UNIVERSIDAD NACIONAL DE COLOMBIA	Flujos de Potencia Newton Raphson (Con SVC - FA Model)
Creado por:	*David Urbaez León*
Docente:	*Ing. Javier Gustavo Herrera Murcia, PhD*

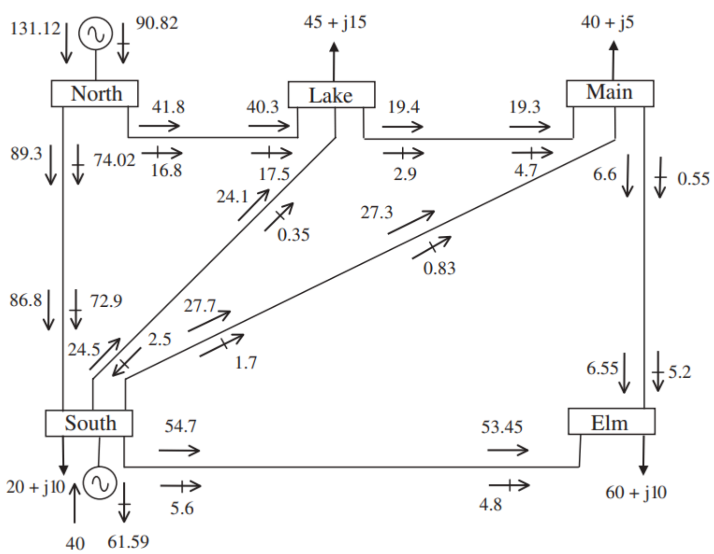
1) Se definen las bases del sistema

- Potencia base $S_b = 100 \cdot 10^6$ [VA]
- Voltaje base $V_b = 230 \cdot 10^3$ [V]

```
Sb = 100e6; %[VA]
Vb = 230e3; %[V]
```

2) Se crean las matrices con la información de la red (br_data, N_data):

Se deben crear dos matrices para ingresar la información referente al circuito. La primera (br_data) brinda información acerca de las conexiones entre buses como la impedancia de la línea o los buses entre los cuales se realiza la conexión , mientras que la segunda (N_data) da información acerca de la naturaleza de cada uno de los buses, tipo de bus (SL, PV o PQ).



a) Para la matriz **br_data** se tiene que el formato es

$$\text{brdata} = [\text{Bus}_{\text{from}}, \text{Bus}_{\text{to}}, R, X, G, B] \text{ in } p.u.$$

b) Para la matriz **N_data** se tiene que el formato es:

$$N\text{data} = \{\#\text{Bus}, \text{type}('\text{SL}', '\text{PQ}', '\text{PV}'), V[p.u.], \angle\text{V}^{\text{o}}, \text{PG}[p.u.], \text{QG}[p.u.], \text{PL}[p.u.], \text{QL}[p.u.]\}$$

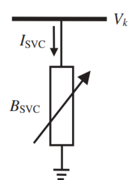
```
% Branches data R, X, G, B
% Types: General in form of impedance. (G & B are split in half at both ends).
```

```
% br_data=[ bus1, bus2,     R,      X,      G,      B] in p.u.
br_data = [
            1,      2,  0.02,    0.06,    0.0,     0.06;
            1,      3,  0.08,    0.24,    0.0,     0.05;
            2,      3,  0.06,    0.18,    0.0,     0.04;
            2,      4,  0.06,    0.18,    0.0,     0.04;
            2,      5,  0.04,    0.12,    0.0,     0.03;
            3,      4,  0.01,    0.03,    0.0,     0.02;
            4,      5,  0.08,    0.24,    0.0,     0.05];

% Node definitions
% {  #, type,   Vpu,    <Vº,   PG pu,  QG pu,  PL pu, QL pu}
N_data = {
    1,  'SL',   1.06,   0.0,    0.0,    0.0,    0.00,    0.00;
    2,  'PV',   1.0,    0.0,    0.4,    0.0,    0.20,    0.10;
    3,  'PQ',   1.0,    0.0,    0.0,    0.0,    0.45,    0.15;
    4,  'PQ',   1.0,    0.0,    0.0,    0.0,    0.40,    0.05;
    5,  'PQ',   1.0,    0.0,    0.0,    0.0,    0.60,    0.10;   };

br_data=array2table(br_data,'VariableNames',{'FromBus','ToBus','R','X','G','B'});
N_data=cell2table(N_data,'VariableNames',{'n','type','Vm','Va','PG','QG','PL','QL'});
```

c) Para el SVC:




```
% STATIC VAR COMPENSATION
% FIRING ANGLE MODEL

% NSVC : Number of SVC’s
% SVCsend : Compensated bus
% Xc : Capacitive reactance (p.u.)
% Xl : Inductive reactance (p.u.)
% FA : Initial SVC’s firing angle value (Deg)
% FALo : Lower limit of firing angle (Deg)
% BHi : Higher limit of firing angle (Deg)
% TarVol : Target nodal voltage magnitude to be controlled by SVC (p.u.)
% VSta : Indicate the status to get control over voltage magnitude nodal : 1
% is on; 0 is off

% SVCsend(1)=3; Xc(1)=1.07; Xl(1)=0.288; FA(1)=140; FALo(1)=90;
% FAHi(1)=180; TarVol(1)=1.0; VSta(1)=1;
% SVC_data = [SVC node,  Xc,    XL,    FA ,  FAmax, Famin, SVC TarVol, SVC Vsta]
SVC_data    = [   3    , 1.07,  0.288, 140 ,  180   ,  90   ,      1,         1  ];

SVC_data=array2table(SVC_data,'VariableNames',{'SVCBus','Xc','XL', 'FA' ,  'FAmax', 'FAmin', '
```

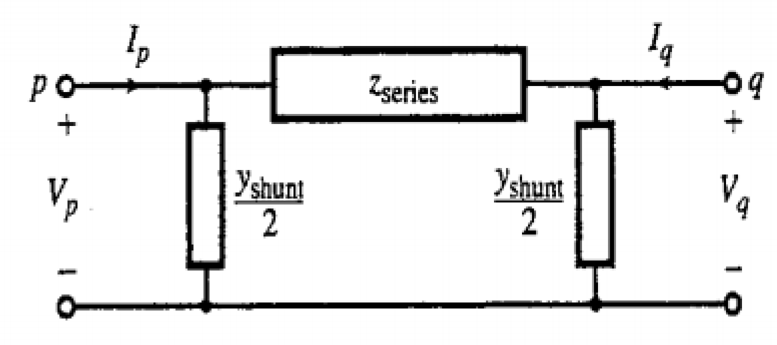
SVC_data = 1×8 table

	SVCBus	Xc	XL	FA	FAmax	FAmin	Tv	Status
1	3	1.0700	0.2880	140	180	90	1	1

3) Se crea Ybus con las redes de 2 puertos:

Se tiene la siguiente red de dos puertos, que representa el circuito del modelo pi de la línea de transmisión

$$\begin{bmatrix} V_i \\ V_j \end{bmatrix} = \begin{bmatrix} \frac{1}{z}+\frac{y}{2} & -\frac{1}{z} \\ -\frac{1}{z} & \frac{1}{z}+\frac{y}{2} \end{bmatrix} \begin{bmatrix} I_i \\ I_j \end{bmatrix}$$



Pi-equvalent model of a transmission line *(Pag 296, Bergen)*

```
n_br = size(br_data, 1); % Number of branches
n = max(max([br_data.FromBus,br_data.ToBus]));  % Number of nodes (starting at 1)
Ybus = zeros(n, n); % Empty Ybus Matrix

for kk = 1: size(br_data, 1)    % Iter over branch Data
    ii = br_data.FromBus(kk);                % From bus
    jj = br_data.ToBus(kk);                  % To Bus
    z = br_data.R(kk) + 1j * br_data.X(kk);  % Line impedance
    y = br_data.G(kk) + 1j * br_data.B(kk);  % Shunt admitance

    Ybr=[1 / z + y / 2 ,    -1 / z;  ...     % Ybr (Two-Port Network)
            -1 / z     , 1 / z + y / 2];

    Ybus([ii,jj],[ii,jj]) = Ybus([ii,jj],[ii,jj])+ Ybr;                      % Add the Two-Por
end
```

Se extrae la información de las potencias y voltajes:

```
Vm_sp = N_data.Vm;                % [V]  Specified Voltages
th_sp = N_data.Va.* pi ./ 180; % [Rads] Specified Angles
PG = N_data.PG;                % [p.u.] Active Power generators
QG = N_data.QG;                % [p.u.] Reactive Power generators
```

```
PL = N_data.PL;                   % [p.u.] Active Power Loads
QL = N_data.QL;                   % [p.u.] Reactive Power Loads

%% Calculated NetPowers
P_sp = PG - PL;                        % [p.u.] Specified Active Power    Pnet= (PGen - PLoad)
Q_sp = QG - QL;                        % [p.u.] Specified Reactive Power  Qnet= (QGen - QLoad)
```

4) Construcción de la matriz Jacobiana

Se encuentran las dimensiones de la matriz jacobiana:

```
% Jacobian matrix size.

nL = sum(strcmp(N_data.type,'PQ'));% Number of PQ nodes  (#Loads)
nG = sum(strcmp(N_data.type,'PV'));% Number of PV nodes  (#Generators)
```

Se divide la matriz Jacobiana en la submatrices H-N-M-L

$$\begin{array}{c c} & \begin{array}{cc} nL+nG & nL \end{array} \\ \begin{array}{c} nL+nG \\ nL \end{array} & \begin{bmatrix} H & N \\ M & L \end{bmatrix}^k \end{array} \begin{bmatrix} \Delta\theta \\ \Delta V/V \end{bmatrix}^k = \begin{bmatrix} \Delta P \\ \Delta Q \end{bmatrix}^k$$

(Eq. 3.32, pag108, Gómez - Exposito)

$$H_{ij} = \frac{\partial P_i}{\partial \theta_j}; \qquad N_{ij} = \frac{V_j\,\partial P_i}{\partial V_j}$$
$$M_{ij} = \frac{\partial Q_i}{\partial \theta_j}; \qquad L_{ij} = \frac{V_j\,\partial Q_i}{\partial V_j}$$

(Eq. 3.34, pag109, Gómez - Exposito)

```
H = zeros( nL + nG, nL + nG );
L = zeros( nL, nL );
N = zeros( nL + nG , nL );
M = zeros( nL , nL + nG );
J = [H, N; M, L];
```

Se crea el vector de estados ($X = [\theta|V]^T$) y el vector de funciones no lineales ($f(x) = [\Delta P|\Delta Q]$

```
x_th = zeros( nL + nG, 1 ); % State vector for storing angles (theta)
x_v = zeros( nL , 1);       % State vector for storing Voltages
```

$$x = [\theta|V]^{\mathrm{T}} = [\theta_1, \theta_2, \ldots, \theta_{n-1}|V_1, V_2, \ldots, V_{n_{\mathrm{L}}}]^{\mathrm{T}}$$ dim= (2nL+nG)

```
x = [x_th; x_v];
```

- Donde se tiene que:

$$\Delta P_i = P_i^{\mathrm{sp}} - V_i \sum_{j=1}^{n} V_j (G_{ij} \cos\theta_{ij} + B_{ij} \sin\theta_{ij}) \quad i = 1, 2, \ldots, n-1$$

$$\Delta Q_i = Q_i^{\mathrm{sp}} - V_i \sum_{j=1}^{n} V_j (G_{ij} \sin\theta_{ij} - B_{ij} \cos\theta_{ij}) \quad i = 1, 2, \ldots, n_{\mathrm{L}}$$

(Eq. 3.30-3.31, pag108, Gómez - Exposito)

```
Dt_P = zeros( nL + nG, 1 ); % Delta P
Dt_Q = zeros( nL, 1);       % Delta Q
```

$$f(x) = [\Delta P|\Delta Q]^{\mathrm{T}} = [\Delta P_1, \Delta P_2, \ldots, \Delta P_{n-1}|\Delta Q_1, \Delta Q_2, \ldots, \Delta Q_{n_{\mathrm{L}}}]^{\mathrm{T}}$$ dim= (2nL+nG)

```
Dt = [Dt_P;Dt_Q];  %Delta Vector (same as f(x) Vector)

%% Define Unkown Values (Voltage and angle in PQ node - Angle in PV node)
% #Buses with unknwon voltage magnitudes ('PQ' buses)  (Delta Q index)
x_v_n=N_data(strcmp(N_data.type,'PQ'),:).n;

% #Buses with unknwon voltage angles ('PQ'|'PV' buses) (Delta P index)
x_th_n=N_data(strcmp(N_data.type,'PV')|strcmp(N_data.type,'PQ'),:).n;


x_n = [x_th_n; x_v_n]; % #Buses with unknown Angles and unknown voltages

max_iter = 100; %Define Max iteration number

V = zeros(n, max_iter); % Matrix for storing node voltages per iter
Vm = zeros(n, max_iter);    % For storing node voltage magnitude per iter
th = zeros(n, max_iter);    % For storing node voltage angles per iter
V(:,1) = Vm_sp .* exp(1j .* th_sp); % Fill with initial Specified Voltages
Vm(:,1) = Vm_sp;                    % Fill with initial Specified Magnitud
th(:,1) = th_sp;                    % Fill with initial Specified Angle

err = 1.0;  % Define Error
k = 1;      % iteration counter
```

5) Inicia el método Newton Raphson

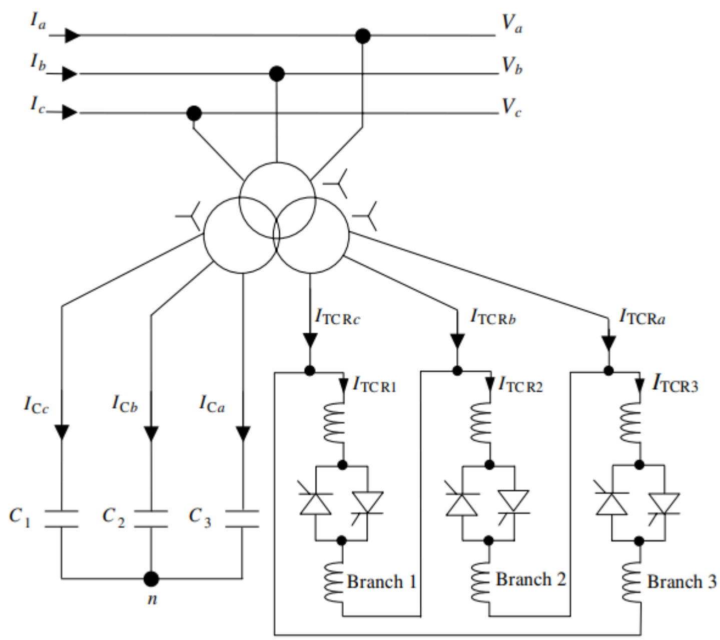
```
while (err > 1e-12 && k < max_iter)
```

```
% for cc = 1 : 3

    % ************************** Jacobian Terms Calculation.
    Vn = V( : , k ); % Phasors!!
    Vd = diag( Vn ); % Voltages in a diagonal matrix

    % Calculate active and reactive power per node
    Sn = Vd * conj( Ybus * V( : , k ) ); %  Sn=V(I)* | I=Y_bus·V | Sn=V·(Ybus·V)*
    Pn = real(Sn);  % Active Power calculated
    Qn = imag(Sn);  % Reactive Power calculated
```

Se tiene que para un SVC:



Para el delta de los TCR la susceptancia es:

$$B_{\mathrm{TCR}} = \frac{2(\pi - \alpha) + \sin 2\alpha}{\omega L \pi}$$ (Eq. 2.6, Acha)

Por ende en el SVC al tener en paralelo el banco de capacitores en Y con el delta de TCR:

$$\left.\begin{aligned} B_{\mathrm{SVC}} &= B_{\mathrm{C}} - B_{\mathrm{TCR}} = \frac{1}{X_C X_L}\left\{X_L - \frac{X_C}{\pi}[2(\pi - \alpha) + \sin 2\alpha]\right\}, \\ X_{\mathrm{L}} &= \omega L, \\ X_{\mathrm{C}} &= \frac{1}{\omega C}. \end{aligned}\right\}$$ (Eq. 2.20, Acha)

Para los reactivos del sistema se sabe que:

$$Q_{\mathrm{SVC}} = Q_k = -V_k^2 B_{\mathrm{SVC}}.$$ (Eq. 5.5, Acha)

es decir,

$$Q_k = \frac{-V_k^2}{X_C X_L}\left\{X_L - \frac{X_C}{\pi}\left[2(\pi - \alpha_{\mathrm{SVC}}) + \sin(2\alpha_{\mathrm{SVC}})\right]\right\}.$$ (Eq. 5.8, Acha)

```
%% Calculate injected bus powers by the SVC
for kk = 1 : size(SVC_data,1)
    FA=SVC_data{kk,"FA"}*pi/180; % Firing Angle [rads]
    SVC_data{kk,"B"} = (2*(pi-FA) + sin(2*FA))*SVC_data{kk,"Xc"}/pi; %Btcr
    SVC_data{kk,"B"} = (SVC_data{kk,"XL"} - SVC_data{kk,"B"})/(SVC_data{kk,"Xc"}*SVC_data{k

    Qn(SVC_data{kk,"SVCBus"})=Qn(SVC_data{kk,"SVCBus"})-(Vm(SVC_data{kk,"SVCBus"}))^2*SVC_d
end
```

Se obtienen las matrices H,L,N,M donde:

$$\text{For } i \neq j$$
$$H_{ij} = L_{ij} = V_i V_j (G_{ij}\sin\theta_{ij} - B_{ij}\cos\theta_{ij})$$
$$N_{ij} = -M_{ij} = V_i V_j (G_{ij}\cos\theta_{ij} + B_{ij}\sin\theta_{ij})$$

$$\text{For } i = j$$
$$H_{ii} = -Q_i - B_{ii}V_i^2 \quad L_{ii} = Q_i - B_{ii}V_i^2$$
$$N_{ii} = P_i + G_{ii}V_i^2 \quad M_{ii} = P_i - G_{ii}V_i^2$$

(Table 3.1, pag109, Gómez - Exposito)

```
% H Matrix.   H -> Dim: (nL+nG) X (nL+nG)

for mm = 1 : nL + nG        %Iter over rows H matrix
    for nn = 1 : nL + nG    %Iter over cols H matrix
        ii = x_th_n(mm);    % #node corresponding to row mm
        jj = x_th_n(nn);    % #node corresponding to column nn

        % From Prev Equations:
        if ii == jj
            H(mm,nn) = - Qn(ii) - imag( Ybus(ii,jj) ) .* abs( V(ii,k) ).^2;
        else
            H(mm,nn) = abs( V(ii,k) ) * abs( V(jj,k) ) .* ( ...
                real(Ybus(ii,jj)) * sin( th(ii,k) - th(jj,k) ) - ...
                imag(Ybus(ii,jj)) * cos( th(ii,k) - th(jj,k) ) );
        end
    end
end
```

```matlab
    % N Matrix. N -> Dim: (nL+nG) X (nL)
    for mm = 1 : nL + nG     %  Iter over rows N matrix
        for nn = 1 : nL      %  Iter over cols N matrix
            ii = x_th_n(mm); % #node corresponding to row mm
            jj = x_v_n(nn);  % #node corresponding to column nn

            % From Prev Equations:
            if ii == jj
                N(mm,nn) = Pn(ii) + real(Ybus(ii,jj)) .* abs( V(ii,k) ).^2;
            else
                N(mm,nn) = abs( V(ii,k) ) * abs( V(jj,k) ) .* ( ...
                    real(Ybus(ii,jj)) * cos( th(ii,k) - th(jj,k) ) + ...
                    imag(Ybus(ii,jj)) * sin( th(ii,k) - th(jj,k) ) );
            end
        end
    end

    % M Matrix. M -> Dim: (nL) X (nL+nG)
    for mm = 1 : nL             %  Iter over rows M matrix
        for nn = 1 : nL + nG    %  Iter over cols M matrix
            ii = x_v_n(mm);     % #node corresponding to row mm
            jj = x_th_n(nn);    % #node corresponding to column nn

            % From Prev Equations:
            if ii == jj
                M(mm,nn) = Pn(ii) - real(Ybus(ii,jj)) .* abs( V(ii,k) ).^2;
            else
                M(mm,nn) = -abs( V(ii,k) ) * abs( V(jj,k) ) .* ( ...
                    real(Ybus(ii,jj)) * cos( th(ii,k) - th(jj,k) ) + ...
                    imag(Ybus(ii,jj)) * sin( th(ii,k) - th(jj,k) ) );
            end
        end
    end

    % L Matrix. L -> Dim: (nL) X (nL)
    for mm = 1 : nL         %  Iter over rows L matrix
        for nn = 1 : nL     %  Iter over cols L matrix
            ii = x_v_n(mm); % #node corresponding to row mm
            jj = x_v_n(nn); % #node corresponding to column nn

            % From Prev Equations:
            if ii == jj
                L(mm,nn) = Qn(ii) - imag(Ybus(ii,jj)) .* abs( V(ii,k) ).^2;
            else
                L(mm,nn) = abs( V(ii,k) ) * abs( V(jj,k) ) .* ( ...
                    real(Ybus(ii,jj)) * sin( th(ii,k) - th(jj,k) ) - ...
                    imag(Ybus(ii,jj)) * cos( th(ii,k) - th(jj,k) ) );
            end
        end
    end
   % The jacobian matrix results in:
    J = [H, N;...
        M, L];
```

Se modifican los valores de J en el SVC.

$$\begin{bmatrix} \Delta P_k \\ \Delta Q_k \end{bmatrix}^{(i)} = \begin{bmatrix} 0 & 0 \\ 0 & \dfrac{2V_k^2}{\pi X_L}[\cos(2\alpha_{\mathrm{SVC}}) - 1] \end{bmatrix}^{(i)} \begin{bmatrix} \Delta \theta_k \\ \Delta \alpha_{\mathrm{SVC}} \end{bmatrix}^{(i)}.$$

(Eq. 5.9, Acha)

```
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
%% SVC Jacobian Update

for ii = 1 : size(SVC_data,1)

    DQ_svc_Index= find(N_data(strcmp(N_data.type,'PQ'),:).n==SVC_data{ii,"SVCBus"});% get P
    DP_svc_Index =find(x_th_n==SVC_data{ii,"SVCBus"});

    if (SVC_data{ii,'Status'} == 1)
        %Delete the voltage magnitud for the SVC bus
        J( : , nL+nG+DQ_svc_Index) = 0;  %Change DeltaV--->Delta alpha  (DeltaV=0 - SVC Cor


        FA=SVC_data{ii,"FA"}*pi/180;
%             JAC(2*SVCsend(ii)-1,2*SVCsend(ii)-1) = ...   % <- DeltaPk/Delta(Vangle)
%             JAC(2*SVCsend(ii)- 1,2*SVCsend(ii)-1)-VM(SVCsend(ii))^2*B(ii); %¿Error?

        J(DP_svc_Index,DP_svc_Index)=J(DP_svc_Index,DP_svc_Index)-Vm(SVC_data{ii,"SVCBus"})
        % [deltaQk] = [Qk]*[delta(Bsvc)/Bsvc]   --   k node= SVCnode
         J(nL+nG+DQ_svc_Index,nL+nG+DQ_svc_Index)=2*Vm(SVC_data{ii,"SVCBus"})^2*(cos(2*FA)-
        % [deltaQk]= J(nL+nG+PQ_Index,nL+nG+PQ_Index)
    end
end
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
```

Se calculan los términos residuales.

$$\Delta P_i = P_i^{\mathrm{sp}} - \overbrace{V_i \sum_{j=1}^{n} V_j (G_{ij}\cos\theta_{ij} + B_{ij}\sin\theta_{ij})}^{P_n} \quad i = 1, 2, \ldots, n-1$$

$$\Delta Q_i = Q_i^{\mathrm{sp}} - \overbrace{V_i \sum^{n} V_j (G_{ij}\sin\theta_{ij} - B_{ij}\cos\theta_{ij})}^{Q_n} \quad i = 1, 2, \ldots, n_{\mathrm{L}}$$

```
% *************************** Residual Terms Calculations

 % Delta P
 Dt_P=P_sp(x_th_n(1:nL+nG))-Pn(x_th_n(1:nL+nG));
 % Delta Q
```

```
    Dt_Q=Q_sp(x_v_n(1:nL))-Qn(x_v_n(1:nL));


    Dt = [ Dt_P ;...
           Dt_Q ];
```

Se actualiza la solución del sistema donde:

$$\begin{bmatrix} \theta_{k+1} \\ V_{k+1} \end{bmatrix} = \begin{bmatrix} \theta_{k+1} \\ V_{k+1} \end{bmatrix} + J^{-1} \cdot \begin{bmatrix} \Delta P_k \\ \Delta Q_k \end{bmatrix}$$

```
    % ************************** System Solution
    x = inv(J)*Dt; % Delta theta -> inv(J)*Dt
    x_th = x( 1 : nL + nG );                   % Adjust in unknown Angles
    x_v = x( nL + nG + 1 : 2 * nL + nG );     % Adjust in unknown Voltages

    Vm(:,k + 1) = Vm(:,k); % new magnitudes
    th(:,k + 1) = th(:,k); % new Angles

    th(x_th_n, k + 1) = x_th + th(x_th_n, k); % New angle    =  Adjust in unknown Angle    + prev
    Vm(x_v_n, k + 1)  = x_v.*Vm(x_v_n, k) + Vm(x_v_n, k);   % new voltage =  Adjust in unknown
```

$$\alpha_{\mathrm{SVC}}^{(i)} = \alpha_{\mathrm{SVC}}^{(i-1)} + \Delta\alpha_{\mathrm{SVC}}^{(i)}.$$

(Eq. 5.10, Acha)

```
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
%       SVC Update Adjust

    for ii = 1 : size(SVC_data,1)
        if (SVC_data{ii,'Status'}  == 1)

            DQ_svc_Index= find(N_data(strcmp(N_data.type,'PQ'),:).n==SVC_data{ii,"SVCBus"});% g

            % Adjust the Voltage Magnitud target
            Vm(SVC_data{ii,"SVCBus"},k + 1) =SVC_data{ii,"Tv"}; %Voltage at SVCnode -> Voltage

            % SVC Susceptance - Delta(Bsvc)
            value = x(nL+nG+DQ_svc_Index); % delta(alpha)


            %% If high or low delta(FA)
            if (value > 0.5236)
                value = 0.5236;
            elseif (value < -0.5236)
                value = -0.5236;
            end

            % Update FA
            SVC_data{ii,'FA'}=SVC_data{ii,'FA'}+ value*180/pi;
```

```
            % Positive Values of FA
            if (SVC_data{ii,'FA'}<0.0)
                SVC_data{ii,'FA'}=SVC_data{ii,'FA'}*(-1);
            end

        end


        % Check susceptance limits in SVC

        if (SVC_data{ii,"FA"} > SVC_data{ii,"FAmax"})
            SVC_data{ii,"FA"} = SVC_data{ii,"FAmax"};
        elseif (SVC_data{ii,"FA"} < SVC_data{ii,"FAmin"})
            SVC_data{ii,"FA"} = SVC_data{ii,"FAmin"};
        end
    end
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
```

```
    V(:,k + 1) = Vm(:,k + 1) .* exp( 1j .* th(:,k + 1) ); % Calculate phasors.

    %err = max( abs( V(:,k+1) - V(:,k) )  );
    err = max( abs( Dt )  ); % Calculate error

    k = k + 1;  % Add 1 to iterations
end
```

6) Cálculos finales:

Para el cálculo de la potencia aparente se tiene que:

$$S = \begin{bmatrix} V_1 & 0 & 0 & 0 \\ 0 & V_2 & 0 & 0 \\ 0 & 0 & \ddots & \vdots \\ 0 & 0 & \cdots & V_n \end{bmatrix} \cdot \left(Y_{\text{Bus}} \cdot \begin{bmatrix} V_1 \\ V_2 \\ \vdots \\ V_n \end{bmatrix} \right)^* = \begin{bmatrix} V_1 & 0 & 0 & 0 \\ 0 & V_2 & 0 & 0 \\ 0 & 0 & \ddots & \vdots \\ 0 & 0 & \cdots & V_n \end{bmatrix} \cdot \left(\begin{bmatrix} I_1 \\ I_2 \\ \vdots \\ I_n \end{bmatrix} \right)^* = \begin{bmatrix} V_1 & 0 & 0 & 0 \\ 0 & V_2 & 0 & 0 \\ 0 & 0 & \ddots & \vdots \\ 0 & 0 & \cdots & V_n \end{bmatrix} \cdot \left(\begin{bmatrix} I_1^* \\ I_2^* \\ \vdots \\ I_n^* \end{bmatrix} \right) = \begin{bmatrix} V_1 I_1^* \\ V_2 I_2^* \\ \vdots \\ V_n I_n^* \end{bmatrix} = \begin{bmatrix} S_1 \\ S_2 \\ \vdots \\ S_n \end{bmatrix}$$

```
% Complex power calculation for each node.
Vn = V( : , k );
Vd = diag( Vn );
Sn = Vd * conj( Ybus * V( : , k ) );
Pn = real(Sn);
Qn = imag(Sn);

SGn = Sn + (PL + 1j * QL);
SLn = SGn - Sn;

% Complex Power Flow Through Branches.
```

```
S_pf = zeros( 2*size(br_data, 1) , 5);

bc = 1;
for kk = 1: size(br_data, 1)
    ii = br_data.FromBus(kk);
    jj = br_data.ToBus(kk);
    z = br_data.R(kk) + 1j * br_data.X(kk);
    y = br_data.G(kk) + 1j * br_data.B(kk);
    Ybr=[1 / z + y / 2 ,    -1 / z;  ...     % Ybr (Two-Port Network)
            -1 / z     , 1 / z + y / 2];
    S_br=diag([Vn(ii),Vn(jj)])*conj(Ybr*[Vn(ii);Vn(jj)]);

    S_pf_br= [ii, jj, real(S_br(1)), imag(S_br(1)), abs(S_br(1));...% Apparent power from i to
              jj, ii, real(S_br(2)), imag(S_br(2)), abs(S_br(2))];  % Apparent power from j to

    S_pf(2*kk-1:2*kk,:)=S_pf_br;
end
```

7) Se presentan los resultados obtenidos

```
%% Results printing.

for i=1:1 % This "for" is used to display everything once.

    fprintf('     ******************************************** \n')
    fprintf('     **           Newton-Raphson Results        ** \n')
    fprintf('     ******************************************** \n\n')

    fprintf('-- Number of Iterarions: %d \n', k-1)
    fprintf('-- Error: %6.3e p.u.\n\n', err)

    VarNames = {'Node#', 'Type', 'V p.u.', ' ∠V(º)','PG p.u.','QG p.u.','PL p.u.','QL p.u.'};
    fprintf(1,'\t%s\t%s\t%s\t%s\t%s\t%s\t%s\t%s\n', VarNames{:})
    fprintf(1, '--------------------------------------------------------------------\n')

    for ii = 1 : n
        fprintf('   \t%d\t%s\t%6.3f\t%6.3f\t%6.3f\t%6.3f\t%6.3f\t%6.3f\t\n', ii, char(N_data{ii
            abs(Vn(ii)), angle(Vn(ii)).*180./pi, real(SGn(ii)), imag(SGn(ii)), real(SLn(ii)), i
    end
end
```

```
     ********************************************
     **          Newton-Raphson Results        **
     ********************************************
-- Number of Iterarions: 6
-- Error: 1.274e-14 p.u.
 Node# Type V p.u.  ∠V(º) PG p.u. QG p.u. PL p.u. QL p.u.
--------------------------------------------------------------------
     1 SL  1.060  0.000  1.311  0.853  0.000  0.000
     2 PV  1.000 -2.053  0.400 -0.771  0.200  0.100
     3 PQ  1.000 -4.838  0.000  0.205  0.450  0.150
     4 PQ  0.994 -5.107  0.000 -0.000  0.400  0.050
```

```
5 PQ  0.975 -5.797  0.000  0.000  0.600  0.100
```

```
array2table(S_pf,'VariableNames',{'FromBus','ToBus','P','Q','S'});
```

Table 5.1 Nodal voltages of modified network

	Network bus				
Nodal voltage	North	South	Lake	Main	Elm
Magnitude (p.u.)	1.06	1	1	0.994	0.975
Phase angle (deg)	0	−2.05	−4.83	−5.11	−5.80

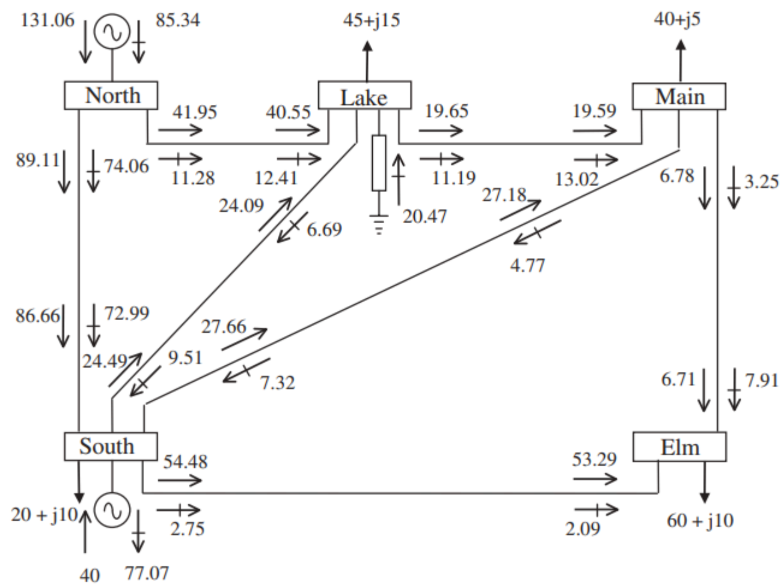


Figure 5.8 Power flow results in the five-bus network with one static VAR compensator

```
SVC_data
```

SVC_data = 1×9 table

...

	SVCBus	Xc	XL	FA	FAmax	FAmin	Tv	Status
1	3	1.0700	0.2880	132.5393	180	90	1	1

Table 5.2 Static *VAR* compensator state variables

	Susceptance model	Firing-angle model	
Iteration	B_{SVC} (p.u.)	B_{SVC} (p.u.)	α_{SVC} (deg)
1	0.1	0.4798	140
2	0.1679	0.1038	130.23
3	0.2047	0.2013	132.47
4	0.2047	0.2047	132.55
5	0.2047	0.2047	132.55

Referencias:

[1] Gomez - Exposito,A. Electrica Energy Systems, Analysis and operation. 2nd Edition. Boca Raton : Taylor & Francis, CRC Press, 2018.

[2] Acha,E. FACTS Modelling and Simulation in Power Networks. 1st Edition. Boca Raton : John Wiley & Sons Inc,2004