



## 1. Description

### 1.1. Project

Project Name	Roboty_Mobilne-STM32_Code
Board Name	NUCLEO-L476RG
Generated with:	STM32CubeMX 6.5.0
Date	05/07/2022

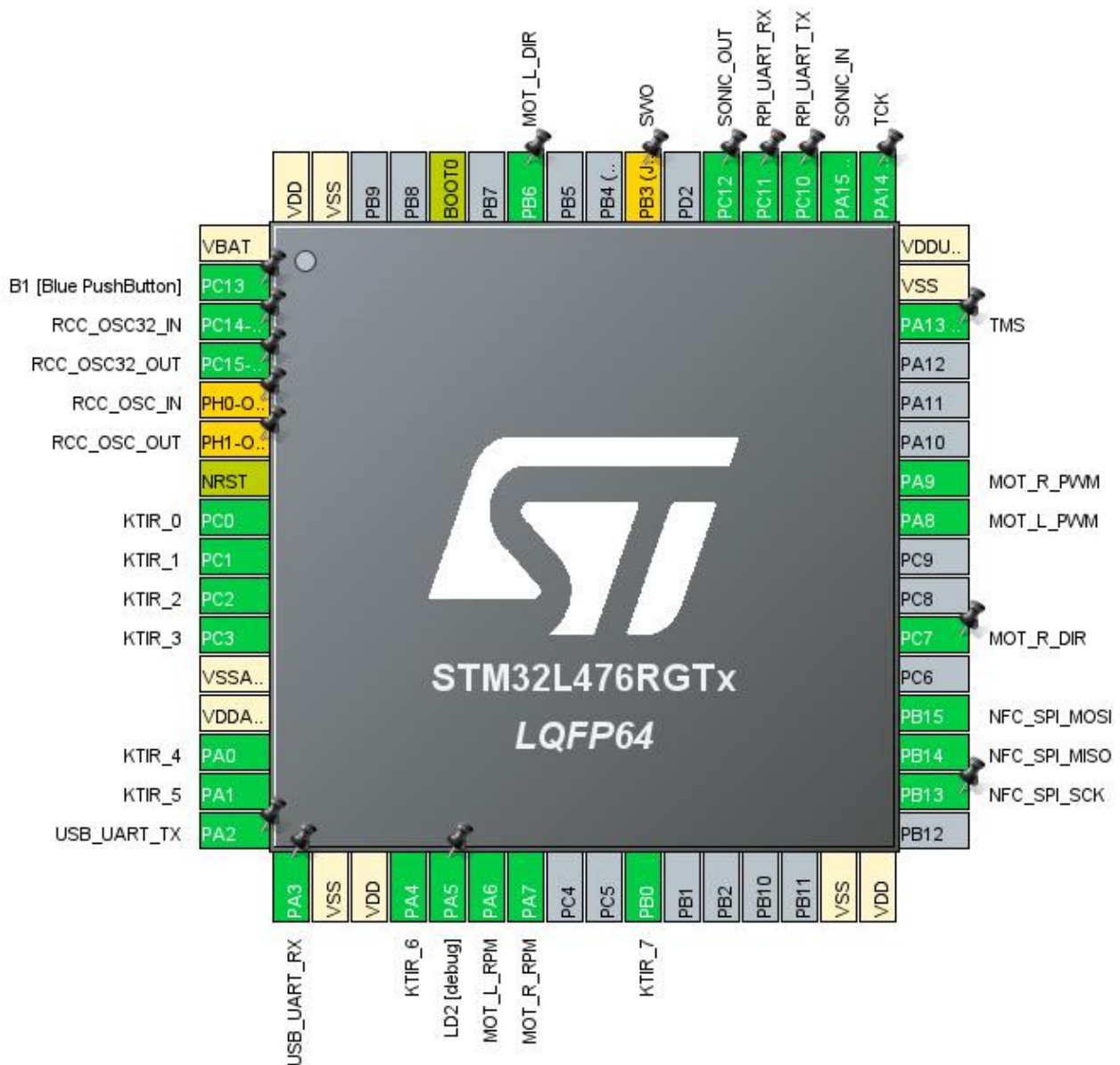
### 1.2. MCU

MCU Series	STM32L4
MCU Line	STM32L4x6
MCU name	STM32L476RGTx
MCU Package	LQFP64
MCU Pin number	64

### 1.3. Core(s) information

Core(s)	Arm Cortex-M4
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## 2. Pinout Configuration



### 3. Pins Configuration

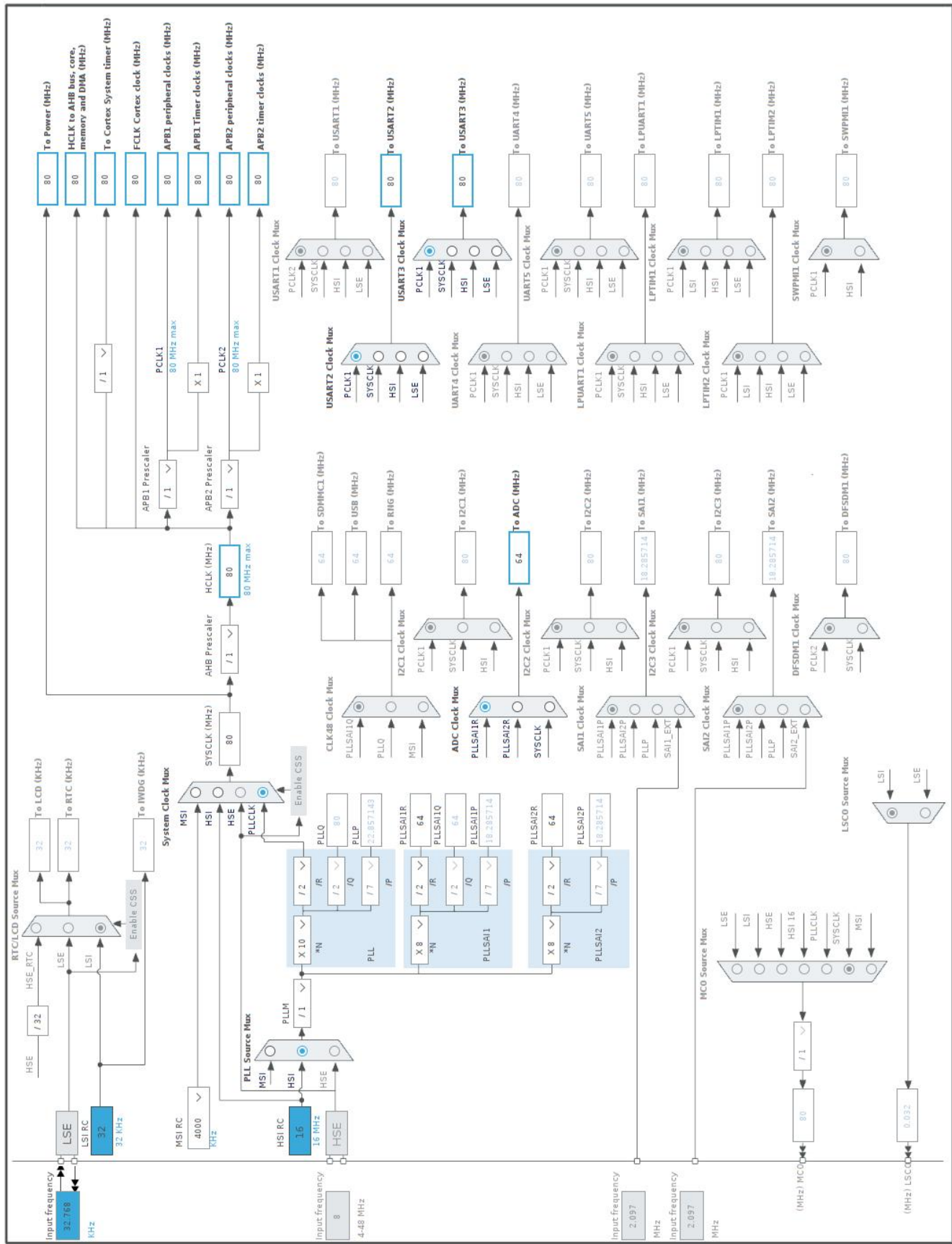
Pin Number LQFP64	Pin Name (function after reset)	Pin Type	Alternate Function(s)	Label
1	VBAT	Power		
2	PC13	I/O	GPIO_EXTI13	B1 [Blue PushButton]
3	PC14-OSC32_IN (PC14)	I/O	RCC_OSC32_IN	
4	PC15-OSC32_OUT (PC15)	I/O	RCC_OSC32_OUT	
5	PH0-OSC_IN (PH0) *	I/O	RCC_OSC_IN	
6	PH1-OSC_OUT (PH1) *	I/O	RCC_OSC_OUT	
7	NRST	Reset		
8	PC0	I/O	ADC1_IN1	KTIR_0
9	PC1	I/O	ADC1_IN2	KTIR_1
10	PC2	I/O	ADC1_IN3	KTIR_2
11	PC3	I/O	ADC1_IN4	KTIR_3
12	VSSA/VREF-	Power		
13	VDDA/VREF+	Power		
14	PA0	I/O	ADC1_IN5	KTIR_4
15	PA1	I/O	ADC1_IN6	KTIR_5
16	PA2	I/O	USART2_TX	USB_UART_TX
17	PA3	I/O	USART2_RX	USB_UART_RX
18	VSS	Power		
19	VDD	Power		
20	PA4	I/O	ADC1_IN9	KTIR_6
21	PA5 **	I/O	GPIO_Output	LD2 [debug]
22	PA6	I/O	TIM3_CH1	MOT_L_RPM
23	PA7	I/O	TIM3_CH2	MOT_R_RPM
26	PB0	I/O	ADC1_IN15	KTIR_7
31	VSS	Power		
32	VDD	Power		
34	PB13	I/O	SPI2_SCK	NFC_SPI_SCK
35	PB14	I/O	SPI2_MISO	NFC_SPI_MISO
36	PB15	I/O	SPI2_MOSI	NFC_SPI_MOSI
38	PC7 **	I/O	GPIO_Output	MOT_R_DIR
41	PA8	I/O	TIM1_CH1	MOT_L_PWM
42	PA9	I/O	TIM1_CH2	MOT_R_PWM
46	PA13 (JTMS-SWDIO)	I/O	SYS_JTMS-SWDIO	TMS
47	VSS	Power		
48	VDDUSB	Power		
49	PA14 (JTCK-SWCLK)	I/O	SYS_JTCK-SWCLK	TCK

Pin Number LQFP64	Pin Name (function after reset)	Pin Type	Alternate Function(s)	Label
50	PA15 (JTDI)	I/O	TIM2_CH1	SONIC_IN
51	PC10	I/O	USART3_TX	RPI_UART_TX
52	PC11	I/O	USART3_RX	RPI_UART_RX
53	PC12 **	I/O	GPIO_Output	SONIC_OUT
55	PB3 (JTDO-TRACESWO) *	I/O	SYS_JTDO-SWO	SWO
58	PB6 **	I/O	GPIO_Output	MOT_L_DIR
60	BOOT0	Boot		
63	VSS	Power		
64	VDD	Power		

\*\* The pin is affected with an I/O function

\* The pin is affected with a peripheral function but no peripheral mode is activated

## 4. Clock Tree Configuration



## 5. Software Project

### 5.1. Project Settings

Name	Value
Project Name	Roboty_Mobilne-STM32_Code
Project Folder	/home/dstronaut/Documents/Projects/Roboty_Mobilne/Roboty_Mobilne-
Toolchain / IDE	STM32CubeIDE
Firmware Package Name and Version	STM32Cube FW_L4 V1.17.2
Application Structure	Advanced
Generate Under Root	Yes
Do not generate the main()	No
Minimum Heap Size	0x200
Minimum Stack Size	0x400

### 5.2. Code Generation Settings

Name	Value
STM32Cube MCU packages and embedded software	Copy only the necessary library files
Generate peripheral initialization as a pair of '.c/.h' files	No
Backup previously generated files when re-generating	No
Keep User Code when re-generating	Yes
Delete previously generated files when not re-generated	Yes
Set all free pins as analog (to optimize the power consumption)	No
Enable Full Assert	No

### 5.3. Advanced Settings - Generated Function Calls

Rank	Function Name	Peripheral Instance Name
1	MX_GPIO_Init	GPIO
2	SystemClock_Config	RCC
3	MX_USART2_UART_Init	USART2
4	MX_TIM1_Init	TIM1
5	MX_TIM3_Init	TIM3
6	MX_ADC1_Init	ADC1
7	MX_USART3_UART_Init	USART3
8	MX_SPI2_Init	SPI2
9	MX_TIM2_Init	TIM2





## 6. Power Consumption Calculator report

### 6.1. Microcontroller Selection

Series	STM32L4
Line	STM32L4x6
MCU	STM32L476RGTx
Datasheet	DS10198_Rev4

### 6.2. Parameter Selection

Temperature	25
Vdd	3.0

### 6.3. Battery Selection

Battery	Li-SOCL2(A3400)
Capacity	3400.0 mAh
Self Discharge	0.08 %/month
Nominal Voltage	3.6 V
Max Cont Current	100.0 mA
Max Pulse Current	200.0 mA
Cells in series	1
Cells in parallel	1

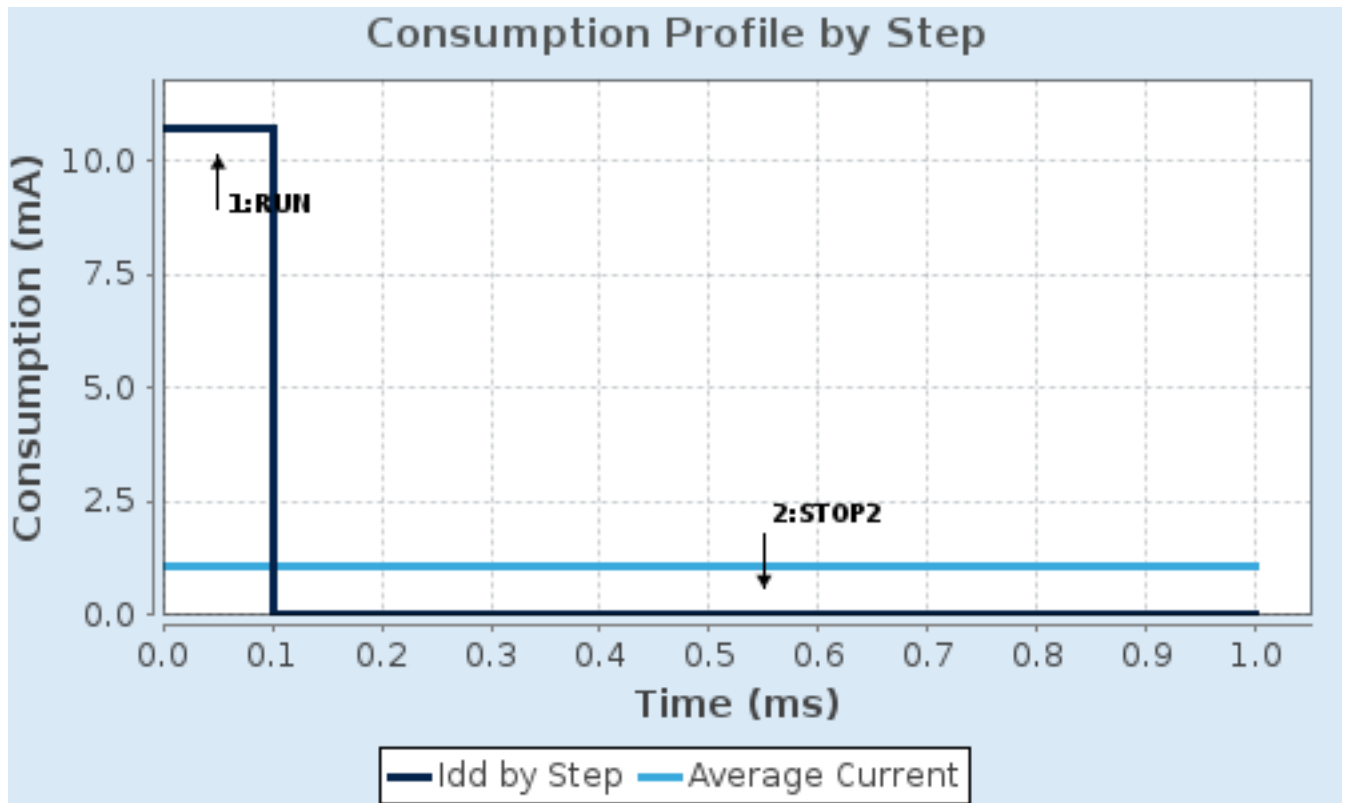
#### 6.4. Sequence

<b>Step</b>	Step1	Step2
<b>Mode</b>	RUN	STOP2
<b>Vdd</b>	3.0	3.0
<b>Voltage Source</b>	Battery	Battery
<b>Range</b>	Range1-High	NoRange
<b>Fetch Type</b>	SRAM2	n/a
<b>CPU Frequency</b>	80 MHz	0 Hz
<b>Clock Configuration</b>	HSE PLL	ALL CLOCKS OFF
<b>Clock Source Frequency</b>	4 MHz	0 Hz
<b>Peripherals</b>		
<b>Additional Cons.</b>	0 mA	0 mA
<b>Average Current</b>	10.7 mA	1.18 $\mu$ A
<b>Duration</b>	0.1 ms	0.9 ms
<b>DMIPS</b>	100.0	0.0
<b>Ta Max</b>	103.56	105
<b>Category</b>	In DS Table	In DS Table

#### 6.5. Results

Sequence Time	1 ms	Average Current	1.07 mA
Battery Life	4 months, 10 days, 3 hours	Average DMIPS	100.0 DMIPS

#### 6.6. Chart



## 7. Peripherals and Middlewares Configuration

### 7.1. ADC1

**IN1: IN1 Single-ended**

**IN2: IN2 Single-ended**

**IN3: IN3 Single-ended**

**IN4: IN4 Single-ended**

**IN5: IN5 Single-ended**

**IN6: IN6 Single-ended**

**IN9: IN9 Single-ended**

**IN15: IN15 Single-ended**

#### 7.1.1. Parameter Settings:

##### **ADCs\_Common\_Settings:**

Mode Independent mode

##### **ADC\_Settings:**

Clock Prescaler Asynchronous clock mode divided by 1

Resolution ADC 12-bit resolution

Data Alignment Right alignment

Scan Conversion Mode Enabled

Continuous Conversion Mode Disabled

Discontinuous Conversion Mode Disabled

DMA Continuous Requests Disabled

End Of Conversion Selection End of single conversion

Overrun behaviour Overrun data preserved

Low Power Auto Wait Disabled

##### **ADC\_Regular\_ConversionMode:**

Enable Regular Conversions Enable

Enable Regular Oversampling Disable

Number Of Conversion **8 \***

External Trigger Conversion Source Regular Conversion launched by software

External Trigger Conversion Edge None

Rank 1

Channel Channel 1

Sampling Time 2.5 Cycles

Offset Number No offset

Rank **2 \***

Channel **Channel 2 \***

Sampling Time 2.5 Cycles

Offset Number No offset

<u>Rank</u>	<b>3 *</b>
Channel	<b>Channel 3 *</b>
Sampling Time	2.5 Cycles
Offset Number	No offset
<u>Rank</u>	<b>4 *</b>
Channel	<b>Channel 4 *</b>
Sampling Time	2.5 Cycles
Offset Number	No offset
<u>Rank</u>	<b>5 *</b>
Channel	<b>Channel 5 *</b>
Sampling Time	2.5 Cycles
Offset Number	No offset
<u>Rank</u>	<b>6 *</b>
Channel	<b>Channel 6 *</b>
Sampling Time	2.5 Cycles
Offset Number	No offset
<u>Rank</u>	<b>7 *</b>
Channel	<b>Channel 9 *</b>
Sampling Time	2.5 Cycles
Offset Number	No offset
<u>Rank</u>	<b>8 *</b>
Channel	<b>Channel 15 *</b>
Sampling Time	2.5 Cycles
Offset Number	No offset
<b>ADC_Injected_ConversionMode:</b>	
Enable Injected Conversions	Disable
<b>Analog Watchdog 1:</b>	
Enable Analog WatchDog1 Mode	false
<b>Analog Watchdog 2:</b>	
Enable Analog WatchDog2 Mode	false
<b>Analog Watchdog 3:</b>	
Enable Analog WatchDog3 Mode	false

## 7.2. RCC

### Low Speed Clock (LSE) : Crystal/Ceramic Resonator

#### 7.2.1. Parameter Settings:

### System Parameters:

VDD voltage (V)	3.3
Instruction Cache	Enabled
Prefetch Buffer	<b>Enabled *</b>
Data Cache	Enabled
Flash Latency(WS)	4 WS (5 CPU cycle)

### RCC Parameters:

HSI Calibration Value	16
MSI Calibration Value	0
MSI Auto Calibration	Disabled
HSE Startup Timeout Value (ms)	100
LSE Startup Timeout Value (ms)	5000

### Power Parameters:

Power Regulator Voltage Scale	Power Regulator Voltage Scale 1
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## 7.3. SPI2

### Mode: Full-Duplex Master

#### 7.3.1. Parameter Settings:

### Basic Parameters:

Frame Format	Motorola
Data Size	4 Bits
First Bit	MSB First

### Clock Parameters:

Prescaler (for Baud Rate)	2
Baud Rate	<b>40.0 MBits/s *</b>
Clock Polarity (CPOL)	Low
Clock Phase (CPHA)	1 Edge

### Advanced Parameters:

CRC Calculation	Disabled
NSSP Mode	Enabled
NSS Signal Type	Software

## 7.4. SYS

### Debug: Serial Wire

## Timebase Source: SysTick

### 7.5. TIM1

**Clock Source : Internal Clock**

**Channel1: PWM Generation CH1**

**Channel2: PWM Generation CH2**

#### 7.5.1. Parameter Settings:

##### Counter Settings:

Prescaler (PSC - 16 bits value)	0
Counter Mode	Up
Counter Period (AutoReload Register - 16 bits value )	65535
Internal Clock Division (CKD)	No Division
Repetition Counter (RCR - 8 bits value)	0
auto-reload preload	Disable

##### Trigger Output (TRGO) Parameters:

Master/Slave Mode (MSM bit)	Disable (Trigger input effect not delayed)
Trigger Event Selection TRGO	Reset (UG bit from TIMx_EGR)
Trigger Event Selection TRGO2	Reset (UG bit from TIMx_EGR)

##### Break And Dead Time management - BRK Configuration:

BRK State	Disable
BRK Polarity	High
BRK Filter (4 bits value)	0
BRK Sources Configuration	
- Digital Input	Disable
- COMP1	Disable
- COMP2	Disable
- DFSDM	Disable

##### Break And Dead Time management - BRK2 Configuration:

BRK2 State	Disable
BRK2 Polarity	High
BRK2 Filter (4 bits value)	0
BRK2 Sources Configuration	
- Digital Input	Disable
- COMP1	Disable
- COMP2	Disable
- DFSDM	Disable

##### Break And Dead Time management - Output Configuration:

Automatic Output State	Disable
Off State Selection for Run Mode (OSSR)	Disable

Off State Selection for Idle Mode (OSSI)	Disable
Lock Configuration	Off

**Clear Input:**

Clear Input Source	Disable
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**PWM Generation Channel 1:**

Mode	PWM mode 1
Pulse (16 bits value)	0
Output compare preload	Enable
Fast Mode	Disable
CH Polarity	High
CH Idle State	Reset

**PWM Generation Channel 2:**

Mode	PWM mode 1
Pulse (16 bits value)	0
Output compare preload	Enable
Fast Mode	Disable
CH Polarity	High
CH Idle State	Reset

## 7.6. TIM2

### Channel1: Input Capture direct mode

#### 7.6.1. Parameter Settings:

**Counter Settings:**

Prescaler (PSC - 16 bits value)	0
Counter Mode	Up
Counter Period (AutoReload Register - 32 bits value )	4294967295
Internal Clock Division (CKD)	No Division
auto-reload preload	Disable

**Trigger Output (TRGO) Parameters:**

Master/Slave Mode (MSM bit)	Disable (Trigger input effect not delayed)
Trigger Event Selection TRGO	Reset (UG bit from TIMx_EGR)

**Input Capture Channel 1:**

Polarity Selection	Rising Edge
IC Selection	Direct
Prescaler Division Ratio	No division
Input Filter (4 bits value)	0



## 7.7. TIM3

**Clock Source : Internal Clock**

**Channel1: Input Capture direct mode**

**Channel2: Input Capture direct mode**

### 7.7.1. Parameter Settings:

#### **Counter Settings:**

Prescaler (PSC - 16 bits value)	0
Counter Mode	Up
Counter Period (AutoReload Register - 16 bits value )	65535
Internal Clock Division (CKD)	No Division
auto-reload preload	Disable

#### **Trigger Output (TRGO) Parameters:**

Master/Slave Mode (MSM bit)	Disable (Trigger input effect not delayed)
Trigger Event Selection TRGO	Reset (UG bit from TIMx_EGR)

#### **Input Capture Channel 1:**

Polarity Selection	Rising Edge
IC Selection	Direct
Prescaler Division Ratio	No division
Input Filter (4 bits value)	0

#### **Input Capture Channel 2:**

Polarity Selection	Rising Edge
IC Selection	Direct
Prescaler Division Ratio	No division
Input Filter (4 bits value)	0

## 7.8. USART2

**Mode: Asynchronous**

### 7.8.1. Parameter Settings:

#### **Basic Parameters:**

Baud Rate	115200
Word Length	8 Bits (including Parity)
Parity	None
Stop Bits	1

#### **Advanced Parameters:**

Data Direction	Receive and Transmit
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Over Sampling	16 Samples
Single Sample	Disable

**Advanced Features:**

Auto Baudrate	Disable
TX Pin Active Level Inversion	Disable
RX Pin Active Level Inversion	Disable
Data Inversion	Disable
TX and RX Pins Swapping	Disable
Overrun	Enable
DMA on RX Error	Enable
MSB First	Disable

## 7.9. USART3

### Mode: Asynchronous

#### 7.9.1. Parameter Settings:

**Basic Parameters:**

Baud Rate	115200
Word Length	8 Bits (including Parity)
Parity	None
Stop Bits	1

**Advanced Parameters:**

Data Direction	Receive and Transmit
Over Sampling	16 Samples
Single Sample	Disable

**Advanced Features:**

Auto Baudrate	Disable
TX Pin Active Level Inversion	Disable
RX Pin Active Level Inversion	Disable
Data Inversion	Disable
TX and RX Pins Swapping	Disable
Overrun	Enable
DMA on RX Error	Enable
MSB First	Disable

\* User modified value

## 8. System Configuration

### 8.1. GPIO configuration

IP	Pin	Signal	GPIO mode	GPIO pull/up pull down	Max Speed	User Label
ADC1	PC0	ADC1_IN1	Analog mode for ADC conversion	No pull-up and no pull-down	n/a	KTIR_0
	PC1	ADC1_IN2	Analog mode for ADC conversion	No pull-up and no pull-down	n/a	KTIR_1
	PC2	ADC1_IN3	Analog mode for ADC conversion	No pull-up and no pull-down	n/a	KTIR_2
	PC3	ADC1_IN4	Analog mode for ADC conversion	No pull-up and no pull-down	n/a	KTIR_3
	PA0	ADC1_IN5	Analog mode for ADC conversion	No pull-up and no pull-down	n/a	KTIR_4
	PA1	ADC1_IN6	Analog mode for ADC conversion	No pull-up and no pull-down	n/a	KTIR_5
	PA4	ADC1_IN9	Analog mode for ADC conversion	No pull-up and no pull-down	n/a	KTIR_6
	PB0	ADC1_IN15	Analog mode for ADC conversion	No pull-up and no pull-down	n/a	KTIR_7
RCC	PC14-OSC32_IN (PC14)	RCC_OSC32_IN	n/a	n/a	n/a	
	PC15-OSC32_OUT (PC15)	RCC_OSC32_OUT	n/a	n/a	n/a	
SPI2	PB13	SPI2_SCK	Alternate Function Push Pull	No pull-up and no pull-down	Very High *	NFC_SPI_SCK
	PB14	SPI2_MISO	Alternate Function Push Pull	No pull-up and no pull-down	Very High *	NFC_SPI_MISO
	PB15	SPI2_MOSI	Alternate Function Push Pull	No pull-up and no pull-down	Very High *	NFC_SPI_MOSI
SYS	PA13 (JTMS-SWDIO)	SYS_JTMS-SWDIO	n/a	n/a	n/a	TMS
	PA14 (JTCK-SWCLK)	SYS_JTCK-SWCLK	n/a	n/a	n/a	TCK
TIM1	PA8	TIM1_CH1	Alternate Function Push Pull	No pull-up and no pull-down	Low	MOT_L_PWM
	PA9	TIM1_CH2	Alternate Function Push Pull	No pull-up and no pull-down	Low	MOT_R_PWM
TIM2	PA15 (JTDI)	TIM2_CH1	Alternate Function Push Pull	No pull-up and no pull-down	Low	SONIC_IN
TIM3	PA6	TIM3_CH1	Alternate Function Push Pull	No pull-up and no pull-down	Low	MOT_L_RPM
	PA7	TIM3_CH2	Alternate Function Push Pull	No pull-up and no pull-down	Low	MOT_R_RPM
USART2	PA2	USART2_TX	Alternate Function Push Pull	No pull-up and no pull-down		USB_UART_TX

IP	Pin	Signal	GPIO mode	GPIO pull/up pull down	Max Speed	User Label
					<b>Very High</b> *	
	PA3	USART2_RX	Alternate Function Push Pull	No pull-up and no pull-down	<b>Very High</b> *	USB_UART_RX
USART3	PC10	USART3_TX	Alternate Function Push Pull	No pull-up and no pull-down	<b>Very High</b> *	RPI_UART_TX
	PC11	USART3_RX	Alternate Function Push Pull	No pull-up and no pull-down	<b>Very High</b> *	RPI_UART_RX
Single Mapped Signals	PH0-OSC_IN (PH0)	RCC_OSC_IN	n/a	n/a	n/a	
	PH1-OSC_OUT (PH1)	RCC_OSC_OUT	n/a	n/a	n/a	
	PB3 (JTDO-TRACESWO)	SYS_JTDO-SWO	n/a	n/a	n/a	SWO
GPIO	PC13	GPIO_EXTI13	<b>External Interrupt Mode with Falling edge trigger detection</b>	No pull-up and no pull-down	n/a	B1 [Blue PushButton]
	PA5	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	LD2 [debug]
	PC7	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	MOT_R_DIR
	PC12	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	SONIC_OUT
	PB6	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	MOT_L_DIR

## 8.2. DMA configuration

nothing configured in DMA service

## 8.3. NVIC configuration

### 8.3.1. NVIC

Interrupt Table	Enable	Preenmption Priority	SubPriority
Non maskable interrupt	true	0	0
Hard fault interrupt	true	0	0
Memory management fault	true	0	0
Prefetch fault, memory access fault	true	0	0
Undefined instruction or illegal state	true	0	0
System service call via SWI instruction	true	0	0
Debug monitor	true	0	0
Pendable request for system service	true	0	0
System tick timer	true	0	0
PVD/PVM1/PVM2/PVM3/PVM4 interrupts through EXTI lines 16/35/36/37/38	unused		
Flash global interrupt	unused		
RCC global interrupt	unused		
ADC1 and ADC2 interrupts	unused		
TIM1 break interrupt and TIM15 global interrupt	unused		
TIM1 update interrupt and TIM16 global interrupt	unused		
TIM1 trigger and commutation interrupts and TIM17 global interrupt	unused		
TIM1 capture compare interrupt	unused		
TIM2 global interrupt	unused		
TIM3 global interrupt	unused		
SPI2 global interrupt	unused		
USART2 global interrupt	unused		
USART3 global interrupt	unused		
EXTI line[15:10] interrupts	unused		
FPU global interrupt	unused		

### 8.3.2. NVIC Code generation

Enabled interrupt Table	Select for init sequence ordering	Generate IRQ handler	Call HAL handler
Non maskable interrupt	false	true	false
Hard fault interrupt	false	true	false
Memory management fault	false	true	false
Prefetch fault, memory access fault	false	true	false
Undefined instruction or illegal state	false	true	false
System service call via SWI instruction	false	true	false
Debug monitor	false	true	false

Enabled interrupt Table	Select for init sequence ordering	Generate IRQ handler	Call HAL handler
Pendable request for system service	false	true	false
System tick timer	false	true	true

\* User modified value

## 9. System Views

### 9.1. Category view

#### 9.1.1. Current

Middleware						
System Core	Analog	Timers	Connectivity	Multimedia	Security	Computing
DMA	ADC1 ✓	TIM1 ✓	SPI2 ✓			
GPIO ⚠		TIM2 ✓	USART2 ✓			
NVIC ✓		TIM3 ✓	USART3 ✓			
RCC ✓						
SYS ✓						

## 10. Docs & Resources

Type	Link
Presentations	<a href="https://www.st.com/resource/en/product_presentation/stm32-stm8_embedded_software_solutions.pdf">https://www.st.com/resource/en/product_presentation/stm32-stm8_embedded_software_solutions.pdf</a>
Presentations	<a href="https://www.st.com/resource/en/product_presentation/stm32_eval-tools_portfolio.pdf">https://www.st.com/resource/en/product_presentation/stm32_eval-tools_portfolio.pdf</a>
Presentations	<a href="https://www.st.com/resource/en/product_presentation/stm32_stm8_functional-safety-packages.pdf">https://www.st.com/resource/en/product_presentation/stm32_stm8_functional-safety-packages.pdf</a>
Presentations	<a href="https://www.st.com/resource/en/product_presentation/stm32l4_marketing-pres.pdf">https://www.st.com/resource/en/product_presentation/stm32l4_marketing-pres.pdf</a>
Presentations	<a href="https://www.st.com/resource/en/product_presentation/stm32-stm8_software_development_tools.pdf">https://www.st.com/resource/en/product_presentation/stm32-stm8_software_development_tools.pdf</a>
Training Material	<a href="https://www.st.com/resource/en/sales_guide/sg_sc2157.pdf">https://www.st.com/resource/en/sales_guide/sg_sc2157.pdf</a>
Flyers	<a href="https://www.st.com/resource/en/flyer/flnucleolrwan.pdf">https://www.st.com/resource/en/flyer/flnucleolrwan.pdf</a>
Flyers	<a href="https://www.st.com/resource/en/flyer/flstm32l4.pdf">https://www.st.com/resource/en/flyer/flstm32l4.pdf</a>
Flyers	<a href="https://www.st.com/resource/en/flyer/flstm32nucleo.pdf">https://www.st.com/resource/en/flyer/flstm32nucleo.pdf</a>
Flyers	<a href="https://www.st.com/resource/en/flyer/flstmcsuite.pdf">https://www.st.com/resource/en/flyer/flstmcsuite.pdf</a>
Flyers	<a href="https://www.st.com/resource/en/flyer/flstm32trust.pdf">https://www.st.com/resource/en/flyer/flstm32trust.pdf</a>
Magazine Articles	<a href="https://www.st.com/resource/en/magazine/design-elektronik_august2017.pdf">https://www.st.com/resource/en/magazine/design-elektronik_august2017.pdf</a>
Magazine Articles	<a href="https://www.st.com/resource/en/magazine/design-elektronik_october2016.pdf">https://www.st.com/resource/en/magazine/design-elektronik_october2016.pdf</a>
Product Certifications	<a href="https://www.st.com/resource/en/certification_document/sesip-2000002-01-cert.pdf">https://www.st.com/resource/en/certification_document/sesip-2000002-01-cert.pdf</a>
Product Certifications	<a href="https://www.st.com/resource/en/certification_document/sesip-2000002-01-st2.pdf">https://www.st.com/resource/en/certification_document/sesip-2000002-01-st2.pdf</a>
Product Certifications	<a href="https://www.st.com/resource/en/certification_document/psa-certificate_stm32l4.pdf">https://www.st.com/resource/en/certification_document/psa-certificate_stm32l4.pdf</a>
Application Notes	<a href="https://www.st.com/resource/en/application_note/an1181-electrostatic-discharge-sensitivity-measurement-stmicroelectronics.pdf">https://www.st.com/resource/en/application_note/an1181-electrostatic-discharge-sensitivity-measurement-stmicroelectronics.pdf</a>
Application Notes	<a href="https://www.st.com/resource/en/application_note/an1709-emc-design-">https://www.st.com/resource/en/application_note/an1709-emc-design-</a>



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