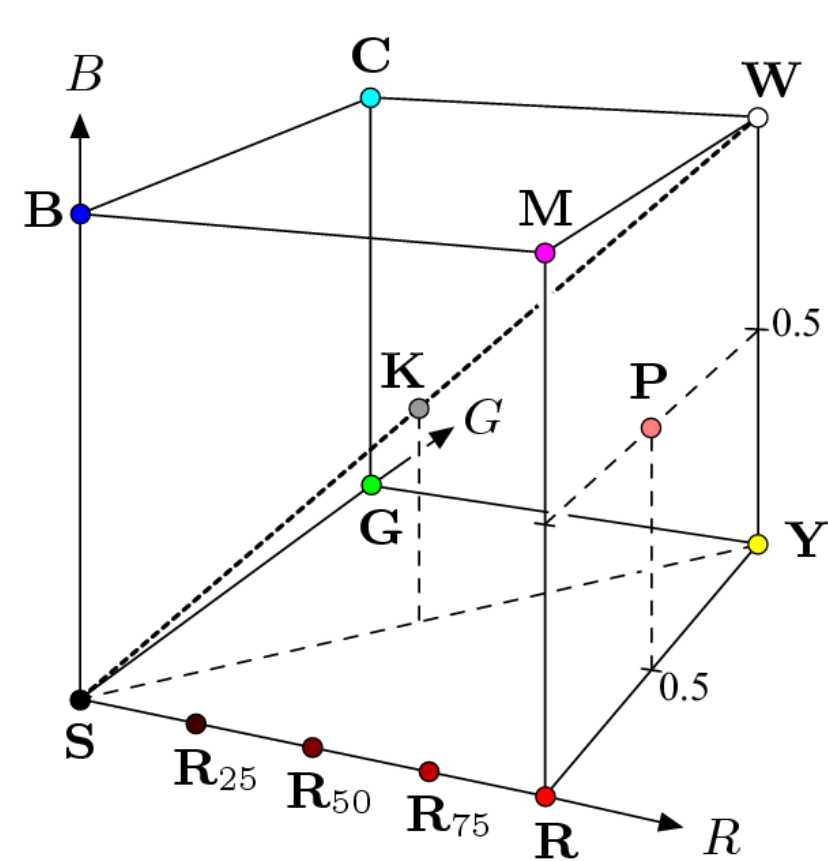


Image source: https://commons.wikimedia.org/wiki/File:RGB_color_cube.svg?uselang=de
CC BY-SA 3.0 <https://commons.wikimedia.org/wiki/User:Maklaan>

RGB Color Space

$$C_i = (R_i, G_i, B_i) \text{ RGB color pixel}$$



| RGB-Werte | | | | |
|-----------------------|----------|----------|----------|----------|
| Pkt. | Farbe | <i>R</i> | <i>G</i> | <i>B</i> |
| S | Schwarz | 0.00 | 0.00 | 0.00 |
| R | Rot | 1.00 | 0.00 | 0.00 |
| Y | Gelb | 1.00 | 1.00 | 0.00 |
| G | Grün | 0.00 | 1.00 | 0.00 |
| C | Cyan | 0.00 | 1.00 | 1.00 |
| B | Blau | 0.00 | 0.00 | 1.00 |
| M | Magenta | 1.00 | 0.00 | 1.00 |
| W | Weiß | 1.00 | 1.00 | 1.00 |
| K | 50% Grau | 0.50 | 0.50 | 0.50 |
| R₇₅ | 75% Rot | 0.75 | 0.00 | 0.00 |
| R₅₀ | 50% Rot | 0.50 | 0.00 | 0.00 |
| R₂₅ | 25% Rot | 0.25 | 0.00 | 0.00 |
| P | Pink | 1.00 | 0.50 | 0.50 |

RGB Color Components (Channels)



R



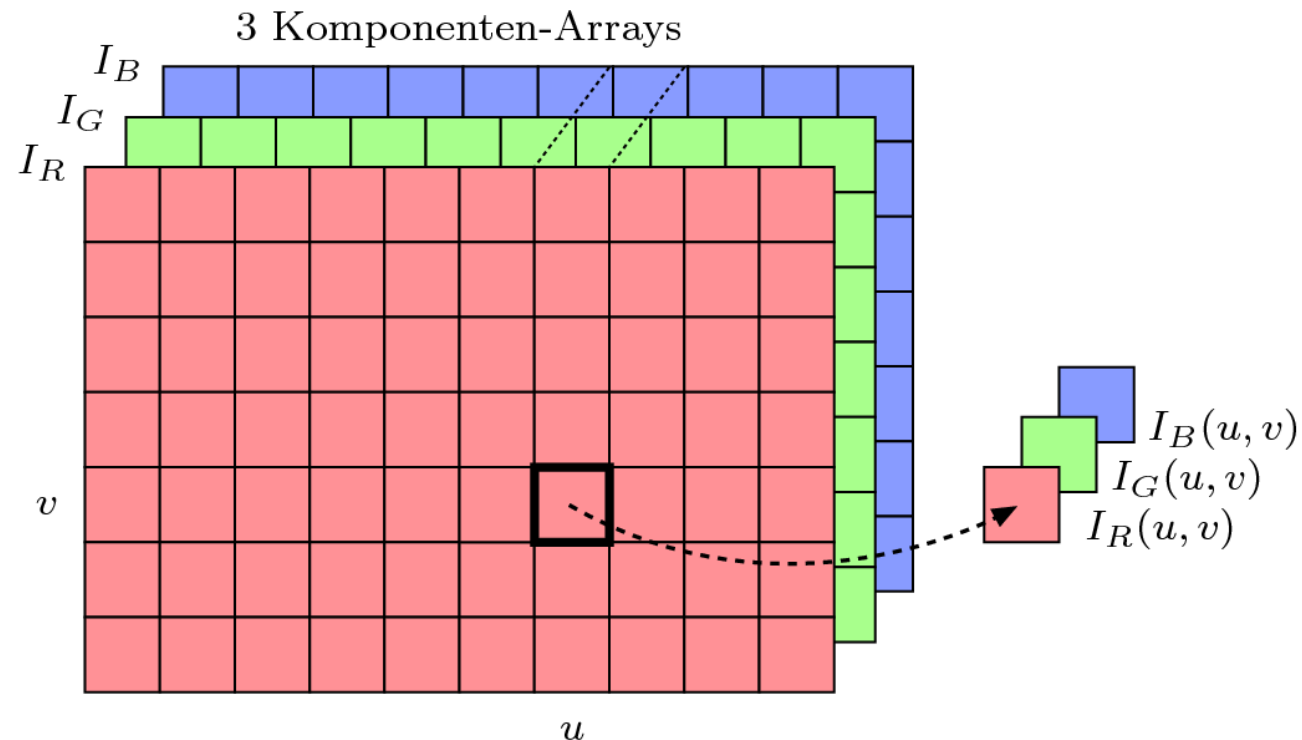
G



B

Image Representation in Memory/Files Ordered by Components (RGB)

- „Planes“: Three components are separated in 3 arrays of same size
- In memory or in files, these arrays are linear, of course

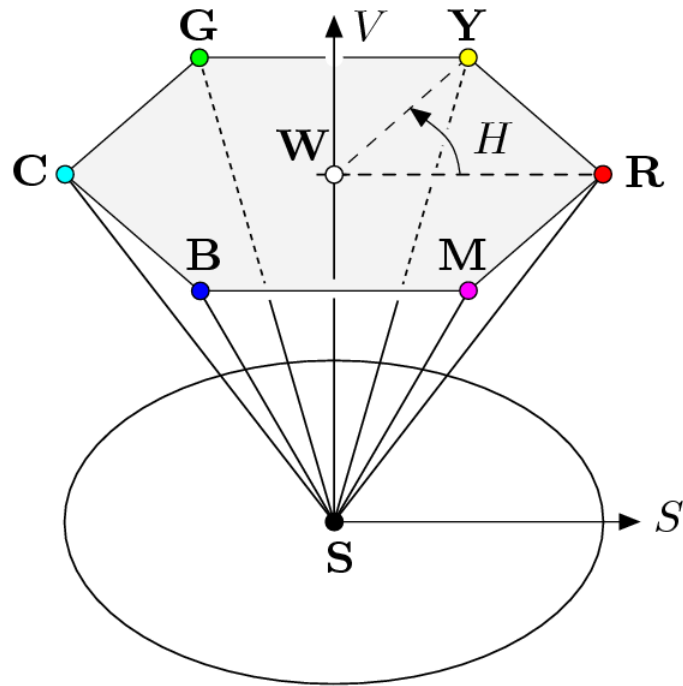


RGB Color Space

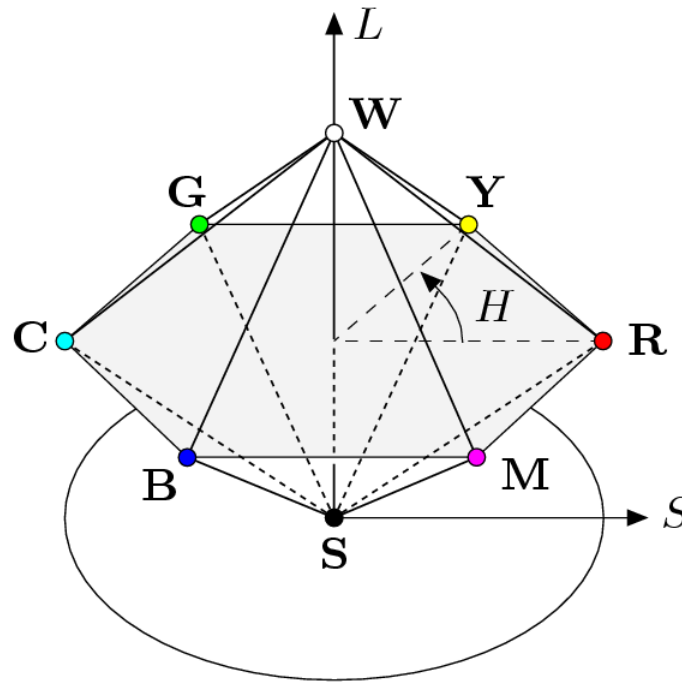
- According to monitors and display technology
- Easily usable from a programmer's perspective
- But
 - changes in RGB can be perceived differently, RGB is non-linear
 - if RGB value changes: Hue **and** saturation **and** brightness change
 - color properties are not represented explicitly
- Properties of displaying RGB are not defined
 - Appearance of colors depends on output device
 - This is addressed by more sophisticated color spaces

HSV and HLS Color Space

Hue • Saturation • Value/Lightness (traditional representations)



HSV color space



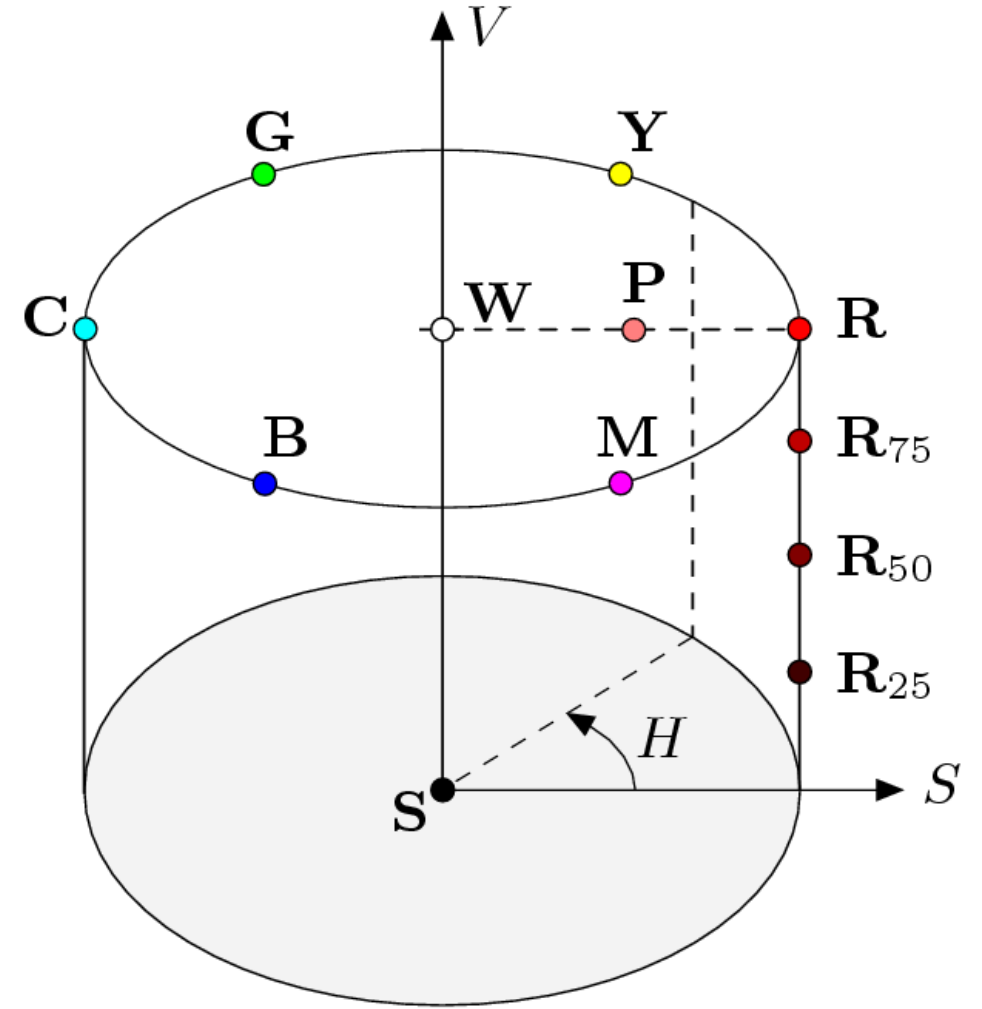
HLS color space

HSV Color Space (also HSB, HSI)

HSV: Hue/Saturation/Value

HSB: Hue/Saturation/Brightness

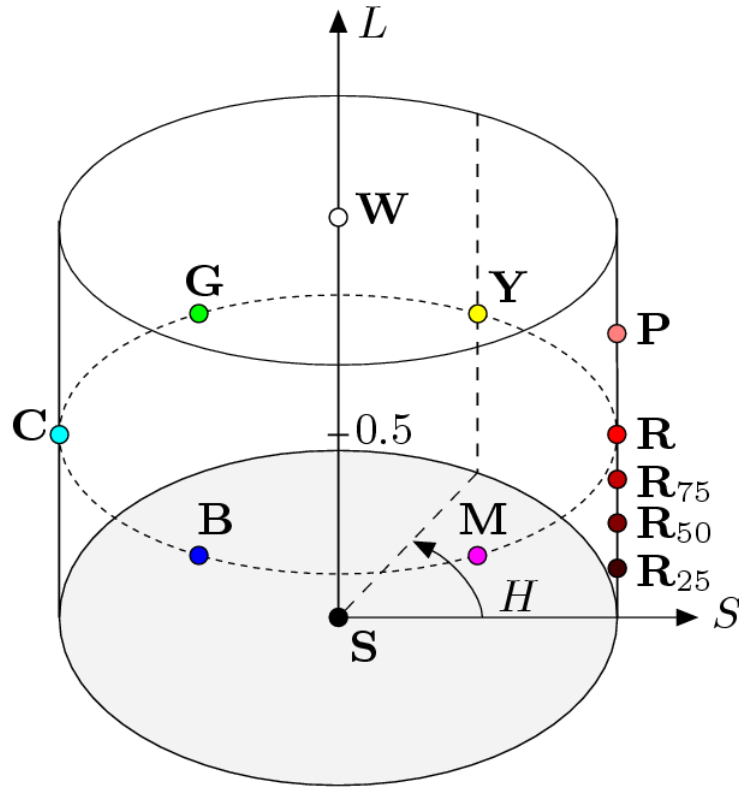
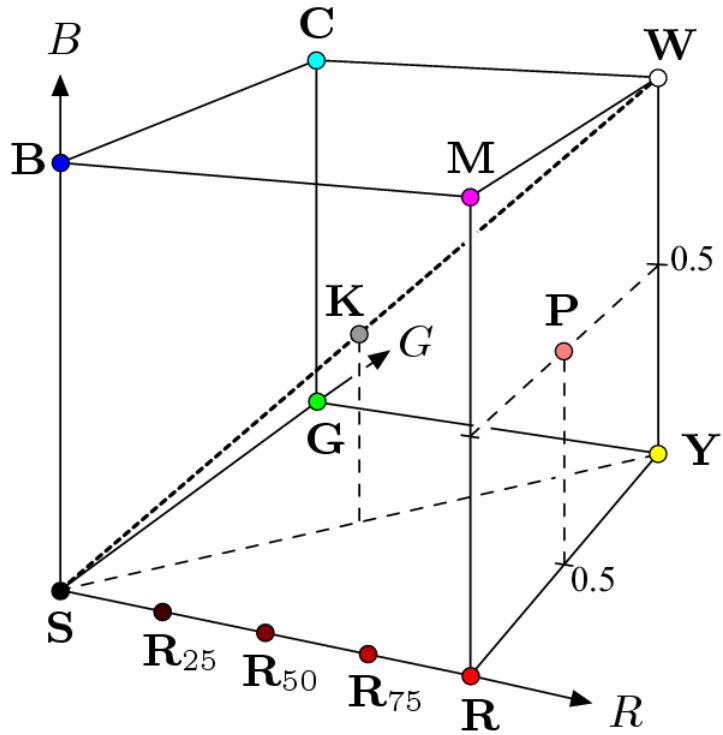
HSI: Hue/Saturation/Intensity



HLS Color Space (also HSL)

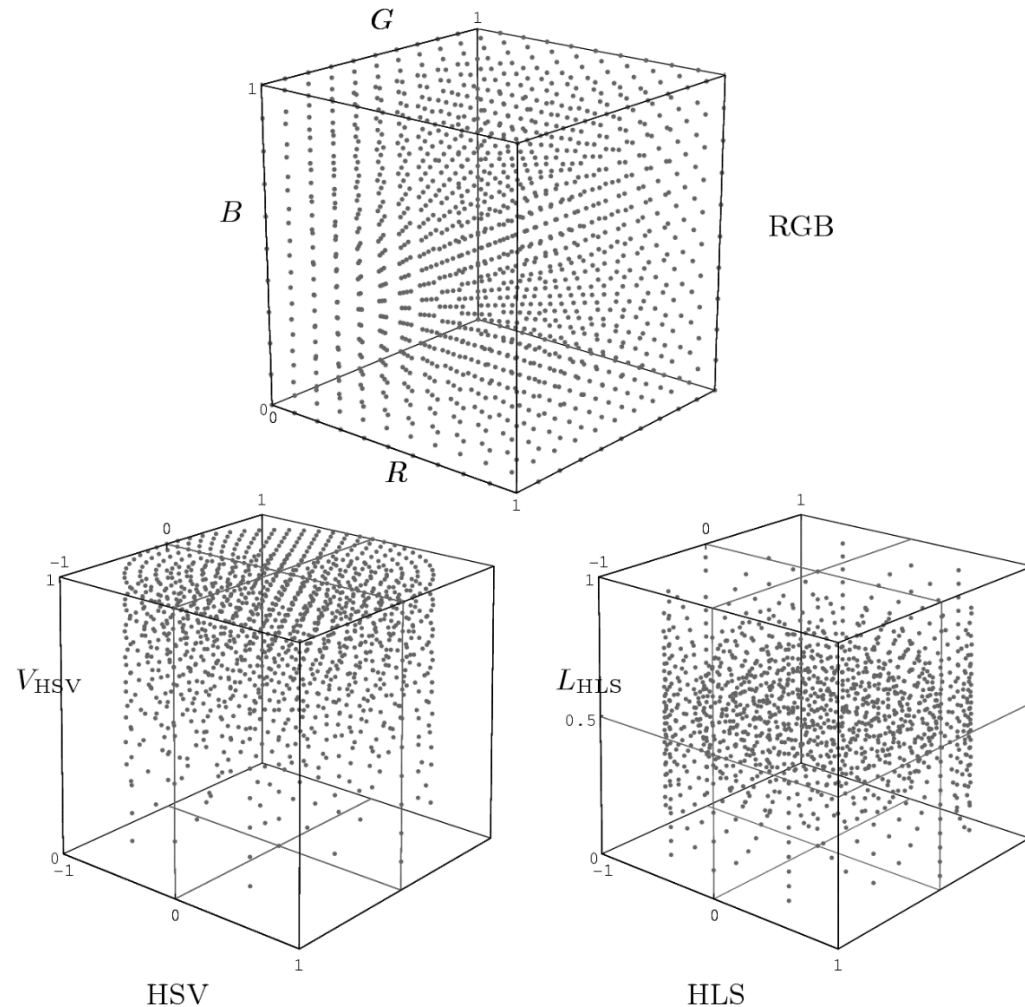
HLS: Hue/Lightness/Saturation (realistic representation)

HSL: Hue/Saturation/Lightness



Color Distribution in RGB/HSV/HLS

Assuming an equal
distribution of
colors in RGB



Color Space Conversion

RGB -> HSV (1)

Intermediate values

$$C_{\text{high}} = \max(R, G, B), \quad C_{\text{low}} = \min(R, G, B), \quad C_{\text{rng}} = C_{\text{high}} - C_{\text{low}}$$

Saturation

$$S_{\text{HSV}} = \begin{cases} \frac{C_{\text{rng}}}{C_{\text{high}}} & \text{für } C_{\text{high}} > 0 \\ 0 & \text{sonst} \end{cases}$$

Value

$$V_{\text{HSV}} = \frac{C_{\text{high}}}{C_{\text{max}}}$$

Color Space Conversion

RGB → HSV (2)

Intermediate

$$C_{\text{high}} = \max(R, G, B), \quad C_{\text{low}} = \min(R, G, B), \quad C_{\text{rng}} = C_{\text{high}} - C_{\text{low}}$$

$$R' = \frac{C_{\text{high}} - R}{C_{\text{rng}}}, \quad G' = \frac{C_{\text{high}} - G}{C_{\text{rng}}}, \quad B' = \frac{C_{\text{high}} - B}{C_{\text{rng}}}$$

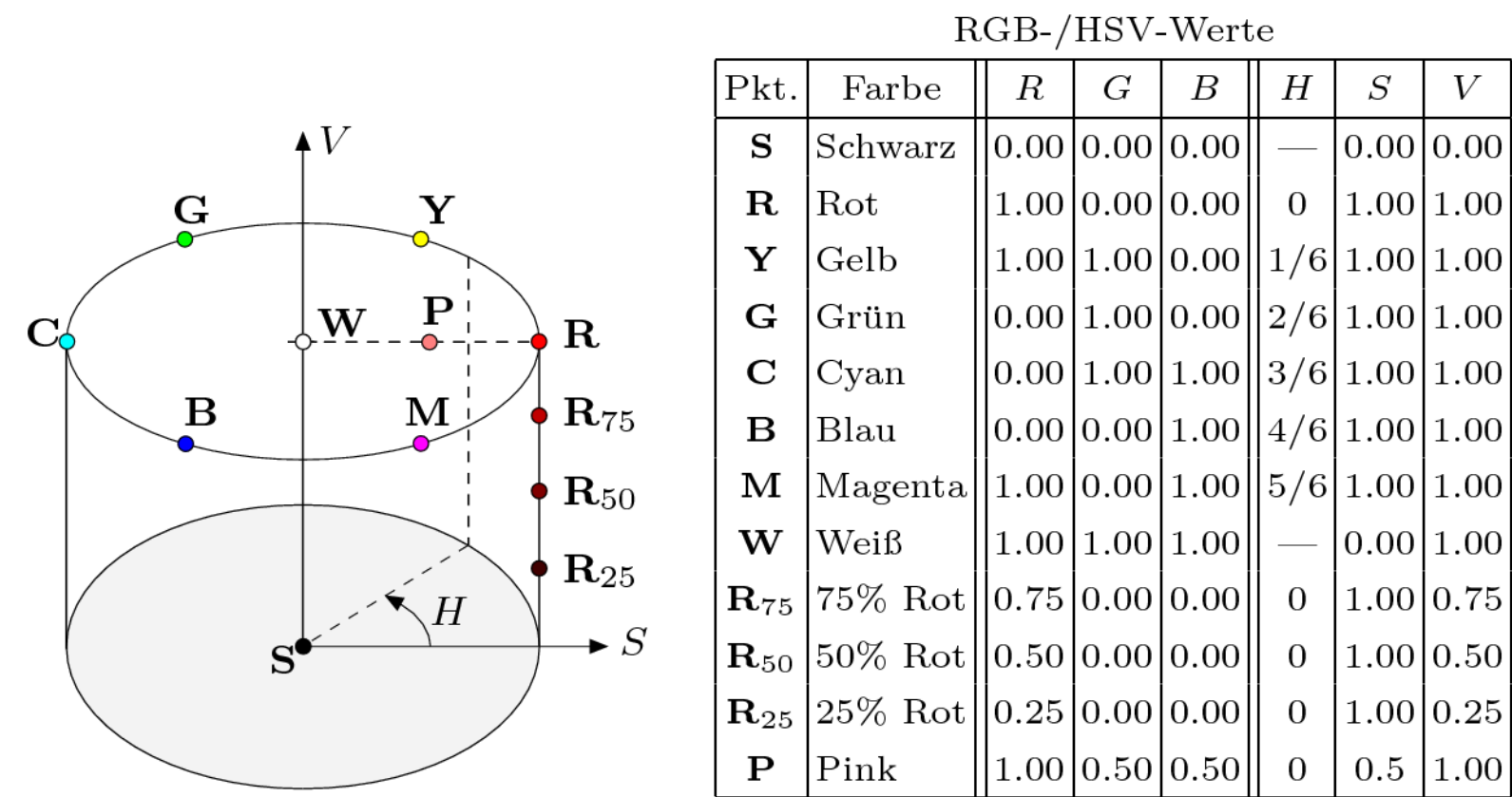
$$H' = \begin{cases} B' - G' & \text{wenn } R = C_{\text{high}} \\ R' - B' + 2 & \text{wenn } G = C_{\text{high}} \\ G' - R' + 4 & \text{wenn } B = C_{\text{high}} \end{cases}$$

Hue

$$H_{\text{HSV}} \leftarrow \frac{1}{6} \cdot \begin{cases} (H' + 6) & \text{für } H' < 0 \\ H' & \text{sonst.} \end{cases}$$

All values in $[0,1]$

Some Particular HSV Color Values



Color Space Conversion:

RGB -> HLS

$$C_{\text{high}} = \max(R, G, B), \quad C_{\text{low}} = \min(R, G, B), \quad C_{\text{rng}} = C_{\text{high}} - C_{\text{low}}$$

Hue

$$H_{\text{HLS}} = H_{\text{HSV}}$$

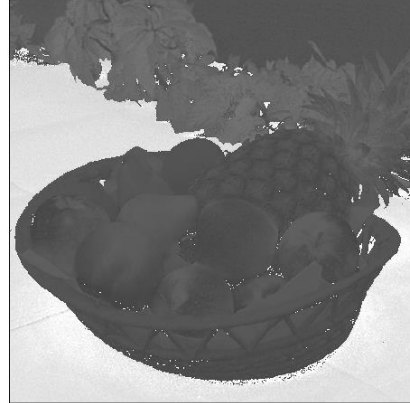
Lightness

$$L_{\text{HLS}} \leftarrow \frac{C_{\text{high}} + C_{\text{low}}}{2}$$

Saturation

$$S_{\text{HLS}} \leftarrow \begin{cases} 0 & \text{für } L_{\text{HLS}} = 0 \\ 0.5 \cdot \frac{C_{\text{rng}}}{L_{\text{HLS}}} & \text{für } 0 < L_{\text{HLS}} \leq 0.5 \\ 0.5 \cdot \frac{C_{\text{rng}}}{1 - L_{\text{HLS}}} & \text{für } 0.5 < L_{\text{HLS}} < 1 \\ 0 & \text{für } L_{\text{HLS}} = 1 \end{cases}$$

Examples for HSV and HLS



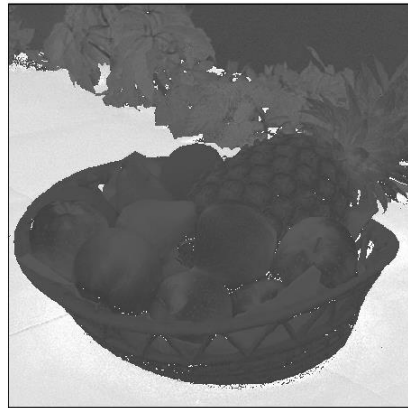
h_{HSV}



s_{HSV}



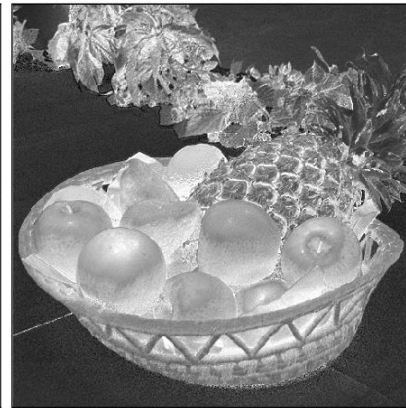
v_{HSV}



H_{HLS}

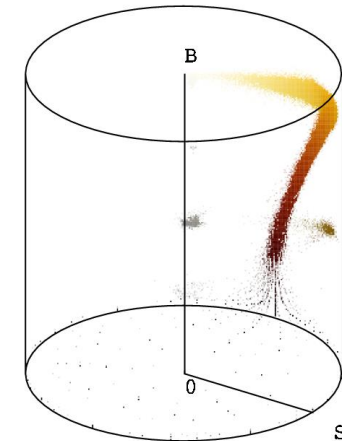
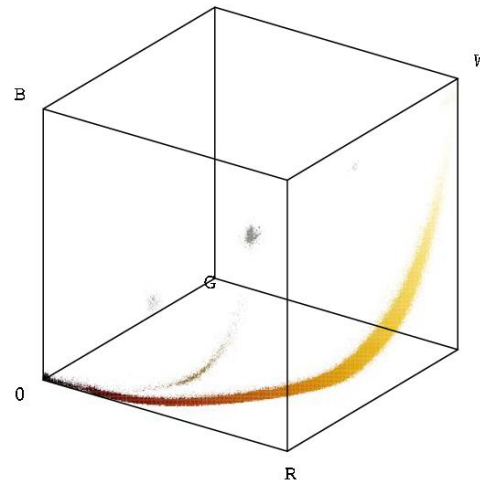
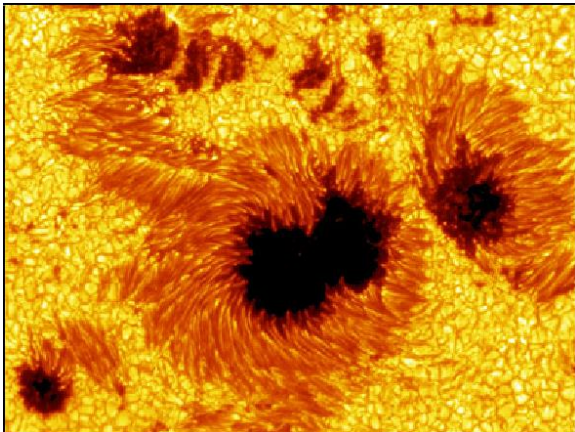
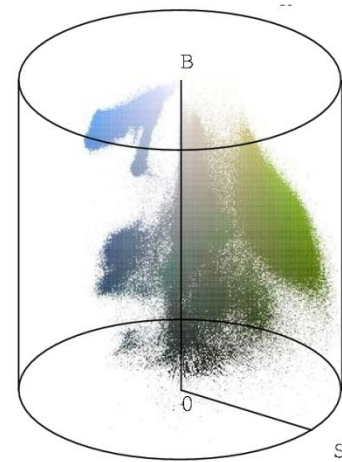
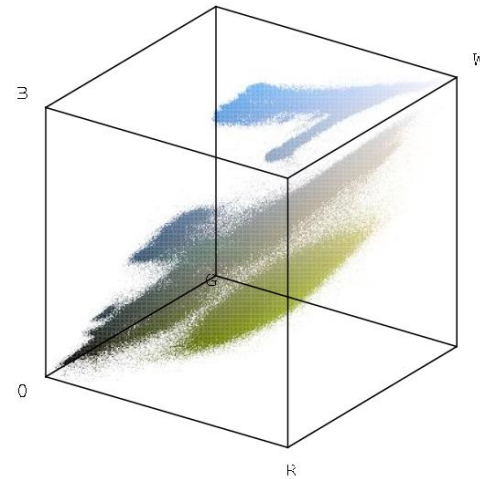


L_{HLS}



S_{HLS}

Color Distribution in RGB and HSV



Color Spaces for TV (Television)

- YUV/ YC_bC_r : Color space(s) for standardized recording, storage, transmission and display of color TV video (frames)
- Color space is separated in (analog TV)
 - 1 luminance component Y and
 - 2 color components U, V
- YUV -> PAL/NTSC analog TV
- YC_bC_r -> digital TV
- Subsampling of chrominance (Cb, Cr) is used very often
 - „4:2:2“: only 1 Cb + 1 Cr is sampled for 2 pixels
 - „4:2:0“: only 1 Cb + 1 Cr is sampled for 4 pixels

YUV (Component) Color Space

- Color space conversion: YUV -> RGB

$$Y = 0.299 \cdot R + 0.587 \cdot G + 0.114 \cdot B$$

$$U = 0.492 \cdot (B - Y)$$

$$V = 0.877 \cdot (R - Y)$$

- In matrix form (linear mapping)

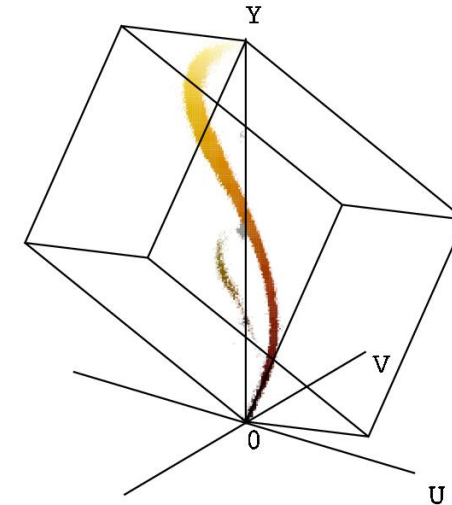
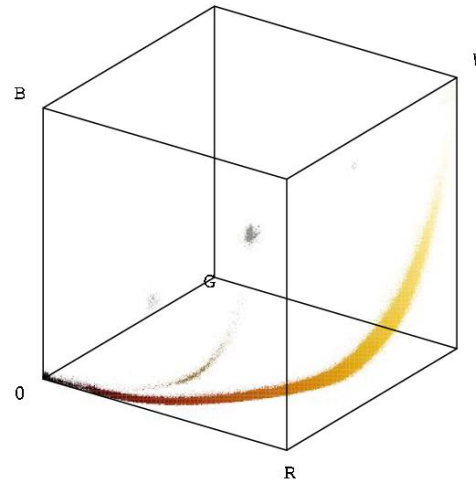
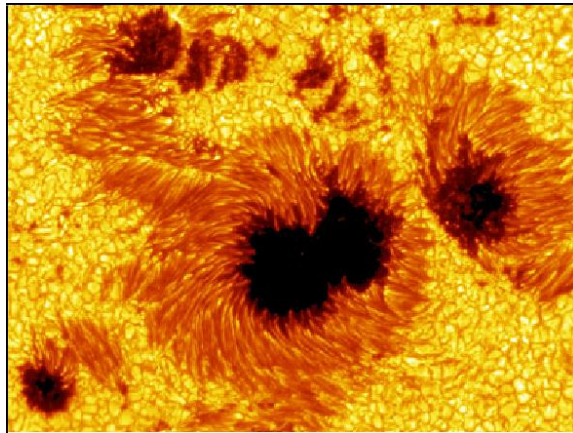
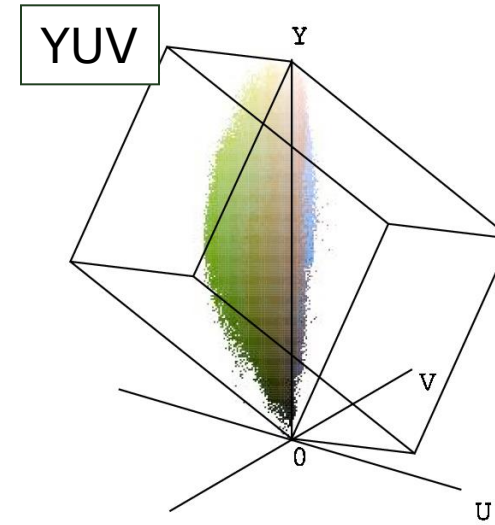
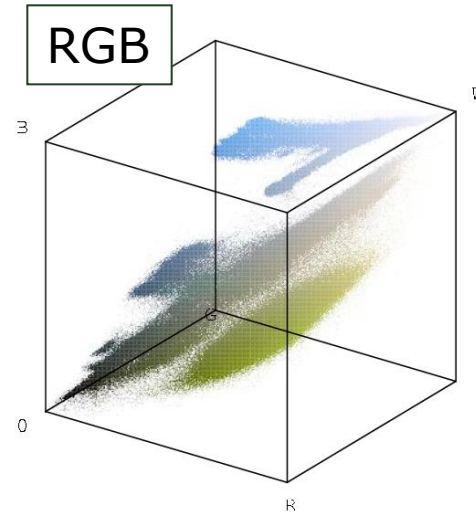
RGB -> YUV

$$\begin{pmatrix} Y \\ U \\ V \end{pmatrix} = \begin{pmatrix} 0.299 & 0.587 & 0.114 \\ -0.147 & -0.289 & 0.436 \\ 0.615 & -0.515 & -0.100 \end{pmatrix} \cdot \begin{pmatrix} R \\ G \\ B \end{pmatrix}$$

YUV -> RGB

$$\begin{pmatrix} R \\ G \\ B \end{pmatrix} = \begin{pmatrix} 1.000 & 0.000 & 1.140 \\ 1.000 & -0.395 & -0.581 \\ 1.000 & 2.032 & 0.000 \end{pmatrix} \cdot \begin{pmatrix} Y \\ U \\ V \end{pmatrix}$$

Color Distribution in RGB/YUV



YCbCr Component Color Space

- Variant (extension) of YUV, international standard für digital TV
- Common for JPEG (JFIF, EXIF) as well

- RGB \rightarrow YCbCr

$$\begin{pmatrix} Y \\ C_b \\ C_r \end{pmatrix} = \begin{pmatrix} 0.299 & 0.587 & 0.114 \\ -0.169 & -0.331 & 0.500 \\ 0.500 & -0.419 & -0.081 \end{pmatrix} \cdot \begin{pmatrix} R \\ G \\ B \end{pmatrix}$$

- YCbCr \rightarrow RGB

$$\begin{pmatrix} R \\ G \\ B \end{pmatrix} = \begin{pmatrix} 1.000 & 0.000 & 1.403 \\ 1.000 & -0.344 & -0.714 \\ 1.000 & 1.773 & 0.000 \end{pmatrix} \cdot \begin{pmatrix} Y \\ C_b \\ C_r \end{pmatrix}$$

ITU-BT.601 (4:3 & 16:9 Digital-TV):

$w_R=0.2990$, $w_B=0.114$

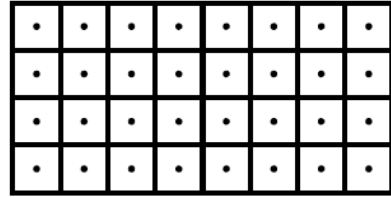
ITU-BT.709 (Digital-HDTV):

$w_R=0.2125$, $w_B=0.0721$

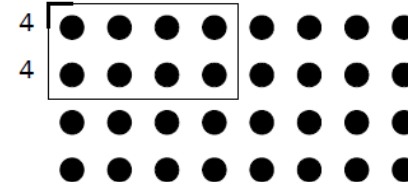
Chrominance Subsampling

4:4:4

H: 1/1
V: 1/1
T: 1/1

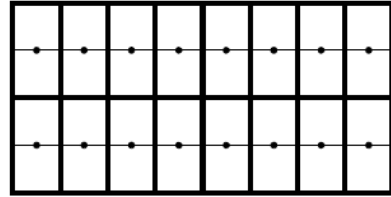


4:4:4

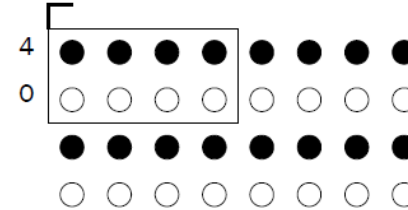


4:4:0

H: 1/1
V: 1/2
T: 1/2

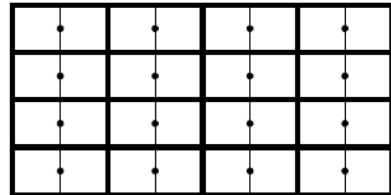


4:4:0

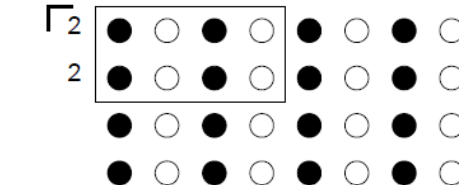


4:2:2

H: 1/2
V: 1/1
T: 1/2



4:2:2



H: chrominance resolution horizontal
V: chrominance resolution vertical
T: chrominance resolution total



Image pixel



Chrominance pixel



Centroid of chrominance pixel



Chrominance sample



No chrominance sample



Pattern identifier
reference "block"



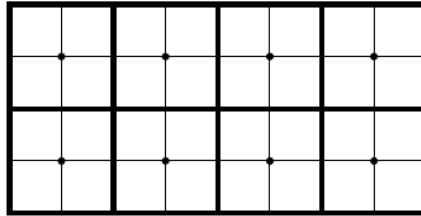
Corner of pixel block shown at left

Source: Kerr, Douglas, 2012, <http://dougkerr.net/pumpkin/articles/Subsampling.pdf>

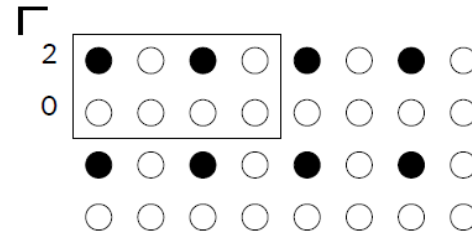
Chrominance Subsampling

4:2:0 ①

H: 1/2
V: 1/2
T: 1/4

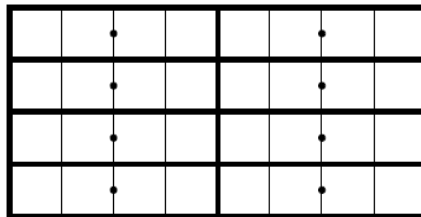


4:2:0

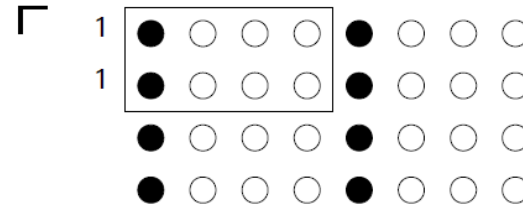


4:1:1

H: 1/4
V: 1/1
T: 1/4

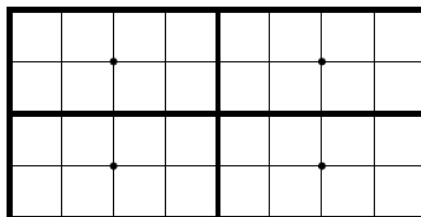


4:1:1

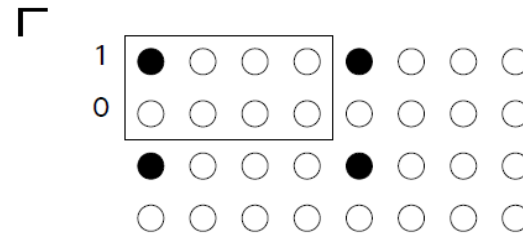


4:1:0

H: 1/4
V: 1/2
T: 1/8



4:1:0



① This is the most common "centered" form for 4:2:0 for still images; others are used in video

Source: Kerr, Douglas, 2012, <http://dougkerr.net/pumpkin/articles/Subsampling.pdf>

Example: YUV and YC_bC_r Components

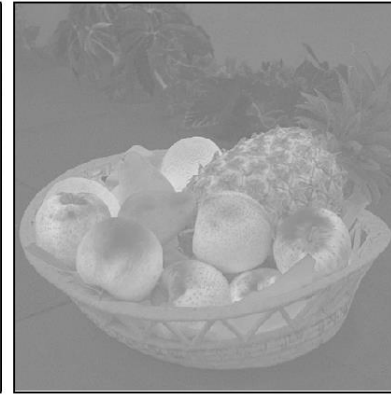


Y



YUV

U



V

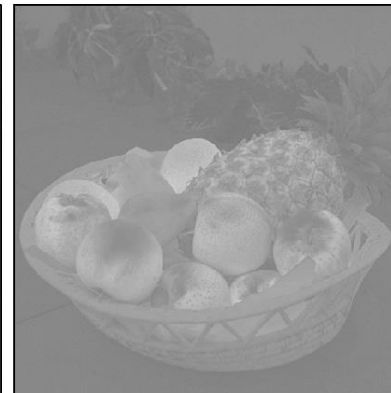


Y



YC_bCr

C_b



C_r

Lessons learned

- (Very) basic principles of color perception
- Introduction: color spaces
 - RGB
 - HLS
 - HSV
 - YCbCr (YUV)