Switching: Position Regulation and Output Feedback with Further Derivatives y-axis Behaviour 6.57 Robot 1 Walls Desired Trajectory 10 30 70 t [s] 6.57 တ္ Robot 2 Walls Desired Trajectory 20 50 70 10 30 60 t [s] 6.57 S II Robot 3 Walls Desired Trajectory 70 30 10 t [s]