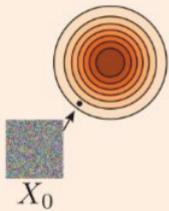


$p$

$q$

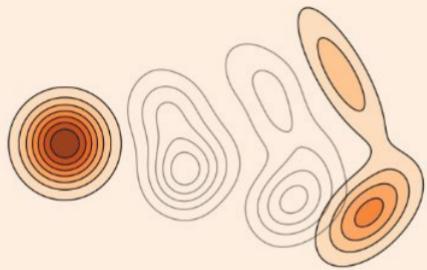


**(a)** Data.

$p$

$p_t$

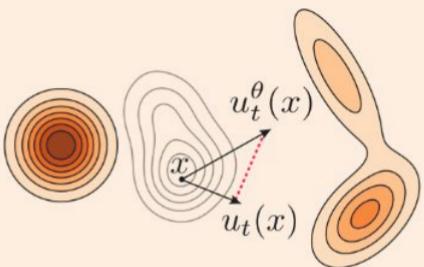
$q$



**(b)** Path design.

$$u_t^\theta(x)$$

$$u_t(x)$$



**(c)** Training.



**(d)** Sampling.