JAX AI Stack Quick Reference

Core Philosophy:

Achieve Performance, Flexibility, and Scalability using **function transformations** on Python & NumPy-like code. Leverages **XLA (Accelerated Linear Algebra)** compiler for optimized, portable code across CPUs, GPUs, and TPUs.

JAX Core: Functional Engine & Transformations

- NumPy-like API: jax.numpy (often imported as jnp) provides a familiar interface.
- Functional Programming: Functions ideally have no side-effects. Model parameters & optimizer states are passed as arguments and returned as results.
- PyTrees: Nested Python dict/list/tuple structures used to manage collections of parameters, gradients, and states. JAX transformations work seamlessly with PyTrees.

Key Function Transformations:

1. jax.jit (Just-In-Time Compilation)

- Purpose: Compiles a JAX-compatible Python function into highly optimized machine code using XLA.
- Usage: Typically used as a decorator: @jax.jit
- Benefits: Dramatically speeds up execution by fusing operations, optimizing memory, and avoiding Python interpreter overhead.
- GSPMD (Automatic Parallelism): jit can also orchestrate automatic parallelism.
 - Decorate function with jit.
 - Provide sharding annotations for inputs/outputs (how data is distributed).
 - XLA compiler partitions computation and inserts cross-device communication.

2. jax.grad (Automatic Differentiation)

 Purpose: Transforms a numerical function (e.g., loss function) into a new function that computes its gradient.

- o Usage: grad_fn = jax.grad(loss_fn)
 gradients = grad_fn(params, *args)
- Note: Composes with jit and other transforms. jax.value_and_grad(fn) is common to get both function's output (e.g., loss) and gradients.

3. jax.vmap (Vectorization / Auto-Batching)

- Purpose: Transforms a function written for a single data point into one that efficiently maps across a batch dimension.
- o Usage: batched_fn = jax.vmap(fn_for_single_example)
- **Benefits:** Simplifies code write logic for one example, vmap handles batching.

Explicit Parallelism:

- shard_map (Manual SPMD Parallelism)
 - Purpose: Provides explicit, manual control over Single-Program Multiple-Data parallelism.
 - Key Components:
 - jax.sharding.Mesh(device_array, axis_names): Defines a logical grid of devices with named axes (e.g., 'data', 'model').
 - jax.sharding.PartitionSpec(...): Describes how tensor dimensions are sharded (split, e.g., P('data')) or replicated (e.g., P(None)) across Mesh axes.
 - Usage: Apply shard_map to a function, specifying input/output sharding with PartitionSpecs over a Mesh.
 - Responsibility: User explicitly defines cross-device communication (e.g., jax.lax.psum for sum-reduction).

Flax NNX: Pythonic Neural Network Models

- **Purpose:** Provides structure for defining and managing Neural Networks (like torch.nn.Module). NNX API focuses on an intuitive, Pythonic experience.
- **Model Definition**: Models are regular Python objects using standard object model and reference semantics.

```
Python
from flax import nnx
class MyModel(nnx.Module):
    def __init__(self, din, dout, *, rngs: nnx.Rngs):
        self.linear = nnx.Linear(din, dout, rngs=rngs)
    def __call__(self, x):
        return self.linear(x)
# Instantiate: model = MyModel(10, 2,
rngs=nnx.Rngs(params=jax.random.PRNGKey(0)))
```

- State Management: Integrates with JAX functional API (jit, grad) to manage state (e.g., 'params', 'batch_stats') explicitly but conveniently.
- nnx.Rngs: Manages PRNG keys for initializations.
- @nnx.jit: Decorator for JIT-compiling NNX model methods or functions operating on NNX models.
- loss, grads = nnx.value_and_grad(loss_fn)(model): Computes loss and gradients for an NNX model. loss_fn should take the model as its first argument.
- nnx.Optimizer(model, tx=optax_optimizer): Wraps an NNX model and an Optax optimizer.
 - optimizer.update(grads): Applies gradient updates in-place to the model wrapped by the optimizer.

Optax: Composable Optimizers

- **Purpose**: Gradient processing and optimization library (like torch.optim).
- Philosophy: Optimizers are chains of composable gradient transformation building blocks (e.g., optax.add_decayed_weights(), optax.scale_by_adam()).
- Usage (Stateful):
 - 1. Define: optimizer_tx = optax.adam(learning_rate=0.01) (or optax.sgd(...) etc.)
 - 2. Initialize (if not using nnx.Optimizer):

```
opt_state = optimizer_tx.init(params)
```

3. Update (if not using nnx.Optimizer):

```
updates, opt_state = optimizer_tx.update(grads, opt_state,
params)
new_params = optax.apply_updates(params, updates)
```

 With Flax NNX: nnx.Optimizer(model, tx=optax_tx) abstracts state initialization and update application.

Orbax: Robust Checkpointing

- Purpose: Saving and loading training state (model params, optimizer state, PyTrees)
 (like torch.save/load).
- Key Features:
 - Designed for distributed (multi-host, multi-device) settings.
 - Manages saving/restoring JAX PyTrees.
 - Critical for fault-tolerance in long-running jobs.
 - o Supports asynchronous checkpointing to minimize impact on training.

More Information

- JAX AI Stack https://jaxstack.ai
- JAX https://jax.dev
- Flax https://flax.readthedocs.io