Davin Kim

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www.github.com/davinism



IROS 2014 Conference Administrative Aide

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Evanston, IL

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Projects	Asocial media application that allows travelers to plan and log their trips ☐ Implemented a route path rendering feature using Google Maps geolocation and Directions Renderer as well as a route saving feature using Google Static Maps API and PostgreSQL ☐ Constructed the Redux architecture that allows the frontend of the application to communicate with the database via AJAX requests to the Rails backend API ☐ Designed a single-page application using React to accelerate the page rendering and provide real-time user experience for features such as friending and commenting on trips ☐ Leveraged Sass to produce the entire stylistic layout of the entire application Sliding Warfare Sole Developer [JavaScript, jQuery] Live • GitHub An original two-player game inspired by Laser Tag and Paintball ☐ Modeled and implemented several physics principles such as friction and momentum using vector analysis in order to deliver a more real-world experience ☐ Coded a collision detection system between all game components with varying geometries ☐ Rendered the entire game using just HTML5 Canvas in order to allow for faster performance Vernacular Frontend Engineer [React Native] GitHub A mobile iOS application for practicing foreign languages with flashcards ☐ Engineered a smooth user interface with native iOS components that allows for features such as navigation across the app and a swipe functionality for viewing the flashcards ☐ Utilized the Redux framework to build a deck creation form that interacts with MongoDB ☐ Collaborated in a team with a git workflow and successfully deployed the app to iTunes Connect						ate de tHub ch as
Skills	Ruby Rails Python	JavaScript jQuery MATLAB	ReactJS React Native Redux	SQL git RSpec	HTML CSS OSX	C C++ Linux	
Education	3% acceptan Northwester B.S. in Mecha GPA: 3.89, Ta	eb Development ce rate rn University anical Engineerin u Beta Pi Engine	Course g, Summa Cum Lau ering Honor Societ C, Python, MATLAE	у	Se	ly 2016 - September San Francisco ptember 2011 - June 2 Evansto	o, CA 2015
Work History	Neuroscience and Robotics Lab Undergraduate Researcher □ Debugged the circuitry of a broken robotic hand and paved a way for further development □ Developed the application environment for the robotic hand using C++ □ Designed and machined a shaft that stabilized the movement of a demonstration robot Institute of Electrical and Electronics Engineers June 2014 - September 2014						

☐ Created Excel VBA scripts to automate the process of creating the conference digests ☐ Led a group of students to handle registration and other logistics of the conference