

Umeyama-Kabsch Algorithm [\[1\]](#)

Aligning point patterns

Davide Malvezzi

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1.1 Umeyama-Kabsch algorithm

Given two sets of n -dimensional points x_i and y_i we want to find the scaling c , rotation R and translation t to align the two sets and which minimize

$$e^2(c, R, t) = \frac{1}{n} \sum_{i=1}^n \|y_i - (cRx_i + t)\|^2 \quad (1.1)$$

1.1.1 Least-square estimation for rotation only

Let's start considering only the estimation of the rotation matrix.

Given A and B , $m \times n$ matrix, whose columns are points from the sets y_i and x_i respectively and R $m \times m$ rotation matrix, we seek to minimize

$$\min_R \|A - RB\|^2 \quad (1.2)$$

under the constraints

$$R^T R = I \quad (1.3)$$

$$\det(R) = 1 \quad (1.4)$$

which define R as a valid rotation matrix.

The corresponding Lagrangian is

$$F = \|A - RB\|^2 + \text{tr}(L(R^T R - I)) + g(\det(R) - 1) \quad (1.5)$$

Note 1.1: What is $\text{tr}(L(R^T R - I))$?

Let $R = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$

then $R^T R = 1$ becomes

$$\begin{bmatrix} a & c \\ b & d \end{bmatrix} \begin{bmatrix} a & b \\ c & d \end{bmatrix} - \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = 0 \quad (1.6)$$

$$\begin{bmatrix} f-1 & g \\ g & h-1 \end{bmatrix} = 0 \quad (1.7)$$

$$(1.8)$$

Therefore, we have 3 constraints, $f = 1$, $h = 1$ and $g = 0$ and the corresponding Lagrangian multipliers α , β and γ .

Then L is a symmetric matrix of Lagrangian multipliers

$$L = \begin{bmatrix} \alpha & \gamma \\ \gamma & \beta \end{bmatrix} \quad (1.9)$$

and $L(R^T R - I)$ is

$$\begin{bmatrix} \alpha & \gamma \\ \gamma & \beta \end{bmatrix} \begin{bmatrix} f-1 & g \\ g & h-1 \end{bmatrix} = \begin{bmatrix} \alpha(f-1) + \gamma g & \alpha g + \gamma(h-1) \\ \gamma(f-1) + \beta g & \gamma g + \beta(h-1) \end{bmatrix} \quad (1.10)$$

But we just need the main diagonal for the Lagrangian, so we apply the tr operator.

1.1.2 Derivatives

Deriving F we obtain

$$\frac{\partial F}{\partial R} = -2AB^T + 2RBB^T + 2RL + gR = 0 \quad (1.11)$$

$$\frac{\partial F}{\partial L} = R^T R - I = 0 \quad (1.12)$$

$$\frac{\partial F}{\partial g} = \det(R) - 1 = 0 \quad (1.13)$$

Note 1.2: Matrix norm

Note that

$$\|A\|^2 = \text{tr}(A^T A)$$

Note 1.3: Matrix derivative

$$\frac{\partial}{\partial \underline{X}} \text{tr}[\underline{X}] = \underline{I} \quad (\text{A.1}) \quad \frac{\partial}{\partial \underline{X}} \text{tr}[\underline{A} \underline{X}^n] = \left(\sum_{i=0}^{n-1} \underline{X}^i \underline{A} \underline{X}^{n-1-i} \right), \quad (\text{A.13})$$

$$\frac{\partial}{\partial \underline{X}} \text{tr}[\underline{A} \underline{X}] = \underline{A}' \quad (\text{A.2}) \quad \frac{\partial}{\partial \underline{X}} \text{tr}[\underline{A} \underline{X} \underline{B} \underline{X}] = \underline{A}' \underline{X}' \underline{B}' + \underline{B}' \underline{X}' \underline{A}' \quad (\text{A.14})$$

$$\frac{\partial}{\partial \underline{X}} \text{tr}[\underline{A} \underline{X}'] = \underline{A} \quad (\text{A.3}) \quad \frac{\partial}{\partial \underline{X}} \text{tr}[\underline{A} \underline{X} \underline{B} \underline{X}'] = \underline{A}' \underline{X} \underline{B}' + \underline{A} \underline{X} \underline{B} \quad (\text{A.15})$$

$$\frac{\partial}{\partial \underline{X}} \text{tr}[\underline{A} \underline{X} \underline{B}] = \underline{A}' \underline{B}' \quad (\text{A.4}) \quad \frac{\partial}{\partial \underline{X}} \text{tr}[e^{\underline{X}}] = e^{\underline{X}'} \quad (\text{A.16})$$

$$\frac{\partial}{\partial \underline{X}} \text{tr}[\underline{A} \underline{X}' \underline{B}] = \underline{B} \underline{A} \quad (\text{A.5}) \quad \frac{\partial}{\partial \underline{X}} \text{tr}[\underline{X}^{-1}] = -(\underline{X}^{-1} \underline{X}^{-1})' = -(\underline{X}^{-2})' \quad (\text{A.17})$$

$$\frac{\partial}{\partial \underline{X}'} \text{tr}[\underline{A} \underline{X}] = \underline{A} \quad (\text{A.6}) \quad \frac{\partial}{\partial \underline{X}} \text{tr}[\underline{A} \underline{X}^{-1} \underline{B}] = -(\underline{X}^{-1} \underline{B} \underline{A} \underline{X}^{-1})' \quad (\text{A.18})$$

$$\frac{\partial}{\partial \underline{X}'} \text{tr}[\underline{A} \underline{X}'] = \underline{A}' \quad (\text{A.7}) \quad \frac{\partial}{\partial \underline{X}} \det[\underline{X}] = (\det[\underline{X}]) (\underline{X}^{-1})' \quad (\text{A.19})$$

$$\frac{\partial}{\partial \underline{X}'} \text{tr}[\underline{A} \underline{X} \underline{B}] = \underline{B} \underline{A} \quad (\text{A.8}) \quad \frac{\partial}{\partial \underline{X}} \log \det[\underline{X}] = (\underline{X}^{-1})' \quad (\text{A.20})$$

$$\frac{\partial}{\partial \underline{X}'} \text{tr}[\underline{A} \underline{X}' \underline{B}] = \underline{A}' \underline{B}' \quad (\text{A.9}) \quad \frac{\partial}{\partial \underline{X}} \det[\underline{A} \underline{X} \underline{B}] = (\det[\underline{A} \underline{X} \underline{B}]) (\underline{X}^{-1})' \quad (\text{A.21})$$

$$\frac{\partial}{\partial \underline{X}} \text{tr}[\underline{X} \underline{X}] = 2 \underline{X}' \quad (\text{A.10}) \quad \frac{\partial}{\partial \underline{X}} \det[\underline{X}'] = \frac{\partial}{\partial \underline{X}} \det[\underline{X}] = (\det[\underline{X}]) (\underline{X}^{-1})' \quad (\text{A.22})$$

$$\frac{\partial}{\partial \underline{X}} \text{tr}[\underline{X} \underline{X}'] = 2 \underline{X} \quad (\text{A.11}) \quad \frac{\partial}{\partial \underline{X}} \det[\underline{X}^n] = n(\det[\underline{X}])^n (\underline{X}^{-1})' \quad (\text{A.23})$$

$$\frac{\partial}{\partial \underline{X}} \text{tr}[\underline{X}^n] = n(\underline{X}^{n-1})' \quad (\text{A.12})$$

1.1.3 Decomposing L'

From the first derivative

$$RL' = AB^T \quad \text{where} \quad L' = BB^T + L + \frac{1}{2}gI \quad (1.14)$$

Note L' is symmetric because sum of symmetric matrices.

Multiplying each side by its transpose

$$(RL')^T RL' = (AB^T)^T AB^T \quad (1.15)$$

$$L'^T R^T RL' = BA^T AB^T \quad (1.16)$$

$$L'^T L = BA^T AB^T \quad (1.17)$$

$$L'^2 = BA^T AB^T \quad (1.18)$$

Let $AB^T = UDV^T$ be the SVD decomposition, then

$$L'^2 = BA^T AB^T \quad (1.19)$$

$$L'^2 = VDU^T UDV^T \quad (1.20)$$

$$L'^2 = VD^2V^T \quad (1.21)$$

Given $S = \text{diag}(s_1, \dots, s_n)$, with $s_i = 1$ or $s_i = -1$, the matrix L' can be written then as

$$L' = VDSV^T \quad (1.22)$$

Proof:

$$L'^2 = L'L' = VDSV^T VDSV^T = VD^2V^T \quad (1.23)$$

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1.1.4 Determinant equivalence

Now we have

$$\det(L') = \det(VDSV^T) = \det(V)\det(D)\det(S)\det(V^T) = \det(D)\det(S) \quad (1.24)$$

$$\det(L') = \det(R^T AB^T) = \det(R^T)\det(AB^T) = \det(AB^T) \quad (1.25)$$

Therefore

$$\det(D)\det(S) = \det(AB^T) \quad (1.26)$$

Since singular value are always positive, $\det(D) > 0$ then $\det(S)$ must be equal to 1 or -1 depending on the sign of $\det(AB^T)$

1.1.5 Replacing into F

We can rewrite F with the results obtained

$$F = \|A - RB\|^2 = \|A\|^2 + \|B\|^2 - 2\text{tr}(AB^T R^T) \quad (1.27)$$

$$= \|A\|^2 + \|B\|^2 - 2\text{tr}(R^T AB^T) \quad \# \text{trace of matrix product is independent on order} \quad (1.28)$$

$$= \|A\|^2 + \|B\|^2 - 2\text{tr}(L') \quad (1.29)$$

$$= \|A\|^2 + \|B\|^2 - 2\text{tr}(VDSV^T) \quad (1.30)$$

$$= \|A\|^2 + \|B\|^2 - 2\text{tr}(V^T VDS) \quad \# \text{trace of matrix product is independent on order} \quad (1.31)$$

$$= \|A\|^2 + \|B\|^2 - 2\text{tr}(DS) \quad (1.32)$$

$$= \|A\|^2 + \|B\|^2 - 2(d_1 s_1 + \dots + d_m s_m) \quad (1.33)$$

Being the singular value in D always positive, the minimum of F is obtained when all $s_i = 1$ if $\det(AB^T) \geq 0$ otherwise if $\det(AB^T) < 0$ we must set $s_m = -1$ to satisfy the determinant equivalence.

1.1.6 Getting optimal R

When AB^T is full rank therefore L'^{-1} exists, so

$$R = AB^T L'^{-1} = UDV^T VD^{-1}SV^T = USV^T \quad (1.34)$$

When $\text{rank}(AB^T) = m - 1$ we have

$$RL' = AB^T \quad (1.35)$$

$$RVDSV^T = UDV^T \quad (1.36)$$

$$RVDS = UD \quad (1.37)$$

$$U^T RVDS = D \quad (1.38)$$

$$QD = D \quad (1.39)$$

where $DS = D$ because $s_i = 1 \quad i = 1 \dots m - 1$ and $d_m = 0$. The new matrix $Q = U^T RV$ is orthogonal by construction, so the last equation is true only if each column $q_i = e_i \quad i = 1 \dots m - 1$. For the last column q_m possible solutions are e_m or $-e_m$, this depends on the determinat value

$$\det(Q) = \det(U^T)\det(R)\det(V) = \det(U)\det(V) \quad (1.40)$$

so if $\det(U)\det(V) = 1$ then $\det(Q) = 1$ so $q_m = e_m$ otherwise $q_m = -e_m$ In conclusion

$$R = UQV^T \quad (1.41)$$

1.1.7 Least-square estimation for c , R and t

Let's now consider the original problem

$$e^2(c, R, t) = \frac{1}{n} \sum_{i=1}^n \|y_i - (cRx_i + t)\|^2 = \frac{1}{n} \|Y - cRX - th^T\|^2 \quad (1.42)$$

Definition 1.1.1: Normalization matrix

We define a $n \times n$ normalization matrix K as

$$K = I - \frac{1}{n} hh^T \quad \text{where} \quad h = (1, \dots, 1)^T \quad (1.43)$$

with the following properties

$$K = K^T = K^2 \quad (1.44)$$

Definition 1.1.2

Then we can define

$$\mu_x = \frac{1}{n} Xh \quad (1.45)$$

$$\mu_y = \frac{1}{n} Yh \quad (1.46)$$

$$\sigma_x^2 = \frac{1}{n} \|XK\|^2 \quad (1.47)$$

$$\sigma_y^2 = \frac{1}{n} \|YK\|^2 \quad (1.48)$$

$$\Sigma_{xy} = \frac{1}{n} YKX^T \quad (1.49)$$

$$X = XK + \frac{1}{n} Xhh^T \quad (1.50)$$

$$Y = YK + \frac{1}{n} Yhh^T \quad (1.51)$$

and substitute in the loss function

$$e^2(c, R, t) = \frac{1}{n} \|Y - cRX - th^T\|^2 \quad (1.52)$$

$$= \frac{1}{n} \|YK + \frac{1}{n} Yhh^T - cRXK - \frac{c}{n} RXhh^T - th^T\|^2 \quad (1.53)$$

$$= \frac{1}{n} \|YK - cRXK + \left(\frac{1}{n} Yh - \frac{c}{n} RXh - t\right) h^T\|^2 \quad (1.54)$$

$$= \frac{1}{n} \|YK - cRXK + t'h^T\|^2 \quad (1.55)$$

$$= \frac{1}{n} (\|YK - cRXK\|^2 + \|t'h^T\|^2 - 2\text{tr}(K(Y^T - cX^T R^T)t'h^T)) \quad (1.56)$$

Let's analyze each single term of the loss.

First term

If we define $A = YK$ and $B = XK$, the optimal R of the first term is given by the solution of 1.2.

Also note that

$$AB^T = YKK^T X^T = YKX^T = n\Sigma_{xy} \quad (1.57)$$

Note 1.4: SVD decomposition of a constant times a matrix

Given a matrix A and the matrix cA , their SVD decomposition are equivalent except the singular value of the second are the singular of the first matrix times c

So, given the SVD decomposition of $\Sigma_{xy} = UDV^T$, the optimal $R = USV^T$.

Then the first term can be decomposed as

$$\frac{1}{n} \|YK - cRXK\|^2 = \frac{1}{n} (\|YK\|^2 + \|cRXK\|^2 - 2\text{tr}((YK)^T(cRXK))) \quad (1.58)$$

$$= \frac{1}{n} (\|YK\|^2 + \|cXK\|^2 - 2\text{tr}((YK)(cRXK)^T)) \quad (1.59)$$

$$= \frac{1}{n} (\|YK\|^2 + \|cXK\|^2 - 2\text{tr}(cYKK^T X^T R^T)) \quad (1.60)$$

$$= \frac{1}{n} (\|YK\|^2 + \|cXK\|^2 - 2\text{tr}(cYKX^T R^T)) \quad (1.61)$$

Let UDV^T be the SVD decomposition of $\Sigma_{xy} = \frac{1}{n} YKX^T$, then

$$YK(cXK)^T = cYKK^T X^T = cYKKX^T = cYK^2 X^T = cYKX^T = cnUDV^T \quad (1.62)$$

Substituting back $R = USV^T$ and $cYKX^T = cnUDV^T$

$$\frac{1}{n} \|YK - cRXK\|^2 = \frac{1}{n} (\|YK\|^2 + \|cXK\|^2 - 2\text{tr}(YKX^T R^T)) \quad (1.63)$$

$$= \frac{1}{n} (\|YK\|^2 + \|cXK\|^2 - 2\text{tr}(cnUDV^T(USV^T)^T)) \quad (1.64)$$

$$= \frac{1}{n} (\|YK\|^2 + \|cXK\|^2 - 2\text{tr}(cnUDV^T V S^T U^T)) \quad (1.65)$$

$$= \frac{1}{n} (\|YK\|^2 + \|cXK\|^2 - 2\text{tr}(cnUDS^T U^T)) \quad (1.66)$$

$$= \frac{1}{n} (\|YK\|^2 + \|cXK\|^2 - 2\text{tr}(cnDS)) \quad (1.67)$$

$$= \sigma_y^2 + c^2 \sigma_x^2 - 2c\text{tr}(DS) \quad (1.68)$$

In conclusion we have a quadratic equation in c , so

$$c = \frac{\text{tr}(DS)}{\sigma_x^2} \quad (1.69)$$

Second term

The second term can be rewritten as

$$\|t'h^T\|^2 = \|t'\|^2 \|h^T\|^2 = n \|t'\|^2 \quad (1.70)$$

So to minimize the loss t' must be 0

$$t' = 0 \quad (1.71)$$

$$\frac{1}{n} Yh - \frac{c}{n} RXh - t = 0 \quad (1.72)$$

$$t = \frac{1}{n} Yh - \frac{c}{n} RXh \quad (1.73)$$

$$t = \mu_y - cR\mu_x \quad (1.74)$$

Third term

Observing that $h^T K = h^T (I - \frac{1}{n} h h^T) = h^T - \frac{1}{n} h^T h h^T = h^T - h^T = 0$, so the third term is always equal to 0

$$\text{tr}(K(YT - cXTRT)t'h^T) = \text{tr}(K(YT - cXTRT)t'h^T K K^{-1}) = 0 \quad (1.75)$$

1.1.8 Algorithm

Algorithm 1 Umeyama-Kabsch Algorithm

Require: X $m \times n$ matrix

Require: Y $m \times n$ matrix

$$\mu_x = \text{mean}(X)$$

$$\mu_y = \text{mean}(Y)$$

$$\sigma_x^2 = \text{var}(X)$$

$$\Sigma_{xy} = \text{cov}(X, Y)$$

$$S = \text{eye}(n)$$

$$U, D, V^T = \text{svd}(\Sigma_{xy})$$

if $\det(U) \det(V^T) < 0$ **then**

$$S[n, n] = -1$$

end if

$$c = \text{trace}(DS) / \sigma_x^2$$

$$R = USV^T$$

$$t = \mu_y - cR\mu_x$$

return c, R, t

Bibliography

- [1] S. Umeyama. Least-squares estimation of transformation parameters between two point patterns. *IEEE Transactions on Pattern Analysis and Machine Intelligence*, 13(4):376–380, 1991.