view_frames Result Recorded at time: 1635820293.735 world Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (1635820293.735 sec old) Buffer length: 0.000 sec base_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: $\overline{100.200}$ Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (1635820293.735 sec old) Most recent transform: 0.000 (1635820293.735 sec old) Most recent transform: 1635820293.725 (0.010 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 4.980 sec link_1 workobject Broadcaster: /robot_state_publisher Average rate: 100.200 Hz Most recent transform: 1635820293.725 (0.010 sec old) Buffer length: 4.980 sec link_2 Broadcaster: /robot_state_publisher Average rate: 100.200 Hz Most recent transform: 1635820293.725 (0.010 sec old) Buffer length: 4.980 sec link_3 Broadcaster: /robot_state_publisher Average rate: 100.200 Hz Most recent transform: 1635820293.725 (0.010 sec old) Buffer length: 4.980 sec link_4 Broadcaster: /robot_state_publisher Average rate: $\overline{100.200}$ Hz Most recent transform: 1635820293.725 (0.010 sec old) Buffer length: 4.980 sec link_5 Broadcaster: /robot_state_publisher Average rate: 100.200 Hz Most recent transform: 1635820293.725 (0.010 sec old) Buffer length: 4.980 sec link_6 Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (1635820293.735 sec old) Buffer length: 0.000 sec tool0 Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (1635820293.735 sec old) Most recent transform: 0.000 (1635820293.735 sec old) Most recent transform: 0.000 (1635820293.735 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec tcp_link laser_head_link camera0