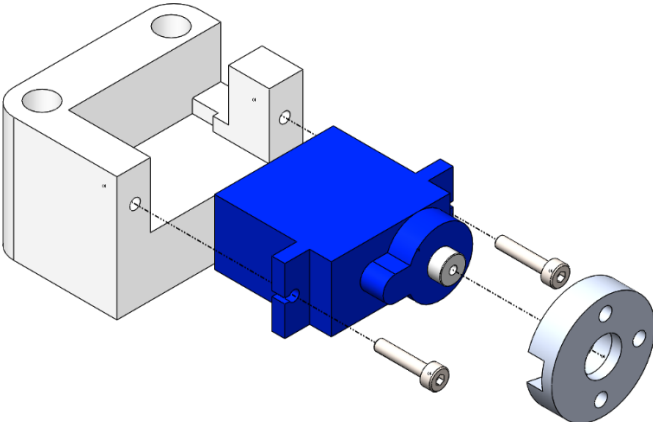
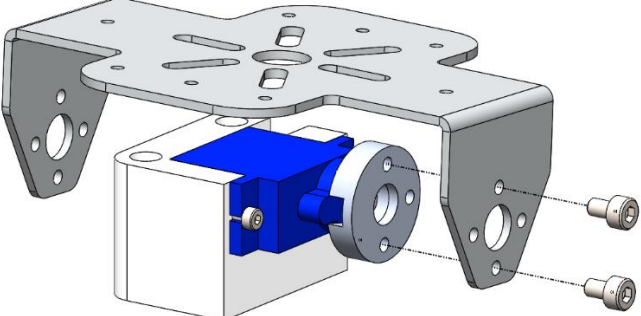
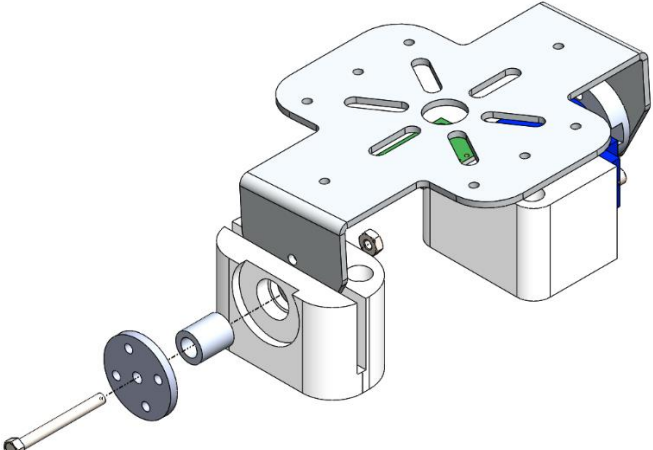
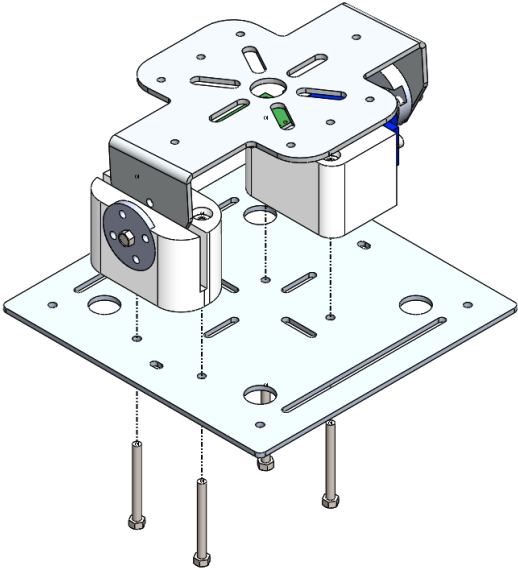
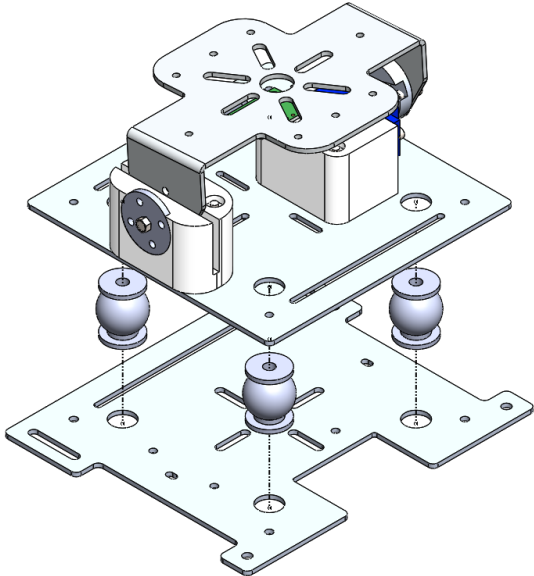


| Step # | Image | Description |
|--------|---|---|
| 1 |  | <p>Attach the servo to the servo block using the screws included with the servo.</p> <p>Attach the servo adapter to the servo horn of the servo using epoxy glue.</p> |
| 2 |  | <p>Attach the camera plate to the servo adapter using the screws included with the metal servo wheel.</p> |
| 3 |  | <p>Assemble the axle block by aligning the camera plate within the slot of the block and pressing an aluminium spacer and servo wheel into the axle block.</p> <p>Use the M2.5 x 25mm screw to secure all the components.</p> |

| Step # | Image | Description |
|--------|--|---|
| 4 |  | <p>Attach the assembly to the base plate using four M2.5x25mm screws and nuts. Pass the screws from the bottom of the gimbal plate.</p> |
| 5 |  | <p>Attach the Matrice plate to the assembly using shock absorbers through the larger holes. Use the included retainer pins or zipties to keep the plates from separating.</p> |

