Switching: Position Regulation and State Feedback with Approximate Linearization y-axis Behaviour 19.78 တ္ Robot 1 Walls Desired Trajectory 10 20 30 50 60 70 t [s] Robot 2 19.78 Walls Desired Trajectory 10 20 50 70 30 60 t [s] Robot 3 19.78 Walls Desired Trajectory 70 20 10 30 50 t [s]