

Part 1 (code: 351HW2Python_part1.ipynb)

I split the training set to 80% of training, 20% of validation set, Validation set is the set that want our model to perform well by tuning hyper-parameters. Then, by using Keras library in python, Generate batches of tensor image data with real-time data augmentation for train, validation and test sets. I used the default setting for ImageDataGenerator (will improve this part in part2).

```
Training data
Found 32353 validated image filenames belonging to 13 classes.
Validation data
Found 8088 validated image filenames belonging to 13 classes.
Test data
Found 4000 validated image filenames.
```

Also, by keras library, I generated the following CNN model:

Model: "sequential_6"

Layer (type)	Output Shape	Param #
conv2d_21 (Conv2D)	(None, 97, 97, 32)	544
max_pooling2d_11 (MaxPooling)	(None, 48, 48, 32)	0
dropout_22 (Dropout)	(None, 48, 48, 32)	0
flatten_6 (Flatten)	(None, 73728)	0
dense_12 (Dense)	(None, 256)	18874624
dropout_23 (Dropout)	(None, 256)	0
dense_13 (Dense)	(None, 13)	3341
Total params: 18,878,509		
Trainable params: 18,878,509		
Non-trainable params: 0		

Input layer: reshape image into the input shape that I want. I set the shape=(100, 100, 1)

Conv2d: this layer extract feature from image dataset, has number of fliters that done convolutional operation. I set the kernel size to (4,4), and set activation function to relu, rectified linear unit. It will output the input if input is positive, otherwise it will output 0.

Maxpooling: It reduces volume of input image after convolution 2d.

Flatten: flatten the input, decreases the dimension of input data.

Dense: A layer that receives input from all neurons of its previous layer.

Dropout: Reduce overfitting and complexity of the model.

(I will make improvement for layers in part2.)

So, for the raw model, I choose to use epoch = 2 to lower the computational cost of my computer. Epoch is the number of passes over the training model for the entire dataset.

Here is the result:

```
Epoch 1/2
808/808 [=====] - 709s 877ms/step - loss: 12.8503 - accuracy: 0.6878 - val_loss: 0.0707 - val_accuracy: 0.8616
Epoch 2/2
808/808 [=====] - 695s 859ms/step - loss: 0.0789 - accuracy: 0.8529 - val_loss: 0.0612 - val_accuracy: 0.8881
: <tensorflow.python.keras.callbacks.History at 0x1a628d39d88>

1 predict = model.predict_generator(test_generator, steps=num_test_samples // batch_size )
2
3 # convert prediction result of integers to categorical names
4 predicted_class_indices=np.argmax(predict,axis=1)
5 labels = (training_generator.class_indices)
6 labels = dict((v,k) for k,v in labels.items())
7 predictions = [labels[k] for k in predicted_class_indices]

C:\Users\24937\Anaconda3\lib\site-packages\tensorflow\python\keras\engine\training.py:1905: UserWarning: `Model.predict_generator` is deprecated and will be removed in a future version. Please use `Model.predict`, which supports generators.
warnings.warn("`Model.predict_generator` is deprecated and ")

1 from sklearn.metrics import accuracy_score
2
3 accuracy_score(test['label'], predictions)

: 0.88525
```

By using the test dataset, the result accuracy for the first raw CNN model is 0.88525.

Part 2:

In part 2, according to the previous model, I will make improvement in the following ways:

1. Turning parameters on a dev set. Though I did something in part 1, I can change some parameters, add more layers to the previous model.
2. Generate more image data for training, by keras ImageGenerator.
3. Apply transfer learning using a popular pre-trained image classification.
4. Combine image and text description
5. Hyperparameter pruning (future improvement)

(1) Turning Parameters: According the turning parameters in part1, I change the kernel size from (4,4) to (3,3), change dropout(0.2) to dropout(0.1). For the last dense layer, I choose to use softmax activation function, rather than 'relu'. Softmax converts a real vector to a vector of categorical probabilities.

For the compile method, I choose adam optimization. Adam optimization is a stochastic gradient descent method that is based on adaptive estimation of first-order and second-order moments. Also, the learning rate is default 0.001.

Also, I add more layers in the model: *(code: 351HW2Python_part2_improved model.ipynb)*

Model: "sequential"

Layer (type)	Output Shape	Param #
conv2d (Conv2D)	(None, 97, 97, 32)	544
conv2d_1 (Conv2D)	(None, 94, 94, 32)	16416
max_pooling2d (MaxPooling2D)	(None, 47, 47, 32)	0
dropout (Dropout)	(None, 47, 47, 32)	0
conv2d_2 (Conv2D)	(None, 44, 44, 32)	16416
conv2d_3 (Conv2D)	(None, 41, 41, 32)	16416
max_pooling2d_1 (MaxPooling2D)	(None, 20, 20, 32)	0
dropout_1 (Dropout)	(None, 20, 20, 32)	0
flatten (Flatten)	(None, 12800)	0
dropout_2 (Dropout)	(None, 12800)	0
dense (Dense)	(None, 256)	3277056
dropout_3 (Dropout)	(None, 256)	0
dense_1 (Dense)	(None, 13)	3341
Total params: 3,330,189		
Trainable params: 3,330,189		
Non-trainable params: 0		

```
In [12]: 1 from sklearn.metrics import accuracy_score
          2
          3 accuracy_score(test['label'], predictions)
```

Out[12]: 0.90525

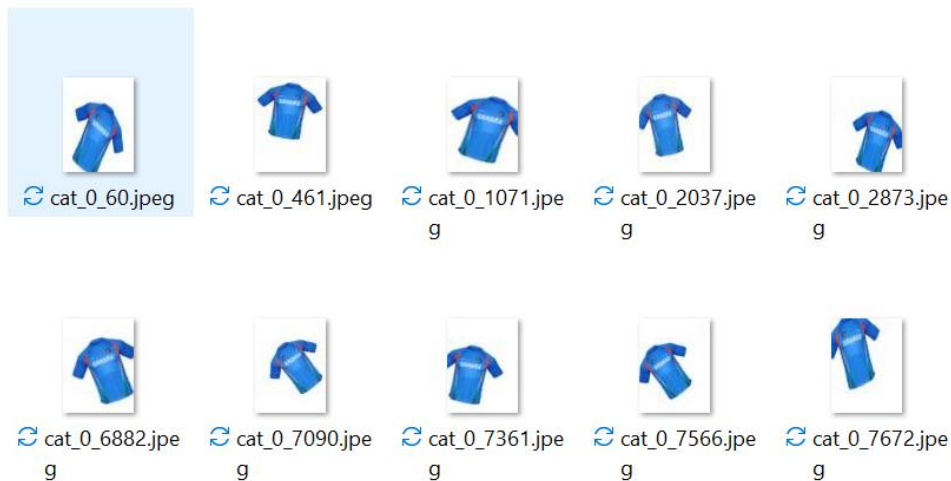
The accuracy is better than part1.

Generate more image data for training: I generated more data by rotation, width & height shift the pictures. As an example of image 1163.jpg:

(2)

Example for (2)

```
In [29]: 1 img = load_img('images/1163.jpg') # this is a PIL image
          2 x = img_to_array(img) # this is a Numpy array with shape (80, 60, 3)
          3 x = x.reshape((1,) + x.shape) # this is a Numpy array with shape (1, 80, 60, 3)
          4 i = 0
          5 for batch in image_generator.flow(x, batch_size=1,
          6                                 save_to_dir='preview', save_prefix='shirt', save_format='jpeg'):
          7     i += 1
          8     if i > 20:
          9         break
```



So, we can create more data for training.

Also I rescale the data to 1/255 and change the activation function to RGB. It is because RGB has coefficients between 0-255.

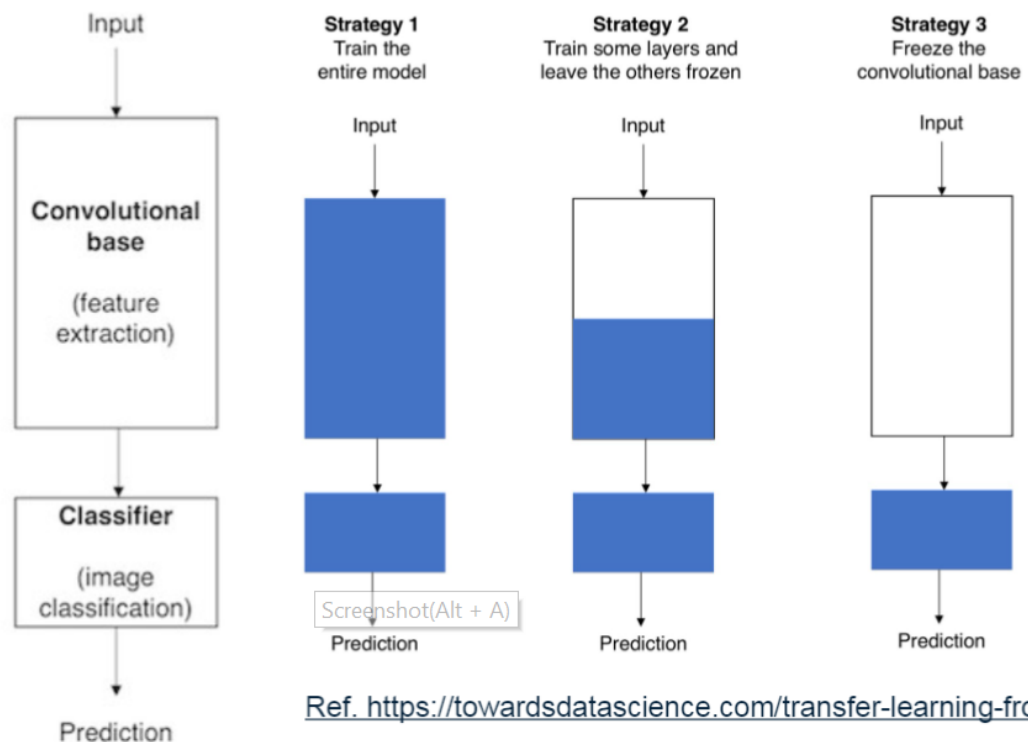
- (3) Apply transfer learning using a popular pre-trained image classification.
I'm trying to do the transfer learning by a pre-trained model. I choose to use Xception because it has the highest accuracy on the website: <https://keras.io/api/applications/>

(code: 351HW2Python_part2_finalmodel.ipynb)

Layer (type)	Output Shape	Param #
xception (Functional)	(None, 3, 3, 2048)	20861480
global_average_pooling2d_1 ((None, 2048)		0
dropout_1 (Dropout)	(None, 2048)	0
dense_1 (Dense)	(None, 256)	524544
dense_2 (Dense)	(None, 13)	3341
=====		
Total params: 21,389,365		
Trainable params: 527,885		
Non-trainable params: 20,861,480		

It includes the freezed xception layer, global average pooling layer, dropout layer, dense layers.

Sharing Strategies



I'm using strategy 2 in the class. Train the top layer and let other layers frozen, then train the full model.

Then, train the top layer by the above model:

```
1 # Train the top layer
2
3 model.compile(
4     optimizer=keras.optimizers.Adam(),
5     loss=keras.losses.BinaryCrossentropy(from_logits=True),
6     metrics=[keras.metrics.BinaryAccuracy()],
7 )
8 epochs = 5
9 model.fit_generator(
10     training_generator,
11     steps_per_epoch=0.8 * num_train_samples // batch_size,
12     epochs=epochs, # lower the computational cost
13     verbose=1,
14     validation_data=validation_generator,
15     validation_steps=0.2 * num_train_samples // batch_size)

```

Epoch 1/5
808/808 [=====] - 1044s 1s/step - loss: 0.2130 - binary_accuracy: 0.9348 - val_loss: 0.1580 - val_binary_accuracy: 0.9453
Epoch 2/5
808/808 [=====] - 1075s 1s/step - loss: 0.1550 - binary_accuracy: 0.9447 - val_loss: 0.1427 - val_binary_accuracy: 0.9477
Epoch 3/5
808/808 [=====] - 1032s 1s/step - loss: 0.1441 - binary_accuracy: 0.9470 - val_loss: 0.1344 - val_binary_accuracy: 0.9481
Epoch 4/5
808/808 [=====] - 1029s 1s/step - loss: 0.1365 - binary_accuracy: 0.9492 - val_loss: 0.1351 - val_binary_accuracy: 0.9489
Epoch 5/5
808/808 [=====] - 1067s 1s/step - loss: 0.1330 - binary_accuracy: 0.9501 - val_loss: 0.1274 - val_binary_accuracy: 0.9505

At last, do the fine turning for the entire model:

Model: "model"

Layer (type)	Output Shape	Param #
input_2 (InputLayer)	[(None, 100, 100, 3)]	0
normalization (Normalization)	(None, 100, 100, 3)	7
xception (Functional)	(None, 3, 3, 2048)	20861480
global_average_pooling2d (Gl	(None, 2048)	0
dropout (Dropout)	(None, 2048)	0
dense (Dense)	(None, 256)	524544
dense_1 (Dense)	(None, 13)	3341

Total params: 21,389,372
Trainable params: 21,334,837
Non-trainable params: 54,535

808/808 [=====] - 5051s 6s/step - loss: 0.1684 - binary_accuracy: 0.9420 - val_loss: 0.1128 - val_binary_accuracy: 0.9566

I choose a low value of epoch, because of high computational cost (my computer cannot support GPU).

```
1 from sklearn.metrics import accuracy_score
2
3 accuracy_score(test['label'], predictions)
4
```

0.768

```
1 score = model.evaluate(validation_generator)
```

203/203 [=====] - 220s 1s/step - loss: 0.1118 - binary_accuracy: 0.9563

The accuracy for testing dataset is low because of low iteration of 'epoch' and slow learning rate for the optimization function. It should be higher if epoch = 20 for each step, both training the top layer and the entire model. I choose number of epoch = 5 and 1 in these two steps, because the training time is 20 minutes for each epoch in top layer, and 1 hour for each epoch in the entire model.

The accuracy for validation set is 0.9563.

(4) Combine image and text description

For CNN in text description itself, I created a sample model for it.

(code: 351HW2Python_text analysis.ipynb)

Model: "sequential_10"

Layer (type)	Output Shape	Param #
flatten_6 (Flatten)	(None, 10000)	0
dense_12 (Dense)	(None, 256)	2560256
dropout_10 (Dropout)	(None, 256)	0
dense_13 (Dense)	(None, 256)	65792
dense_14 (Dense)	(None, 13)	3341
Total params: 2,629,389		
Trainable params: 2,629,389		
Non-trainable params: 0		

To check if this model works well with description words. This raw model has accuracy 71% by using first 300 descriptions in training dataset and all descriptions in testing dataset.

Then, combine the model with description words with the transformation model, to see the performance increases or not. (I choose epoch = 1 because it runs for 1 hour and 20 minutes)

(code: 351HW2Python_part2_final_model.ipynb)

Model: "model_2"

Layer (type)	Output Shape	Param #	Connected to
input_2 (InputLayer)	[None, 100, 100, 3]	0	
normalization (Normalization)	(None, 100, 100, 3)	7	input_2[0][0]
flatten_1_input (InputLayer)	[None, 10000]	0	
xception (Functional)	(None, 3, 3, 2048)	20861480	normalization[0][0]
flatten_1 (Flatten)	(None, 10000)	0	flatten_1_input[0][0]
global_average_pooling2d (GlobalAveragePooling2D)	(None, 2048)	0	xception[0][0]
dense_5 (Dense)	(None, 256)	2560256	flatten_1[0][0]
dropout (Dropout)	(None, 2048)	0	global_average_pooling2d[0][0]
dropout_2 (Dropout)	(None, 256)	0	dense_5[0][0]
dense (Dense)	(None, 256)	524544	dropout[0][0]
dense_6 (Dense)	(None, 256)	65792	dropout_2[0][0]
dense_1 (Dense)	(None, 13)	3341	dense[0][0]
dense_7 (Dense)	(None, 13)	3341	dense_6[0][0]
add_13 (Add)	(None, 13)	0	dense_1[0][0] dense_7[0][0]
Total params: 24,018,761			
Trainable params: 23,964,226			
Non-trainable params: 54,535			

The solution is:

```
1138/1138 [=====] - 5103s 4s/step - loss: 120.4788 - binary_accuracy: 0.9074 - val_loss: 0.1687 - val_binary_accuracy: 0.9231

: 1 score = newModel.evaluate([X_test_p,x_test], y_test, batch_size=batch_size, verbose=1)

125/125 [=====] - 114s 838ms/step - loss: 0.1701 - binary_accuracy: 0.9231
```

The validation binary accuracy is 0.9231, the binary accuracy for test set is 0.9231. It is better than the previous model, CNN with transform learning.

(5) Hyperparameter pruning (further improvement)

By keras tuner API, we can set different parameters such as learning rate, loss function, to get the optimal answer for our current model.

Summary:

I created a basic CNN model in part 1. Then in part 2, I improve the previous CNN model in part 1, then using transfer learning with Xception pre-trained model. After that, I combined text analysis with descriptions of clothes, made the performance of model better. Also, Hyper

parameter pruning can optimize the current model performance.

The further improvement could be, run the model by GPU, that can allow my computer to have more iteration, or larger number of epochs. For most of the models I run the parameter for epoch between 1-5, which is a low number of epoch.