

# Nikolas "Dax" Manuel

CANADIAN CITIZEN

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## EDUCATION

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### University of New Brunswick

Fredericton, NB

*B. S. Software Engineering (Co-op), Minor in Mathematics*

*Sep 2024 – Apr 2028*

- **Relevant Coursework:** Electrical Circuits, Data Structures & Algorithms, Software Engineering, System Design.

## TECHNICAL SKILLS

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**Languages:** C/C++, Python, Java, JavaScript, SQL

**Frameworks/Libraries:** Spring Boot, PyTorch, NumPy, Pandas

**Developer/Engineering Tools:** Git, AWS, Google Cloud Platform, Postman, Docker, Linux, Jira

## EXPERIENCE

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### UNB EV Formula Racing

Sep 2025 – Present

*Electrical Member*

*Fredericton, NB*

- Designed a PCB schematic to integrate with a potentiometer as an acceleration pedal position sensor to implement into the low-voltage system with the vehicle control unit.
- Authored technical documentation for the APPS system integration to enable team knowledge transfer and long-term maintainability.
- Working on wiring harness research/implementation to ensure reliable signal transmission across the low-voltage system.

### Intelligent Mobility and Robotics Lab

Feb 2026 – Present

*Research Assistant*

*Fredericton, NB*

- Contributing to computer vision research for safe speed estimation in semi-autonomous trucks in varying road and weather conditions using machine learning.
- Processing and annotating autonomous driving datasets to prepare for training computer vision based models.

## PROJECTS

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### Neural Network From Scratch in C | [GitHub](#)

- Built a neural network handwritten digit classifier with the MNIST dataset in C achieving **98% accuracy**.
- Implemented matrix operations, back-propagation, gradient descent, and Relu + Softmax activation functions.
- Designed dynamic memory allocation for neural network tensors and matrices to eliminate memory leaks.

### Vehicle Perception Model | [GitHub](#)

- Implemented PointPillars architecture for 3D object detection from LiDAR point clouds, building complete pipeline from data preprocessing to bounding box prediction with visualization.
- Preprocessed **150,000+** LiDAR frames from the Waymo Open Dataset, converting Parquet formatted data into NumPy arrays for neural network training in **PyTorch**.
- Reduced training time by **75%** by leveraging **AWS EC2** instances to perform scalable training.

### HR System | CS2043 Term Project

- Led a group of four as scrum master, to build a full stack application integrating **RESTful API** architecture with **Spring Boot/Java**, JavaScript, and PostgreSQL, following Agile methodology.
- Designed **PostgreSQL** relational database schemas and API endpoints to support scalable complex queries.
- Managed tasks and sprint planning using Jira by organizing backlog items and tracking sprint progress.
- Implemented unit tests with JUnit and Postman to validate RESTful API ensuring correct request handling and responses for software validation and performed debugging, slashing errors by **99%**.