# CPSC 213

# Introduction to Computer Systems

Summer Session 2019, Term 2

Unit 2d - Aug 8 - NOT ON THE FINAL

Virtual Memory

### Overview

### Reading

text: 9.1-9.2, 9.3.2-9.3.4

### Learning Goals

- explain how multiple programs can reside in memory concurrently, but preserve the single-system illusion
- explain why one program can not access the memory of another program and why this is important
- give key benefit and key drawback of base-and-bounds translation
- give key benefit and key drawback of segmentation
- give key benefit of paging
- translate a virtual address to a physical address using any of these three schemes

# Multiple Concurrent Program Executions

#### The last lie

- we've been assuming that the computer executes one program at a time
- but, really multiple programs can execute simultaneously

### Each Program Execution is

- called a process
- multiple threads executing a program with state stored in memory
- compiler-assigned addresses for static things (e.g., code and globals)
- memory is viewable and changeable only by the program execution

#### Problem

- there is only one memory that they must all share
- compiler-assigned addresses overlap
  - its okay for multiple processes to share code (or anything that is read-only)
  - global variables must be private to each process, but they can be at the same address
- programs can access any address
  - must ensure that each process's memory is completely isolated

## Virtual Memory

#### Basic Idea

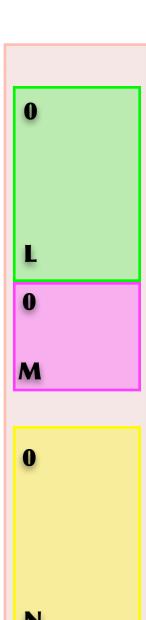
- each process is allocated a portion of physical memory
- allowed to use its own addresses for it
- disallowed from accessing any other part of memory

### Changes to Program Execution

- hardware translates address of every memory access
  - by memory management unit (MMU): part of CPU
- from process's virtual address to machine's real physical address

### Virtual Address Space

- one per process
- maps process's virtual addresses to machine's physical addresses
- mapping data structure
  - created and maintained by operating system
  - accessed directly by hardware to translate addresses on every memory access



# Implementing the MMU

- Lets think of this in the simulator ...
  - introduce a class to simulate the MMU hardware

- currentAddressSpace is a hardware register
- the address space performs virtual-to-physical address translation

# Implementing Address Translation

#### Goal

- translate any virtual address to a unique physical address (or none)
- fast and efficient hardware implementation
- Lets look at a couple of alternatives ...

### Base and Bounds

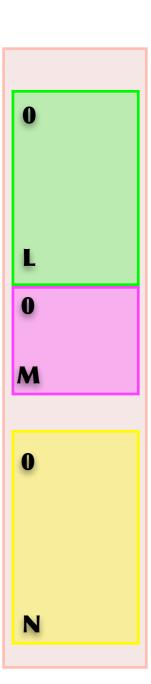
### An address space is

- a single, variable-size, non-expandable chunk of physical memory
- named by its base physical address and its length
- As a class in the simulator

```
class AddressSpace {
  int baseVA, basePA, bounds;

int translate (int va) {
  int offset = va - baseVA;
  if (offset < 0 || offset > bounds)
     throw new IllegalAddressException ();
  return basePA + offset;
  }
}
```

#### Problems



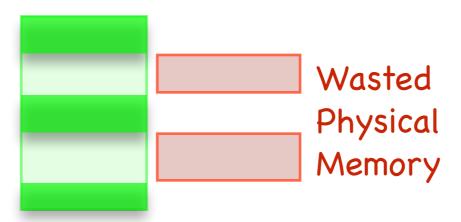
### But, Address Space Use May Be Sparse

#### Issue

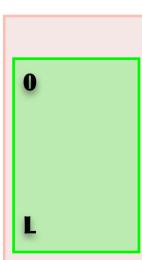
- the address space of a program execution is divided into regions
- for example: code, globals, heap, shared-libraries and stack
- there are large gaps of unused address space between these regions

#### Problem

- a single base-and-bounds mapping from virtual to physical addresses
- means that gaps in virtual address space will waste physical memory
- this is the Internal Fragmentation problem



Solution



# Segmentation

#### Address Space

a set of segments

#### Segment

- a single, variable-size, non-expandable chunk of physical memory
- named by its base virtual address, physical address and length

#### Implementation in Simulator

```
class AddressSpace {
   Segment segment[];

int translate (int va) {
   for (int i=0; i<segments.length; i++) {
     int offset = va - segment[i].baseVA;
     if (offset >= 0 && offset < segment[i].bounds) {
       pa = segment[i].basePA + offset;
       return pa;
     }
   }
   throw new IllegalAddressException (va);
}</pre>
```

Problem

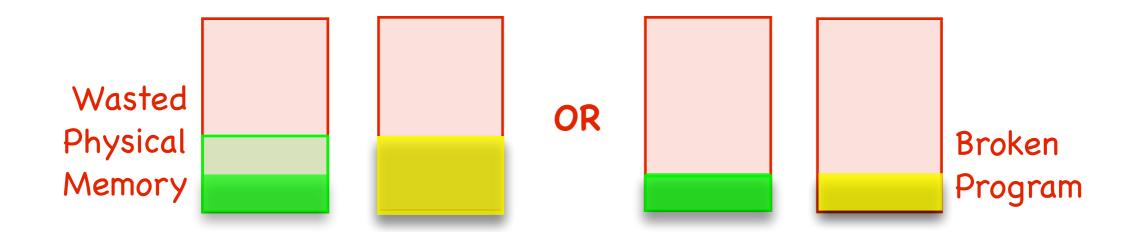
## Memory Use is Not Known Statically

#### Issue

- segments are not expandable; their size is fixed when segment is created
- some segments such as stack and heap change size dynamically

#### Problem

- segment size is chosen when segment is created
- too large and internal fragmentation wastes memory
- too small and stack or heap restricted



#### Solution

allow segments to expand?

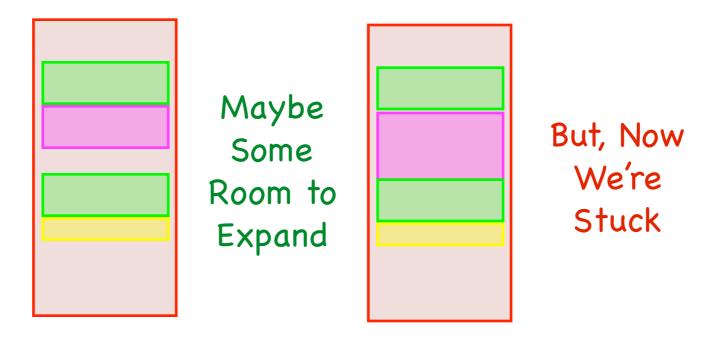
# There May Be No Room to Expand

#### Issue

- segments are contiguous chunks of physical memory
- a segment can only expand to fill space between it and the next segment

#### Problem

- there is no guarantee there will be room to expand a segment
- the available memory space is not where we want it (i.e., adjacent to segment)
- this is the External Fragmentation problem



Solution

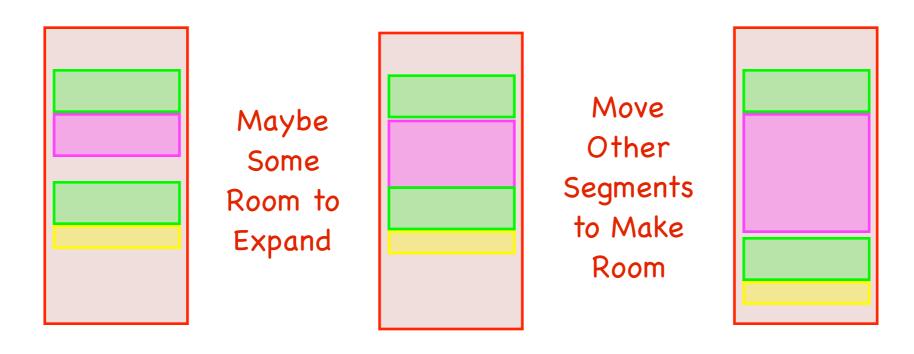
# Moving Segments is Expensive

#### Issue

- if there is space in memory to store expanding segment, but not where it is
- could move expanding segment or other segments to make room
- external fragmentation is resolved by moving things to consolidate free space

#### Problem

- moving is possible, but expensive
- to move a segment, all of its data must be copied
- segments are large and memory copying is expensive



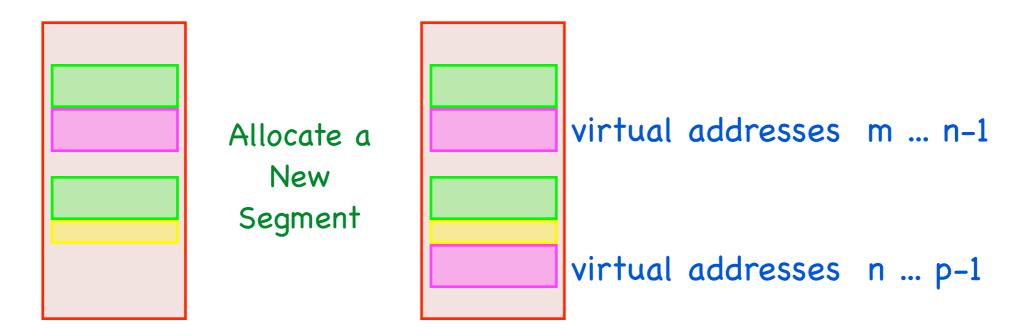
# Expand Segments by Adding Segments

#### What we know

- segments should be non-expandable
- size can not be effectively determined statically

#### Idea

- instead of expanding a segment
- make a new one that is adjacent virtually, but not physically

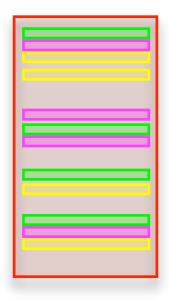


#### Problem

oh no! another problem! what is it? why does it occur?

# Eliminating External Fragmentation

- The problem with what we are doing is
  - allocating variable size segments leads to external fragmentation of memory
  - this is an inherent problem with variable-size allocation
- What about fixed sized allocation
  - could we make every segment the same size?
  - this eliminates external fragmentation
  - but, if we make segments too big, we'll get internal fragmentation
  - · so, they need to be fairly small and so we'll have lots of them



Problem

# Translation with Many Segments

What is wrong with this approach if there are many segments?

```
class AddressSpace {
   Segment segment[];

int translate (int va) {
   for (int i=0; i<segments.length; i++) {
      int offset = va - segment[i].baseVA;
      if (offset > 0 && offset < segment[i].bounds) {
       pa = segment[i].basePA + offset;
       return pa;
      }
   }
   throw new IllegalAddressException (va);
}</pre>
```

- Now what?
  - is there another way to locate the segment, when segments are fixed size?

# **Paging**

#### Key Idea

- Address Space is divided into set of fixed-size segments called pages
- every page of virtual address space has a number (VPN)
- virtual address (VA) is comprised of

```
- VPN = VA / PAGE_SIZE
```

- OFFSET = VA % PAGE\_SIZE

every page frame of physical memory has a number too (PFN) that yields physical address (PA)

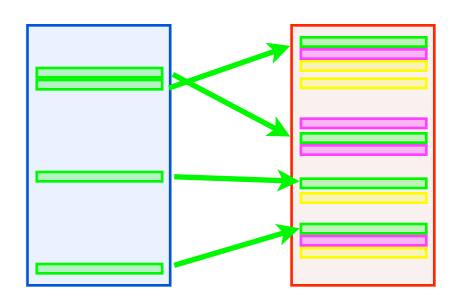
```
- PA = PFN * PAGE_SIZE + OFFSET
```

#### Page Table

- stored in memory
  - (address with physical addresses or operating-system's virtual addresses)
- one for every address space
- array of page-table entries, one for virtual page in address space
- indexed by VPN

#### Page Table Entry

- indicates whether virtual page is valid
- if valid stores the page's PFN
- also stores access permissions
  - is reading okay? is writing okay? is executing okay?
- stores a bit of other stuff too (e.g., access and dirty flags)



- New terminology
  - page a small, fixed-sized (4-KB) segment
  - page table virtual-to-physical translation table
  - pte page table entry
  - vpn virtual page number
  - pfn physical page frame number
  - offset byte offset of address from beginning of page
- Translation using a Page Table

```
class PageTableEntry {
  boolean isValid;
  boolean isReadAllowed;
  boolean isWriteAllowed;
  boolean isExecuteAllowed;
  int     pfn;
}
```

```
class AddressSpace {
   PageTableEntry pte[];

int translate (int va) {
   int vpn = va / PAGE_SIZE;
   int offset = va % PAGE_SIZE;
   if (pte[vpn].isValid)
     return pte[vpn].pfn * PAGE_SIZE + offset;
   else
     throw new IllegalAddressException (va);
}}
```

### The bit-shifty version

- assume that page size is  $4-KB = 4096 = 2^{12}$
- assume addresses are 32 bits
- then, vpn and pfn are 20 bits and offset is 12 bits
- pte is pfn plus valid bit, so 21 bits or so, say 4 bytes
- page table has 2<sup>20</sup> pte's and so is 4-MB in size

#### The simulator code

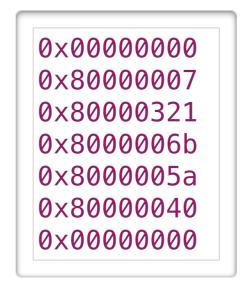
```
class PageTableEntry {
  boolean isValid;
  int pfn;
}
```

```
class AddressSpace {
   PageTableEntry pte[];

int translate (int va) {
   int vpn = va >>> 12;
   int offset = va & 0xfff;
   if (pte[vpn].isValid)
      return pte[vpn].pfn << 12 | offset;
   else
      throw new IllegalAddressException (va);
}}</pre>
```

## Question

Consider this page table



- Is 0x43a0 a valid virtual address and if so what is the corresponding physical address?
  - (A) Not valid
  - (B) 0x43a0
  - (C) 0x5a3a0
  - (D) 0x73a0
  - (E) 0x3a0

# Translation and Exceptions

### Virtual-to-Physical translation

- occurs on every memory reference
- handled by hardware (sometimes with some software)
- aided by a cache of recent translations
- but, in general requires reading page table entry from memory

### Page fault

- is an exception raised by the CPU
- when a virtual address is invalid
- an exception is just like an interrupt, but generated by CPU not IO device
- page fault handler runs each time a page fault occurs

### Handling a page fault

- extending the heap or stack, handler can just deliver a new zero-filled page
- what about the code, global variables, or existing parts of heap or stack?

# Demand Paging

#### Key Idea

- some application data is not in memory
- transfer from disk to memory, only when needed

#### Page Table

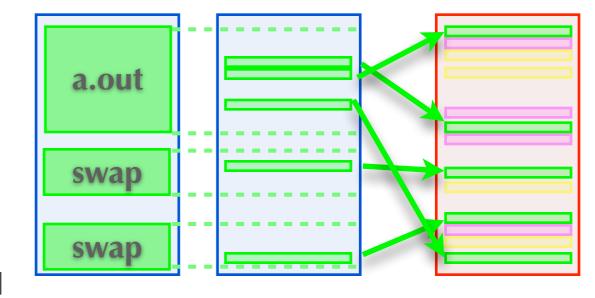
- only stores entries for pages that are in memory
- pages that are only on disk are marked invalid
- access to non-resident page- causes a page-fault interrupt

#### Memory Map

- a second data structure managed by the OS
- divides virtual address space into regions, each mapped to a file
- page-fault interrupt handler checks to see if faulted page is mapped
- if so, gets page from disk, update Page Table and restart faulted instruction

#### Page Replacement

- pages can now be removed from memory, transparent to program
- a replacement algorithm choose which pages should be resident and swaps out others



### Context Switch

#### A context switch is

- switching between threads from different processes
- each process has a private address space and thus its own page table

### Implementing a context switch

- change PTBR to point to new process's page table
- switch threads (save regs, switch stacks, restore regs)

#### Context Switch vs Thread Switch

- changing page tables can be much slower than just changing threads
- mainly because caching techniques used to make translation fast

# Summary

#### Process

- a program execution
- a private virtual address space and a set of threads
- private address space required for static address allocation and isolation

#### Virtual Address Space

- a mapping from virtual addresses to physical memory addresses
- programs use virtual addresses
- the MMU translates them to physical address used by the memory hardware

#### Paging

- a way to implement address space translation
- divide virtual address space into small, fixed sized virtual page frames
- page table stores base physical address of every virtual page frame
- page table is indexed by virtual page frame number
- some virtual page frames have no physical page mapping
- some of these get data on demand from disk

# Address Space Translation Tradeoffs

- Single, variable-size, non-expandable segment
  - internal fragmentation of segment due to sparse address use
- Multiple, variable-size, non-expandable segments
  - internal fragmentation of segments when size isn't know statically
  - external fragmentation of memory because segments are variable size
  - moving segments would resolve fragmentation, but moving is costly

### Expandable segments

- expansion must by physically contiguous, but there may not be room
- external fragmentation of memory requires moving segments to make room

### Multiple, fixed-size, non-expandable segments

- called pages
- need to be small to avoid internal fragmentation, so there are many of them
- since there are many, need indexed lookup instead of search