## Switching: Position Regulation and State Feedback with Exact Linearization y-axis Behaviour S Robot 1 Walls Desired Trajectory 10 30 70 t [s] တ Robot 2 Walls Desired Trajectory 10 20 70 30 50 60 t [s] ഗ് Robot 3 Walls Desired Trajectory 70 10 60 t [s]