Switching: Posture Regulation and State Feedback with Approximate Linearization x-axis Behaviour Robot 1 23.34 Walls Desired Trajectory 10 20 30 50 60 70 t [s] Robot 2 23.34 Walls Desired Trajectory ິດ ໄ 10 20 50 70 30 60 t [s] Robot 3 23.34 Walls Desired Trajectory ഗ[†] 20 70 10 30 60 t [s]