Switching: Position Regulation and Output Feedback with Change of Variables y-axis Behaviour 18.12 Robot 1 Walls Desired Trajectory 10 20 30 50 60 70 t [s] 18.12 ່ທ້ Robot 2 Walls Desired Trajectory 20 50 70 10 30 60 t [s] =,18.12 S Robot 3 Walls Desired Trajectory 70 10 20 30 50 60 t [s]