

## MIL

### CLASSICAL MULTI-DIMENSIONAL SCALING

Used in problem of following form:

- For set of data points  $\{x_i\}$  in  $\mathbb{R}^d$  (d.c.m) such that inter-point distances match the original data (d.c.m) as closely as possible
- MDS leads to producing a lower dimensional rep of the data such that distance between points  $i$  and  $j$  in the rep is as close to the dist betw  $x_i$  and  $x_j$  as possible for all  $i, j$
- Essentially produces a map of data
- To reproduce dist betw  $x_i$  and  $x_j$  as closely as possible, up to  $n-1$  dists may be required
- Dist of MDS is to produce an 'optimal' config of data in a space  $\neq$  original

### Scaling Method

- 2 approach to 'matching'  $\{d_{ij}\}$  in  $\mathbb{R}^d$   $\Rightarrow$  2 technique, both which aim to find set of points such that  $d_{ij} \approx d_{ij}^*$

Metric MDS - refers to when  $F$  is continuous and monotonic function, eg identity function or a first ascending dist into a distance function

Non-Metric MDS - only makes use of the rank order of the dist. As such, the function  $F$  need only map the distances monotonically, i.e.:

$$d_{ij} < d_{kl} \Rightarrow F(d_{ij}) \leq F(d_{kl})$$

Sum in  $F$  need only preserve rank order.

- Classical Metric Scaling: Metric least squares fitting, Kruskal non-metric Scaling
- Procrustes Analysis: technique for matching one configuration with another and for producing a measure of the match

### Classical Metric Scaling

- Produce a config of points from the dist via an objective reconstruction model
- Assume that the (continuous monotonic) function of dist is the identity function

Objective is to find the coordinate locates of each observation i.e.:

$$X = \begin{pmatrix} x_{11} & x_{12} & \dots & x_{1d} \\ \vdots & \vdots & \ddots & \vdots \\ x_{n1} & x_{n2} & \dots & x_{nd} \end{pmatrix}$$

- Here  $d$  is the dimension of the configuration (generally want  $d=2$  or  $3$ )
- Since sum a config of coordinate is invariant to rotations, translations and translations, we fix the centroid to be at the origin.

For ease of interpretation assume obs  $i$  is located at origin of the first obs  $j$  and  $k$ . Distances:  $d_{ij}$ ,  $d_{ik}$ ,  $d_{jk}$

$$-1/2 (d_{ij}^2 + d_{jk}^2 - d_{ik}^2) = x_j^T x_k$$

- Seeking vector  $x_j$

After shift  $\Rightarrow X = VA^{1/2}$   
 $V$  - matrix of e vectors  
 $A$  - diagonal matrix of e-values

### Dimensionality

- (could explain) Squared euclidean distance between two points  $x_i$  and  $x_j$  in an  $(n-1)$  dimensional space is  $\delta_{ij} = \sum_{k=1}^{n-1} \lambda_k (v_{ik} - v_{jk})^2$
- Here only "small" e-values contribute little to squared distance and so the  $d$  e-values associated with the  $d$  "large" e-values can be used to form the space representing the configuration of points.
- Aim is  $d=2$  or  $d=3$
- To choose appropriate  $d$  we could consider  $\sum_{k=1}^d \lambda_k / \sum_{k=1}^{n-1} \lambda_k$  which is a measure of the proportion of variance explained by using only  $d$  dimensions.

### Pseudo Code

1. Obtain dissimilarity  $\{ \delta_{ij} \}$
2. Form  $B$ , each element of which is given by  $b_{ijk} = -1/2 (\delta_{ik}^2 - \delta_{ij}^2 - \delta_{jk}^2)$  with  $i$  representing the coordinates of all observations.
3. Create matrix  $A$  from e-values  $\lambda_1, \dots, \lambda_{n-1}$  and matrix  $V$  from the associated e-vectors  $v_1, \dots, v_{n-1}$  of  $B$ .
4. Choose an appropriate # dimension  $d$  using suitable measure.
5. The coordinates of the  $n$  original points that are used to represent the  $n$  obs in  $d$ -dimensional space are given by:  

$$x_{ij} = \sum_{j=1}^d v_{ij} \lambda_j^{1/2}$$
 for  $i = 1 \dots n$  and  $j = 1 \dots d$

- Can construct a distance matrix for the points in the MDS plot.
- Hope that it should not be very different from the original dissimilarity matrix.

### STRESS

- Stress of a MDS defined to be  $\sum_{i=1}^n \sum_{j=1}^n (\delta_{ij} - d_{ij})^2$
- $\delta_{ij}$  is distance between  $i$  and  $j$  in plot and  $d_{ij}$  is dissimilarity measure

### Summarised Stress

- Summarised measure of stress takes into account the size of distances being approximated  

$$S_j = (d, \delta) = \frac{\sum_{i=1}^n \sum_{j=1}^n d_{ij}^{-1} (\delta_{ij} - d_{ij})^2}{\sum_{i=1}^n \sum_{j=1}^n d_{ij}^2}$$
- Now small dissimilarities have more weight in the loss function (can lose out providing motivation for them to be reproduced more accurately)



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## MULTIDIMENSIONAL SCALING

### Metric (or Squared) Scaling

- Find a config by matching  $\{d_{ij}\}$  to  $\{\delta_{ij}\}$  by minimizing a loss function, which possibly involved a continuous monotonic transform or be dimensionless.
- An iterative approach (numerical) (method of steepest descent) is used to minimize Sammon's loss function.
- Classical MDS is the situation in which a Euclidean dist. model is chosen and the goal is to minimize the stress value.
- Alternative metric MDS options specifically or designed to interpret a different distance metric, or to minimize an altered loss function such as Sammon's.

### Non Metric MDS

- Rank order of dist must be preserved by the transformation  $f$  of dist.

$$\text{Stress}^2_{\text{Kruskal}} = \frac{\sum_{i=1}^n \sum_{j \neq i} [f(d_{ij}) - \delta_{ij}]^2}{\sum_{i=1}^n \sum_{j \neq i} \delta_{ij}^2}$$

- Kruskal approach choose a d-dim config to minimize the stress. However, the input distances are allowed to be subject to a monotonic transform.
- Similar to Sammon method of 1967, it is used to minimize the stress (steepest descent method).
- D. Kruskal proposed experimenting with fixed value of d and plotting resulting stress against d and choosing d value where a 'statistical elbow' appears in plot (stress should always decrease as dimensionality increases).

### Procrustes analysis

- Matches one MDS config with another by dilation, rotation, reflection and translation.
  - See 2 mds method have been applied to sets of n points, resulting in coordinate matrices X and Y respectively.
  - There is a one to one mapping from the points in X to the points in Y.
  - The sum of squared distances between corresponding points in the two config is
- $$1) R^2 = \sum_{i=1}^n \sum_{j=1}^d (y_{ij} - x_{ij})^2$$
- To match config, one of them is kept constant (the reference config) while the other is transformed.
  - Assume Y is ref config, while X is to be transformed to achieve best match with Y.
  - The new coordinates of points in X space will be  $x'_i = pAx_i + b$
  - $p$  = a dilation matrix
  - $A$  = orthogonal matrix (carry a rotation and/or reflection)
  - $b$  = a translation factor.

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## MULTI DIMENSIONAL SCALING

MDS used in problems of following form:

→ For a set of dissimilarities between every pair of  $n$  items, find a representation of the items in  $\mathbb{R}^d$  ( $d < n$ ) such that the inter-point distances match the original dissimilarities as closely as possible.

Here MDS seeks to produce a lower dimensional representation of the data such that distances between points  $i$  and  $j$  in the representation,  $\delta_{ij}$ , are close to the dissimilarities between these points,  $d_{ij}$  for all  $i, j$ .

MDS essentially produces a map of the observations.

To reproduce the dissimilarities between  $n$  observations as closely as possible, up to  $(n-1)$  dimensions may be required. Objective of MDS is to produce an "optimal" configuration of the observations in a smaller number of dimensions.

- Example, road distances in Europe

→ Objectives of MDS is to take this set of dissimilarities and return a set of two dimensional points, such that the distances between the points are approximately equal to the dissimilarities.

### MDS Methods

- Different approaches to idea of matching  $d_{ij}$  and  $\delta_{ij}$ , 2 different techniques which aim to find a representable set of points such that  $\delta_{ij} = f(d_{ij})$ .

- METRIC MDS refers to when  $f$  is a continuous and monotonic function, e.g. the identity function or a function converting dissimilarities into a distance like form.

- NON-METRIC MDS only makes use of the rank order of the dissimilarities. As such the transformation  $f$  need only obey the monotonicity constraint:

$$d_{ij} < d_{kl} \Rightarrow f(d_{ij}) \leq f(d_{kl})$$

Such an  $f$  need only preserve rank order.



Metric Method - Classical metric scaling and metric least squares scaling.

→ Kruskal non metric scaling

- Not always true that different MDS techniques will produce the same results from data set, so we will consider PROCRUSTES analysis which is a technique for matching one configuration with another and for producing a measure of error.

Classical Metric Scaling.

- Produce a configuration of points from the dissimilarity via an algebraic reconstruction method.
- Assume that the (continuous monotonic) function of dissimilarity is the identity function. The objective is to find the coordinate location of each observation, i.e.

$$X = \begin{pmatrix} x_{11} & x_{12} & \dots & x_{1d} \\ x_{21} & x_{22} & \dots & x_{2d} \\ \vdots & \vdots & \ddots & \vdots \\ x_{n1} & x_{n2} & \dots & x_{nd} \end{pmatrix}$$

- Here  $d$  is the dimension of the configuration (generally want  $d=2$  or  $3$ ).
- Since such a configuration of coordinates is invariant to rotations, reflections, and translations, we fix the centroid to be at the origin.
- Assume observation  $i$  is located at the origin and that there are two further observations  $J$  and  $K$ . Distances between them are given by  $d_{ij}$ ,  $d_{ik}$ , and  $d_{jk}$ .

$$d_{jk}^2 = d_{ij}^2 + d_{ik}^2 - 2d_{ij}d_{ik}\cos(\theta_{jik})$$

$$\Rightarrow -1/2 (d_{jk}^2 - d_{ij}^2 - d_{ik}^2) = d_{ij}d_{ik}\cos(\theta_{jik})$$

$\theta_{jik}$  is angle between  $d_{ij}$  and  $d_{ik}$

Since  $\|x_j\| = d_{ij}$  and  $\|x_k\| = d_{ik}$  by definition because:

$$x_j^T x_k = \|x_j\| \|x_k\| \cos(\theta_{jik})$$

Then:

$$-1/2 (d_{jk}^2 - d_{ij}^2 - d_{ik}^2) = x_j^T x_k$$

- Vectors  $x_j$  are what we are seeking

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## MULTI DIMENSIONAL SCALING.

How do we obtain the  $X_T$ 's?

- Let  $B$  denote a matrix with elements  $b_{jk} = -1/2 (d_{jk}^2 - d_{jj}^2 - d_{kk}^2)$
- We know that  $B = XX^T$
- As  $B$  is symmetric it can be decomposed into  $B = V\Lambda V^T$   
with  $V$  a matrix of eigenvectors and  $\Lambda$  a diagonal matrix of eigen values.
- Hence  $X = V\Lambda^{1/2}$

## Dimensionality

- Important issue with any MDS technique is number of dimensions required to represent the configuration of points
- Could express the squared euclidean distance between  $x_i$  and  $x_j$  in an  $(n-1)$  dimensional space as  $d_{ij}^2 = \sum_{k=1}^{n-1} (v_{ik} - v_{jk})^2$
- Hence only "small" eigenvalues contribute little to the squared distance and so the  $d$  eigenvalues associated with the  $d$  "large" eigenvalues can be used to form the space representing the configuration of points
- Aim of MDS is to represent the observations graphically with  $d=2$  or  $3$  dimensions
- To choose  $d$  we consider something like  $\sum_{k=1}^d \lambda_k / \sum_{k=1}^{n-1} \lambda_k$  which is a measure of the proportion of variance explained by using only  $d$  dimensions

## Pseudocode:

1. Obtain the dissimilarities  $\{d_{ij}\}$
2. Form  $B$ , each element of which is given by  $b_{jk} = -1/2 (d_{jk}^2 - d_{jj}^2 - d_{kk}^2)$  with  $i$  representing the centroid/origin of all the observations
3. Create matrix  $\Lambda$  from the eigenvalues  $\lambda_1, \dots, \lambda_{n-1}$  and the matrix  $V$  from the associated eigenvectors  $v_1, \dots, v_{n-1}$  of  $B$
4. Choose an appropriate number of dimensions  $d$  using a suitable measure
5. The coordinates of the  $n$  required points that are used to represent the  $n$  observations in  $d$ -dimensional space are given by  
$$x_{ij} = \lambda_j^{1/2} v_{ij}$$
  
for  $i$  in  $1 \dots n$  and  $j = 1 \dots d$



- Produced a graph, similar points placed close to each other
- rotation does not affect result

How well did it work?

- Construct a distance matrix from the points in the MDS plot
- Hope that it's not very different from original dissimilarity matrix

The STRESS of a MDS is defined to be  $\sum_{i < j} \sum_{k < l} (\delta_{ij} - d_{kl})^2$   
 $\delta_{ij}$  is dissimilarity between  $i$  and  $j$  in the plot,  $d_{kl}$  is the dissimilarity between  $k$  and  $l$  in the dissimilarity matrix.

Sammon Stress

- Sammon Stress takes into account the size of the distances being approximated

$$\text{Sammon Stress} = (d, \delta) = \frac{\sum_{i=1}^n \sum_{j=1, j \neq i}^n d_{ij}^{-1} (d_{ij} - \delta_{ij})^2}{\sum_{i=1}^n \sum_{j=1, j \neq i}^n d_{ij}}$$

- Now small dissimilarities have more weight in the loss function than large ones providing motivation for them to be reproduced more accurately

Metric Least Squares Scaling

- MDS finds a configuration by matching  $\{\delta_{ij}\}$  to  $\{d_{ij}\}$  by minimizing a loss function  $S$ , which possibly involves a monotonic transform of the dissimilarities
- An iterative numerical approach (method of steepest descent) is taken to minimize Sammon's loss function
- Classical MDS is the situation in which a Euclidean distance model is chosen and the objective is to minimize the Stress value
- Alternative metric MDS options specifically are designed to incorporate a different distance metric, or to minimize an altered loss function such as Sammon Stress

## MULTI DIMENSIONAL SCALING

## Non metric Multidimensional Scaling

- In non metric, not only the rank order of the dissimilarity must be preserved by the transformation of  $f$  of dissimilarity
- Stress? Kruskal =  $\frac{\sum_{i=1}^n \sum_{j \neq i}^n [f(d_{ij}) - \delta_{ij}]^2}{\sum_{i=1}^n \sum_{j \neq i}^n \delta_{ij}^2}$
- Kruskal's approach: choose a  $d$ -dimensional configuration to minimize the 'stress'
- The input dissimilarities are allowed to be subject to a monotonic transformation
- Similar to Sammon's method, an iterative algorithm used to minimize the stress
- For dimension  $d$ , Kruskal proposed experimenting with several values of  $d$  and plotting the resulting stress against  $d$  and choosing the  $d$  value where a "statistical elbow" appeared in the plot.  
(Stress should always decrease as dimensionality increases)

## Procrustes Analysis

- Procrustes Analysis involves one  $m \times n$  configuration with another by dilation, rotation, reflection and translation
- Say two  $m \times n$  methods have been applied to a set of  $n$  points, resulting in coordinate matrices  $X$  and  $Y$  respectively
- There is a one to one mapping from the  $i$ th point in  $X$  to  $i$ th point in  $Y$
- The sum of squared distance between corresponding points in the configuration is  
$$R^2 = \sum_{i=1}^n \sum_{j=1}^n (y_{ij} - x_{ij})^2$$
- To match the configurations, one Df from it kept constant (the reference configuration), whilst the other is transformed
- Assume that  $Y$  is the reference configuration, whilst  $X$  is to be transformed to achieve the best match with  $Y$
- The new coordinates of the points in the  $X$  space will be  
$$X_i' = p A^T X_i + b$$
- $p$  = a dilation matrix
- $A$  = orthogonal matrix causing a rotation (and/or reflection)
- $b$  = a translation factor



New sum of squared distances is then:

$$R^2 = \sum_{i=1}^n (y_i - pA^T x_i - b)^2$$

- By minimizing this we can estimate optimal  $p, A$  and  $b$
- The measure of match between the two configurations is the minimized value of  $R^2$
- known as procrustes Sum of Squares
- can also examine plots of pairwise residuals between the final transformed configuration and the "reference" configuration

Pseudocode:

1. Translate the configuration to the origin by subtracting the average vector for each configuration from its coordinates
2. Compute optimal values for  $p, A$  and  $b$  and apply it to non-reference configuration
3. Calculate the procrustes Sum of Squares (smaller values indicate likeness)

Standardized pull data logs

(connection) with PCA:

- PCA is performed by eigen decomposition of the data covariance matrix to provide new variables that are found from linear combination of the original variables. The new variables are uncorrelated and account for maximum variance in the original variable
- Classical MDS perform eigen decomposition of the data dissimilarity matrix to find a low dimensional configuration of the entities such that distances are preserved as closely as possible in a least square sense
- When Euclidean distance is used within classical MDS, the resulting low dimensional co-ordinates are the same as the principle co-ordinates that would be obtained from PCA

New Sum of Squared distances between points is the

$$R^2 = \sum_{i=1}^N (y_i - pAx_i - b)^T (y_i - pAx_i - b)$$

By minimizing this we can obtain the optimal  $p$ ,  $A$  and  $b$

The measure of the match between the 2 config is the minimized value of  $R^2$   
known as the Procrustes Sum of Squared

- Can also examine plots of pointwise residuals between the final transformed config and the 'ref' config

### Procrustes Code

1. Translate the config to the origin by subtracting the average vector for each config from its coordinate vector
2. Compute optimal values for  $p$ ,  $A$  and  $b$  and apply to non-ref config
3. Calculate Procrustes Sum of Squared - smaller value indicates 'better'

### Connection with PCA

- PCA performed by eigen decomposition of the data cov matrix to produce new variables that are formed from linear combos of the original variables. The new variables are uncorrelated and account for max var in the original variables.
- Classical MDS performs e-decomp of the data distance matrix to find a lower dimensional config of the entities such that the distance of points is as close as possible to a least squares sense.
- When euclidean dist is used within Classical MDS, the resulting low dimensional co-ordinates are the same as the principal co-ordinates that would be obtained from PCA.