

Nº 1 ENTRADA $\Rightarrow \frac{V_i(s) - V_o(s)}{1}$

SABEM $\Rightarrow \frac{V_o}{s} + \frac{V_o}{2}$

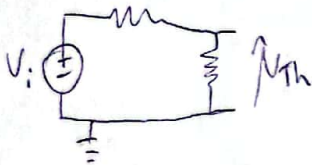
$$\left. \begin{aligned} V_i(s) - V_o(s) &= \frac{V_o}{s} + \frac{V_o}{2} \\ V_i(s) &= V_o(s) \left(\frac{1}{s} + \frac{1}{2} + 1 \right) \end{aligned} \right\}$$

$$\frac{V_i(s)}{V_o(s)} = \frac{2s}{3s+2}$$

$$G(s) = \frac{V_o(s)}{V_i(s)}$$

$$G(s) = \frac{2s}{3s+2}$$

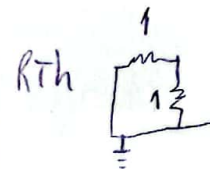
V_{Th}



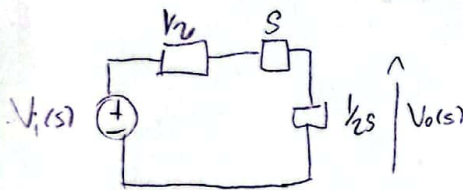
$$V_i(s) - 2i = 0$$

$$i = \frac{V_i(s)}{2}$$

$$V_{Th} = \frac{V_i(s)}{2}$$

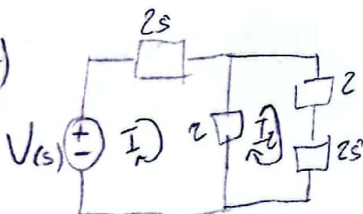


$$R_{Th} = R_{eq} = \frac{1}{2} \Omega$$



$$V_o(s) = \frac{V_i(s)}{2} \cdot \frac{1}{\frac{1}{2} + s + \frac{1}{2s}} = V_i(s) \cdot \frac{1}{2} \cdot \frac{2s}{s + 2s^2 + 1} = \frac{1}{4s^2 + 2s + 2} \Rightarrow G(s) = \frac{1}{4s^2 + 2s + 2}$$

18/a)

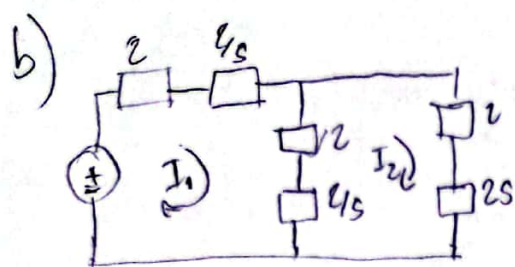


$$V_i(s) = 2s \cdot I_2$$

$$\begin{bmatrix} V_i(s) \\ 0 \end{bmatrix} = \begin{bmatrix} 2s+2 & -2 \\ -2 & 4+2s \end{bmatrix} \cdot \begin{bmatrix} I_1 \\ I_2 \end{bmatrix}$$

$$I_2 = \frac{\begin{bmatrix} 2s+2 & V_i(s) \\ -2 & 0 \end{bmatrix}}{\begin{bmatrix} 2s+2 & -2 \\ -2 & 4s+2 \end{bmatrix}} \Rightarrow I_2 = \frac{2V_i(s)}{(2s+2)(4s+2) - 4} = \frac{2V_i(s)}{8s^2 + 4s + 8s + 4 - 4} = \frac{2V_i(s)}{2s(4s+6)} \Rightarrow$$

$$\Rightarrow \underbrace{I_2 \cdot 2s}_{V_L(s)} = \frac{2V(s)}{8(2s+3)} \Rightarrow V_L(s) = \frac{V(s)}{2s+3} \Rightarrow G(s) = \frac{1}{2s+3}$$



$$G(s) = \frac{V_L(s)}{V(s)}$$

$$V_L(s) = 2s \cdot I_2$$

$$\begin{bmatrix} V(s) \\ 0 \end{bmatrix} = \begin{bmatrix} 4 + \frac{4}{s} & -2 - \frac{2}{s} \\ -(2 + \frac{2}{s}) & 4 + \frac{2}{s} + 2s \end{bmatrix} \cdot \begin{bmatrix} I_1 \\ I_2 \end{bmatrix}$$

$$\Delta = \begin{bmatrix} \frac{4s+4}{s} & -\frac{(2s+2)}{s} \\ -\frac{(2s+2)}{s} & \frac{2s^2+4s+2}{s} \end{bmatrix} = \frac{1}{s^2} \cdot [(4s+4)(2s^2+4s+2) - (2s+2)^2] =$$

$$= \frac{1}{s^2} [8s^3 + 16s^2 + 8s + 8s^2 + 16s + 8 - (4s^2 + 8s + 4)] =$$

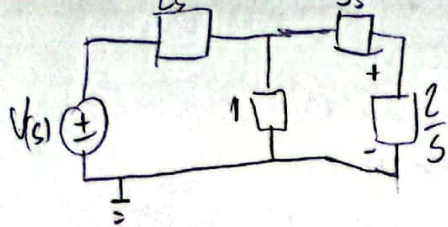
$$= \frac{8s^3 + 12s^2 + 16s + 4}{s^2}$$

$$I_2 = \frac{\begin{bmatrix} \frac{4s+4}{s} & V(s) \\ -\frac{2s+2}{s} & 0 \end{bmatrix}}{\Delta} = -\frac{V(s) \cdot (2s+2)}{\frac{8s^3 + 12s^2 + 16s + 4}{s^2}} = \frac{-V(s) \cdot s(2s+2)}{8s^3 + 12s^2 + 16s + 4}$$

$$V_L(s) = I_2 \cdot 2s$$

$$I_2 2s = \frac{-V(s) s(2s+2) \cdot 2s}{8s^3 + 12s^2 + 16s + 4} \Rightarrow G(s) = \frac{-4s^3 - 4s^2}{8s^3 + 12s^2 + 16s + 4}$$

13) a)



$$\begin{bmatrix} V(s) \\ 0 \end{bmatrix} = \begin{bmatrix} 2s+1 & -1 \\ -1 & 3s+1+\frac{2}{s} \end{bmatrix} \begin{bmatrix} I_1 \\ I_2 \end{bmatrix}$$

$$\Delta = \begin{bmatrix} 2s+1 & -1 \\ -1 & 3s+1+\frac{2}{s} \end{bmatrix} \Rightarrow \Delta = (2s+1)\left(3s+1+\frac{2}{s}\right) - 1 = 6s^2 + 2s + 4 + 3s + 1 + \frac{2}{s} - 1 =$$

$$= \frac{6s^3 + 5s^2 + 4s + 2}{s}$$

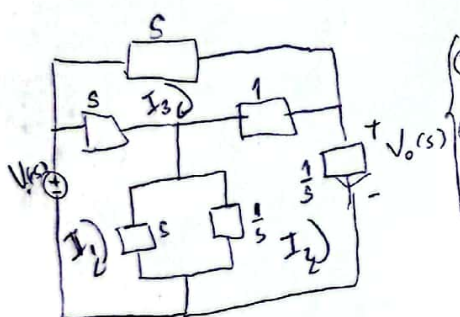
$$I_2 = \frac{\begin{bmatrix} 2s+1 & V(s) \\ -1 & 0 \end{bmatrix}}{\Delta} \Rightarrow I_2 = V(s) \cdot \frac{1}{\Delta} = V(s) \cdot \frac{s}{6s^3 + 5s^2 + 4s + 2} \Rightarrow \frac{V_o(s)}{3s} = V(s) \cdot \frac{s}{6s^3 + 5s^2 + 4s + 2}$$

$$V_o(s) = 3s \cdot I_2$$

$$I_2 = \frac{V_o(s)}{3s}$$

$$G(s) = \frac{3s^2}{6s^3 + 5s^2 + 4s + 2}$$

b)



$$\begin{cases} \text{MALHA 1} & V(s) = \left(1s + \frac{s}{s^2+1}\right) \cdot I_1 - 1s \cdot I_3 - \frac{s}{s^2+1} I_2 \\ \text{MALHA 2} & 0 = \left(1 + \frac{1}{s} + \frac{s}{s^2+1}\right) I_2 - \frac{s}{s^2+1} I_1 - 1 \cdot I_3 \\ \text{MALHA 3} & 0 = (2s+1)I_3 - sI_1 - I_2 \end{cases}$$

$$\Rightarrow I_3 = \frac{sI_1 + I_2}{2s+1}$$

III Em II

$$\frac{sI_1 + I_2}{2s+1} = \left[\frac{(s^3+s) + (s^2+1)s^2}{s^3+s} \right] I_2 - \frac{s}{s^2+1} I_1$$

$$\frac{sI_1 + I_2}{2s+1} = \left(\frac{s^3 + 2s^2 + s + 1}{s^3+s} \right) I_2 - \frac{s}{s^2+1} I_1$$

$$\frac{s(s^3+s)I_1 + (2s+1)(s^3+s)I_2}{(2s+1)(s^2+1)s} = \frac{(s^3 + 2s^2 + s + 1)(2s+1)I_2 - s(2s+1)sI_1}{(2s+1)(s^2+1)s} \Rightarrow$$

$$\Rightarrow (s^4 + s^2)I_1 + (2s^4 + 2s^2 + s^3 + s)I_2 = (2s^4 + 1s^3 + 2s^2 + 2s + s^3 + 2s^2 + s + 1)I_2 - (2s^3 + s^2)I_1 \Rightarrow$$

$$\Rightarrow I_1 = \frac{4s^3 + 2s^2 + 2s + 1}{s^4 + 2s^3 + 2s^2} I_2 \Rightarrow I_3 = \frac{s}{2s+1} \cdot \frac{4s^3 + 2s^2 + 2s + 1}{s(s^3 + 2s^2 + 2s)} I_2 + \frac{I_2}{2s+1}$$

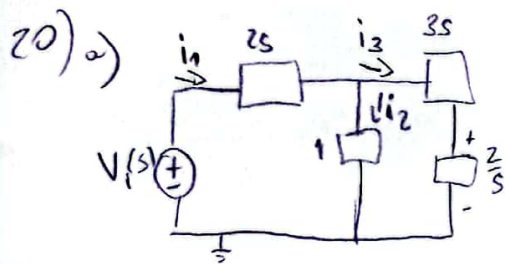
(3)

$$I_3 = I_2 \left[\frac{(4s^3 + 2s^2 + 2s + 1) + (s^3 + 2s^2 + 2s)}{(2s+1)(s^3 + 2s^2 + 2s)} \right] = I_2 \cdot \frac{(5s^3 + 4s^2 + 4s + 1)}{(2s+1)(s^3 + 2s^2 + 2s)}$$

MALHA FORA: $V_i(s) = \frac{1}{s} I_2 + s I_3 \Rightarrow V_i(s) = \frac{1}{s} I_2 + s I_2 \frac{(5s^3 + 4s^2 + 4s + 1)}{s(2s+1)(s^3 + 2s^2 + 2s)}$

$V_o(s)$ COLOCA EVIDÊNCIA

$$G(s) = \frac{V_o(s)}{V_i(s)} = \frac{2s^3 + 5s^2 + 6s + 2}{5s^4 + 6s^3 + 9s^2 + 7}$$



$i_1 = i_2 + i_3$ • AS IMPEDÂNCIAS SÃO INVERSAMENTE PROPORCIONAIS ÀS CORRENTES, QUANDO ESTAS SE DIVIDEM

$$\frac{3s + \frac{2}{s}}{1} \Leftrightarrow \frac{i_3}{i_2} \rightarrow \frac{3s^2 + 2}{s} = \frac{i_2}{i_3} \rightarrow \frac{3s^2 + 2}{s} = \frac{i_2}{i_3}$$

$$i_1 = i_3 \frac{(3s^2 + 2)}{s} + i_3 \Rightarrow i_1 = i_3 \frac{(3s^2 + s + 2)}{s}$$

$$V_i(s) + 2s \cdot i_1 + V_o(s) = i_2 + V_o(s) \quad V_o(s) = 3s \cdot i_3$$

$$V_i(s) + 2s \cdot i_3 \frac{(3s^2 + s + 2)}{s} + V_o(s) = i_3 \frac{(3s^2 + 2)}{s}$$

$$V_i(s) + 2s \cdot i_3 \frac{s}{s} + V_o(s) = 0$$

$$3V_i(s) = (-V_o(s) - 2s i_3) \cdot 3$$

$V_o(s)$

$$3V_i(s) = -5V_o(s)$$

$$G(s) = -\frac{3}{5}$$

$$26) G(s) = \frac{X_2(s)}{F(s)} \quad \begin{bmatrix} 0 \\ 0 \\ F(s) \end{bmatrix} = \begin{bmatrix} 8s^2+6s & -4s & 0 \\ -4s & 4s+2 & -2 \\ 0 & -2 & 2 \end{bmatrix} \cdot \begin{bmatrix} X_1(s) \\ X_2(s) \\ X_3(s) \end{bmatrix}$$

$$\Delta = (8s^2+6s)(4s+2) \cdot 2 + 0 + 0 - 0 - 4s \cdot 4s \cdot 2 - (8s^2+6s) \cdot 2 \cdot 2 =$$

$$= (32s^3 + 24s^2 + 16s^2 + 12s) \cdot 2 - 32s^2 - 24s = 64s^3 + 80s^2 - 32s^2 - 24s = 16(4s^3 + 5s^2)$$

$$X_2 = \frac{\begin{bmatrix} 8s^2+6s & 0 & 0 \\ -4s & 0 & -2 \\ 0 & F(s) & -2 \end{bmatrix}}{\Delta} \Rightarrow X_2 = \frac{-(8s^2+6s) F(s) \cdot (-2)}{16(4s^3+5s^2)} = \frac{4s(4s+3) F(s)}{16s^2(4s+5)}$$

$$X_2 = \frac{(4s+3) F(s)}{16s^2+4s}$$

$$G(s) = \frac{X_2(s)}{F(s)} = \frac{4s+3}{16s^2+4s}$$

$$27) \begin{bmatrix} 0 \\ F(s) \end{bmatrix} = \begin{bmatrix} s^2+6s+9 & -3s-5 \\ -3s-5 & 2s^2+5s+5 \end{bmatrix} \cdot \begin{bmatrix} X_1 \\ X_2 \end{bmatrix}$$

$$\Delta = (s^2+6s+9)(2s^2+5s+5) - (3s+5)(3s+5) = 2s^4 + 5s^3 + 5s^2 + 12s^3 + 30s^2 + 30s + 18s^2 + 45s + 45 - 9s^2 - 30s$$

$$= 2s^4 + 17s^3 + 44s^2 + 45s + 20$$

$$X_1 = \frac{\begin{bmatrix} 0 & -(3s+5) \\ F(s) & 2s^2+5s+5 \end{bmatrix}}{\Delta} \Rightarrow X_1 = \frac{F(s) \cdot (3s+5)}{\Delta}$$

$$G(s) = \frac{X_1(s)}{F(s)} = \frac{3s+5}{2s^4+17s^3+44s^2+45s+20}$$

$$29) G(s) = \frac{X_3(s)}{F(s)} \quad \begin{bmatrix} 0 \\ F(s) \\ 0 \end{bmatrix} = \begin{bmatrix} 4s^2+2s+6 & -2s & 0 \\ -2s & 4s^2+4s+6 & -6 \\ 0 & -6 & 4s^2+2s+6 \end{bmatrix} \cdot \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$$

$$\Delta = (4s^2+2s+6)(4s^2+2s+6)(4s^2+4s+6) + 0 + 0 - 0 - 4s^2(4s^2+2s+6) - 36(4s^2+2s+6) \\ = (4s^2+2s+6)[(4s^2+2s+6)(4s^2+4s+6) - 4s^2 - 36] = (4s^2+2s+6) \cdot 4 \cdot (4s^4+6s^3+13s^2+3s)$$

$$X_3 = \frac{\begin{bmatrix} 4s^2+2s+6 & -2s & 0 \\ -2s & 4s^2+4s+6 & F(s) \\ 0 & -6 & 0 \end{bmatrix}}{\Delta} \quad X_3 = \frac{-18s^3 \cdot F(s) \cdot (4s^2+2s+6)}{(4s^2+2s+6) \cdot 4 \cdot (4s^4+6s^3+13s^2+3s)}$$

$$G(s) = \frac{X_3(s)}{F(s)} = \frac{3}{2(4s^4+6s^3+13s^2+3s)}$$

$$29) a) G(s) = \frac{X_3(s)}{F(s)} \quad \begin{bmatrix} F(s) \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 4s^2+8s+5 & -8s & -5 \\ -8s & 4s^2+16s & -4s \\ -5 & -4s & 4s+5 \end{bmatrix} \cdot \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$$

$$\Delta = (4s^2+8s+5)(4s^2+16s)(4s+5) - 160s^2 - 160s^2 - 2s(4s^2+16s) - 64s^2(4s+5) - 16s^2(4s^2+8s+5) + 8s+5$$

$$X_3 = \frac{\begin{bmatrix} 4s^2+8s+5 & -8s & F(s) \\ -8s & 4s^2+16s & 0 \\ -5 & -4s & 0 \end{bmatrix}}{\Delta} = \frac{32s^2 F(s) + 5(4s^2+16s) F(s)}{\Delta}$$

$$\Delta = (4s^2+16s) \cdot (16s^3+32s^2+20s+20s^2+40s+25) - 320s^2 - 2s(4s^2+16s) - 256s^3 - 320s^3 - 16s^2(4s^2+8s+5) + 8s+5$$

$$\Delta = (4s^2+16s)(16s^3+52s^2+60s) - 256s^3 - 640s^2 - 64s^4 - 128s^3 - 80s^2$$

$$\Delta = (4s^2+16s)(16s^3+52s^2+60s) - 384s^3 - 720s^2 - 64s^4$$

$$\Delta = (4s^2+16s)(16s^3+52s^2+60s) - 16s^2(4s^2+24s+4s)$$

$$\Delta = 4s[(s+4)(16s^3 + 52s^2 + 60s) - 4s(4s^2 + 24s + 4s)]$$

$$\Delta = 16s^2[4s^3 + 13s^2 + 15s + 16s^2 + 52s + 60 - 4s^2 - 24s - 4s]$$

$$\Delta = 16s^2(4s^3 + 25s^2 + 43s + 15)$$

$$X_3 = \frac{4s(13s+20) \cdot F(s)}{16s^2(4s^3 + 25s^2 + 43s + 15)}$$

$$G(s) = \frac{13s+20}{4s(4s^3 + 25s^2 + 43s + 15)}$$

$$b) G(s) = \frac{X_3(s)}{F(s)}$$

$$\begin{bmatrix} 0 \\ F(s) \\ 0 \end{bmatrix} = \begin{bmatrix} 8s^2 + 4s + 16 & -(4s+1) & -15 \\ -(4s+1) & 3s^2 + 20s + 1 & -16s \\ -15 & -16s & 16s+15 \end{bmatrix} \cdot \begin{bmatrix} X_1 \\ X_2 \\ X_3 \end{bmatrix}$$

$$\Delta = (8s^2 + 4s + 16)(3s^2 + 20s + 1)(16s + 15) - 2 \cdot 240s(4s+1) - 22s(3s^2 + 20s + 1) - (4s+1)(16s+15) - 256s^2(8s^2 + 43s + 16)$$

$$X_3 = \frac{\begin{bmatrix} 8s^2 + 4s + 16 & -(4s+1) & 0 \\ -(4s+1) & 3s^2 + 20s + 1 & F(s) \\ -15 & -16s & 0 \end{bmatrix}}{\Delta} = \frac{15(4s+1)F(s) + 16s(8s^2 + 4s + 16)F(s)}{\Delta}$$

$$\begin{aligned} \Delta &= (8s^2 + 4s + 16)[(48s^3 + 365s^2 + 316s + 15) - 256s^2] - 480s(4s+1) - 22s(3s^2 + 20s + 1) - (4s+1) \\ &= (8s^2 + 4s + 16)(48s^3 + 109s^2 + 316s + 15) - (4s+1)(480s + 64s^2 + 76s + 15) - 22s(3s^2 + 20s + 1) \\ &= (8s^2 + 4s + 16)(48s^3 + 109s^2 + 316s + 15) - (4s+1)(64s^2 + 556s + 15) - 22s(3s^2 + 20s + 1) \\ &= (8s^2 + 4s + 16)(48s^3 + 109s^2 + 316s + 15) - 15[(172s^3 + 148s^2 + 4s + 43s^2 + 37s + 1)(45s^2 + 300s + 15)] - 4s^2 - s \\ &= (8s^2 + 4s + 16)(48s^3 + 109s^2 + 316s + 15) - 4s^2 - s - 15[172s^3 + 281s^2 + 341s + 16] \\ &= 384s^5 + 872s^4 + 2528s^3 + 120s^2 + 132s^4 + 436s^3 + 1264s^2 + 60s + 768s^3 + 1744s^2 + 5056s + 240 - 4s^2 - s \\ &\quad - 2580s^3 - 4215s^2 - 5115s - 240 \end{aligned}$$

$$\Delta = 384s^5 + 1064s^4 + 1152s^3 - 109s^2 - 5s$$

$$X_3 = \frac{F(s) [(60s + 15) + (128s^3 + 64s^2 + 256s)]}{\Delta}$$

$$G(s) = \frac{X_3(s)}{F(s)} = \frac{128s^3 + 64s^2 + 316s + 15}{384s^5 + 1064s^4 + 1152s^3 - 1091s^2}$$

$$32) a) \begin{aligned} \theta_1(s^2 + 9s + 8) - \theta_2(15 + s) &= 0 \\ \theta_2(3s^2 + s + 12) - \theta_1(s + 9) &= T(s) \end{aligned}$$

$$b) \begin{aligned} \theta_1(J_1 s^2 + K_1) - \theta_{12}(K_1) &= T(s) \\ -\theta_1(K_1) + \theta_{12}(D_1 s + K_1) - \theta_2(D_1 s) &= 0 \\ -\theta_{12}(D_1 s) + \theta_2(D_1 s + J_2 s^2 + K_2) - \theta_{23}(K_2) &= 0 \\ -\theta_2(K_2) + \theta_{23}[D_2 s + (K_2 + K_3)] - \theta_3(D_2 s + K_3) &= 0 \\ -\theta_{23}(D_2 s + K_3) + \theta_3(J_3 s^2 + D_2 s + K_3) &= 0 \end{aligned}$$

$$33) \begin{bmatrix} T(s) \\ 0 \end{bmatrix} = \begin{bmatrix} s^2 + 2s + 1 & -(s+1) \\ -(s+1) & 2s+1 \end{bmatrix} \cdot \begin{bmatrix} \theta_1 \\ \theta_2 \end{bmatrix} \quad G(s) = \frac{\theta_2(s)}{T(s)}$$

$$\Delta = (s^2 + 2s + 1)(2s + 1) - (s+1)^2 = 2s^3 + 4s^2 + 2s + 1 - s^2 - 2s - 1 = 2s^3 + 3s^2$$

$$\Delta = 2s^3 + 4s^2 + 2s$$

$$\theta_2 = \frac{\begin{bmatrix} s^2 + 2s + 1 & T(s) \\ -(s+1) & 0 \end{bmatrix}}{2s^3 + 4s^2 + 2s} = \frac{-T(s) \cdot (-1) \cdot (s+1)}{2s^3 + 4s^2 + 2s} \Rightarrow G(s) = \frac{\theta_2}{T(s)} = \frac{s+1}{2s^3 + 4s^2 + 2s}$$

$$34) G(s) = \frac{\theta_1(s)}{T(s)}$$

$$\begin{bmatrix} T(s) \\ 0 \end{bmatrix} = \begin{bmatrix} s^2 + s + 1 & -(s+1) \\ -(s+1) & s^2 + s + 2 \end{bmatrix} \cdot \begin{bmatrix} \theta_1 \\ \theta_2 \end{bmatrix}$$

$$\Delta = (s^2 + s + 1)(s^2 + s + 2) - (s+1)^2 = s^4 + s^3 + 2s^2 + s^3 + s^2 + \cancel{s} + \cancel{s} + 2 - \cancel{s^2} - \cancel{s} - 1$$

$$\Delta = s^4 + 2s^3 + 3s^2 + s + 1$$

$$\theta_1 = \frac{\begin{bmatrix} T(s) & -(s+1) \\ 0 & s^2 + s + 2 \end{bmatrix}}{\Delta} \Rightarrow \theta_1 = \frac{T(s) \cdot (s^2 + s + 2)}{s^4 + 2s^3 + 3s^2 + s + 1} \Rightarrow G(s) = \frac{s^2 + s + 2}{s^4 + 2s^3 + 3s^2 + s + 1}$$