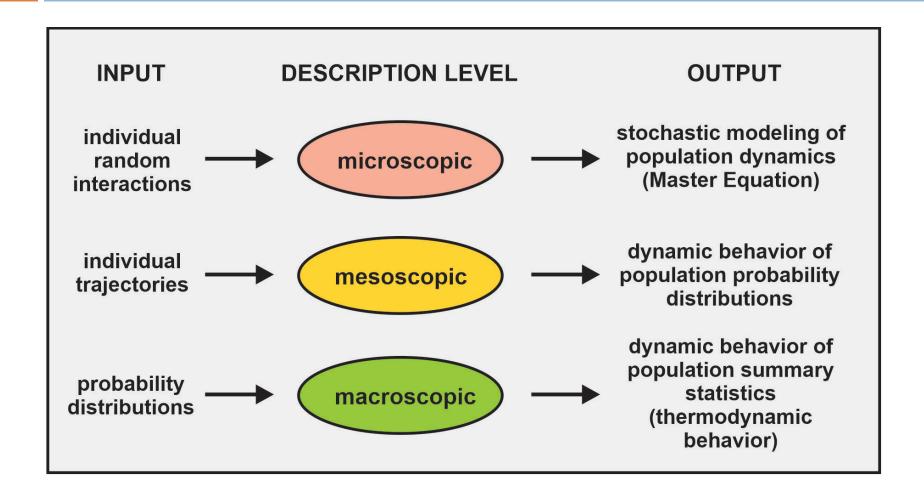
# LECTURE #2

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#### Description Levels of Complex Systems



#### Stochastic Modeling

- $\hfill\Box$  Each interacting component  $X_n$  in a complex network assumes a state  $X_n(t)$  at each time  $t\geq 0$  .
- □ The  $N \times 1$  state vector  $\mathbf{X}(t)$  completely characterizes the system at time t.
- $\square$  Here,  $\mathbf{X}(t)$  evolves with time, but <u>not deterministically</u>.

#### Stochastic Modeling

- If we run multiple simulations of the same system from identical initial conditions, we cannot expect to obtain the same dynamics in each simulation.
- Therefore,  $\mathbf{X}(t)$  is a multivariate <u>stochastic process</u> with <u>realizations</u>  $\mathbf{X}(t)$ .
- We are interested in calculating the probability

$$p_X(\mathbf{x};t) \triangleq \Pr[\mathbf{X}(t) = \mathbf{x} \mid \mathbf{X}(0) = \mathbf{x}_0], \ t > 0$$

#### Markov Processes

- A <u>Markov process</u> (or <u>continuous-time Markov Chain</u>) is a particular case of a stochastic process that satisfies an important property.
- The dynamic evolution of a Markov process does not depend on all past values but only on the immediate past values:

$$\begin{aligned} \Pr[\mathbf{X}(t_q) &= \mathbf{x}_q \mid \mathbf{X}(t_{q-1}) = \mathbf{x}_{q-1}, \mathbf{X}(t_{q-2}) = \mathbf{x}_{q-2}, ..., \mathbf{X}(t_1) = \mathbf{x}_1] \\ &= \Pr[\mathbf{X}(t_q) = \mathbf{x}_q \mid \mathbf{X}(t_{q-1}) = \mathbf{x}_{q-1}] \\ &\qquad \qquad t_q > t_{q-1} > \cdots > t_1 \end{aligned}$$

transition probability

#### Markov Processes

For a Markov process, we have:

$$\begin{split} \Pr[\mathbf{X}(t_1) = \mathbf{x}_1, \mathbf{X}(t_2) = \mathbf{x}_2, ..., \mathbf{X}(t_q) = \mathbf{x}_q] \\ = \Pr[\mathbf{X}(t_1) = \mathbf{x}_1] \prod_{i=1}^{q-1} \Pr[\mathbf{X}(t_{i+1}) = \mathbf{x}_{i+1} \mid \mathbf{X}(t_i) = \mathbf{x}_i] \\ \text{initial probability} \end{split}$$

Therefore, only the <u>initial</u> and <u>transition probabilities</u> are required for specifying the joint probabilities of a Markov process.

#### Markov Processes

Chapman-Kolmogorov equation:

$$\begin{split} \Pr[\mathbf{X}(t_{q+1}) &= \mathbf{x}_{q+1} \mid \mathbf{X}(t_{q-1}) = \mathbf{x}_{q-1}] \\ &= \sum_{\mathbf{x}_q} \Pr[\mathbf{X}(t_{q+1}) = \mathbf{x}_{q+1} \mid \mathbf{X}(t_q) = \mathbf{x}_q] \Pr[\mathbf{X}(t_q) = \mathbf{x}_q \mid \mathbf{X}(t_{q-1}) = \mathbf{x}_{q-1}] \\ &\text{see supplement \#1 for proof} \end{split}$$

 An alternative form of this identity is known as the <u>master</u> <u>equation</u> and is fundamental when modeling stochastic dynamics on complex networks.

#### Homogeneous Markov Processes

- □ We will focus on <u>homogeneous</u> Markov processes.
- This means that the transition probabilities depend only on the difference between time points:

$$\Pr[\mathbf{X}(t_q) = \mathbf{x}_q \mid \mathbf{X}(t_{q-1}) = \mathbf{x}_{q-1}] = \Pr[\mathbf{X}(t_q + \tau) = \mathbf{x}_q \mid \mathbf{X}(t_{q-1} + \tau) = \mathbf{x}_{q-1}]$$

for any constant au .

- $\Box$  Consider transitions in the <u>infinitesimally small</u> time-interval [t,t+dt)
- $T(\mathbf{x}_{q+1} \mid \mathbf{x}_q)dt$ : probability that a transition from  $\mathbf{x}_q$  to  $\mathbf{x}_{q+1}$  takes place during [t,t+dt).
- $\Box$  We set  $T(\mathbf{x} \mid \mathbf{x}) = 0$ .
- $\Box$   $a_0(\mathbf{x}_q)dt$ : probability that a transition takes place during [t,t+dt).
- $\Box$  1- $a_0(\mathbf{x}_q)dt$ : probability that no transition takes place during [t,t+dt).
- Note that

$$a_0(\mathbf{x}_q) = \sum_{\mathbf{x}} T(\mathbf{x} \mid \mathbf{x}_q)$$

 $\square$  For small enough dt, note that:

$$\begin{split} \Pr[\mathbf{X}(t+dt) &= \mathbf{x}_{q+1} \mid \mathbf{X}(t) = \mathbf{x}_q] \\ &= [1 - a_0(\mathbf{x}_q)dt] \mathcal{S}(\mathbf{x}_{q+1} - \mathbf{x}_q) + T(\mathbf{x}_{q+1} \mid \mathbf{x}_q)dt \\ \text{Kronecker delta } \delta(x) &= \begin{cases} 1, & \text{if } x = 0 \\ 0, & \text{if } x \neq 0 \end{cases} \end{split}$$

This requires the assumption that <u>at most one</u> transition can take place during [t, t+dt).

#### From

$$\begin{aligned} \bullet & & \Pr[\mathbf{X}(t_{q+1}) = \mathbf{x}_{q+1} \mid \mathbf{X}(t_{q-1}) = \mathbf{x}_{q-1}] \\ & = \sum_{\mathbf{x}_q} \Pr[\mathbf{X}(t_{q+1}) = \mathbf{x}_{q+1} \mid \mathbf{X}(t_q) = \mathbf{x}_q] \Pr[\mathbf{X}(t_q) = \mathbf{x}_q \mid \mathbf{X}(t_{q-1}) = \mathbf{x}_{q-1}] \end{aligned}$$

• 
$$\Pr[\mathbf{X}(t+dt) = \mathbf{x}_{q+1} \mid \mathbf{X}(t) = \mathbf{x}_q] = [1 - a_0(\mathbf{x}_q)dt]\delta(\mathbf{x}_{q+1} - \mathbf{x}_q) + T(\mathbf{x}_{q+1} \mid \mathbf{x}_q)dt$$

• 
$$a_0(\mathbf{x}_q) = \sum_{\mathbf{x}} T(\mathbf{x} \mid \mathbf{x}_q)$$

we can show that (set  $t_{q-1}=0,\,t_q=t,\,t_{q+1}=t+dt$ )

$$\frac{\Pr[\mathbf{X}(t+dt) = \mathbf{x}_{q+1} \mid \mathbf{X}(0) = \mathbf{x}_{q-1}] - \Pr[\mathbf{X}(t) = \mathbf{x}_{q+1} \mid \mathbf{X}(0) = \mathbf{x}_{q-1}]}{dt}$$

$$= \sum_{\mathbf{x}_{q}} T(\mathbf{x}_{q+1} \mid \mathbf{x}_{q}) \Pr[\mathbf{X}(t) = \mathbf{x}_{q} \mid \mathbf{X}(0) = \mathbf{x}_{q-1}]$$

$$- \sum_{\mathbf{x}_{q}} T(\mathbf{x}_{q} \mid \mathbf{x}_{q+1}) \Pr[\mathbf{X}(t) = \mathbf{x}_{q+1} \mid \mathbf{X}(0) = \mathbf{x}_{q-1}]$$

see supplement #2 for details

 $\square$  By taking the limit as  $dt \rightarrow 0$ , we obtain

$$\frac{\partial \Pr[\mathbf{X}(t) = \mathbf{x}_{q+1} \mid \mathbf{X}(0) = \mathbf{x}_{q-1}]}{\partial t}$$

$$= \sum_{\mathbf{x}_{q}} \left\{ T(\mathbf{x}_{q+1} \mid \mathbf{x}_{q}) \Pr[\mathbf{X}(t) = \mathbf{x}_{q} \mid \mathbf{X}(0) = \mathbf{x}_{q-1}] - T(\mathbf{x}_{q} \mid \mathbf{x}_{q+1}) \Pr[\mathbf{X}(t) = \mathbf{x}_{q+1} \mid \mathbf{X}(0) = \mathbf{x}_{q-1}] \right\}$$

- This <u>differential form</u> of the Chapman-Kolmogorov equation is called the <u>Master Equation (ME)</u>.
- For simplicity, we write the ME in the form:

$$\frac{\partial \Pr[\mathbf{X}(t) = \mathbf{x} \mid \mathbf{X}(0) = \mathbf{x}_0]}{\partial t} \\
= \sum_{\mathbf{x}'} \left\{ T(\mathbf{x} \mid \mathbf{x}') \Pr[\mathbf{X}(t) = \mathbf{x}' \mid \mathbf{X}(0) = \mathbf{x}_0] - T(\mathbf{x}' \mid \mathbf{x}) \Pr[\mathbf{X}(t) = \mathbf{x} \mid \mathbf{X}(0) = \mathbf{x}_0] \right\}$$

This leads to:

$$\frac{\partial p_X(\mathbf{x};t)}{\partial t} = \sum_{\mathbf{x}'} \{ T(\mathbf{x} \mid \mathbf{x}') p_X(\mathbf{x}';t) - T(\mathbf{x}' \mid \mathbf{x}) p_X(\mathbf{x};t) \}, \quad t > 0$$

since we have defined  $p_X(\mathbf{x};t) = \Pr[\mathbf{X}(t) = \mathbf{x} \mid \mathbf{X}(0) = \mathbf{x}_0], \ t > 0.$ 

- □ The ME is initialized with  $p_X(\mathbf{x};0) = \delta(\mathbf{x} \mathbf{x}_0)$ . Kronecker delta
- lacktriangle Note that  $p_{X}(\mathbf{x};t)$  depends on the initial condition  $\mathbf{x}_0$  in general.
- We do not show this dependence explicitly for notational simplification.

- The state of a general complex network can only be updated based upon the firing of reactions.
- When a reaction fires, the state instantaneously updates according to the stoichiometry of the network.
- If the m-th reaction is the only one that fires within the time interval [t, t+dt) and if  $\mathbf{s}_m$  is the m-th column of the net stoichiometric matrix  $\mathbf{S}$ , then we would have:

$$\mathbf{x}(t+dt) = \mathbf{x}(t) + \mathbf{s}_m$$

If we assign a firing rule  $\pi_m(\mathbf{x})$ , characteristic to the m-th reaction, such that the probability that the reaction will fire during the time interval [t, t+dt) when  $\mathbf{X}(t) = \mathbf{x}$  is given by

$$T(\mathbf{x} + \mathbf{s}_m \mid \mathbf{x})dt = \pi_m(\mathbf{x})dt$$

then we can arrive at the following ME:

$$\frac{\partial p_X(\mathbf{x};t)}{\partial t} = \sum_{m=1}^{M} \{ \pi_m(\mathbf{x} - \mathbf{s}_m) p_X(\mathbf{x} - \mathbf{s}_m;t) - \pi_m(\mathbf{x}) p_X(\mathbf{x};t) \}, \quad t > 0$$

propensity function

This is because

$$T(\mathbf{x}' \mid \mathbf{x}) = 0$$
 for any  $\mathbf{x}' \neq \mathbf{x} + \mathbf{s}_m$ 

$$\frac{\partial p_X(\mathbf{x};t)}{\partial t} = \sum_{m=1}^{M} \{ \pi_m(\mathbf{x} - \mathbf{s}_m) p_X(\mathbf{x} - \mathbf{s}_m;t) - \pi_m(\mathbf{x}) p_X(\mathbf{x};t) \}, \quad t > 0$$

From the ME, we have that:

$$p_X(\mathbf{x};t+dt) \simeq p_X(\mathbf{x};t) + \sum_{m=1}^{M} \pi_m(\mathbf{x}-\mathbf{s}_m)dt \, p_X(\mathbf{x}-\mathbf{s}_m;t) - \sum_{m=1}^{M} \pi_m(\mathbf{x})dt \, p_X(\mathbf{x};t)$$

probability that the system will switch to state  $\mathbf{X}$  within the infinitesimal time interval [t,t+dt).

probability that the system will switch state within the infinitesimal time interval [t,t+dt), given that it is in state **x** at time t.

#### Degree of Advancement

- Let  $Z_m(t)$  be the number of times that the m-th reaction occurs within the time interval [0,t).
- $\square$  This is known as the <u>degree of advancement</u> of the m-th reaction.
- □ The degree of advancement is random and  $\{Z_m(t), t \ge 0\}$  is a counting process.
- $\square$  By convention,  $Z_m(0) = 0$ .
- The state of a complex network can also be characterized by the degree of advancement vector  $\mathbf{Z}(t)$ .
- $\square$  We refer to  $\{\mathbf{Z}(t), t \geq 0\}$  as the <u>DA process</u>.

#### Degree of Advancement

- What is the best choice for the state of a complex network, the population process  $\{X(t), t \ge 0\}$  or the DA process  $\{Z(t), t \ge 0\}$ ?
- Note that

$$\mathbf{X}(t) = \mathbf{x}_0 + \mathbf{S}\mathbf{Z}(t), \quad t \ge 0$$

Therefore,

$$\mathbf{Z}(t) \Rightarrow \mathbf{X}(t), \quad t \ge 0$$

However,

$$\mathbf{X}(t) \not\Rightarrow \mathbf{Z}(t), \quad t \ge 0$$

in general (unless  $S^TS$  is invertible).

This implies that the DA process is more informative than the population process!

If we denote

$$p_Z(\mathbf{z};t) = \Pr[\mathbf{Z}(t) = \mathbf{z} \mid \mathbf{Z}(0) = 0]$$

then we have the following ME:

$$\frac{\partial p_Z(\mathbf{z};t)}{\partial t} = \sum_{m=1}^{M} \left\{ a_m(\mathbf{z} - \mathbf{e}_m) p_Z(\mathbf{z} - \mathbf{e}_m;t) - a_m(\mathbf{z}) p_Z(\mathbf{z};t) \right\}, \quad t > 0$$

where

m-th column of the  $M \times M$  identity matrix

$$a_m(\mathbf{z}) = \begin{cases} \pi_m(\mathbf{x}_0 + \mathbf{S}\mathbf{z}), & \text{if } \mathbf{z} \ge 0 \\ 0, & \text{otherwise} \end{cases}$$

This equation is initialized with  $p_Z(\mathbf{z};0) = \delta(\mathbf{z})$ .

Kronecker delta

If the previous equation is solved for  $p_Z(\mathbf{z};t), t>0$ , then

$$p_X(\mathbf{x};t) = \sum_{\mathbf{z} \in \mathfrak{B}(\mathbf{x})} p_Z(\mathbf{z};t)$$

where

$$\mathfrak{G}(\mathbf{x}) = \{\mathbf{z} : \mathbf{x} = \mathbf{x}_0 + \mathbf{S}\mathbf{z}\}$$

## Topological Structure and Propensity Functions

The MEs

$$\frac{\partial p_Z(\mathbf{z};t)}{\partial t} = \sum_{m=1}^{M} \left\{ a_m(\mathbf{z} - \mathbf{e}_m) p_Z(\mathbf{z} - \mathbf{e}_m;t) - a_m(\mathbf{z}) p_Z(\mathbf{z};t) \right\}, \quad t > 0$$

$$\frac{\partial p_X(\mathbf{x};t)}{\partial t} = \sum_{m=1}^{M} \left\{ \pi_m(\mathbf{x} - \mathbf{s}_m) p_X(\mathbf{x} - \mathbf{s}_m;t) - \pi_m(\mathbf{x}) p_X(\mathbf{x};t) \right\}, \quad t > 0$$

may give the impression that the probabilities  $p_X(\mathbf{x};t)$  and  $p_Z(\mathbf{z};t)$  do not depend on a detailed knowledge of the topological structure of the network.

The first ME seems not to depend on the stoichiometric coefficients  $\nu, \nu'$ , whereas, the second equation seems to depend only on the net stoichiometric coefficients  $s = \nu' - \nu$ .

#### Topological Structure and Propensity Functions

- It turns out that, for all reactions encountered in practice, the propensity function  $\pi_m(\mathbf{x})$  does not depend on all elements of the state vector  $\mathbf{x}$  but only on those elements associated with the adjacent reactant nodes, as specified by the stoichiometric matrix  $\mathbf{V}$ .
- Consequently, the topological structure of a reaction network directly affects its dynamics through this mathematical property of the propensity functions.