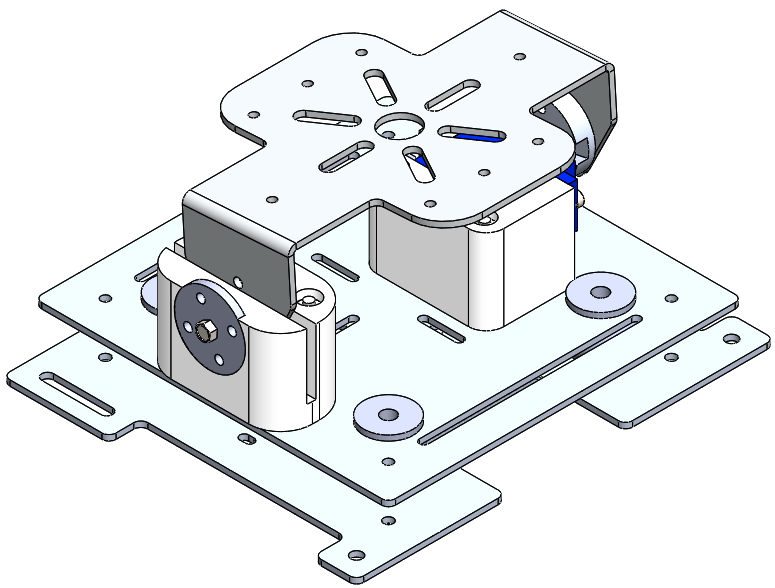
| **Step #** | **Image** | **Description** |
| --- | --- | --- |
| 1 |  | Attach the servo to the servo block using the screws included with the servo.  Attach the servo adapter to the servo horn of the servo using epoxy glue. |
| 2 |  | Attach the camera plate to the servo adapter using the screws included with the metal servo wheel. |
| 3 |  | Assemble the axle block by aligning the camera plate within the slot of the block and pressing an aluminium spacer and servo wheel into the axle block.  Use the M2.5 x 25mm screw to secure all the components. |
| 4 |  | Attach the assembly to the base plate using four M2.5x25mm screws and nuts. Pass the screws from the bottom of the gimbal plate. |
| 5 |  | Attach the Matrice plate to the assembly using shock absorbers through the larger holes. Use the included retainer pins or zipties to keep the plates from separating. |

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