Davide Montagno B.

Assignment 6 (**Image processing assignment)**

Using Sobel Filter for Edge Detection

Project for Intelligent Systems for Pattern Recognition

Set up environment

- Use OpenCV and Numpy

```
import numpy as np
import cv2 as cv
```

- Take Image

```
cv.cvtColor(cv.imread(path,cv.COLOR_BGR2GRAY)
```

- Construct Sobel Filter
  - Direction X
  - Direction Y

```
sobelX = np.array((
   [+1, 0, -1],
   [+2, 0, -2],
   [+1, 0, -1]), dtype="int")
```

```
sobelY = np.array((
   [+1, +2, +1],
   [0, 0, 0],
   [-1, -2, -1]), dtype="int")
```

Apply Sobel Filter

- Convolution Function
  - Replicate Border
  - Take Region of Interest
  - Compute the convolution
  - Sum over the pixel
  - Rescale output
- Take results
  - Compute Magnitude
  - Take initial gradient
  - Take gradient direction

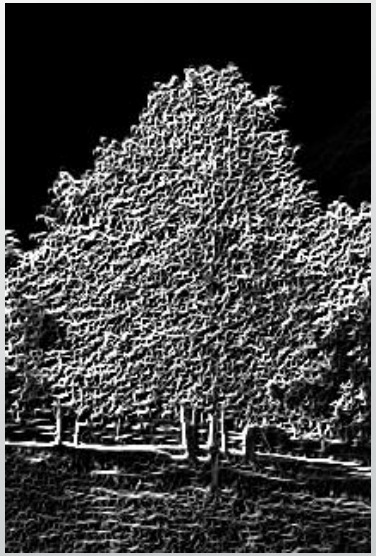
```
cv.copyMakeBorder(params, cv.BORDER_REPLICATE)

roi = image[y - pad:y + pad + 1, x - pad:x + pad + 1]

for i in range(kH):
    for j in range(kW):
        D[i][j] = np.dot(roi[i][j],kernel[i][j])

output[y - pad, x - pad] = D.sum()

output = rescale_intensity(output, in_range=(0, 255))
output = (output * 255).astype("uint8")

magnitude = np.hypot(intensityX, intensityY)

np.hypot(convolutionOperation(gray, sobelX*(1/8)),
convolutionOperation(gray, sobelY*(1/8)))

np.arctan(np.divide(intensityY,intensityX))
```

Results

Gradient X direction

Gradient Y direction

Magnitude



Not only: By using *phase* of OpenCV, you can get the direction (angleInDegrees=true) of the gradient; finally you can map it as colors.. Use the code to try it!

Blur Image

- Reuse the same function
- Better result applying a filter

```
blur = np.ones((3, 3), dtype="float") * (1.0 /
(3 * 3))
```

Gradient X direction

Gradient Y direction

Magnitude