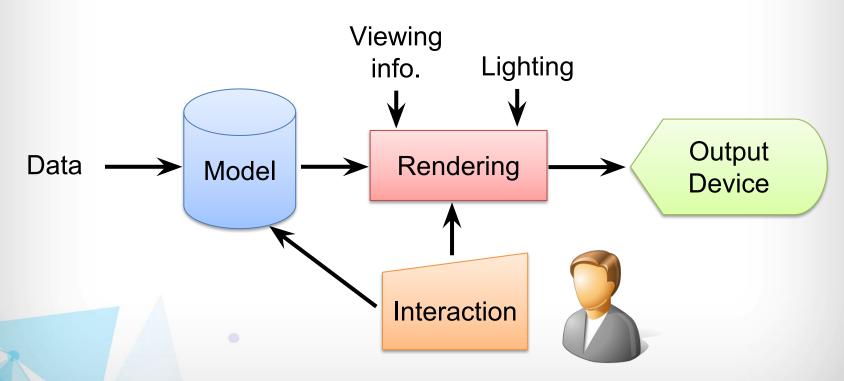
CG Basics I



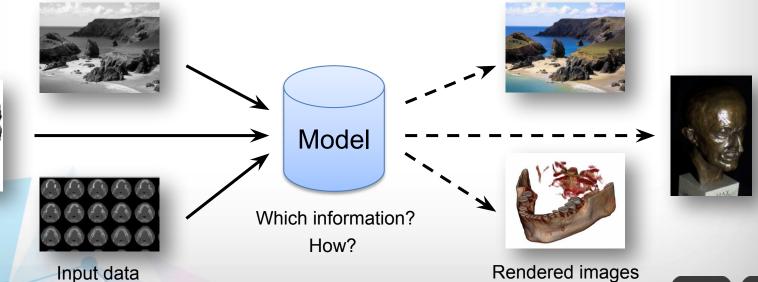
Image Synthesis

Functional diagram





- "Virtual" representation of the input data
 - Geometric information: vertices, edges, polygons...
 - Colors, materials, textures...
 - Intensity or density values...



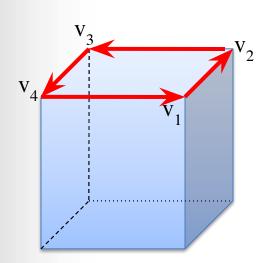


- In this course we will work with Polygonal Models
 - We should store geometric information
 - Faces, edges and vertices
 - Also topological information
 - Adjacency information between geometric element
 - They must be valid:
 - Oriented faces
 - Each edge limits 2 faces
 - Closed and simple models
 - Vertices sorted according to the faces' orientation
 - They have associated a Coordinate System
 - To render them: flat faces → triangulation





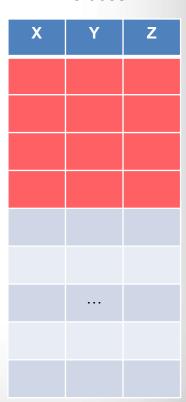
Example 1



Faces

Normal	Nº V	ld 1st V
(a1, b1, c1)	4	1

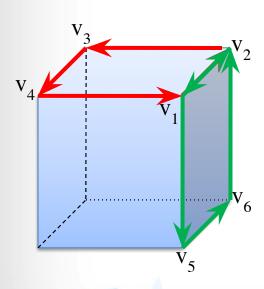
Vertices







Example 1



Faces

Normal	Nº V	ld 1st V
(a1, b1, c1)	4	1
(a2, b2, c2)	4	5

Vertices

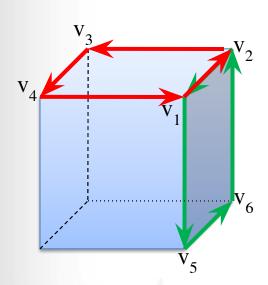
X	Y	Z
	•••	

Repeated vertices!!





Example 2



Faces

Normal	Id Vertices
(a1, b1, c1)	1, 2, 3, 4
(a2, b2, c2)	1, 5, 6, 2

Vertices

Х	Y	Z

Better representation!

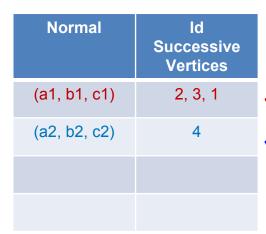




Example 3

V₄
V₁
V₅

Faces



Vertices

	X	Y	Z
4			
A			
1			
//			

Even better representation!

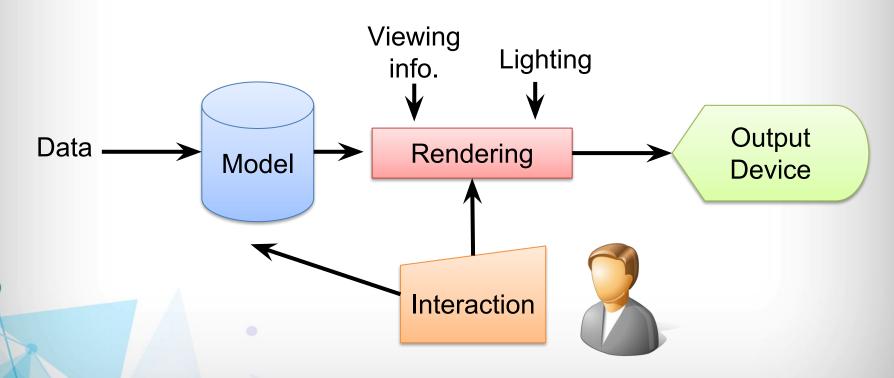




Strips

Image Synthesis

Functional diagram



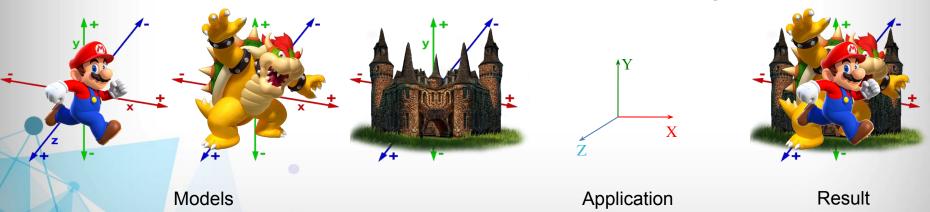


Transformations

Coordinate systems

- The elements of each model (vertices, edges, ...) are defined according to a local coordinate system
- In order to render a model, its elements must be transformed to the global coordinate system of the application

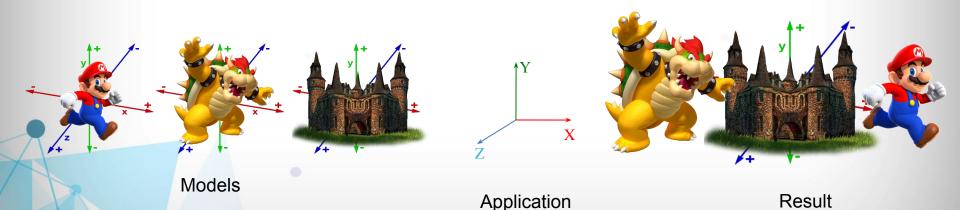
Problem! All CS with the same origin!!







- Coordinate systems
 - Furthermore, they must be placed in the correct position!
 - To do this, we use geometric transformations
 - Translations, rotations and scaling
 - The combination of them can be represented as a 4x4 matrix!







Geometric transformations

$$Translation = \begin{bmatrix} 1 & 0 & 0 & T_x \\ 0 & 1 & 0 & T_y \\ 0 & 0 & 1 & T_z \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$Rot_x(\theta) = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & \cos\theta & -\sin\theta & 0 \\ 0 & \sin\theta & \cos\theta & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$Rot_y(\theta) = \begin{bmatrix} \cos\theta & 0 & \sin\theta & 0 \\ 0 & 1 & 0 & 0 \\ -\sin\theta & 0 & \cos\theta & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$Scaling = \begin{bmatrix} S_x & 0 & 0 & 0 \\ 0 & S_y & 0 & 0 \\ 0 & 0 & S_z & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$Rot_{x}(\theta) = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & cos\theta & -sin\theta & 0 \\ 0 & sin\theta & cos\theta & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$Rot_{y}(\theta) = \begin{bmatrix} cos\theta & 0 & sin\theta & 0 \\ 0 & 1 & 0 & 0 \\ -sin\theta & 0 & cos\theta & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$Scaling = \begin{bmatrix} S_x & 0 & 0 & 0 \\ 0 & S_y & 0 & 0 \\ 0 & 0 & S_z & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \qquad Rot_z(\theta) = \begin{bmatrix} cos\theta & -sin\theta & 0 & 0 \\ sin\theta & cos\theta & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$





So, to place objects all over the scene...

```
var mvMatrix = mat4.create();
```

```
mat4.identity(mvMatrix);
```

```
mat4.translate(mvMatrix, [0.0, -1.0, -10.0]);
```

```
mat4.rotate(mvMatrix, radians, [0.0, 0.0, 1.0]);
```

```
mat4.scale(mvMatrix, [1.0, -1.0, 1.0]);
```



Viewing information





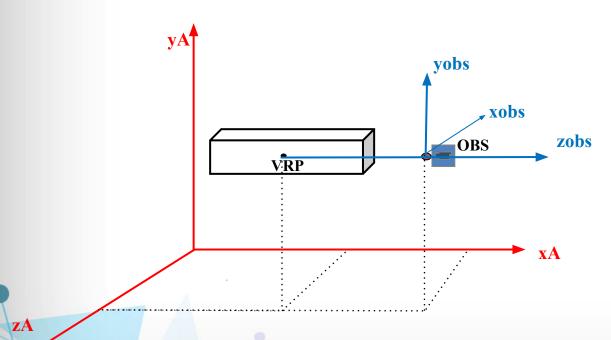








OpenGL/WebGL camera



OBS = Observer

VRP = View Reference Point

up = View Up Vector

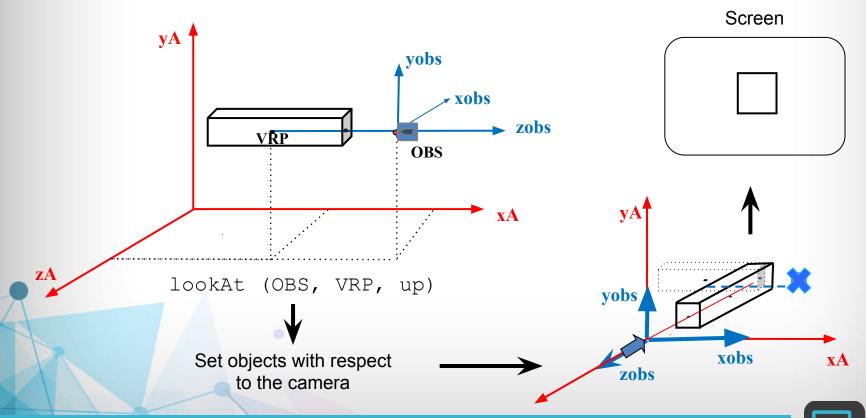
lookAt (OBS, VRP, up)

CS Observer/eye/camera

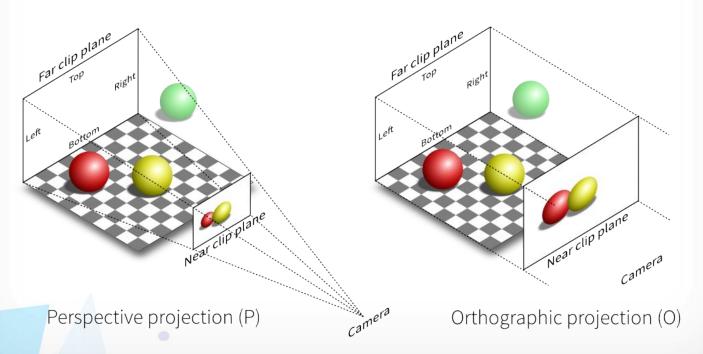




View transformation



Projection transformation



perspective (FOV, ra , zN, zF) ortho (left, right, bottom, top, zN,zF)





So, to configure the camera position and projection...

```
var vMatrix = mat4.create();
```

```
mat4.lookAt(vMatrix, [5.0, 5.0, 5.0], [0.0, 0.0, 0.0], [0.0, 1.0, 0.0]);
```

```
var pMatrix = mat4.create();
```

mat4.perspective(45, gl.viewportWidth / gl.viewportHeight, 0.1, 100.0, pMatrix);





OpenGL/WebGL pipeline

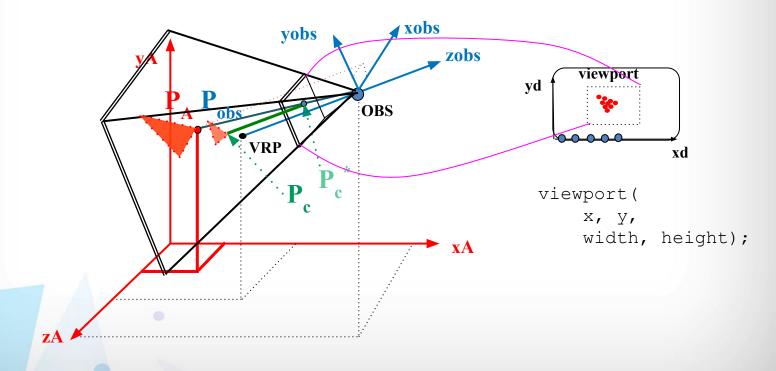
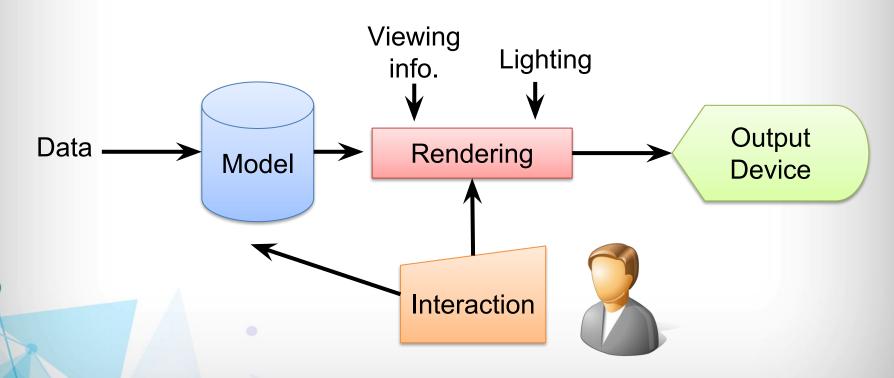




Image Synthesis

Functional diagram





Rendering process in WebGL

2b Modelview transform (position/orientation) 100kAt (...) or geom transforms.

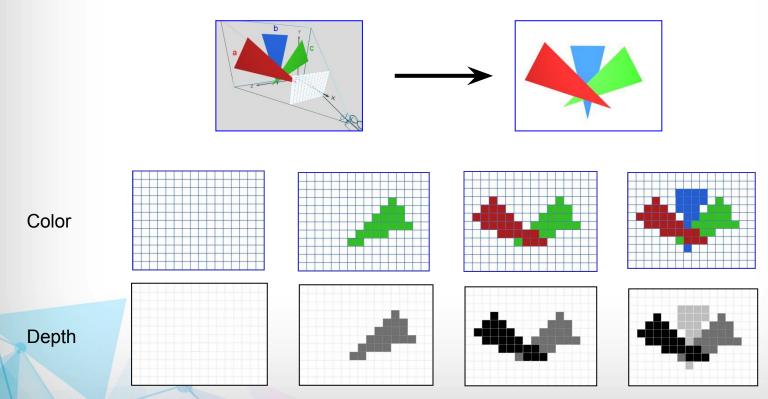
2c Projection Transformation
(lens optical properties) → perspective(...) or ortho(...)

3. Draw the scene — drawScene (...)





Color and depth of the scene





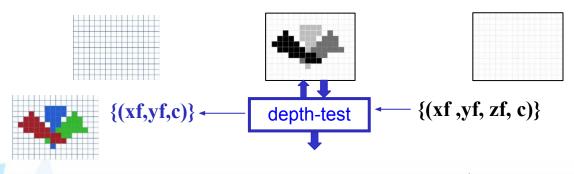
- Color and depth of the scene
 - Stored in 2 buffers with the screen's resolution

Frame Buffer: $(r, g, b) \in [0, 2^{n-1}]$

Depth Buffer: $z \in [0, 2^{n_z-1}]$

1. Init with the background color

1. Init with the furthest value

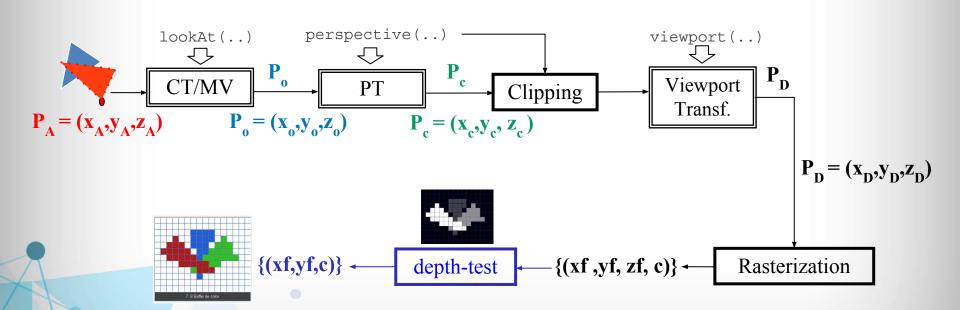


```
if (zf < depth_buffer(xf,yf)) {
          depth_buffer(xf,yf) = zf;
          frame_buffer(xf,yf) = c;
}</pre>
```



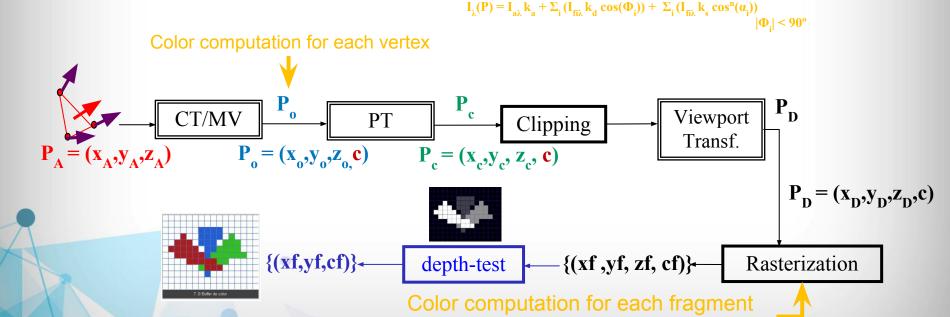


OpenGL/WebGL pipeline

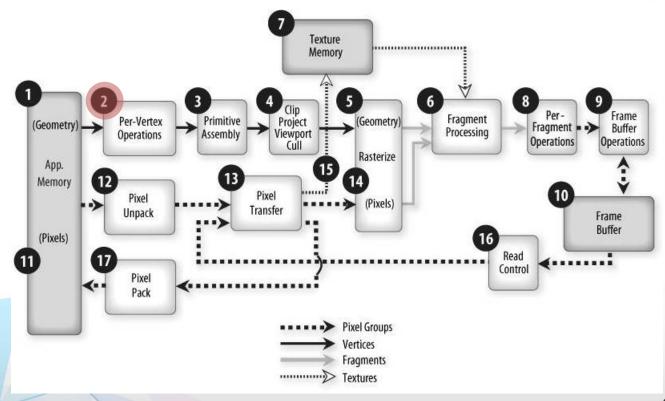




- Lighting in OpenGL/WebGL
 - Active light sources (position, direction, color)
 - Ambient light
 - Object material

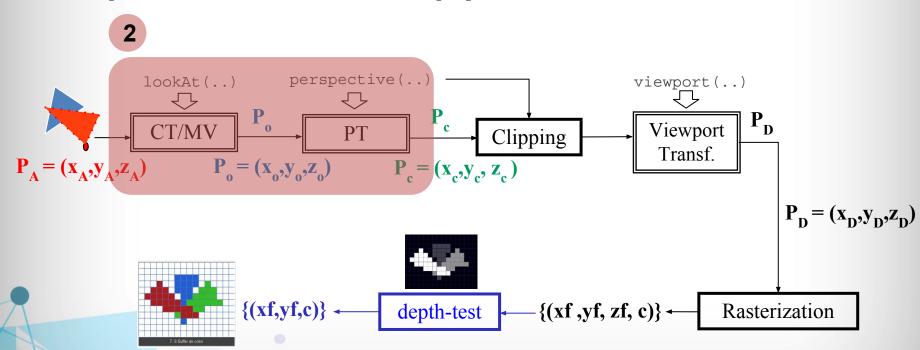


from the vertex's colors

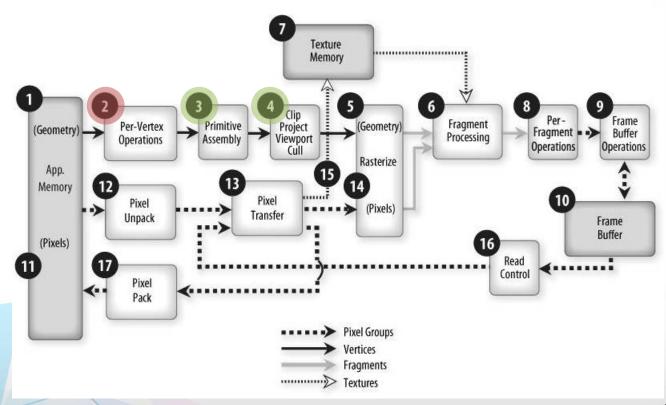






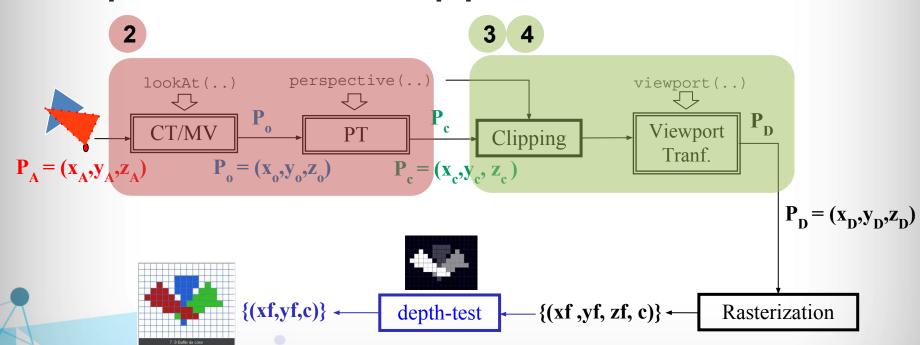




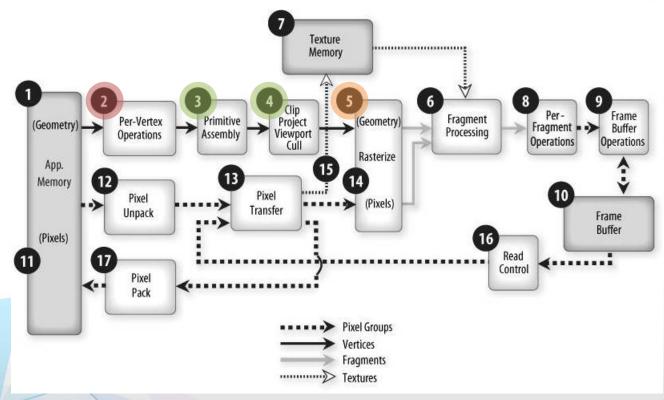






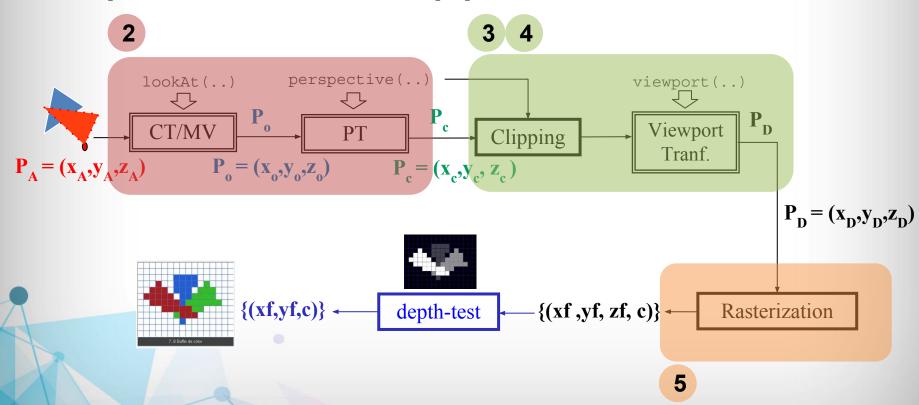




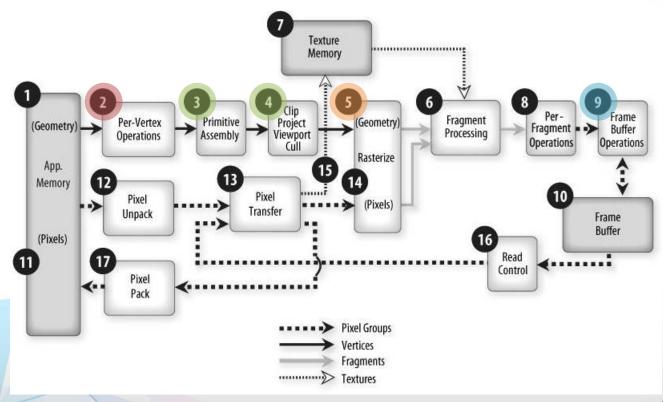






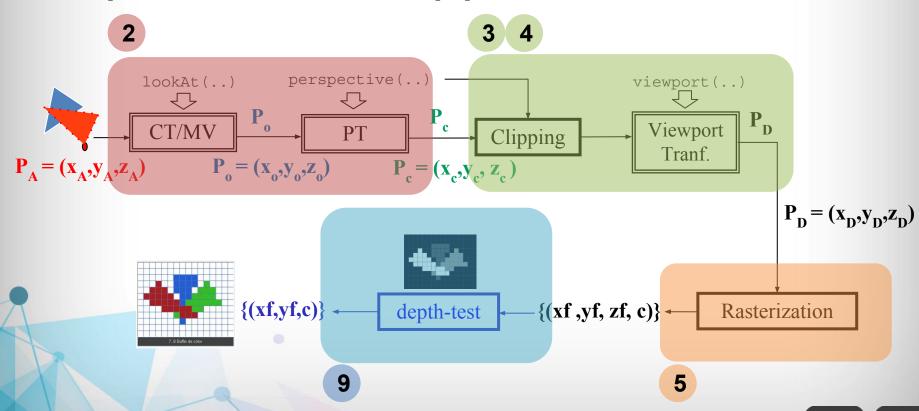






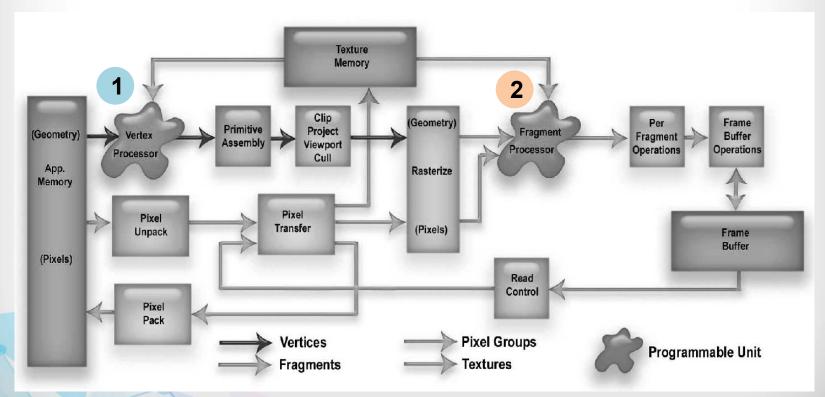






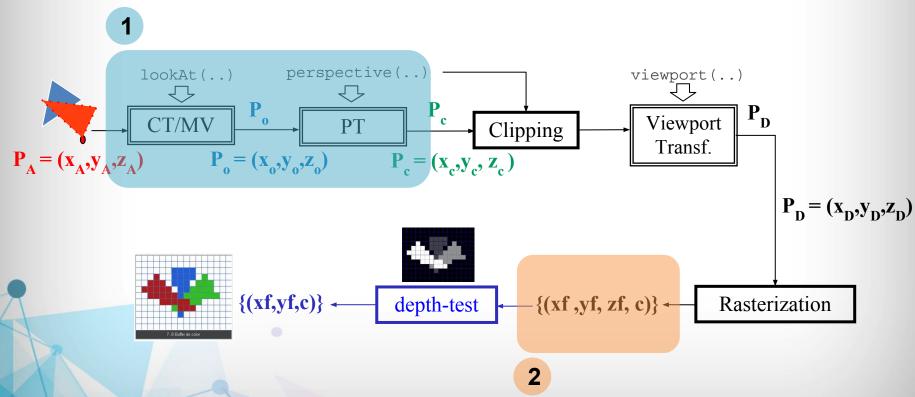


OpenGL/WebGL programmable pipeline











Questions?

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