

I. PART 1: Digging for Details

1. Atomic Motherboards (go boom)

- a. Realtek ALC888
- b. Super IO Winbond W83627DHG
- c. 2 LAN devices
 - i. GbE LAN1: Intel 82567V
 - ii. GbE LAN2: Intel 82583V
- d. 6 serial ports. In the specification section we can see it has 3 rear IO 3 (2 of RS-232, 1 of RS-232/422/485) serial ports. And it also has 3 (RS-232) internal serial ports.

2. Network Noodling

LAN2 Intel 822583V

a.

Signal	Pin
LED0	31
LED1	30
LED2	33

- b. Device Control Register offset - 0x00000 / 0x00004
- c. Bit 26 (400000_hex)

3. Winken, Blinken, and Nod

9.2.2.14 LED Control - LEDCTL (0x00E00; RW)

Field	Bit(s)	Initial Value	Description
LED0_MODE	3:0	0010b ¹	LED0 (LINK_UP_N) Mode This field specifies the control source for the LED0 output. An initial value of 0010b selects LINK_UP indication.
Reserved	4	0b	Reserved Read-only as 0b. Write as 0b for future compatibility.
GLOBAL_BLINK_MODE	5	0b ¹	Global Blink Mode This field specifies the blink mode of all LEDs. 0b = Blink at 200 ms on and 200 ms off. 1b = Blink at 83 ms on and 83 ms off.
LED0_IVRT	6	0b ¹	LED0 (LINK_UP_N) Invert This field specifies the polarity/ inversion of the LED source prior to output or blink control. 0b = Do not invert LED source. 1b = Invert LED source.
LED0_BLINK	7	0b ¹	LED0 (LINK_UP_N) Blink This field specifies whether to apply blink logic to the (inverted) LED control source prior to the LED output. 0b = do not blink asserted LED output. 1b = blink asserted LED output.

a.

LED Control – LEDCTL 0x00E00

b.

LED1_MODE	11:8	0011b ¹	LED1 (ACTIVITY_N) Mode This field specifies the control source for the LED1 output. An initial value of 0011b selects ACTIVITY indication.
1110	LED_ON		Always asserted.
1111	LED_OFF		Always de-asserted.

From the above screenshot we can see we write a 1111-bit pattern to the LED1_MODE register bits 11:8 this will turn off LED1 until we write a 1110 to turn the LED1 back on.

Field	Bit(s)	Initial Value	Description
LED2_MODE	19:16	0110b ¹	LED2 (LINK_100_N) Mode This field specifies the control source for the LED2 output. An initial value of 0110b selects LINK_100 indication.
Reserved	20	0b	Reserved Read-only as 0b. Write as 0b for future compatibility.
LED2_BLINK_MODE	21	0b ¹	LED2 (LINK_100_N) Blink Mode This field needs to be configured with the same value as GLOBAL_BLINK_MODE, it specifies the blink mode of the LED. 0b = Blink at 200 ms on and 200 ms off. 1b = Blink at 83 ms on and 83 ms off.
LED2_IVRT	22	0b ¹	LED2 (LINK_100_N) Invert.
LED2_BLINK	23	0b ¹	LED2 (LINK_100_N) Blink
Reserved	31:24	0x0	Reserved

- c.
- Here we can see we would want to set the LED2_MODE first for constant on we would write 1110 we would then want to set the LED blink mode by writing to LED2_BLINK_MODE bit 21 to set blink timing 1 for 83ms blink and 0 for 200 ms blink then we would write to LED2_BLINK bit 23 and we would write a 1 to turn the led blinking on.

II. PART 2: Make it Blink

Source code, typescript file (attempt3) and makefile are in zipped folder with this document

```

root@Linux-Unbuntu-22:/home/pnevins/Document: Writing 0000000e to the driver to turn on LED0
@0:03 LEDs: . . . . . Writing 0000000f to the driver to turn off LED0
pnevins@Linux-Unbuntu-22:~/Documents/Homework/HW3$ sudo ./userspacehw3
The value from the driver is 0000000f
Writing 0000000e to the driver to turn on LED0
Writing 0000000f to the driver to turn off LED0
pnevins@Linux-Unbuntu-22:~/Documents/Homework/HW3$ sudo ./userspacehw3
The value from the driver is 0000000f
Writing 0000000e to the driver to turn on LED0
Writing 0000000f to the driver to turn off LED0
pnevins@Linux-Unbuntu-22:~/Documents/Homework/HW3$ sudo ./userspacehw3
The value from the driver is 0000000f
Writing 0000000e to the driver to turn on LED0
Writing 0000000f to the driver to turn off LED0
pnevins@Linux-Unbuntu-22:~/Documents/Homework/HW3$ sudo ./userspacehw3

```

Before running userspacehw3 (previous ones were tests)

```

root@Linux-ubuntu-22:/home/pnevins/Documents# ls
hw3_pci_driver.c  hw3_pci_driver.mod.o  led
root@Linux-ubuntu-22:/home/pnevins/Documents# ls
hw3_pci_driver.ko  hw3_pci_driver.o  led
root@Linux-ubuntu-22:/home/pnevins/Documents# cat /sys/class/leds/led0/trigger
00:03 LEDs:  0 . . . . .
pnevins@Linux-ubuntu-22:~/Documents/Homework/HW3$ sudo ./userspacehw3
The value from the driver is 0000000f
Writing 0000000e to the driver to turn on LED0
Writing 0000000f to the driver to turn off LED0
pnevins@Linux-ubuntu-22:~/Documents/Homework/HW3$ sudo ./userspacehw3
The value from the driver is 0000000f
Writing 0000000e to the driver to turn on LED0
Writing 0000000f to the driver to turn off LED0
pnevins@Linux-ubuntu-22:~/Documents/Homework/HW3$ sudo ./userspacehw3
The value from the driver is 0000000f
Writing 0000000e to the driver to turn on LED0
Writing 0000000f to the driver to turn off LED0
pnevins@Linux-ubuntu-22:~/Documents/Homework/HW3$ sudo ./userspacehw3
The value from the driver is 0000000f
Writing 0000000e to the driver to turn on LED0

```

LED signaled on (by the left most 0)

```

root@Linux-ubuntu-22:/home/pnevins/Documents# cat /sys/class/leds/led0/trigger
00:03 LEDs:  . . . . .
pnevins@Linux-ubuntu-22:~/Documents/Homework/HW3$ sudo ./userspacehw3
The value from the driver is 0000000f
Writing 0000000e to the driver to turn on LED0
Writing 0000000f to the driver to turn off LED0
pnevins@Linux-ubuntu-22:~/Documents/Homework/HW3$ sudo ./userspacehw3
The value from the driver is 0000000f
Writing 0000000e to the driver to turn on LED0
Writing 0000000f to the driver to turn off LED0
pnevins@Linux-ubuntu-22:~/Documents/Homework/HW3$ sudo ./userspacehw3
The value from the driver is 0000000f
Writing 0000000e to the driver to turn on LED0
Writing 0000000f to the driver to turn off LED0
pnevins@Linux-ubuntu-22:~/Documents/Homework/HW3$

```

LED off

9.2.2.14 LED Control - LEDCTL (0x00E00; RW)

Field	Bit(s)	Initial Value	Description
LED0_MODE	3:0	0010b ¹	LED0 (LINK_UP_N) Mode This field specifies the control source for the LED0 output. An initial value of 0010b selects LINK_UP indication.
Reserved	4	0b	Reserved Read-only as 0b. Write as 0b for future compatibility.
GLOBAL_BLINK_MODE	5	0b ¹	Global Blink Mode This field specifies the blink mode of all LEDs. 0b = Blink at 200 ms on and 200 ms off. 1b = Blink at 83 ms on and 83 ms off.
LED0_IVRT	6	0b ¹	LED0 (LINK_UP_N) Invert This field specifies the polarity/ inversion of the LED source prior to output or blink control. 0b = Do not invert LED source. 1b = Invert LED source.
LED0_BLINK	7	0b ¹	LED0 (LINK_UP_N) Blink This field specifies whether to apply blink logic to the (inverted) LED control source prior to the LED output. 0b = do not blink asserted LED output. 1b = blink asserted LED output.
LED1_MODE	11:8	0011b ¹	LED1 (ACTIVITY_N) Mode This field specifies the control source for the LED1 output. An initial value of 0011b selects ACTIVITY indication.
Reserved	12	0b	Reserved Read-only as 0b. Write as 0 for future compatibility.
LED1_BLINK_MODE	13	0b ¹	LED1 (ACTIVITY_N) Blink Mode This field needs to be configured with the same value as GLOBAL_BLINK_MODE, it specifies the blink mode of the LED. 0b = Blink at 200 ms on and 200 ms off. 1b = Blink at 83 ms on and 83 ms off.
LED1_IVRT	14	0b ¹	LED1 (ACTIVITY_N) Invert.
LED1_BLINK	15	1b ¹	LED1 (ACTIVITY_N) Blink

Field	Bit(s)	Initial Value	Description
LED2_MODE	19:16	0110b ¹	LED2 (LINK_100_N) Mode This field specifies the control source for the LED2 output. An initial value of 0110b selects LINK_100 indication.
Reserved	20	0b	Reserved Read-only as 0b. Write as 0b for future compatibility.
LED2_BLINK_MODE	21	0b ¹	LED2 (LINK_100_N) Blink Mode This field needs to be configured with the same value as GLOBAL_BLINK_MODE, it specifies the blink mode of the LED. 0b = Blink at 200 ms on and 200 ms off. 1b = Blink at 83 ms on and 83 ms off.
LED2_IVRT	22	0b ¹	LED2 (LINK_100_N) Invert.
LED2_BLINK	23	0b ¹	LED2 (LINK_100_N) Blink
Reserved	31:24	0x0	Reserved

1. These bits are read from the NVM.

The following mapping is used to specify the LED control source (MODE) for each LED output:

MODE	Selected Mode	Source Indication
0000	LINK_10/1000	Asserted when either 10 or 1000 Mb/s link is established and maintained.
0001	LINK_100/1000	Asserted when either 100 or 1000 Mb/s link is established and maintained.
0010	LINK_UP	Asserted when any speed link is established and maintained.
0011	FILTER_ACTIVITY	Asserted when link is established and packets are being transmitted or received that passed MAC filtering.
0100	LINK/ACTIVITY	Asserted when link is established AND when there is NO transmit or receive activity.
0101	LINK_10	Asserted when a 10 Mb/s link is established and maintained.
0110	LINK_100	Asserted when a 100 Mb/s link is established and maintained.
0111	LINK_1000	Asserted when a 1000 Mb/s link is established and maintained.
1000	Reserved	Reserved
1001	FULL_DUPLEX	Asserted when the link is configured for full-duplex operation.
1010	COLLISION	Asserted when a collision is observed.
1011	ACTIVITY	Asserted when link is established and packets are being transmitted or received.
1100	BUS_SIZE	Asserted when the device detects a 1-lane PCIe connection.
1101	PAUSED	Asserted when the device's transmitter is flow controlled.
1110	LED_ON	Always asserted.
1111	LED_OFF	Always de-asserted.

Notes:

- When LED blink mode is enabled the appropriate *LED Invert* bit should be set to zero.
- The dynamic Leds modes (FILTER_ACTIVITY, LINK/ACTIVITY, COLLISION, ACTIVITY, PAUSED) should be used with LED blink mode enabled.
- When LED blink mode is enabled and CCM PLL is shut, the blinking frequencies are 1/5 of the rates stated in the previous table.