

## Stability of convolutional neural network

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## 1 Stability

Recall that, in the simplest case, a one-layer convolutional neural network can be written as the following:

$$y(u) = \sigma(x * \psi(u)) \quad (1)$$

where  $x$  is the signal,  $\psi$  is the filter and  $\sigma$  is a transformation that is applied at every neuron. Usually,  $\sigma$  is sigmoid function or ReLU.

### 1.1 $L_2$ stability

The  $L_2$  stability comes in a Lipchitz format. More specifically, a function  $y$  is  $L_2$  stable if

$$\|y(x) - y(\tilde{x})\|_2 \leq C \|x - \tilde{x}\|_2$$

for any choice of  $x$  and  $\tilde{x}$ . Next, we are going to show that (1) is  $L_2$  stable under certain conditions, and thus by induction, a multi-layer CNN is also  $L_2$  stable.

First, when  $\sigma$  is non-expansive, i.e.,  $|\sigma(z) - \sigma(z')| \leq |z - z'|$  for any  $z$  and  $z'$ ,

$$\begin{aligned} \|y(x) - y(\tilde{x})\|_2^2 &= \int |\sigma(x * \psi(u)) - \sigma(\tilde{x} * \psi(u))|^2 du \\ &\leq \int |x * \psi(u) - \tilde{x} * \psi(u)|^2 du \end{aligned} \quad (2)$$

Next, we will show that (2) is  $L_2$  stable under the mild assumption that  $\|\psi\|_1$  is bounded.

**Proposition 1.**

$$\|x * \psi\|_2 \leq \|\psi\|_1 \|x\|_2$$

*Proof.*

$$\begin{aligned} \|x * \psi\|_2^2 &= \int |x * \psi(u)|^2 du \\ &= \int \left| \int x(v) \psi(u - v) dv \right|^2 du \\ &\leq \int \left( \int |x(v)|^2 |\psi(u - v)| dv \right) \left( \int |\psi(u - v)| dv \right) du \\ &= \|x\|_2^2 \|\psi\|_1^2 \end{aligned} \quad (3)$$

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Here (3) is a consequence of the Cauchy-Schwarz inequality on  $x(v)\psi(u - v)^{\frac{1}{2}}$  and  $\psi(u - v)^{\frac{1}{2}}$ . Note that we do not apply the Cauchy-Schwarz inequality to  $x(v)$  and  $\psi(u - v)$  directly, since the Hilbert-Schmidt condition is often not preferred. Recall that a integration operator is defined as the following.

**Definition 1** (Integration Operator). *For a real-valued kernel function  $k(\cdot, \cdot)$  defined over measurable space  $\mathcal{X} \times \mathcal{Y}$ , the integration operator defined with respect to  $k$  is defined as*

$$T_k f(u) = \int_Y k(u, v) f(v) dv$$

*In addition, a kernel  $k(\cdot, \cdot)$  is said to be Hilbert-Schmidt if  $\int \int |k(u, v)|^2 dv du < \infty$ .*

It is easy to check that the (translation-invariant) hat function  $k(u, v) = \mathbf{1}_{[-1,1]}(u - v)$  is not Hilbert-Schmidt. On the other hand, its 1-norm is finite. Therefore, applying the Cauchy-Schwarz inequality to  $x(v)$  and  $\psi(u - v)$  directly will result in a bound that is looser than applying the Cauchy-Schwarz inequality to  $x(v)\psi(u - v)^{\frac{1}{2}}$  and  $\psi(u - v)^{\frac{1}{2}}$ .

In fact, Proposition 1 is a special case of Theorem 1.

**Theorem 1** (Schur's Test). *Suppose  $T_k$  is the integration operator with kernel  $k(\cdot, \cdot)$ . If there exists  $C > 0$  s.t.*

$$\begin{cases} \int |k(u, v)| dv \leq C, & \forall u \\ \int |k(u, v)| du \leq C, & \forall v \end{cases}$$

*then  $\|T_k\|_2 \leq C$ , i.e.,  $\|T_k f\|_2 \leq C \|f\|_2$ . Here  $\|T_k\|_2 = \sup_{f, \|f\|_2=1} \|T_k f\|_2$ .*