Due date: 25-04-2023.

Assignment-3

- 1. Consider the following points to derive and simulate the dynamics of the guided projectile.
 - a. Assume that it is a point mass.
 - b. Assume that it is launched from parental aircraft with $20 \frac{m}{s}$ initial velocity at a different projectile angle $(0^0, 5^0, 10^0)$.
 - Use aerodynamic characteristics of projectile from the wind tunnel data processing assignment.
- 2. Simulate the 6-DOF dynamics of HANSA-3 Research Aircraft, flying in steady level condition, using 3 dynamics and 3 kinematics equation as discussed in lecture and control inputs given in following figures.
- a. Simulate the aircraft dynamics by giving 3-2-1-1, doublet and sinusoidal inputs separately to elevator.
 - b. Simulate the aircraft dynamics by giving 3-2-1-1, doublet and sinusoidal inputs separately to aileron.
- 3 c. Simulate the aircraft dynamics by giving 3-2-1-1, doublet and sinusoidal inputs separately to rudder.
 - d. Simulate the aircraft dynamics by giving 3-2-1-1, doublet and sinusoidal inputs separately to elevator.
- e. Simulate the aircraft dynamics by giving 3-2-1-1 type of input to elevator, aileron, and rudder simultaneously.
- f. Simulate the aircraft dynamics by giving doublet type of input to elevator, aileron, and rudder simultaneously.
- g. Simulate the aircraft dynamics by giving sinusoidal type of input to elevator, aileron, and rudder simultaneously.

Geometric and Inertial properties:

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m = 750 \ kg, IXX = 873 \ kgm^2, IYY = 907 \ kgm^2, IZZ = 1680 \ kgm^2, IXZ = 1144 \ kgm^2, S = 12.47 \ m^2, b = 10.47 \ m, \bar{c} = 1.211 \ m, AR = 8.8
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Aerodynamic Parameters:

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CD0 = 0.035, k = 0.045, CL0 = 0.370, CL\alpha = 5.0, CLq = 37.211, CL\delta e = 0.374 Cm0 = 0.091, Cm\alpha = -2.937, Cmq = -8.719, Cm\delta e = -0.735 CY0 = 0, CY\beta = -0.531, CYp = -0.0571, CYr = 0.4657, CY\delta r = 0.1502 Cl0 = 0, Cl\beta = -0.031, Clp = -0.262, Clr = -0.0541, Cl\delta r = 0.005, Cl\delta a = -0.153 Cn0 = 0, Cn\beta = 0.01, Cnp = -0.007, Cnr = -0.067, Cn\delta r = -0.047
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Note: Please do not consider control surface deflections blindly as given in following figures. You need to consider the similar control input about trim control surface deflection.





