Assignment 5

111550142 尤瑋辰

I use MATLAB to calculate the result. Here is the result and code:

 Use predictor-corrector method(predictor: Euler method; corrector: modified Euler method) to solve this problem. Choose step size 0.001 to ensure five digits correct.

```
f = @(y, x) \sin(x) + y;
x0 = 0;
y0 = 2;
h = 0.001;
y01 = modified_euler(f, y0, x0, h, 0.1);
y05 = modified_euler(f, y0, x0, h, 0.5);
fprintf('y(0.1) = \%.5f\n', y01);
fprintf('y(0.5) = \%.5f\n', y05);
function y = modified_euler(f, y0, x0, h, xn)
    for i = x0:h:xn-h
       % Predicxor:
       y_next = y + h*f(y, i);
       % Correcxor
       y_next = y + 0.5*h*f(y, i) + 0.5*h*f(y_next, i+h);
                                                           >> Q1
                                                            y(0.1) = 2.21551
       y = y_next;
   end
                                                            y(0.5) = 3.44330
end
```

2.

$$\frac{d}{dt} \mathcal{K}(t) = f(x,t) \quad \int_{tn}^{tn} f(x,t) dt = \int_{tn}^{tn} \frac{dx(t)}{dt} dt = \chi(t_{n+1}) - \chi(t_n) = c_0 f_{n+1} + c_1 f_n$$

$$Choose \quad t = -h, \quad 0 \quad \text{and} \quad f(x,t) = 1, \quad f(x,t) = t$$

$$\begin{bmatrix} 1 & 1 & \\ -h & 0 & \\ \end{bmatrix} \begin{bmatrix} c_0 & \\ c_1 & \end{bmatrix} = \begin{bmatrix} c_0 & \\ \frac{h^2}{2} & \\ \end{bmatrix} \begin{bmatrix} c_0 & \\ c_1 & \end{bmatrix} = h \begin{bmatrix} -\frac{1}{2} & \\ \frac{3}{2} & \\ \end{bmatrix}$$

$$\chi(t_{n+1}) = \chi(t_n) + \frac{h}{2} \left(-f(\chi_{n-1}, t_{n-1}) + 3f(\chi_{n}, t_n) \right)$$

3. a. Use ODE45 to solve

```
% Define the system of differential equations
f = @(t, y) [y(2); y(3); 2*y(1) - t*y(2) + t];
% Initial conditions
y0 = [0; 1; 0];
\% Solve the system using ode45
[\sim, y] = ode45(f, [0, 0.2], y0);
y02 = y(end, :)';
[\sim, y] = ode45(f, [0, 0.4], y0);
y04 = y(end, :)';
[~,~y] = ode45(f, [0, 0.6], y0);
                                          y(0.2) = 0.20013
y06 = y(end, :)';
                                          y(0.4) = 0.40213
% Display the results
fprintf('y(0.2) = %.5f\n', y02(1));
fprintf('y(0.4) = \%.5f\n', y04(1));
                                          y(0.6) = 0.61078
fprintf('y(0.6) = \%.5f\n', y06(1));
```

b. Use the results from (a) and the initial condition for the first 4 steps. Apply the Adams-Moulton method to derive y (0.8). Then, use the same method to derive y (1.0).

```
% b
% Step size
h = 0.2;
yn = y06;
yn_1 = y04;
yn_2 = y02;
yn_3 = y0;
% Solve the system using the Adams-Moulton method
for i = 0.6:h:0.8
   % Predictor
    y_next = y_n + h/24 * (55*f(i, y_n) - 59*f(i-h, y_n_1) + 37*f(i-2*h, y_n_2) - 9*f(i-3*h,y_n_3));
    % Corrector
    y_next = y_n + h/24 * (9*f(i+h, y_next) + 19*f(i, y_n) - 5*f(i-h, y_n_1) + 1*f(i-2*h,y_n_2));
    yn_3 = yn_2;
    yn_2 = yn_1;
    yn_1 = yn;
    yn = y_next;
fprintf('y(1.0) = \%.5fh', yn(1));
```

$$y(1.0) = 1.08256$$

$$A^{1}(t_{1}) = \frac{A_{1}+1-2A_{1}+A_{1}-1}{A^{2}}, A^{1}(t_{1}) = \frac{A_{1}+1-A_{1}-1}{2h}$$

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$$A^{1}(t_{1}) = \frac{A_{1}+1-2A_{1}+A_{1}-1}{A^{2}}, A^{1}(t_{1}) = 0$$

$$A^{1}(t_{1}) = \frac{A_{1}+1-2A_{1}+A_{1}-1}{A^{2}}, A^{2}(t_{1}) = 0$$

$$A^{1}(t_{1}) = \frac{A_{1}+1-A_{1}-1}{A^{2}}, A^{2}(t_{1}) = 0$$

$$A^{1}(t_{1}) = \frac{A^{1}(t_{1})}{A^{2}}, A^{2}(t_{1}) = 0$$

$$A^{1}(t$$

```
h = pi/8;
A = [1, h^2-2, 1, 0, 0, 0, 0;
    0, 1, h^2-2, 1, 0, 0, 0;
    0, 0, 1, h^2-2, 1, 0, 0;
    0, 0, 0, 1, h^2-2, 1, 0;
    0, 0, 0, 0, 1, h^2-2, 1;
    -1/(2*h), 1, 1/(2*h), 0, 0, 0, 0;
    0, 0, 0, 0, -1/(2*h), 1, 1/(2*h)];
b = [0; 0; 0; 0; 0; 2; -1];
                                              y(0.00000) = 1.50931
                                              y(0.39270) = 1.58563
y = A \setminus b;
                                              v(0.78540) = 1.41742
for i = -1:5
   fprintf('y(%.5f) = %.5f\n', i*h, y(i+2, 1)); Y(1.17810) = 1.03063
end
                                             v(1.57080) = 0.48490
```