

1.1 ARIMA (0,0,0)(0,2,0)₄

we have a seasonal ARIMA with $S=4$
moving average that with $Q=1$

usual assumptions regarding error terms:

$$E[\varepsilon_t] = 0 \quad E[\varepsilon_t^2] = \sigma^2 \quad \text{and} \quad E[\varepsilon_t, \varepsilon_{t+h}] = 0 \quad h \neq 0$$

ACF Shape: will be zero for lags which are not multiples of 4
- at lag 0 value will be 1
- for multiples of 4 (4, 8, 12, ...) will have values which create a shape similar to an exponential decrease or damped sine wave shape

proof: rewrite eqⁿ

$$\begin{aligned} y_t &= c + \alpha \varepsilon_{t-4} + \varepsilon_t & \varepsilon_{t-4} &= y_{t-4} - c - \alpha \varepsilon_{t-8} \quad \Rightarrow \text{Sub in} \\ &= c + \alpha(y_{t-4} - c - \alpha \varepsilon_{t-8}) + \varepsilon_t & & \Rightarrow \text{multiply out} \\ &= c + \alpha y_{t-4} - \alpha c - \alpha^2 \varepsilon_{t-8} + \varepsilon_t & \varepsilon_{t-8} &= y_{t-8} - c - \alpha \varepsilon_{t-12} \\ &= (1 - \alpha + \alpha^2)c + \alpha y_{t-4} - \alpha^2 y_{t-8} + \alpha^3 \varepsilon_{t-12} + \varepsilon_t \\ &= (1 - \alpha + \alpha^2 - \alpha^3 + \dots)c + \alpha y_{t-4} - \alpha^2 y_{t-8} + \alpha^3 y_{t-12} - \alpha^4 \varepsilon_{t-12} + \varepsilon_t \end{aligned}$$

We can keep expanding the eqⁿ in similar manner
 α will be the ACF value at lag 4, $-\alpha^2$ is value at lag 8 and
 α^3 is value at lag 12 and so on
Since $|\alpha| < 1$ this creates an exponential decrease or a
damped sine wave if α is negative

i. Expectation $E[y_t] = E[c + \alpha \varepsilon_{t-4} + \varepsilon_t]$

$$\begin{aligned} \text{expectation is a linear operator} &= E[c] + E[\alpha \varepsilon_{t-4}] + E[\varepsilon_t] \\ &= c + \alpha E[\varepsilon_{t-4}] + E[\varepsilon_t] = c \end{aligned}$$

$$E[y_t] = c$$

ii. Variance $V[y_t] = E[(y_t - E[y_t])^2]$

$$\begin{aligned} &= E[(c + \alpha \varepsilon_{t-4} + \varepsilon_t - c)^2] \\ &= E[\alpha^2 \varepsilon_{t-4}^2 + \varepsilon_t^2 + 2\alpha \varepsilon_{t-4} \varepsilon_t] \\ &= \alpha^2 E[\varepsilon_{t-4}^2] + E[\varepsilon_t^2] + 2\alpha E[\varepsilon_{t-4} \varepsilon_t] \\ &= \alpha^2 \sigma^2 + \sigma^2 + 0 = (1 + \alpha^2) \sigma^2 = \text{Var}[y_t] \end{aligned}$$

Q1

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i Biii $\text{Cov}[y_t, y_{t-k}] = E[(y_t - E[y_t])(y_{t-k} - E[y_{t-k}])]$

$$E[y_t] = c \quad E[y_{t-k}] \text{ also } = c$$

$$= E[(c + \alpha \varepsilon_{t-4} + \varepsilon_t - c)(c + \alpha \varepsilon_{t-k-4} + \varepsilon_{t-k} - c)]$$

$$= E[(\alpha \varepsilon_{t-4} + \varepsilon_t)(\alpha \varepsilon_{t-k-4} + \varepsilon_{t-k})]$$

$$= E[\alpha^2 \varepsilon_{t-4} \varepsilon_{t-k-4} + \alpha \varepsilon_t \varepsilon_{t-k-4} + \alpha \varepsilon_{t-4} \varepsilon_{t-k} + \varepsilon_t \varepsilon_{t-k}]$$

$$= \alpha^2 E[\varepsilon_{t-4} \varepsilon_{t-k-4}] + \alpha E[\varepsilon_t \varepsilon_{t-k-4}] + \alpha E[\varepsilon_{t-4} \varepsilon_{t-k}] + E[\varepsilon_t \varepsilon_{t-k}]$$

When $k=0$ $\text{Cov} = \alpha^2 E[\varepsilon_{t-4} \varepsilon_t] + \alpha E[\varepsilon_t \varepsilon_{t-4}] + \alpha E[\varepsilon_{t-4} \varepsilon_t] + E[\varepsilon_t \varepsilon_t]$
 $= (1 + \alpha^2) \sigma^2$

When $k=-4$ $\text{Cov} = \alpha^2 E[\varepsilon_{t-4} \varepsilon_t] + \alpha E[\varepsilon_t \varepsilon_t] + \alpha E[\varepsilon_{t-4} \varepsilon_t] + E[\varepsilon_t \varepsilon_{t-4}]$
 $= \alpha \sigma^2$

At every other value $\text{Cov} = 0$

i Biv $\text{Corr}[y_t, y_{t-k}] = \frac{\text{Cov}[y_t, y_{t-k}]}{\sqrt{\text{Var}[y_t] \text{Var}[y_{t-k}]}}$

When $k=0$ $\Rightarrow \frac{(1 + \alpha^2) \sigma^2}{\sqrt{(1 + \alpha^2) \sigma^2 (1 + \alpha^2) \sigma^2}} = 1$

Note: $\text{Var}[y_t] = \text{Var}[y_{t-k}]$

When $k=-4$ $\frac{\alpha \sigma^2}{\sqrt{(1 + \alpha^2) \sigma^2 (1 + \alpha^2) \sigma^2}} = \frac{\alpha \sigma^2}{(1 + \alpha^2) \sigma^2} = \frac{\alpha}{1 + \alpha^2} \quad k=-4$

Otherwise $\frac{0}{\sqrt{(1 + \alpha^2) \sigma^2 (1 + \alpha^2) \sigma^2}} = 0$

ACF Shape: will show a spike at lag $k=-4$

Q1

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i. Model $y_{n+k} = c + \alpha y_{n+k-4} + \epsilon_{n+k}$

The term ϵ_{n+k-4} can be expressed as a weighted sum of the past observations y_{n+k-4} , y_{n+k-8} , y_{n+k-12} etc as shown in 1A circle. All those observations are available to compute for $k \in \{1, 2, 3, 4\}$ for ϵ_{n+k} .

Forecast is then: $\hat{y}_{n+k} = c + \alpha \epsilon_{n+k-4}$

95% CI \Rightarrow forecast $\pm 2\sigma$

$= \hat{y}_{n+k} \pm 2\sigma = 95\% \text{ CI}$

ii. When $k > 4$ the expectation is utilized of the forecast \hat{y}_{n+k}

$E[y_t] = c$ along with the error term

Error term will be $\alpha \epsilon_{n+k-4} + \epsilon_{n+k}$ which has a variance associated with it of $(1+\alpha^2)\sigma^2$

So the 95% CI will be $c \pm 2\sqrt{(1+\alpha^2)}\sigma^2$

iii. Forecast from $k = 9 \dots 12$ will follow the same procedure as forecasts from $k = 4 \dots 8$

Thus our 95% CI for $k = 9 \dots 12$ will be

$c \pm 2\sqrt{(1+\alpha^2)}\sigma^2$

Q2

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2A. $ARIMA(1,0,3)(1,2,0)_5$

$$(1-\phi_1 B)(1-\beta_1 B^5)(1-B^5)^2 = c + (1-w_1 B - w_2 B^2 - w_3 B^3)(1)(\epsilon_t) = ARIMA(1,4,3)(1,2,0)_5$$

This is the $ARIMA(1,0,3)(1,2,0)_5$ model with backshift operator

B. Without backshift operator:

$$\text{Expand } (1-\phi_1 B)(1-\beta_1 B^5)(1-B^5)^2$$

$$= (1-\phi_1 B^5 - \phi_1 B + \phi_1 \beta_1 B^6)(1-2B^5+B^{10})$$

$$1-\beta_1 B^5 - \phi_1 B + \phi_1 \beta_1 B^6 - 2B^5 + 2\beta_1 B^{10} + 2\phi_1 \beta_1 B^6 - 2\phi_1 \beta_1 B^{11} + B^{10} - \beta_1 B^{15} - \phi_1 B^{11} + \phi_1 \beta_1 B^{16}$$

Applied to y_t LHS:

$$1-\phi_1 y_t - \beta_1 y_{t-5} + \phi_1 \beta_1 y_{t-6} - 2y_{t-5} + 2\phi_1 y_{t-6} + 2\beta_1 y_{t-10} - 2\phi_1 \beta_1 y_{t-11} + y_{t-10} - \phi_1 y_{t-11} - \beta_1 y_{t-15} + \phi_1 \beta_1 y_{t-16}$$

is Left hand side of $ARIMA(1,4,3)(1,2,0)_5$ model

$$\text{Right hand side: } c + (\epsilon_t - w_1 \epsilon_t - w_2 \epsilon_t^2 - w_3 \epsilon_t^3)$$

$$\Rightarrow c + \epsilon_t - w_1 \epsilon_{t-1} - w_2 \epsilon_{t-2} - w_3 \epsilon_{t-3}$$

= RHS without backshift operator

1a $y_t = c + \alpha \varepsilon_{t-4} + \varepsilon_t$

PACF \Rightarrow The equation can be rewritten

$$\varepsilon_{t-4} = (y_{t-4} - c - \alpha \varepsilon_{t-8})$$

$$y_t = c + y_{t-4} - c + \alpha$$

$$y_t = (c + \alpha (y_{t-4} - c - \alpha \varepsilon_{t-8})) + \varepsilon_t$$

$$= c + \alpha y_{t-4} - \alpha c - \alpha^2 \varepsilon_{t-8} + \varepsilon_t$$

This can be extended further

$$\varepsilon_{t-8} = y_{t-8} - c - \alpha \varepsilon_{t-12}$$

$$\Rightarrow = c + \alpha y_{t-4} - \alpha c + \alpha^2 (y_{t-8} - c - \alpha \varepsilon_{t-12})$$

can keep expanding

PACF is zero for lags that are not multiple of 4.
At lag 0, PACF is 1, at 4, 8, 12 will have an exponential decay
or damped sine wave shape

2 $E[y_t] = E[c + \alpha \varepsilon_{t-4} + \varepsilon_t]$

Expectation of a linear operator: Expectation of linear sum is the linear sum of expectations

$$E[c] + E[\alpha \varepsilon_{t-4}] + E[\varepsilon_t]$$

c is a constant so $E[c] = c$

$\alpha E[\varepsilon_{t-4}]$ α is a constant

$E[\varepsilon_{t-4}] = 0$ by our hypothesis that error is zero
 $E[\varepsilon_t] = 0$ also

So $E[y_t] = c$

$$B) Var = \frac{E[E^2] - E[E]^2}{E[X^2] - E[X]^2}$$

$$y_t^2 = (c + \alpha \varepsilon_{t-4} + \varepsilon_t)^2$$

$$E[(y_t - E[y_t])^2]$$

$$E[(c + \alpha \varepsilon_{t-4} + \varepsilon_t - c)^2]$$

$$E[\alpha^2 \varepsilon_{t-4}^2 + 2\alpha \varepsilon_t \varepsilon_{t-4} + \varepsilon_t^2]$$

$$\alpha^2 E[\varepsilon_{t-4}^2] + 2\alpha E[\varepsilon_t \varepsilon_{t-4}] + E[\varepsilon_t^2]$$

$$= \alpha^2 \sigma^2 + 0 + \sigma^2$$

$$+ (1+\alpha) \sigma^2$$

$$C. Covariance [y_t, y_{t-k}] \neq 0$$

$$= E[(y_t - E[y_t])(y_{t-k} - E[y_{t-k}])]$$

$$E[(c + \alpha \varepsilon_{t-4} + \varepsilon_t - c)(c + \alpha \varepsilon_{t-k-4} + \varepsilon_{t-k})]$$

$$E[\alpha \varepsilon_{t-4} \varepsilon_{t-k-4} + \alpha \varepsilon_{t-4} \varepsilon_{t-k} + \varepsilon_t \varepsilon_{t-k-4} + \varepsilon_t \varepsilon_{t-k}]$$

$$E[\alpha^2 \varepsilon_{t-4} \varepsilon_{t-k-4} + \alpha \varepsilon_{t-4} \varepsilon_{t-k} + \alpha \varepsilon_t \varepsilon_{t-k-4} + \varepsilon_t \varepsilon_{t-k}]$$

$$\alpha^2 E[\varepsilon_{t-4} \varepsilon_{t-k-4}] + \alpha E[\varepsilon_{t-4} \varepsilon_{t-k}] + \alpha E[\varepsilon_t \varepsilon_{t-k-4}] + E[\varepsilon_t \varepsilon_{t-k}]$$

When $k=0$

$$\Rightarrow \alpha^2 E[\varepsilon_{t-4} \varepsilon_{t-4}] + \alpha E[\varepsilon_{t-4} \varepsilon_t] + \alpha E[\varepsilon_t \varepsilon_{t-4}] + E[\varepsilon_t \varepsilon_t]$$

$$k=0 \quad \alpha^2 \sigma^2 + (1+\alpha) \sigma^2 = \sigma^2$$

$$\text{When } k=4 \Rightarrow \alpha E[\varepsilon_{t-4} \varepsilon_{t-8}] + \alpha E[\varepsilon_{t-4} \varepsilon_{t-4}] + \alpha E[\varepsilon_t \varepsilon_{t-8}] + E[\varepsilon_t \varepsilon_{t-4}]$$

0 otherwise \Rightarrow error after figure will be 0

$$\text{Cov}(y_t, y_{t-k})$$

$$E[(y_t - E(y_t))(y_{t-k} - E(y_{t-k}))]$$

$$E(y_t) = c \quad E(y_{t-k}) = c$$

$$E[(\alpha \varepsilon_{t-1} + \varepsilon_t)(\alpha \varepsilon_{t-k-1} + \varepsilon_{t-k})]$$

$$E[\alpha^2 \varepsilon_{t-1} \varepsilon_{t-k-1} + \alpha \varepsilon_{t-1} \varepsilon_{t-k} + \alpha \varepsilon_t \varepsilon_{t-k-1} + \varepsilon_t \varepsilon_{t-k}]$$

$$= \alpha^2 E[\varepsilon_{t-1} \varepsilon_{t-k-1}] + \alpha E[\varepsilon_{t-1} \varepsilon_{t-k}] + \alpha E[\varepsilon_t \varepsilon_{t-k-1}] + E[\varepsilon_t \varepsilon_{t-k}]$$

$$k=0 \quad (1 + \alpha^2) \sigma^2$$

$$\text{at } k=-1 \quad \alpha \sigma^2$$

everywhere else it is 0.

Correction:

$$\frac{\text{Cov}}{\sqrt{\text{Var}(y_t) \text{Var}(y_{t-k})}}$$

$$\text{at } k=0. \quad \frac{(1 + \alpha^2) \sigma^2}{\sqrt{(1 + \alpha^2) \sigma^2}}$$

Correlation of y_t, y_{t-k}

$$= \frac{\text{Cov}(y_t, y_{t-k})}{\sqrt{\text{Var}(y_t) \text{Var}(y_{t-k})}}$$

$$k=0: \frac{(1+\alpha)\sigma^2}{((1+\alpha)\sigma^2)((1+\alpha)\sigma^2)} = \frac{(1+\alpha)\sigma^2}{(1+\alpha)\sigma^2} = 1$$

$$k=1: \frac{\alpha\sigma^2}{((1+\alpha)\sigma^2)((1+\alpha)\sigma^2)} = \frac{\alpha\sigma^2}{(1+\alpha)\sigma^2} = \frac{\alpha}{1+\alpha}$$

$k \neq 0, 1 \Rightarrow 0$ autocorrelation

Given the information, there will only be one spike at lag 1 on the ACF

C $y_t = c + \alpha \epsilon_{t-1} + \epsilon_t$

\hat{y}_{t+k} and 95% CI for $k=1..4$

Open for the four values is

$$y_{t+k} = c + \alpha \epsilon_{t-k+1} + \epsilon_{t+k}$$

ϵ_{t-k+1} can be re wrote in term of a weight sum of past observations such as y_{t-k-1}, y_{t-k-2} etc.

All these past observations are available to compute ϵ_{t-k}

Hence forecasted value is $\hat{y}_{t+k} = c + \alpha \epsilon_{t-k}$

with 95% CI using $\pm 2\sigma$

- Beyond

ARIMA(1,0,3)(1,2,0)₅

$$(1 - \phi_1 B)(1 - \beta_1 B^5)(1)^0(1 - B^5)^2 y_t = \epsilon_t + c + (1 - \omega_1 B - \omega_2 B^2 - \omega_3 B^3)(1)(\epsilon_t)$$

$$(1 - \phi_1 B)(1 - \beta_1 B^5)(1 - B^5)^2 y_t = c + (1 - \omega_1 B - \omega_2 B^2 - \omega_3 B^3)(\epsilon_t)$$

Expand left hand side

$$(1 - \phi_1 B)(1 - \beta_1 B^5)(1 - 2B^5 + B^{10})$$

$$(1 - \beta_1 B^5 - \phi_1 B + \phi_1 \beta_1 B^6)(1 - 2B^5 + B^{10})$$

$$\underbrace{1 - \beta_1 B^5 - \phi_1 B + \phi_1 \beta_1 B^6}_{\check \check \check \check} - \underbrace{2B^5 + 2\phi_1 B^6 - 2\phi_1 \beta_1 B^{11}}_{\check \check \check \check} + \underbrace{B^{10} + \beta_1 B^{15} + \phi_1 B^{11} - \phi_1 \beta_1 B^{16}}_{\check \check \check \check}$$

apply this to y_t

\Rightarrow

$$1 - \beta_1 y_{t-5} - \phi_1 y_t + \phi_1 \beta_1 y_{t-6} - 2y_{t-5} + 2\beta_1 y_{t-10} + 2\phi_1 \beta_1 y_{t-6} - 2\phi_1 \beta_1 y_{t-11} + y_{t-10} + \beta_1 y_{t-15} + \phi_1 y_{t-11} - \phi_1 \beta_1 y_{t-16}$$

RHS:

$$c + 1 - \omega_1 \epsilon_{t-1} - \omega_2 \epsilon_{t-2} - \omega_3 \epsilon_{t-3}$$