Tracking: Output Feedback with Further Derivatives w/ Input Saturations and w/ Derivative Saturations x-axis Behaviour Robot 1 Walls Desired Trajectory 15 20 25 30 10 35 t [s] Robot 2 Walls Desired Trajectory 15 20 25 35 40 5 10 30 45 t [s] Robot 3 Walls Desired Trajectory 30 15 35 10 t [s]