

#1 Given: What follows is the VMLAB project information and AVR code for an 8-bit up/down counter, where the count direction is controlled by the state of PIN B, bit 0...

Find: Modify this code to create a 3-bit up counter that stops the count when PIN D, bit 1, is LOW. Use the 3 least significant bits of R16.

Solution:

.prj file:

```
K0 PD1 VSS LATCHED
R0 VDD PD1 5000
```

.hex file:

```
.include "C:\VMLAB\include\m168def.inc"
```

```
setup:
```

```
clr r16
```

```
clr r17
```

```
ldi r17, 7
```

```
rjmp main
```

```
main:
```

```
    sbic PIND, 1
```

```
    inc r16
```

```
    CPSE r16, r17
```

```
    sbis PIND, 1
```

```
    loop1:
```

```
    brne setup
```

```
rjmp main
```

The screenshot displays the AVR Studio IDE interface with several windows open:

- Project File:** Shows project configuration for "hw61.hex".
- Code Maker:** Displays assembly code for "hw61.asm".
- Run Time:** Shows the status of the hardware-software co-simulation.
- Registers:** A window showing the state of the microcontroller's registers. The "General purpose / Stack / SREG" section is active, displaying a table of registers (0-31) and their values. Below the table, it shows the PC (Program Counter) at 00007, SPL (Stack Pointer) at 00000000, and SREG (Status Register) at 00000010.
- Control Panel:** A window for configuring the microcontroller's hardware parameters. It includes sliders for Speed (100%), Temp. (25°C), Clock (1.250 MHz), and Micro Idd (201.2 uA). It also features a table for pin configurations (S1, S2, S3) and a section for Kx instances.
- Code Editor:** Shows the assembly code for "hw61.asm". The code includes a setup routine and a main routine. The setup routine initializes registers r16 and r17, and sets the stack pointer. The main routine sets the stack pointer, initializes the stack, and enters a loop.

The assembly code in the Code Editor is as follows:

```
.include "C:\VMLA"

setup:
    clr r16
    clr r17
    ldi r17, 7
    rjmp main

main:
    sbic PIND, 1
    inc r16
    CPSE r16, r17

    sbis PIND, 1
    loop1:
        brne setup
    rjmp main
```

#2 Given: Single 4-bit Johnson counter. Assume the counter is reset to all 0's before the sequence starts.

Find: Design an 8-bit one-hot counter. What would be the problem with trying to build a 16-bit one-hot counter from a single 4-bit Johnson counter?

Solution:

Truth Table

Q_x = output from DFFs (Johnson Counter)

Z_x = 8-bits of the One Hot Counter

State	Q3	Q2	Q1	Q0	Z7	Z6	Z5	Z4	Z3	Z2	Z1	Z0
0	0	0	0	0	1	0	0	0	0	0	0	0
1	1	0	0	0	0	1	0	0	0	0	0	0
2	1	1	0	0	0	0	1	0	0	0	0	0
3	1	1	1	0	0	0	0	1	0	0	0	0
4	1	1	1	1	0	0	0	0	1	0	0	0
5	0	1	1	1	0	0	0	0	0	1	0	0
6	0	0	1	1	0	0	0	0	0	0	1	0
7	0	0	0	1	0	0	0	0	0	0	0	1

Using a state machine solver, we have:

$$Z7 = (Q3' Q0')$$

$$Z6 = (Q3 Q2')$$

$$Z5 = (Q2 Q1')$$

$$Z4 = (Q1 Q0')$$

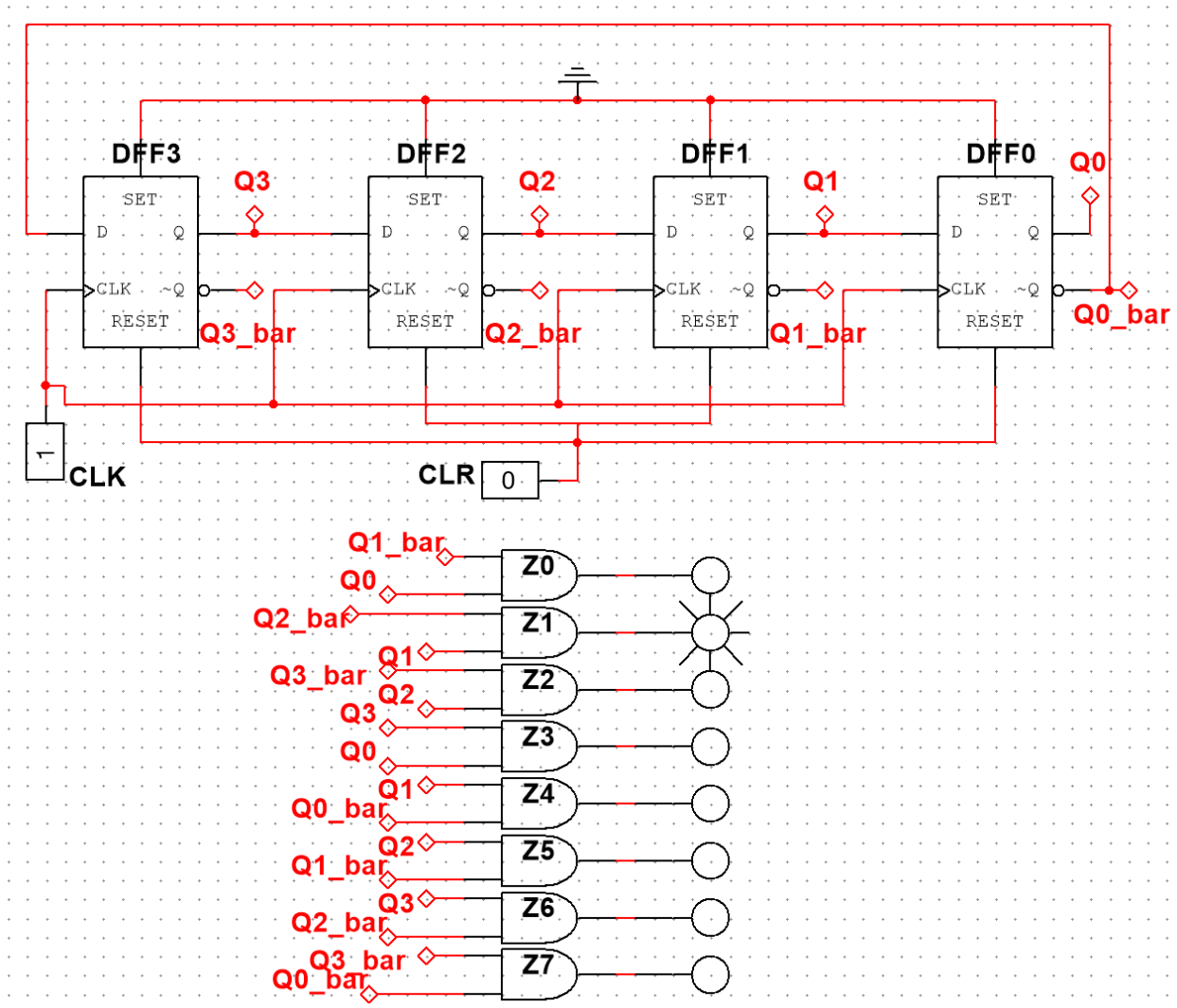
$$Z3 = (Q3 Q0)$$

$$Z2 = (Q3' Q2)$$

$$Z1 = (Q2' Q1)$$

$$Z0 = (Q1' Q0)$$

There is no problem building a 16-bit One Hot Counter from a single 4-bit Johnson Counter. With the Johnson Counter, we have $2^4 = 16$ states, and we need 16 states for each of the 16 bits in the 16-bit One Hot Counter. So there is no problem.



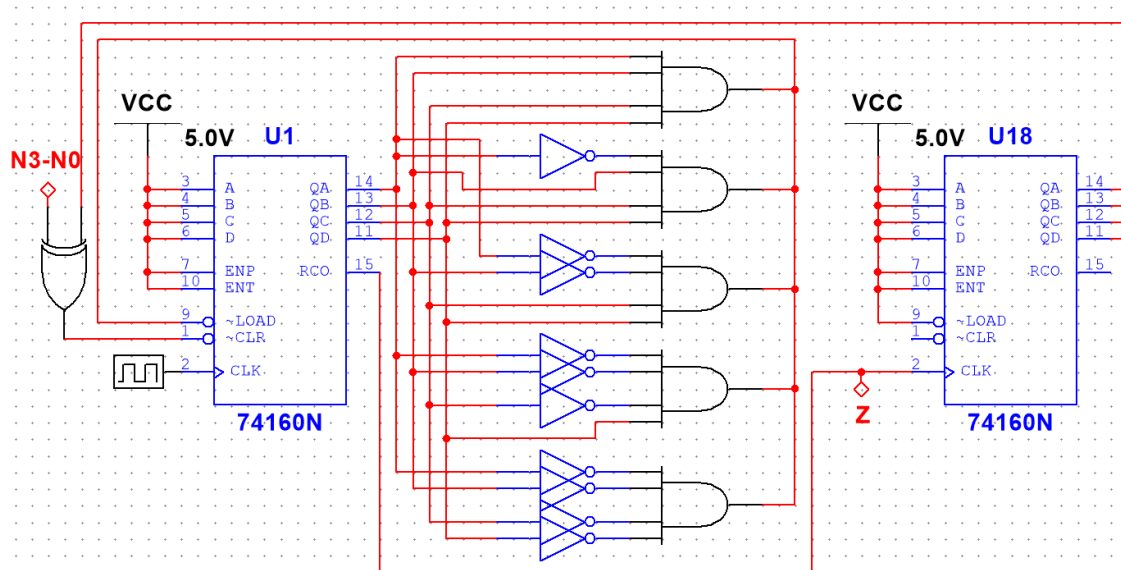
#3 Given: Circuit from Homework 5, #5

Find: Modify this circuit so that Z produces N transitions in each 16-tick interval. The resulting circuit is called a binary rate multiplier and was once sold as a TTL MSI part, the 7497.

Solution:

This is not a “functioning” circuit in Multisim, this is just to display the schematic. You would need a BUS between the outputs of the AND4 gates and the LOAD’ of U1 for it to work properly. I could not get it to work correctly in Multisim, so I just removed the BUS and added this disclaimer.

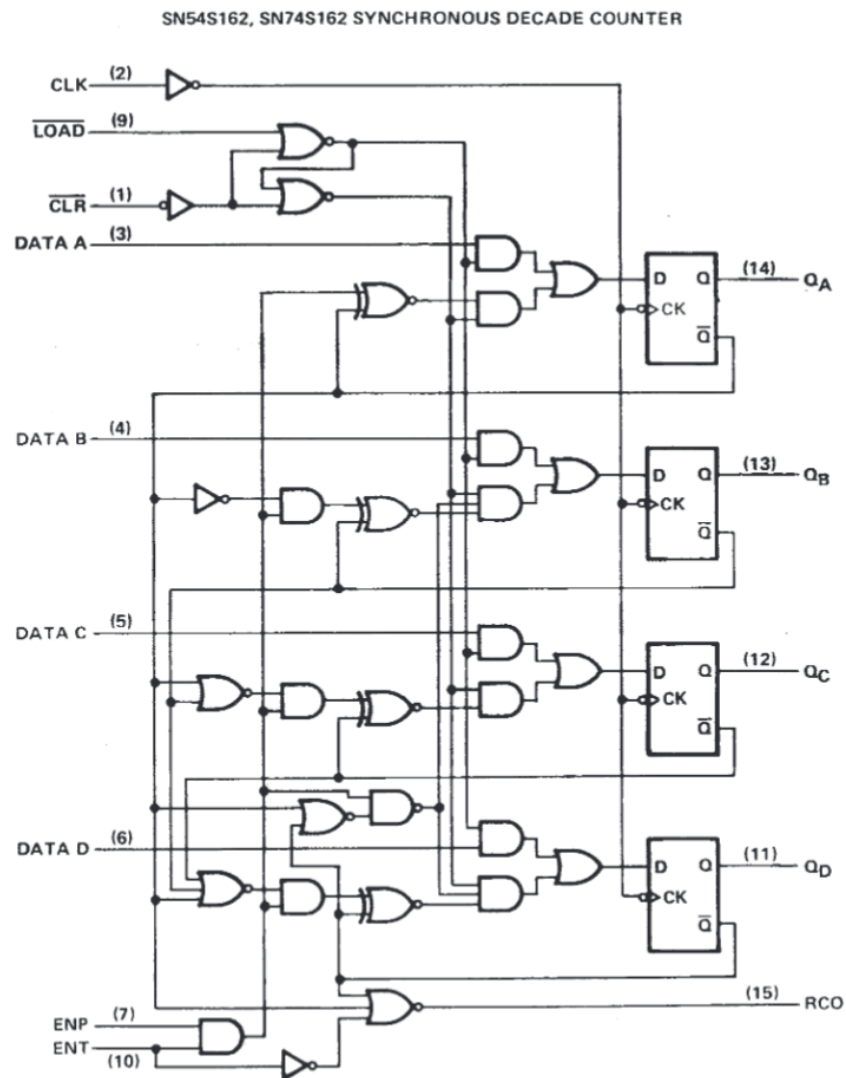
The output Z asserts when the count is 2, 4, 8 and 16. There will be N number of transitions. The second binary counter is being used to count the transitions, and the output Z is not asserted once the values of N3-0 and QD-A are equal. This is how we easily change the circuit so that Z produces N transitions in each 16-tick interval.



#4 Given: Datasheet with the internal logic diagram for a 74162 synchronous decade counter

Find: Write a state table and include its counting behavior in the normally unused states 10-15

Solution: I used this specific synchronous decade counter, the SN54S162



Present State	Next State	Behavior
1000	0100	Normal Count -4
0100	1100	Normal Count +8
1100	0010	Normal Counter -12
0010	1010	Normal Count +8
1010	0110	Normal Count -4
0110	1110	Normal Count +8
1110	0001	Normal Count -13
0001	1001	Normal Count + Ripple Carry Out +8
1001	0000	Normal Count -9
0000	1000	Normal Count +8
0011	x	Invalid State
0101	x	Invalid State
0111	x	Invalid State
1011	x	Invalid State
1101	x	Invalid State
1111	1000	Clear enabled

#5 Given: (From the Wakerly textbook, problems 11.62) Prove that X_0 must appear on the right hand side of any LFSR feedback equation that generates a maximum-length sequence. (*Note:* Assume the LFSR bit ordering and shift direction are as given in the text; that is, the LFSR counter shifts right, toward the X_0 stage.)

Find: Prove that X_0 must appear on the right hand side of any LFSR feedback equation that generates a maximum-length sequence

Solution:

0 in the X_0 spot can signify an invalid state, so we must always consider what is in the X_0 position. Having X_0 on the right side of the LFSR equation equates to always checking if the “first” decimal number is an invalid state or not; if it’s a 0, it is paired with another X_1 -x to ensure it is indeed not an invalid state. Since X_0 is the LSB of the LFSR, it must always be considered to have maximum length, since it denotes the decimal number 1. If you discount this, you will have skipped states without the 1 representation. IE: Taking the 1 out of the right side of the LFSR equation, you would have the states (decimal #) 2, 4, 8, 12, 16, etc.