

Shortest paths

Single-source shortest paths

- Nonnegative edge weights
 - ◆ Dijkstra's algorithm: $O(E + V \lg V)$
- General
 - ◆ Bellman-Ford: $O(VE)$

DAG Shortest Paths

- Bellman-Ford takes $O(VE)$ time.

DAG Shortest Paths

- Bellman-Ford takes $O(VE)$ time.
- Use DAG properties!

DAG-Shortest-Paths(G, s)

1. $L = \text{Topological_Sort}(G)$

2. **for** u in V : $\text{dist}(u) = \text{INF}$;

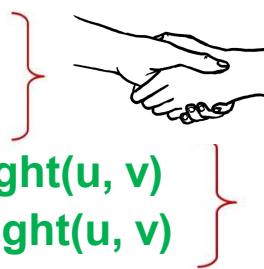
3. $\text{dist}(s) = 0$

4. **for** u from s to $L.\text{end}()$:

5. **for each vertex** $v \in \text{Adj}[u]$

6. **if** $\text{dist}(v) > \text{dist}(u) + \text{weight}(u, v)$

7. $\text{dist}(v) = \text{dist}(u) + \text{weight}(u, v)$

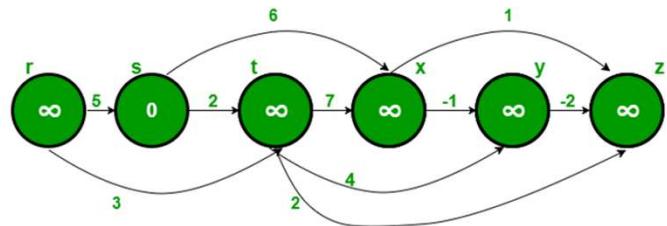


*relaxation
step*

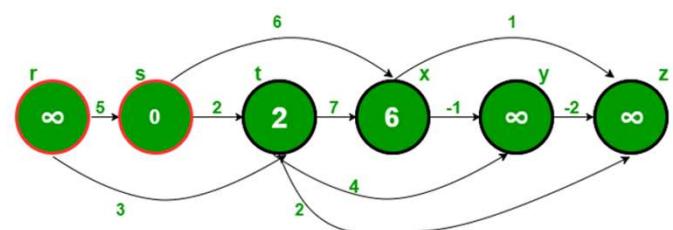
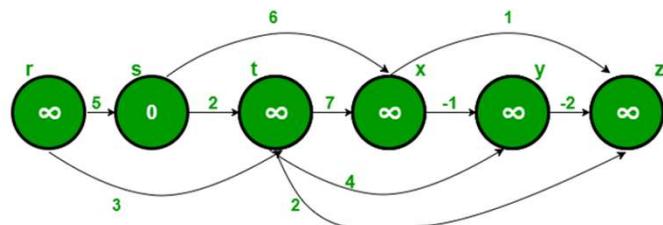


Time: $O(V+E)$

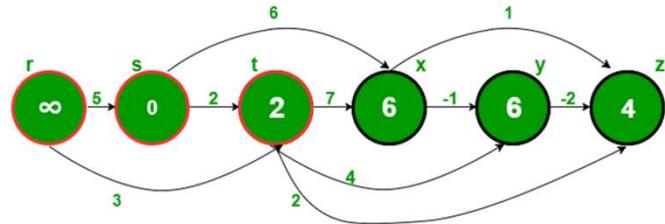
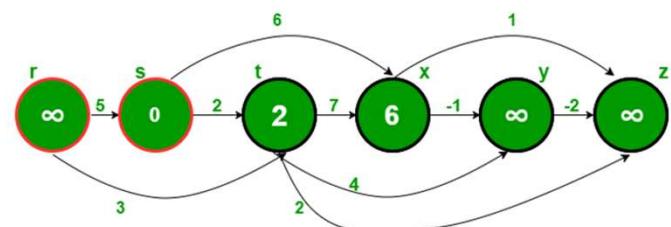
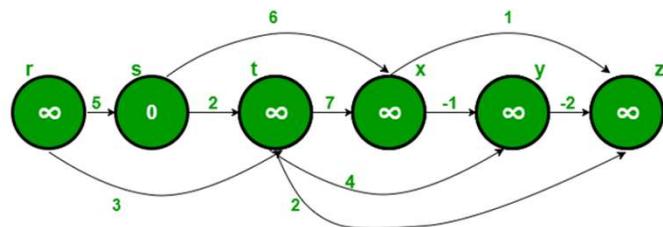
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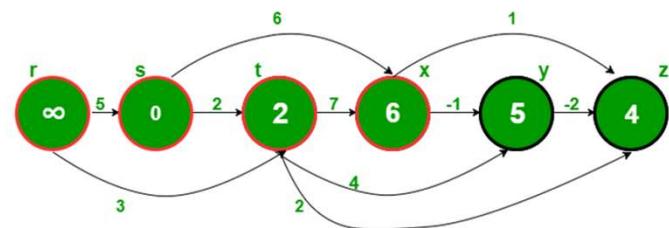
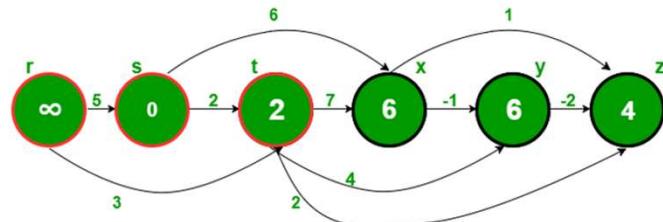
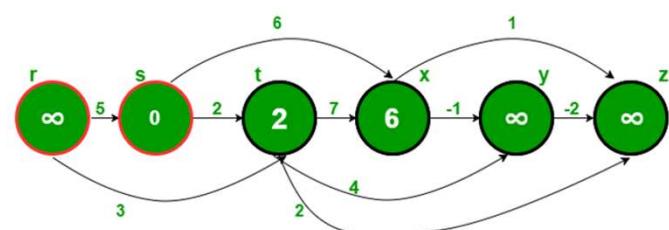
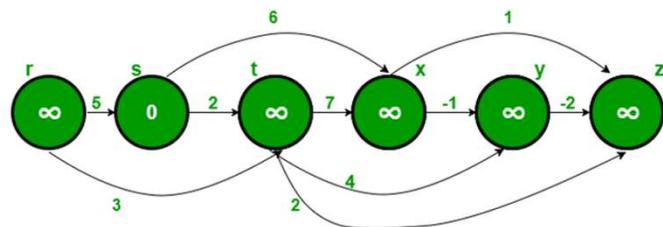
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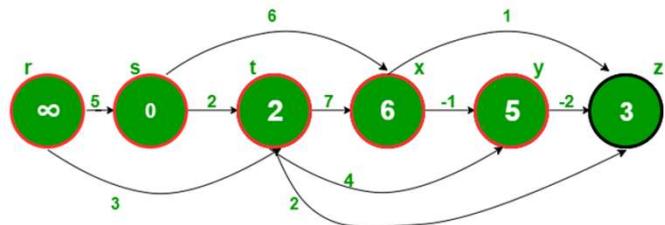
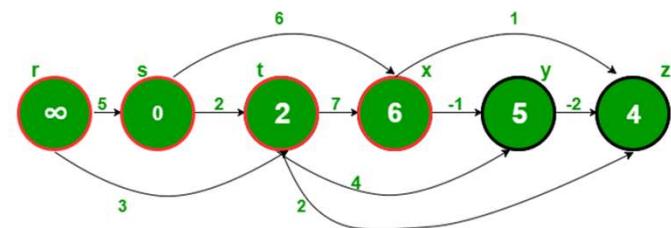
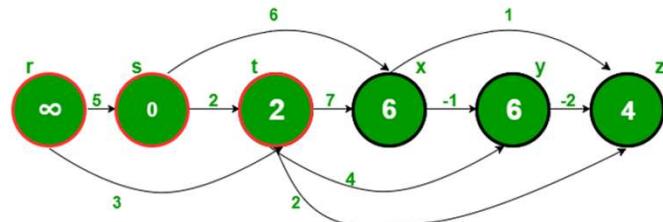
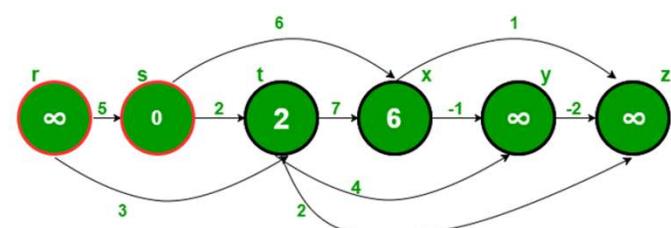
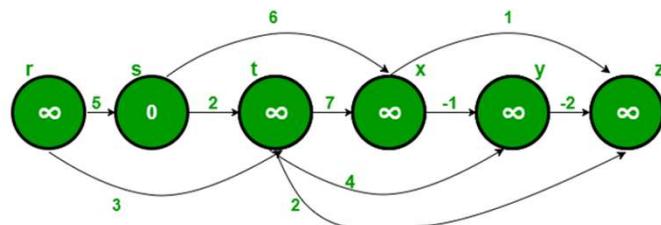
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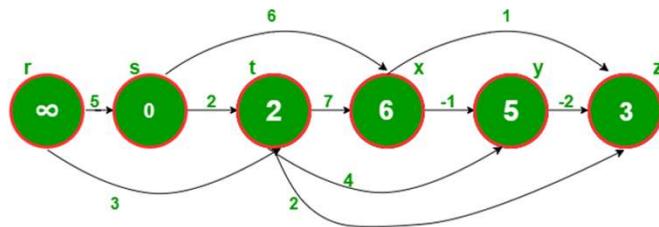
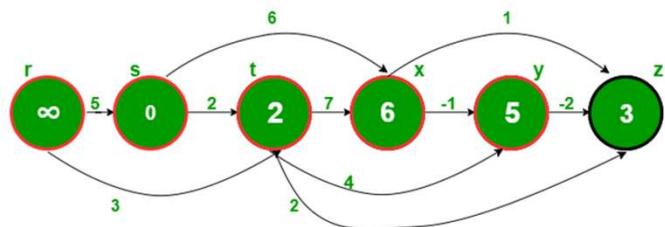
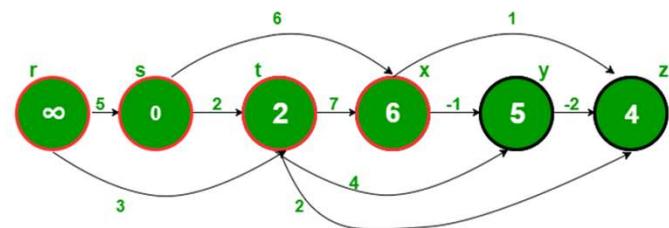
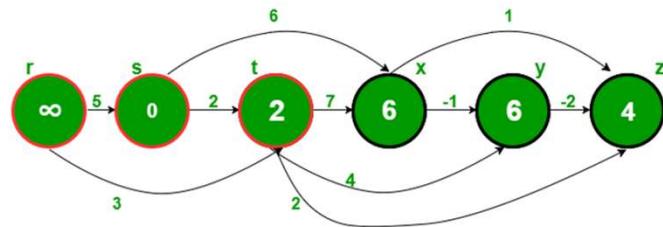
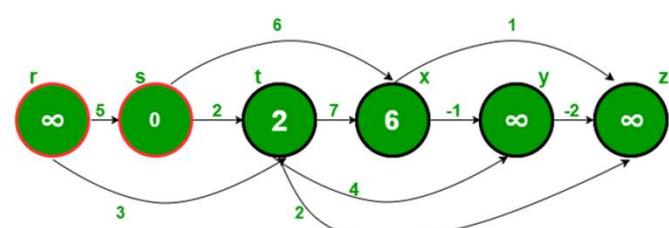
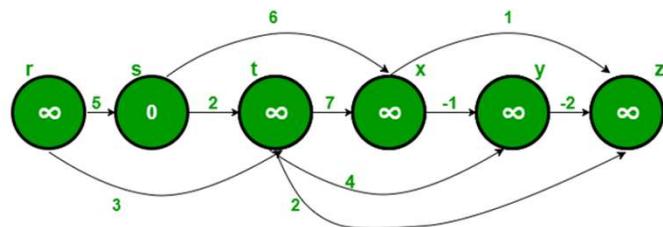
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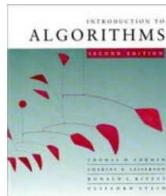


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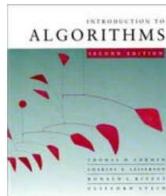




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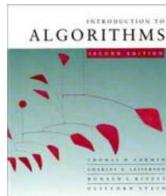


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All-pairs shortest paths



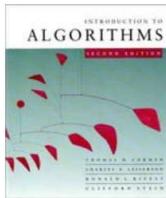
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 - Dijkstra's algorithm $|V|$ times



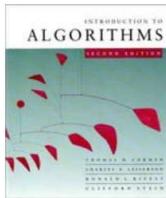
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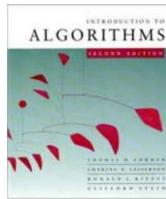
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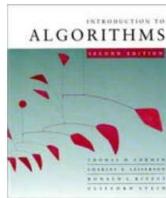
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All-pairs shortest paths

Input: Digraph $G = (V, E)$, where $V = \{1, 2, \dots, n\}$, with edge-weight function $w : E \rightarrow \mathbb{R}$.

Output: $n \times n$ matrix of shortest-path lengths $\delta(i, j)$ for all $i, j \in V$.



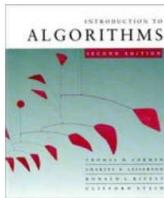
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- Run Bellman-Ford once from each vertex.



All-pairs shortest paths

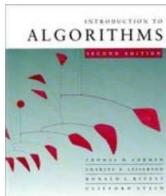
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IDEA:

- Run Bellman-Ford once from each vertex.
- Time = $O(V^2E)$.
- Dense graph (n^2 edges) $\Rightarrow \Theta(n^4)$ time in the worst case.

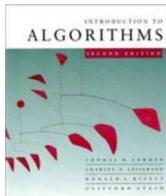
Good first try!



Dynamic programming

Consider the $n \times n$ adjacency matrix $A = (a_{ij})$ of the digraph, and define

$d_{ij}^{(m)}$ = weight of a shortest path from i to j that uses at most m edges.



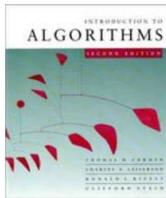
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$$d_{ij}^{(0)} = \begin{cases} 0 & \text{if } i = j, \\ \infty & \text{if } i \neq j; \end{cases}$$



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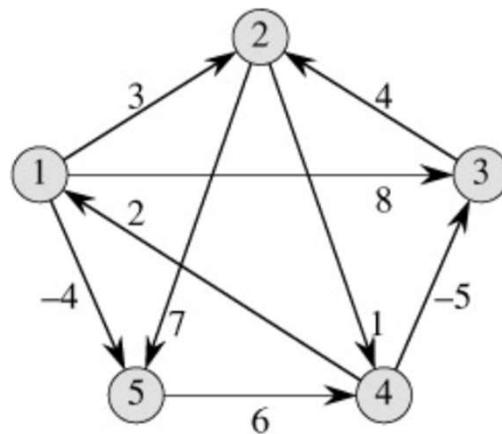
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and for $m = 1, 2, \dots, n - 1$,

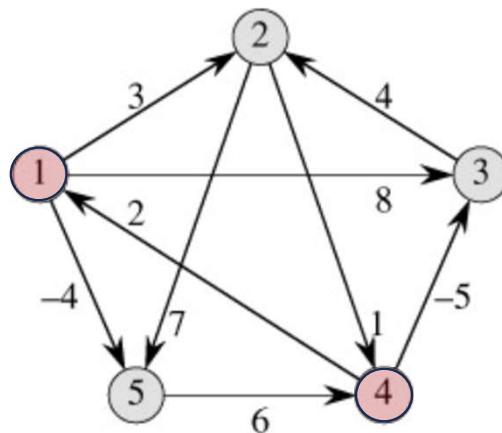
$$d_{ij}^{(m)} = \min_k \{ d_{ik}^{(m-1)} + a_{kj} \}.$$



$$\begin{pmatrix} 0 & 3 & 8 & \infty & -4 \\ \infty & 0 & \infty & 1 & 7 \\ \infty & 4 & 0 & \infty & \infty \\ 2 & \infty & -5 & 0 & \infty \\ \infty & \infty & \infty & 6 & 0 \end{pmatrix}$$

$m=1$

$d_{ij}^{(m)}$ = weight of a shortest path from i to j that uses at most m edges.

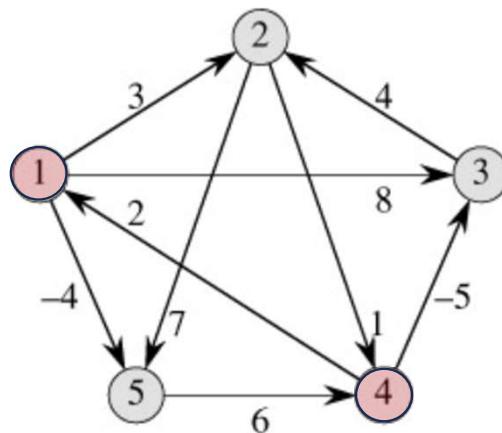


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$m=2$

$d_{ij}^{(m)}$ = weight of a shortest path from i to j that uses at most m edges.



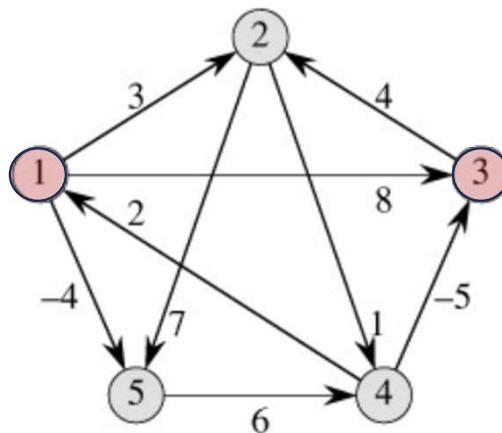
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$$\left(\begin{array}{ccccc} 0 & 3 & 8 & 2 & -4 \\ 3 & 0 & -4 & 1 & 7 \\ \infty & 4 & 0 & 5 & 11 \\ 2 & -1 & -5 & 0 & -2 \\ 8 & \infty & 1 & 6 & 0 \end{array} \right)$$

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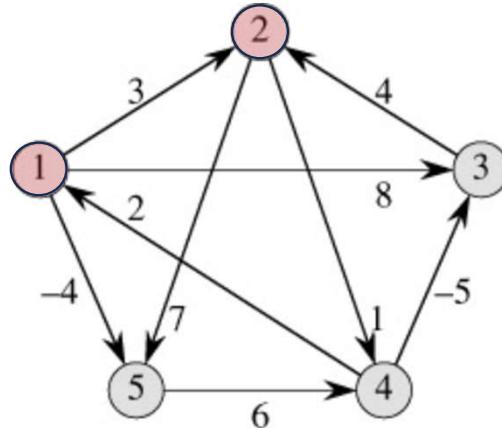
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$m=3$

$d_{ij}^{(m)}$ = weight of a shortest path from i to j that uses at most m edges.



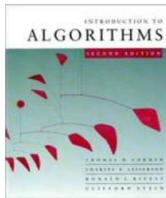
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$$\begin{pmatrix} 0 & 1 & -3 & 2 & -4 \\ 3 & 0 & -4 & 1 & -1 \\ 7 & 4 & 0 & 5 & 3 \\ 2 & -1 & -5 & 0 & -2 \\ 8 & 5 & 1 & 6 & 0 \end{pmatrix}$$

$m=4$

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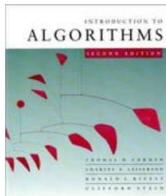


Matrix multiplication

Compute $C = A \cdot B$, where C, A , and B are $n \times n$ matrices:

$$c_{ij} = \sum_{k=1}^n a_{ik} b_{kj}.$$

Time = $\Theta(n^3)$ using the standard algorithm.



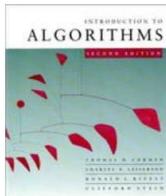
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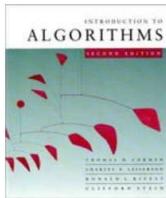
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$$c_{ij} = \min_k \{a_{ik} + b_{kj}\}.$$

Thus, $D^{(m)} = D^{(m-1)} \times A$.

Identity matrix = $I = \begin{pmatrix} 0 & \infty & \infty & \infty \\ \infty & 0 & \infty & \infty \\ \infty & \infty & 0 & \infty \\ \infty & \infty & \infty & 0 \end{pmatrix} = D^0 = (d_{ij}^{(0)}).$



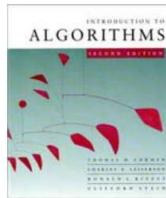
Matrix multiplication (continued)

The $(\min, +)$ multiplication is ***associative***, and with the real numbers, it forms an algebraic structure called a ***closed semiring***.

Consequently, we can compute

$$\begin{aligned} D^{(1)} &= D^{(0)} \cdot A = A^1 \\ D^{(2)} &= D^{(1)} \cdot A = A^2 \\ &\vdots && \vdots \\ D^{(n-1)} &= D^{(n-2)} \cdot A = A^{n-1}, \end{aligned}$$

yielding $D^{(n-1)} = (\delta(i, j))$.



Matrix multiplication (continued)

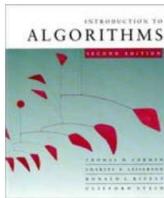
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Time = $\Theta(n \cdot n^3) = \Theta(n^4)$. No better than $n \times$ B-F.



Improved matrix multiplication algorithm

Repeated squaring: $A^{2k} = A^k \times A^k$.

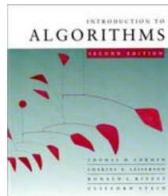
Compute $\underbrace{A^2, A^4, \dots, A^{2^{\lceil \lg(n-1) \rceil}}}$.

$O(\lg n)$ squarings

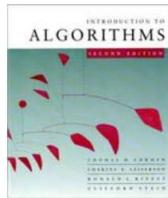
Note: $A^{n-1} = A^n = A^{n+1} = \dots$

Time = $\Theta(n^3 \lg n)$.

To detect negative-weight cycles, check the diagonal for negative values in $O(n)$ additional time.



Pseudocode for Floyd-Warshall

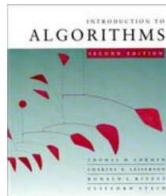


Pseudocode for Floyd-Warshall

```
for  $k \leftarrow 1$  to  $n$ 
    do for  $i \leftarrow 1$  to  $n$ 
        do for  $j \leftarrow 1$  to  $n$ 
            do if  $c_{ij} > c_{ik} + c_{kj}$ 
                then  $c_{ij} \leftarrow c_{ik} + c_{kj}$ 
```

} *relaxation*





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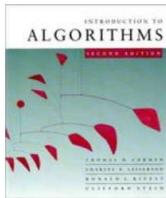
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Notes:

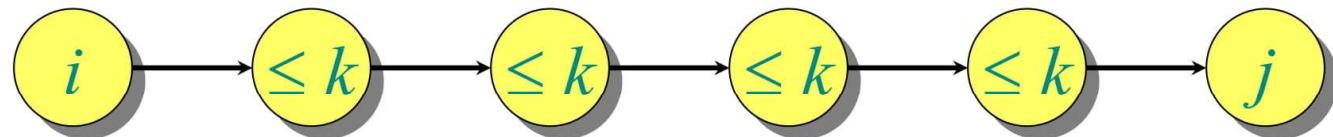
- Okay to omit superscripts, since extra relaxations can't hurt.
- Runs in $\Theta(n^3)$ time.
- Simple to code.
- Efficient in practice.



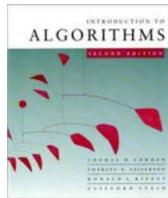
Floyd-Warshall algorithm

Also dynamic programming, but faster!

Define $c_{ij}^{(k)}$ = weight of a shortest path from i to j with intermediate vertices belonging to the set $\{1, 2, \dots, k\}$.

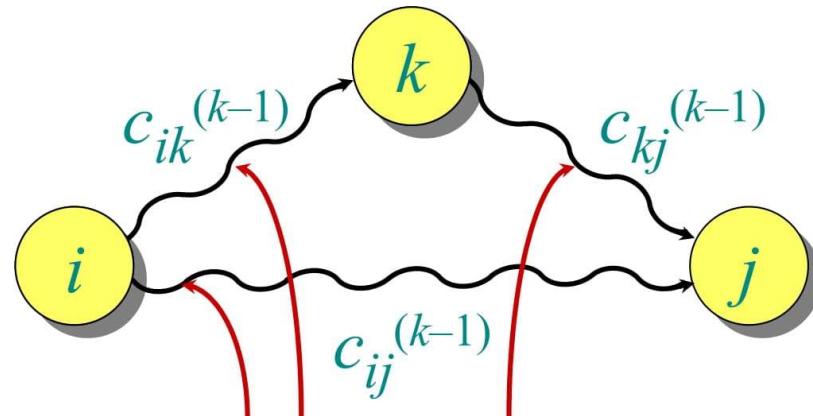


Thus, $\delta(i, j) = c_{ij}^{(n)}$. Also, $c_{ij}^{(0)} = a_{ij}$.

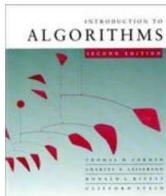


Floyd-Warshall recurrence

$$c_{ij}^{(k)} = \min_k \{c_{ij}^{(k-1)}, c_{ik}^{(k-1)} + c_{kj}^{(k-1)}\}$$



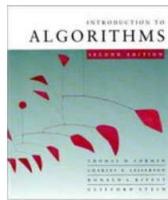
intermediate vertices in $\{1, 2, \dots, k\}$



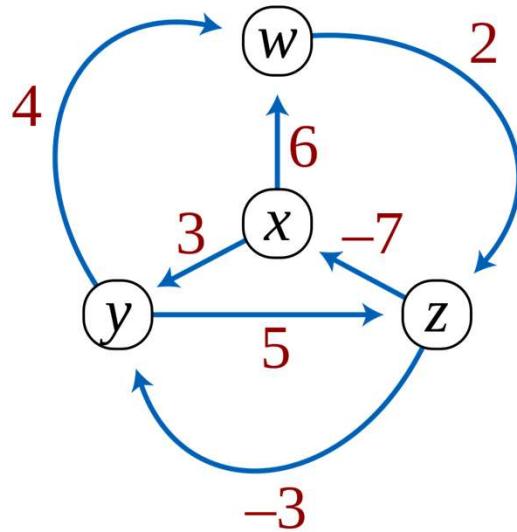
Johnson's algorithm

1. Find a function $h : V \rightarrow \mathbb{R}$ such that $w_h(u, v) \geq 0$ for all $(u, v) \in E$ by using Bellman-Ford to solve the difference constraints $h(v) - h(u) \leq w(u, v)$, or determine that a negative-weight cycle exists.
 - Time = $O(VE)$.
2. Run Dijkstra's algorithm using w_h from each vertex $u \in V$ to compute $\delta_h(u, v)$ for all $v \in V$.
 - Time = $O(VE + V^2 \lg V)$.
3. For each $(u, v) \in V \times V$, compute
$$\delta(u, v) = \delta_h(u, v) - h(u) + h(v).$$
 - Time = $O(V^2)$.

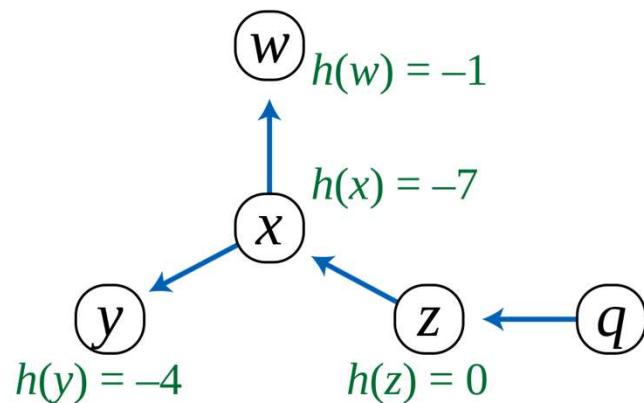
Total time = $O(VE + V^2 \lg V)$.



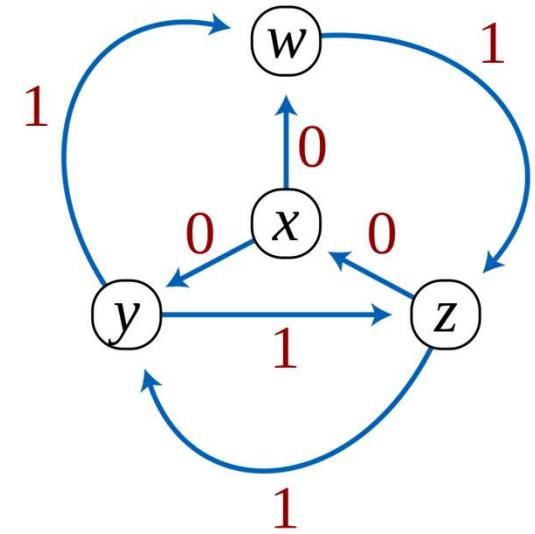
Johnson's algorithm



original graph
with negative edges



shortest path tree
found by Bellman-Ford



reweighted graph with
no negative edges

אלגוריתם קירוב



אלגוריתם קירוב - אינטואיציה

אלגוריתם שモצא פתרון שאינו בהכרח פתרון אופטימלי
לבעיה נתונה, אלא פתרון שקרוב לפתרון אופטימלי.

אלגוריתם קירוב - אינטואיציה

אלגוריתם שמודצא פתרון שאינו בהכרח פתרון אופטימלי
לבעיה נתונה, אלא פתרון שקרוב לפתרון אופטימלי.



למה להסתפק רק בקירוב ??

אלגוריתם קירוב - אינטואיציה

אלגוריתם שמודצא פתרון שאינו בהכרח פתרון אופטימלי
לבעיה נתונה, אלא פתרון שקרוב לפתרון אופטימלי.



מציאת פתרון אופטימלי היא
בלתי מעשית

NP

אלגוריתם קירוב

אלגוריתם שモץ פתרון שאינו בהכרח פתרון אופטימלי
לבעיה נתונה, אלא פתרון שקרוב לפתרון אופטימלי.

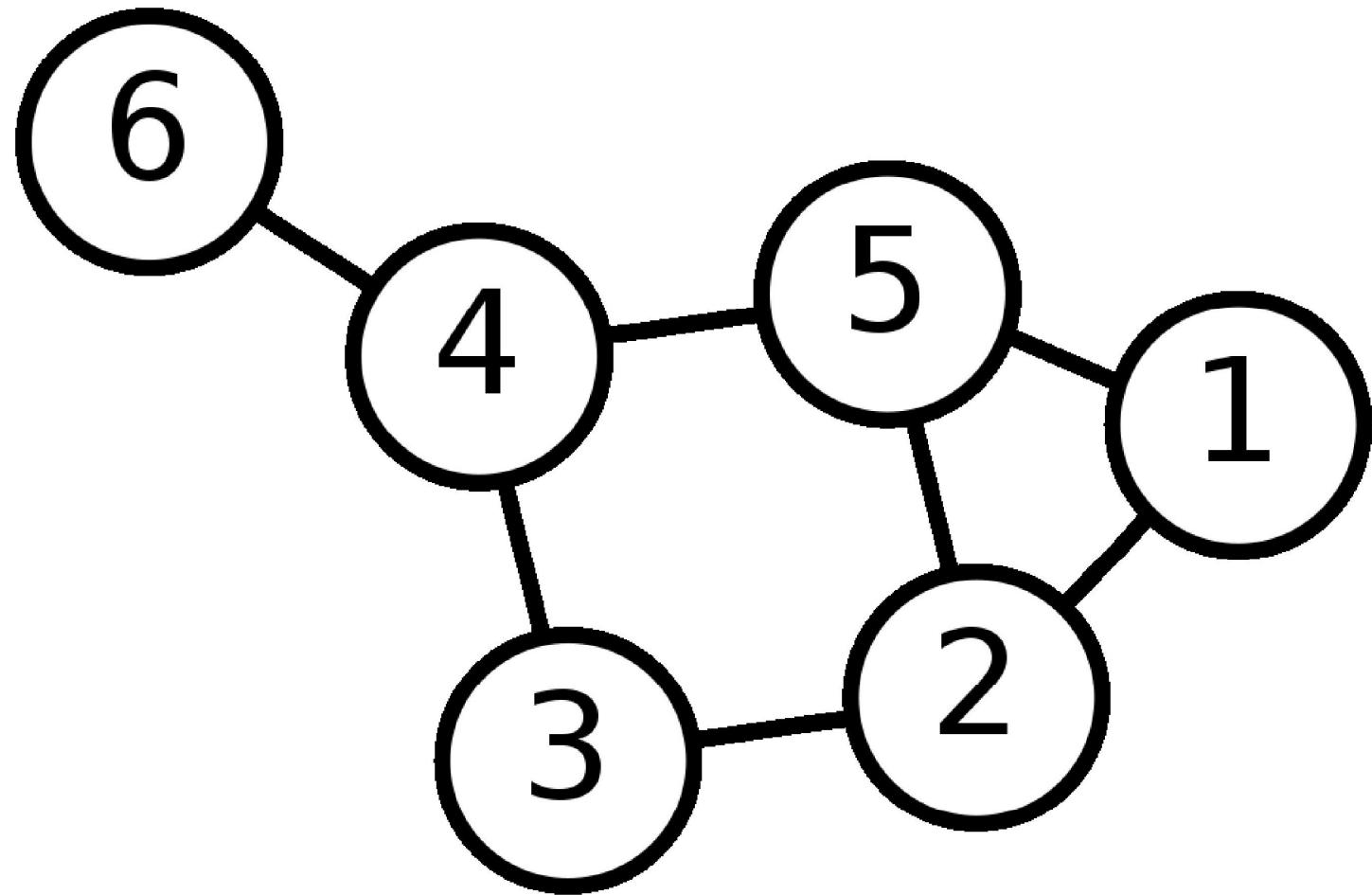
מודדים את הקירוב של אלגוריתם בהתאם ליחס בין הפתרון
שנמצא על ידי האלגוריתם לבין הפתרון האופטימלי.

אלגוריתם קירוב – בעיות אופטימיזציה

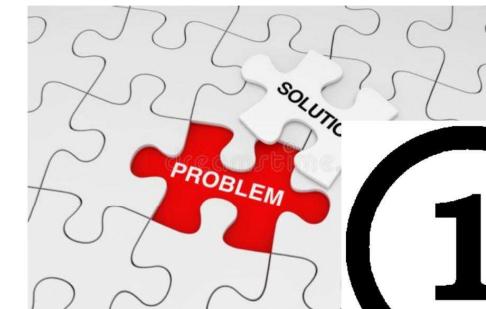
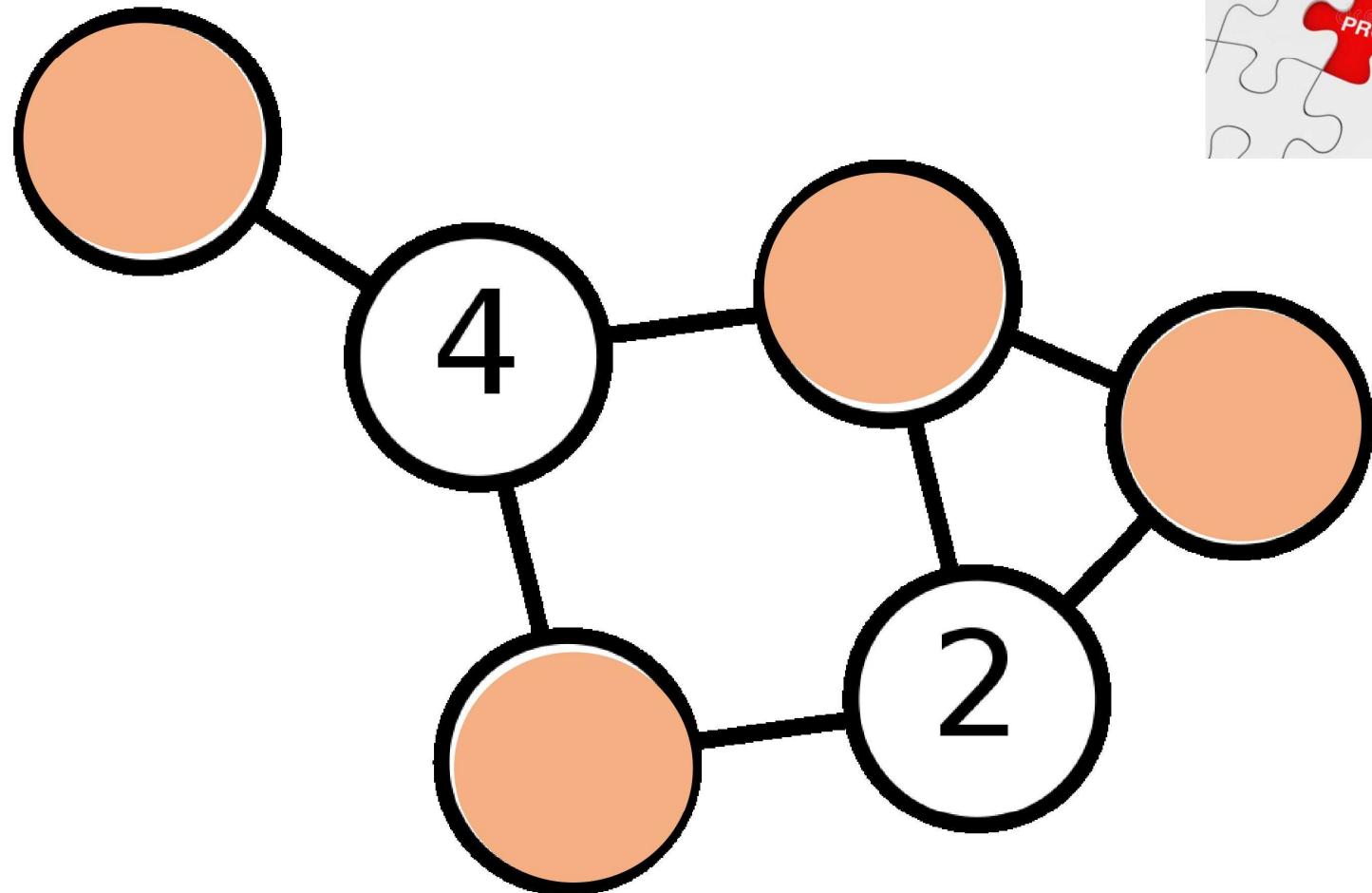
אלגוריתם קירוב A הוא בעל יחס קירוב $\rho(n)$
אם עבור כל קלט בגודל n ,
היחס בין הגודל C של הפתרון שմפיק A
לגודל הפתרון האופטימלי C^*
אינו עולה על $\rho(n)$

$$\max \left(\frac{C}{C^*}, \frac{C^*}{C} \right) \leq \rho(n)$$

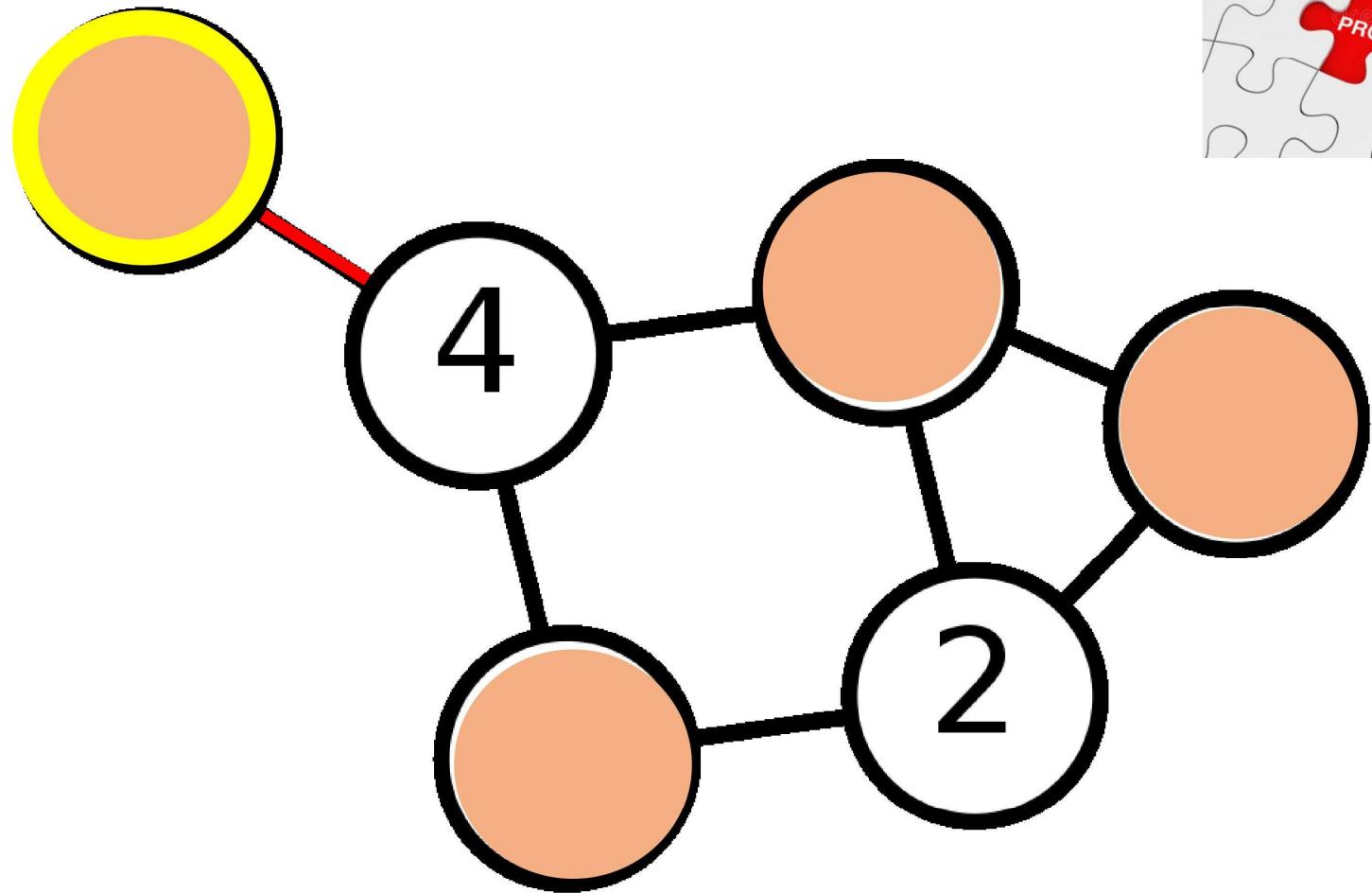
ריכוז הודהות



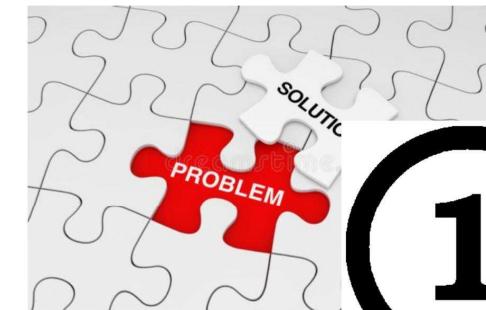
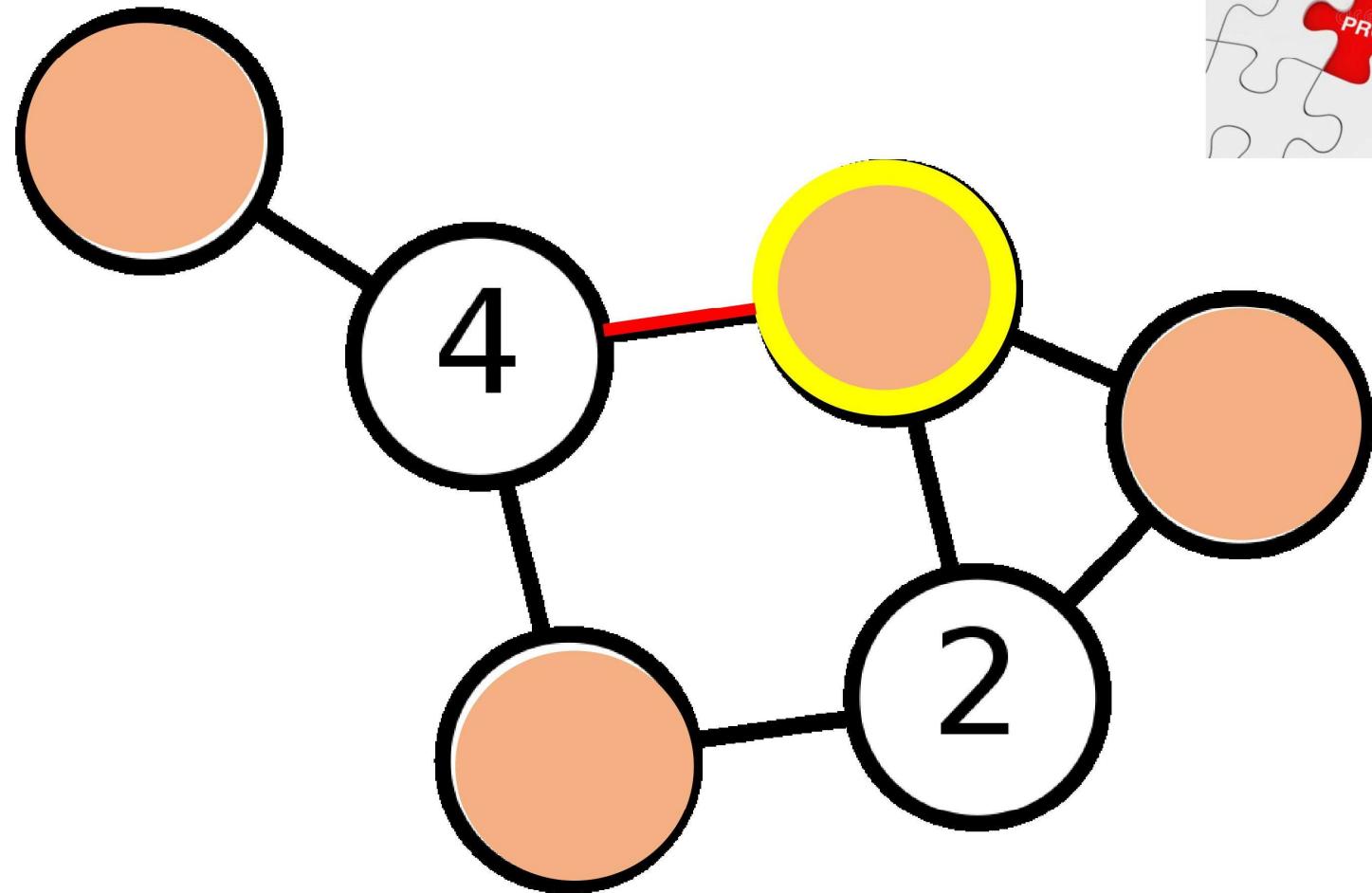
ריכוז הودהות



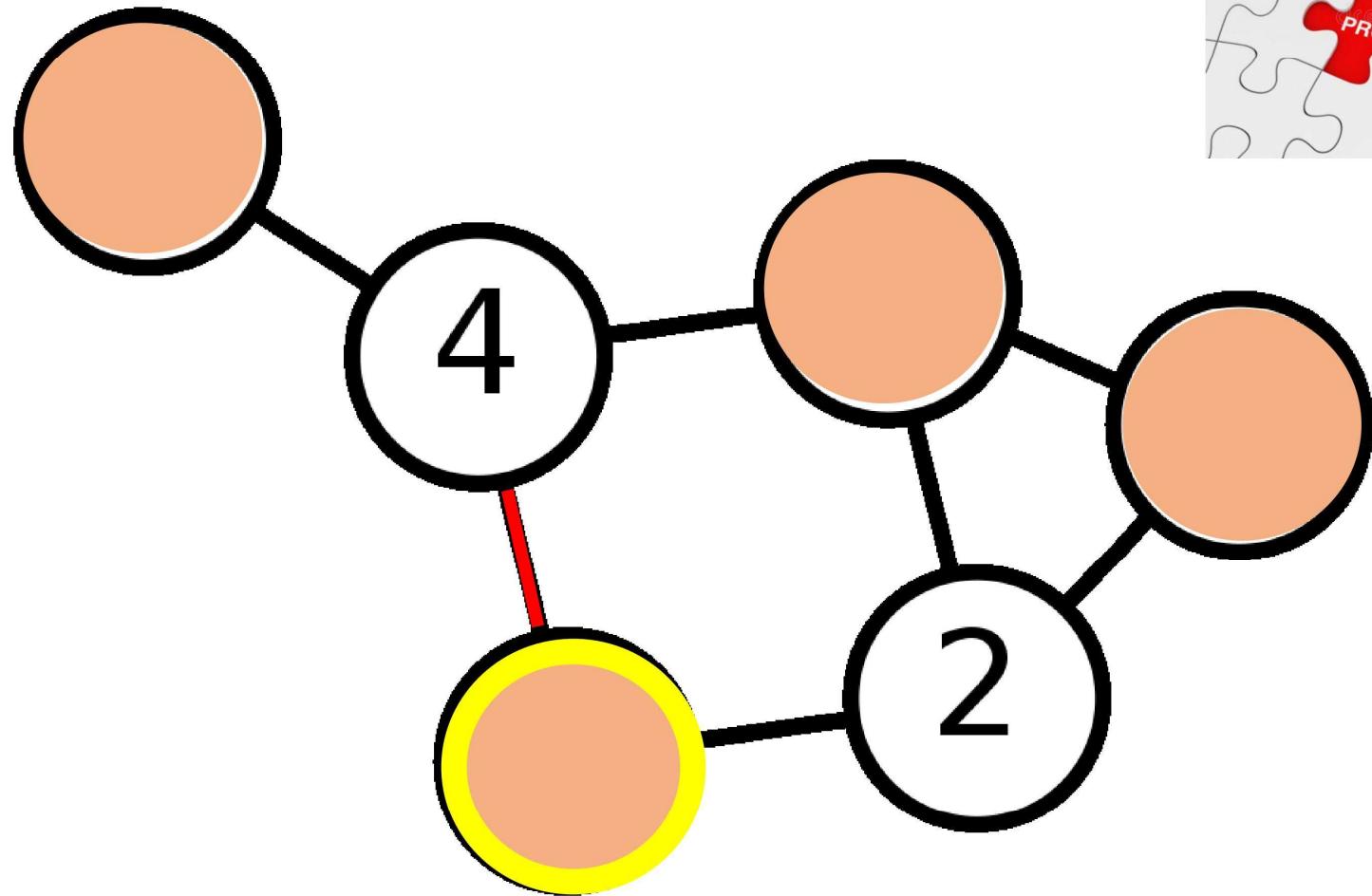
ריכוז הودהות



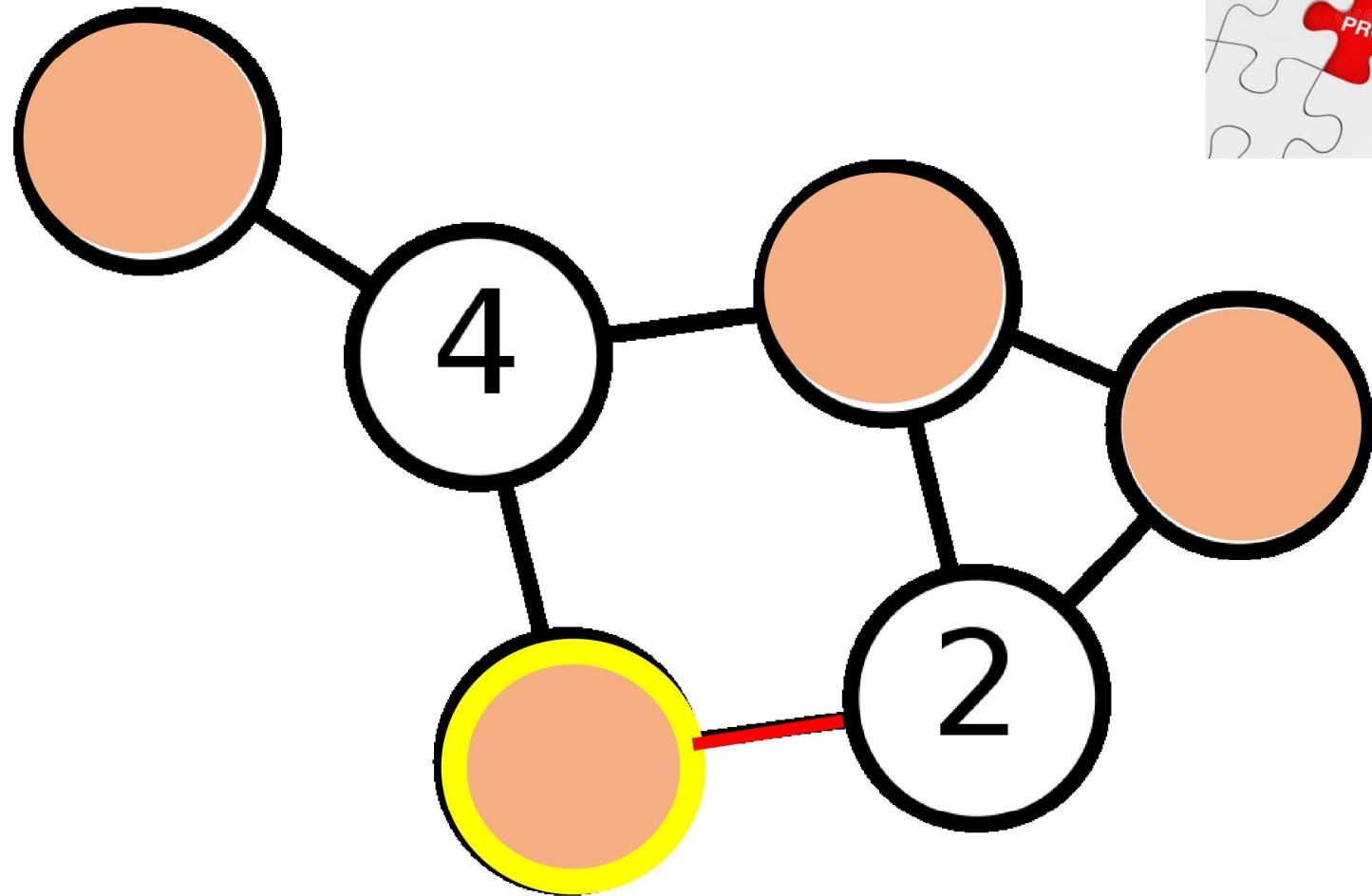
ריכוז הودהות



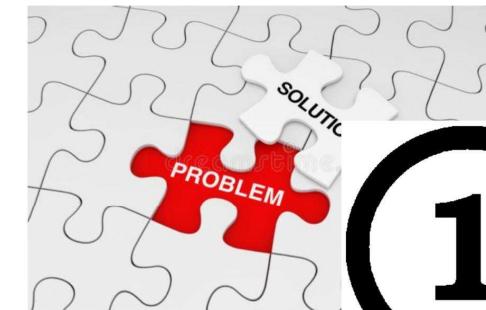
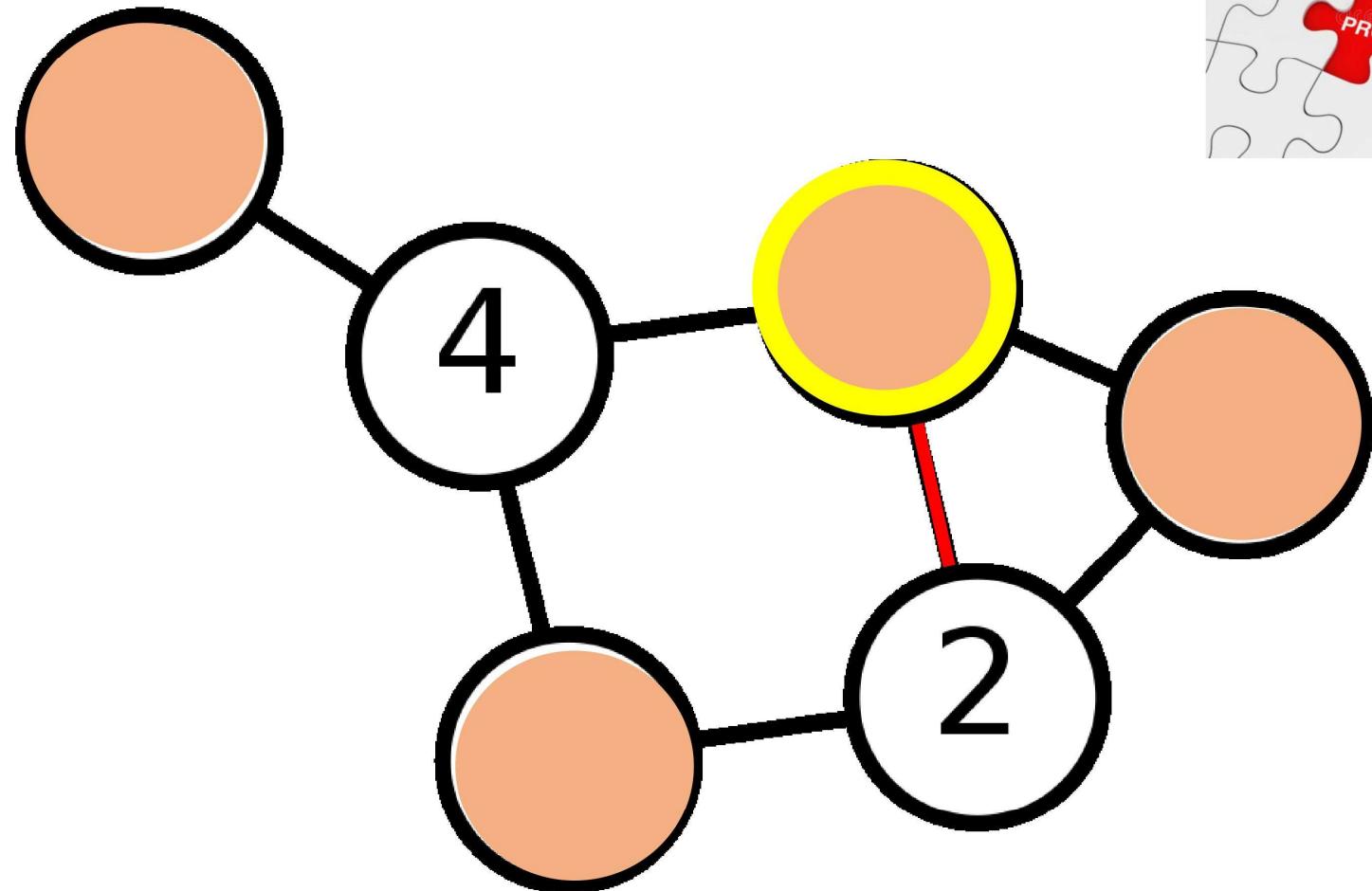
ריכוז הودהודי



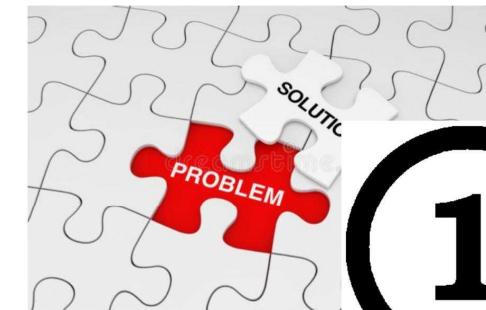
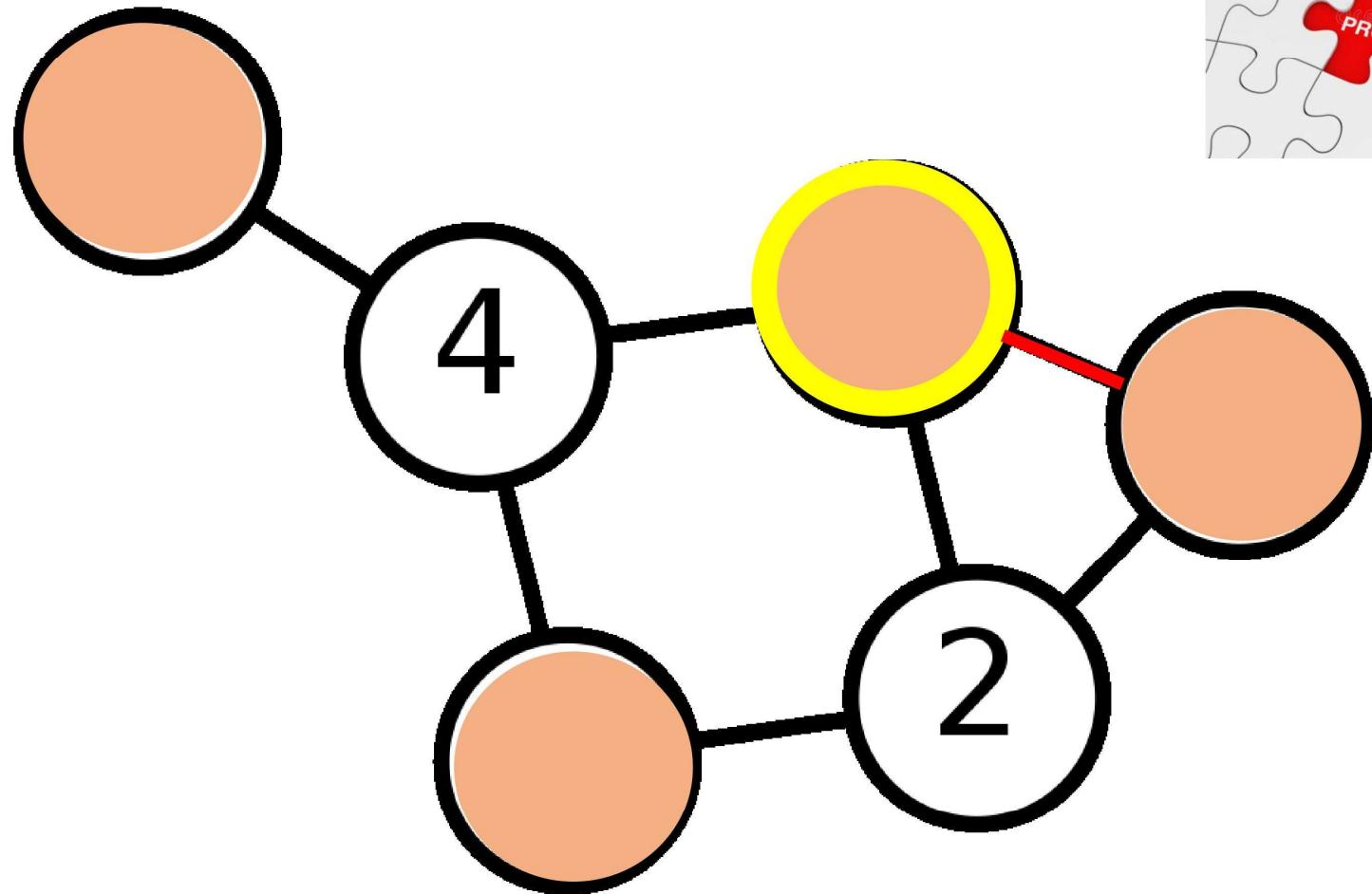
ריכוז הودהודייה

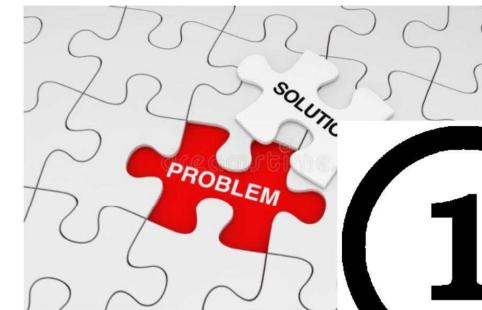
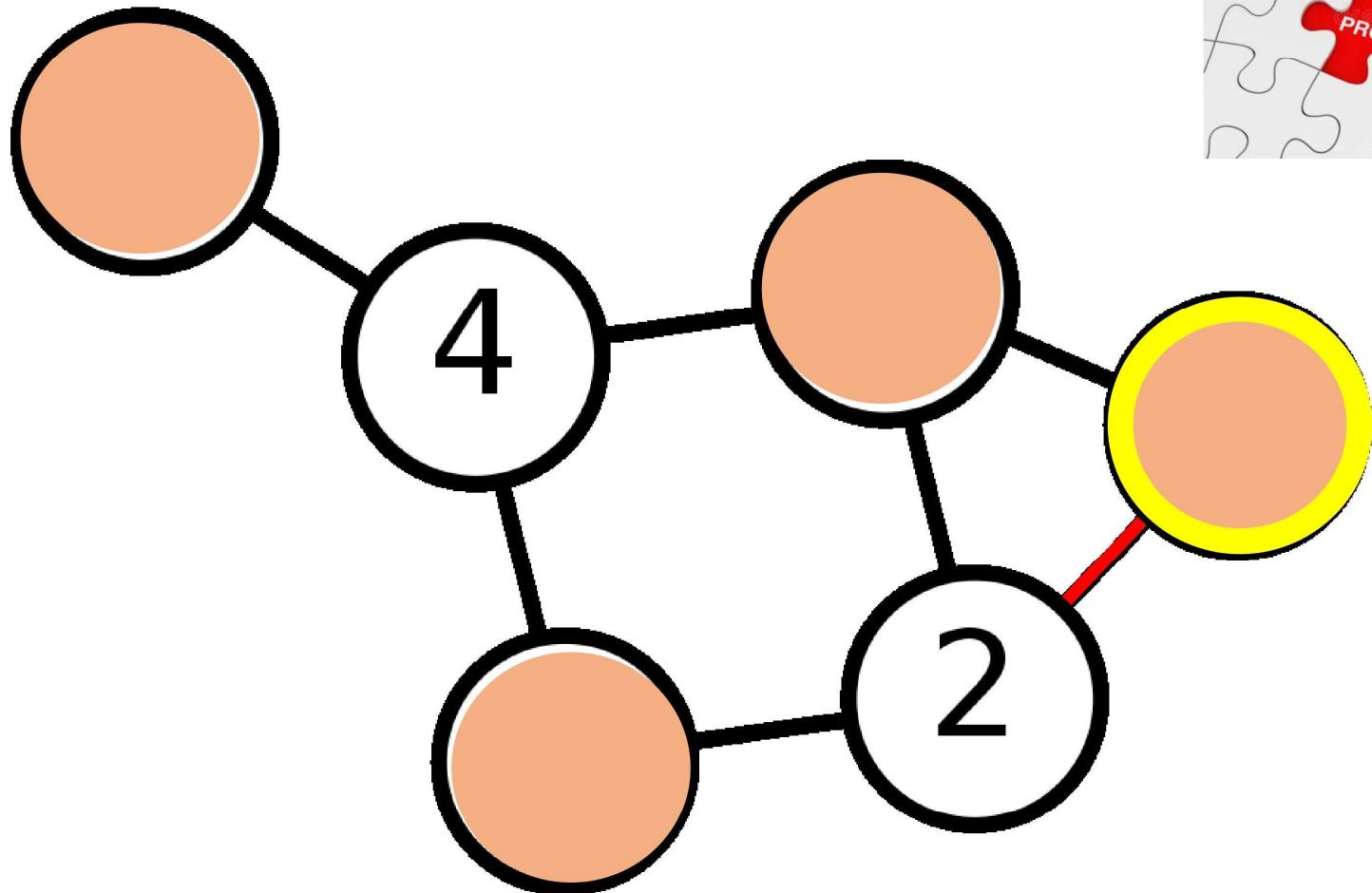


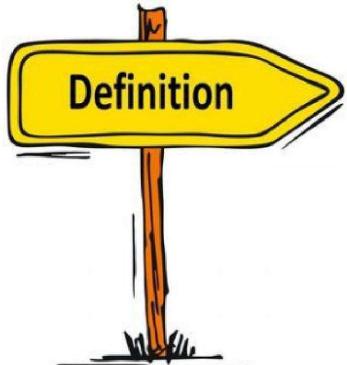
ריכוז הودהות



ריכוז הودהות







כיסוי קודקודים

כיסוי על ידי קודקודים (vertex cover) של גרף בchner
מכוון ($G = (V, E)$) הוא

תת קבוצה $V' \subseteq V$ כך שאם $(u, v) \in E$, אז $u \in V'$ או $v \in V'$.
(או שניהם).



כיסוי קודקודים

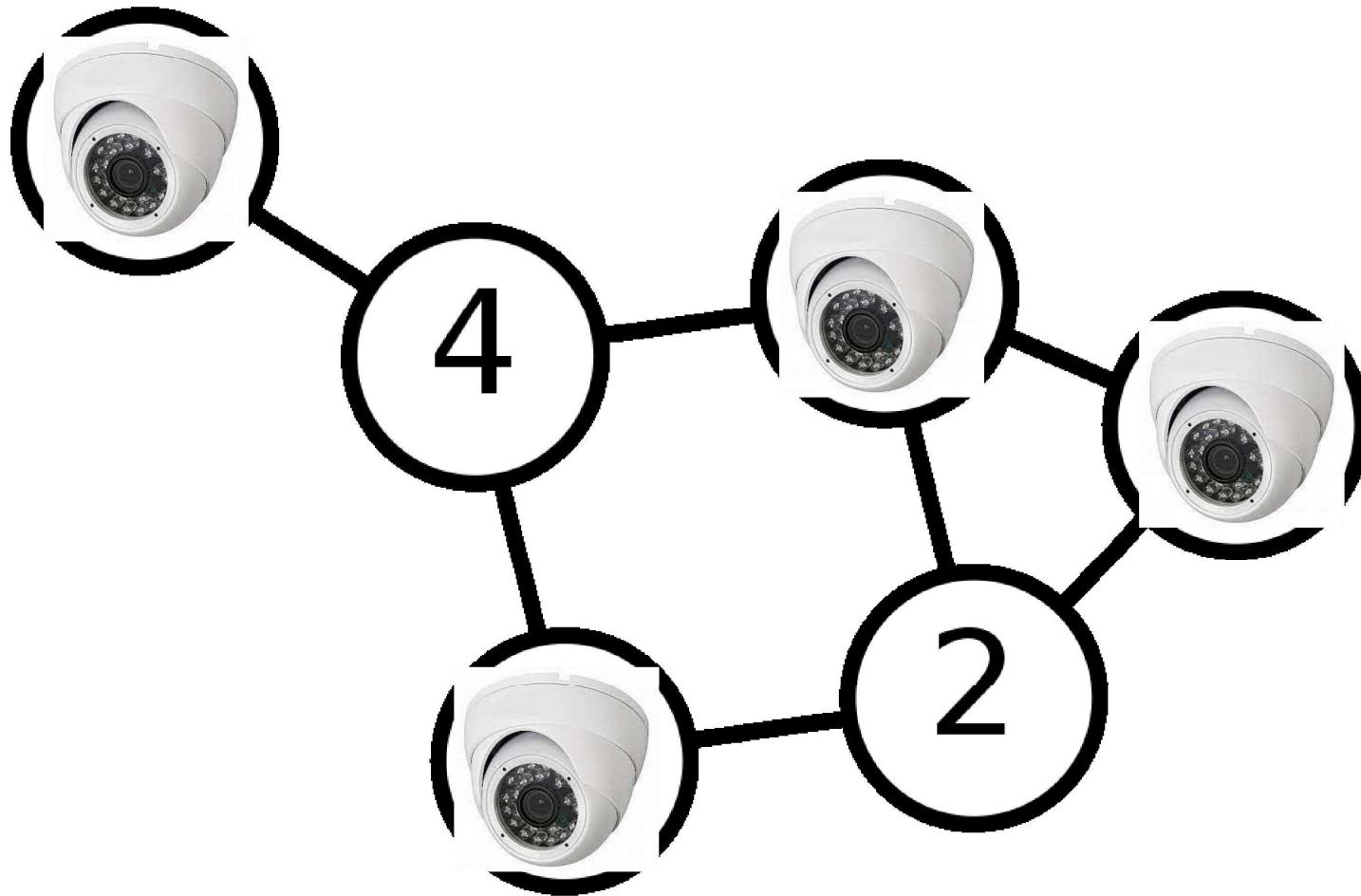
כיסוי על ידי קודקודים (*vertex cover*) של גרף בchner
מכוון $(E, V) = G$ הוא

תת קבוצה $V \subseteq V$ כך שאם $E \in E$, אז $v \in V$ או $u \in V$ (או שניהם).

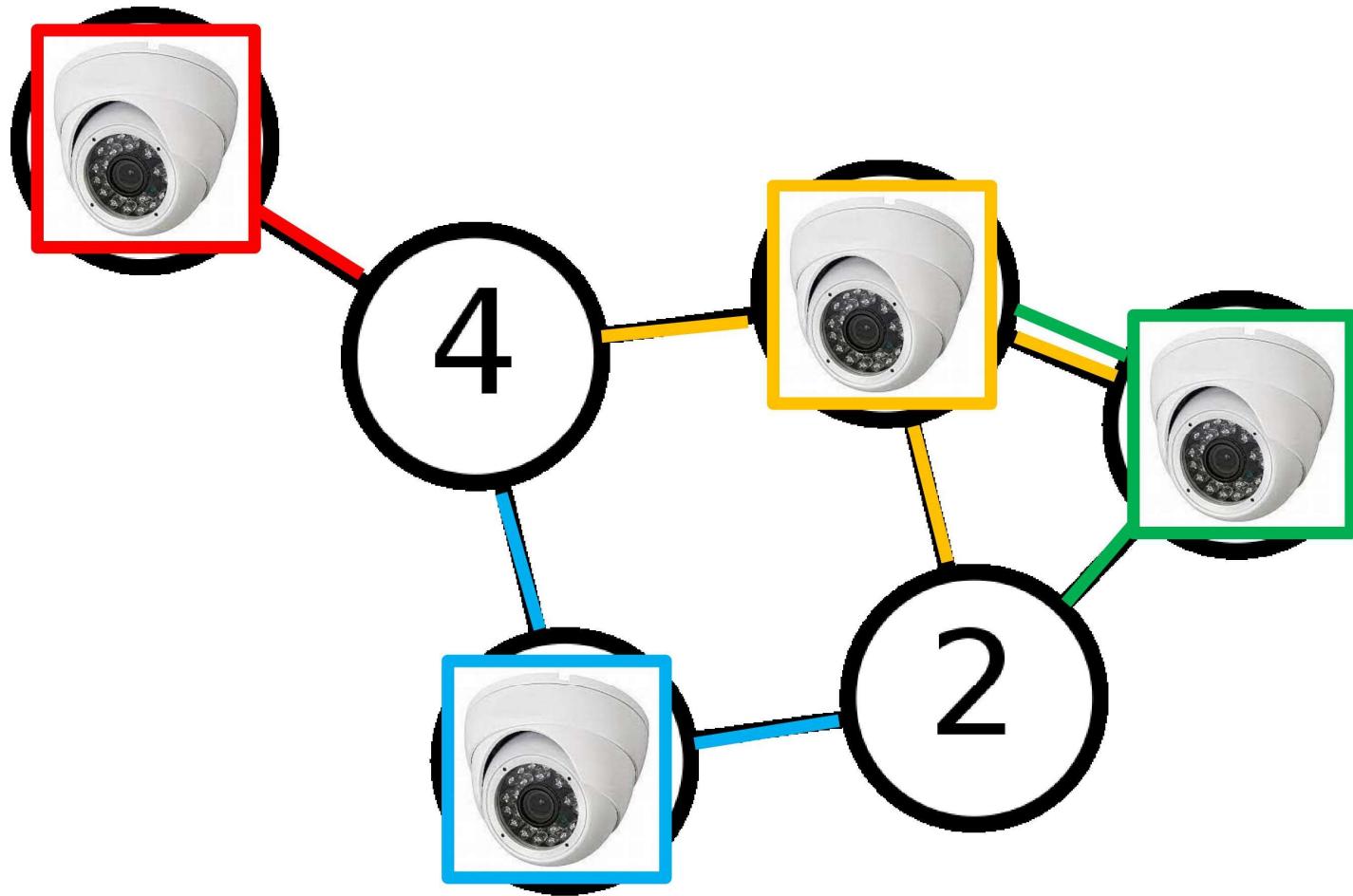
מה הבעיה מעניינת?
מה יכולה לייצג בחינם האמתיים?



תיאור חלחות ארכואה רפחתי מחדרו



תיאור חלחות אבטחה רפחתי מודרנו





כעיהת כיסוי קודקודים

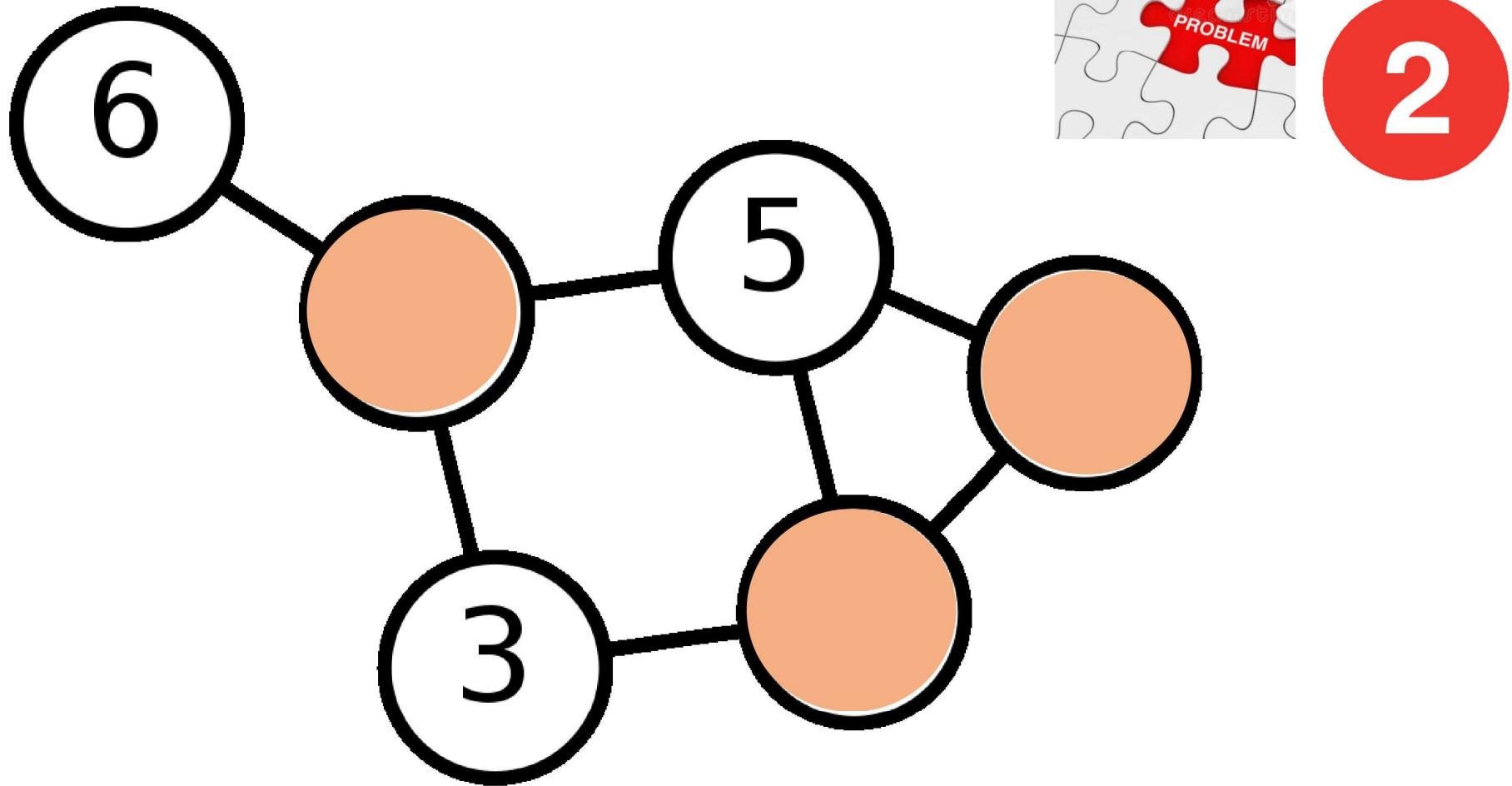
כיסוי על ידי קודקודים (*vertex cover*) של גרף בchner
מכוון ($G = (V, E)$) הוא

תת קבוצה $V \subseteq V$ כך שאם $v, u \in V$, אז $(v, u) \in E$ או $(u, v) \in E$.
(או שניהם).

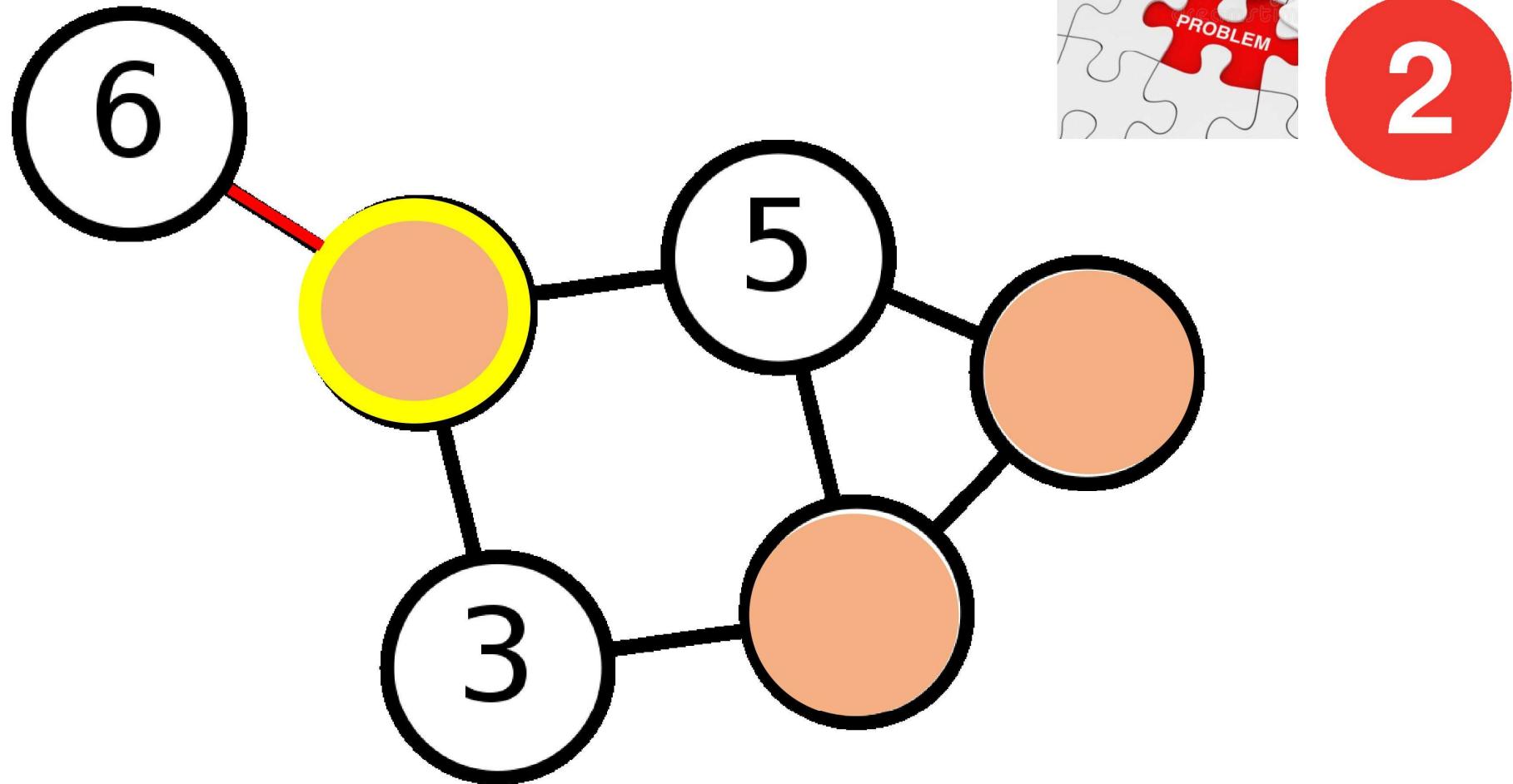


מציאת הכיסוי המינימלי

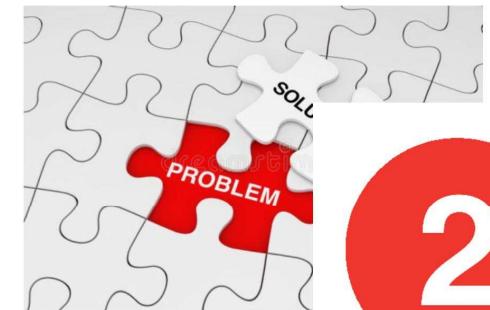
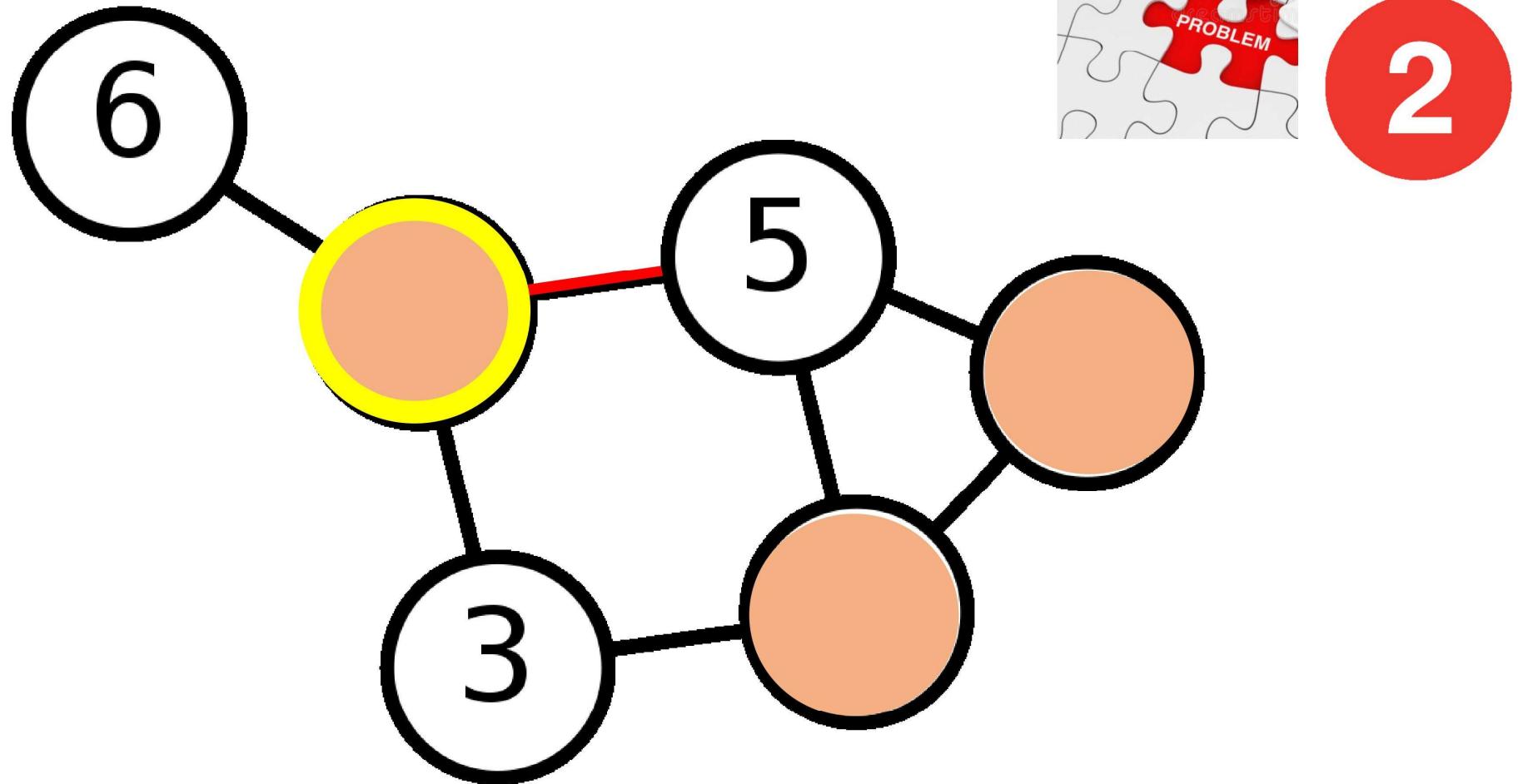
רוויזיה ריבוחית הדרודוית



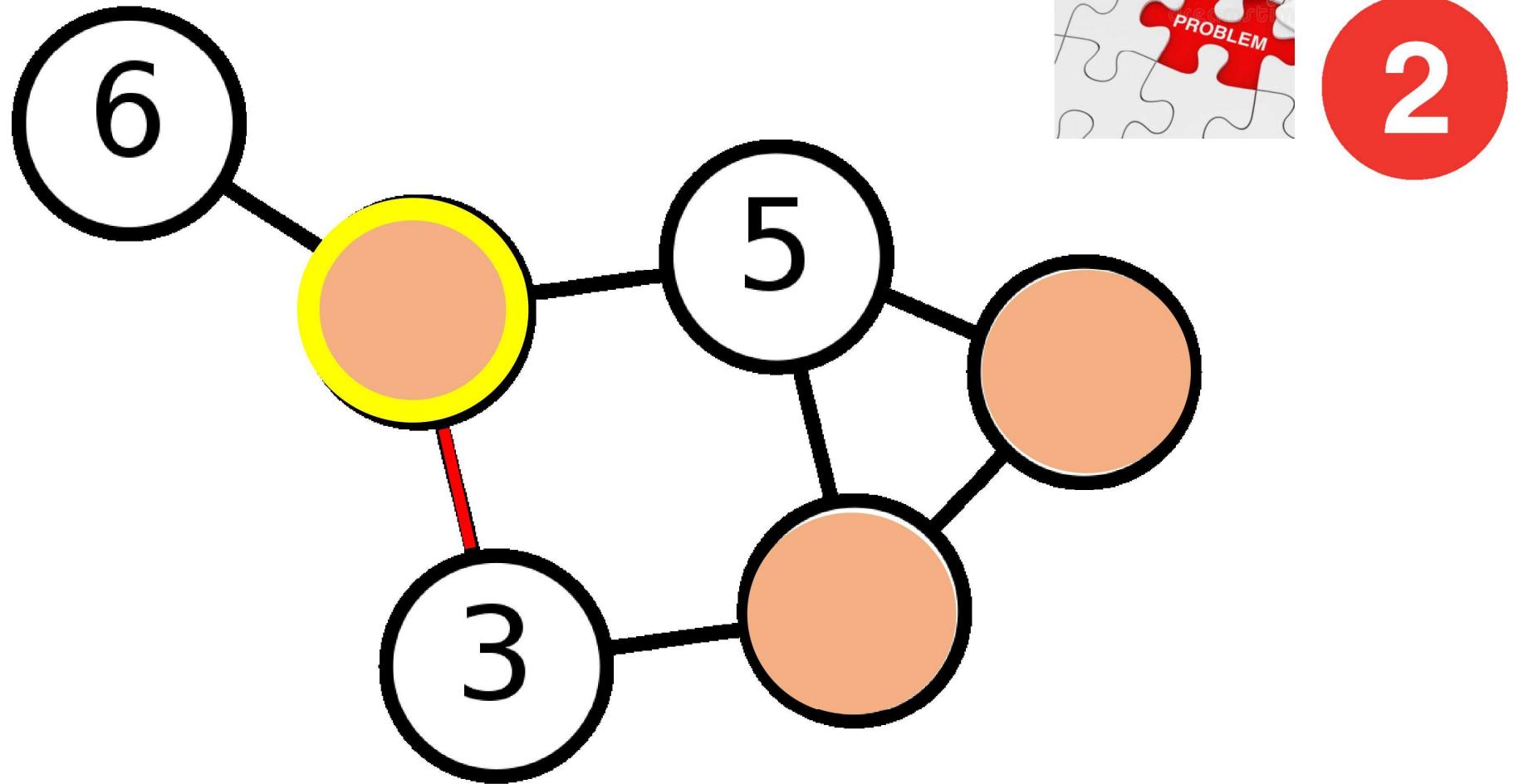
רוויזיה ריבוחית הדרודוינית



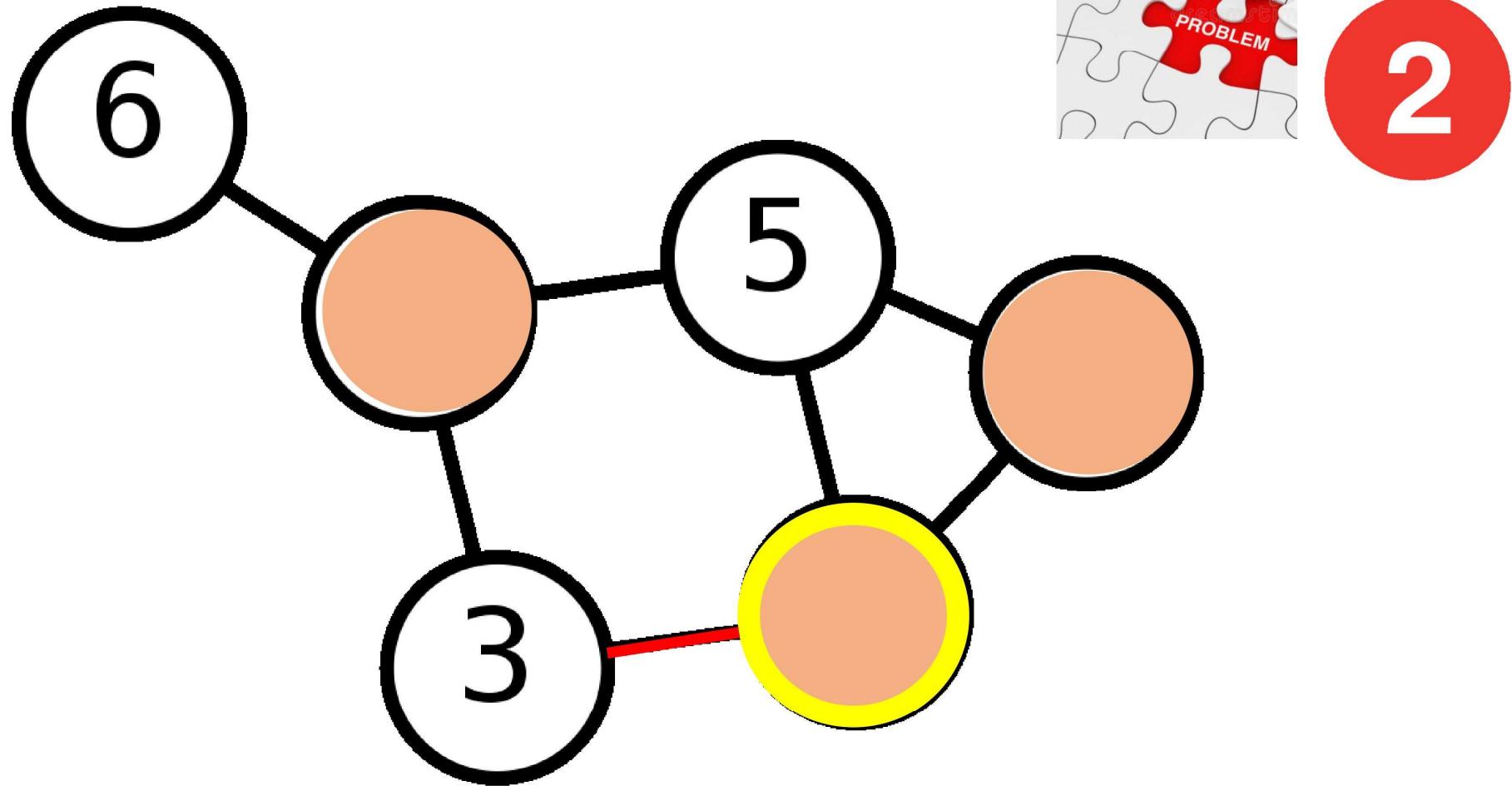
רוויזיה ריבוחית הדרודוינית



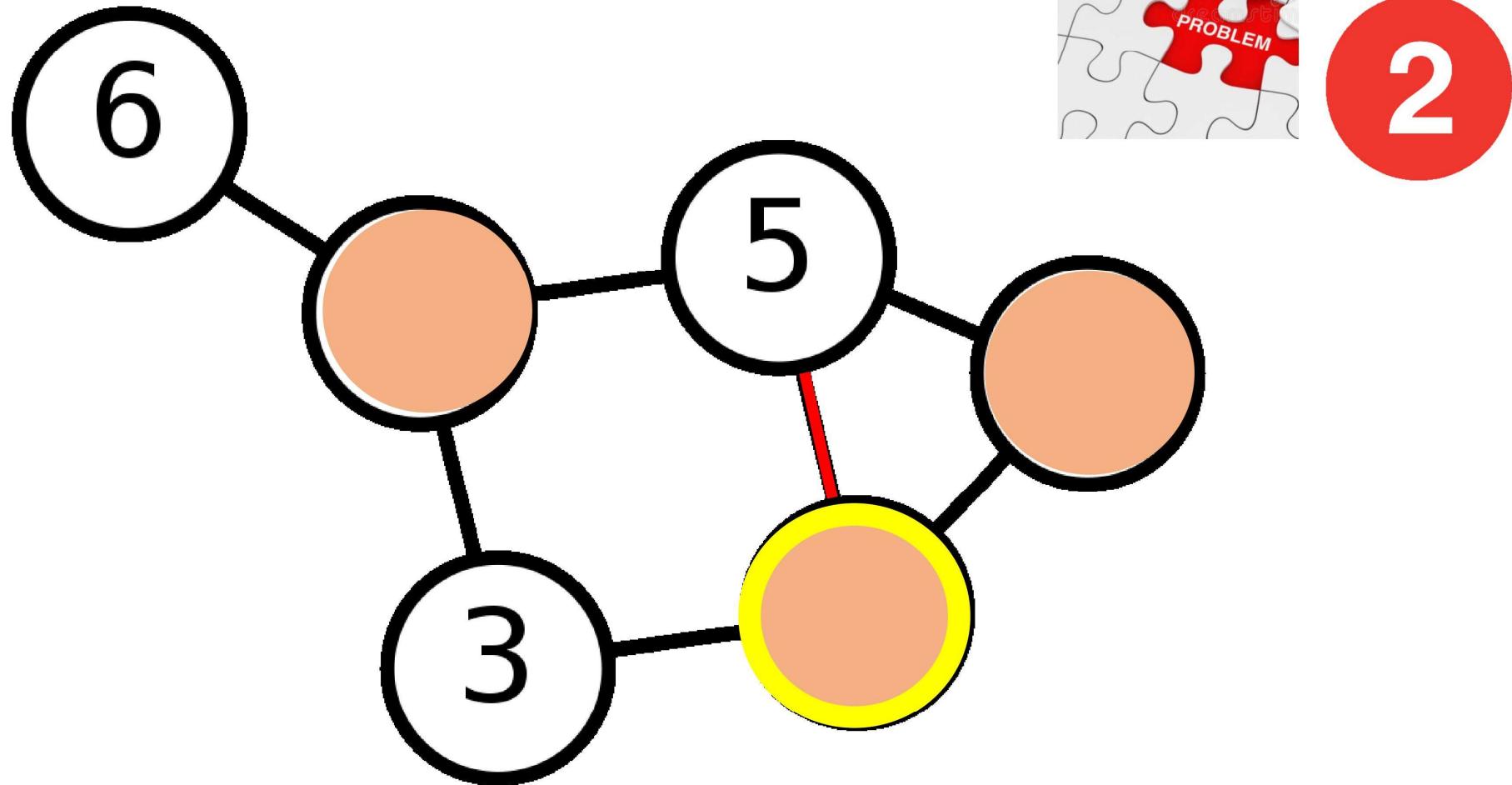
רוויזיה ריבוחית הדרודוינית



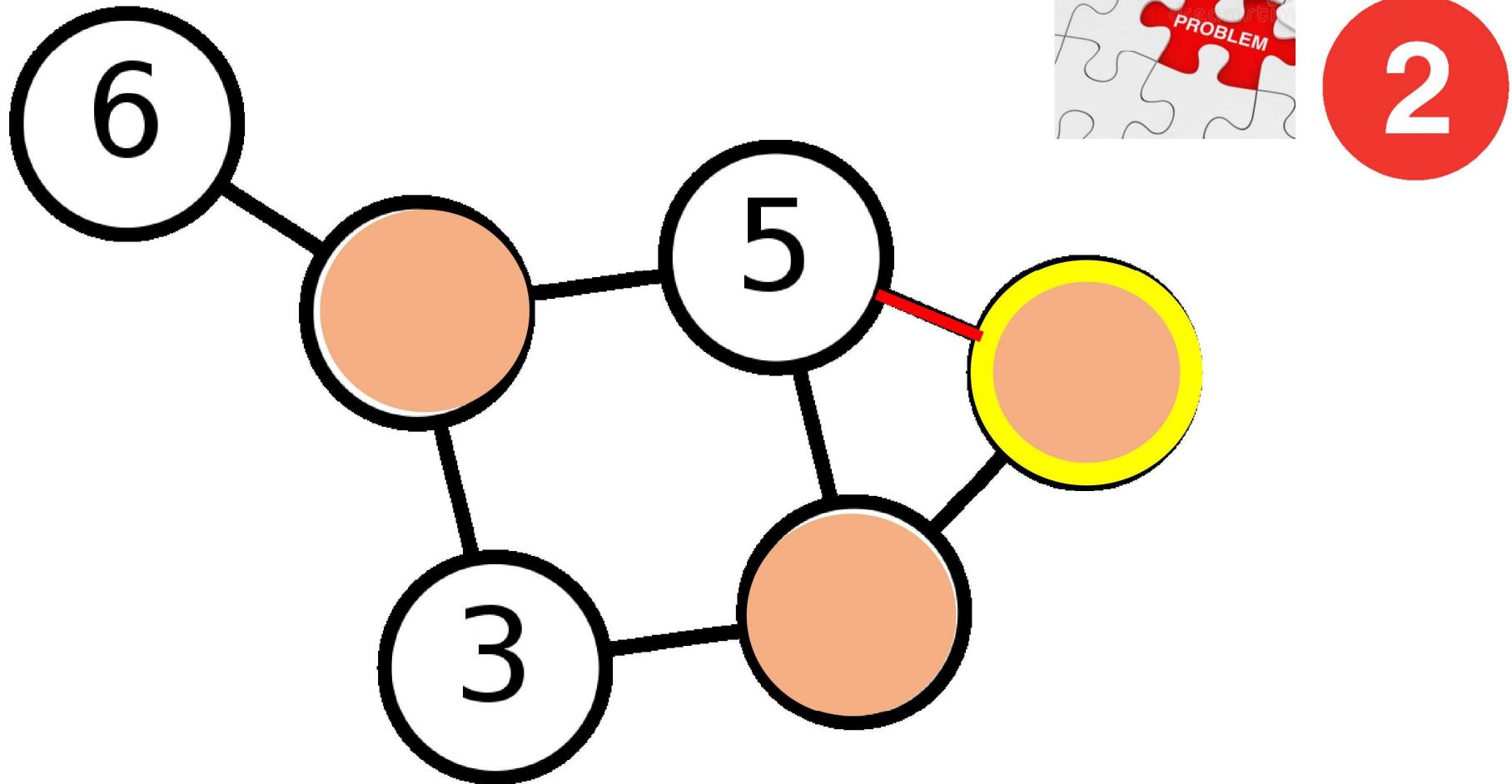
רוויזיה ריבוחית הדרודוידית



רוויזיה ריבוחית הדרודוידית

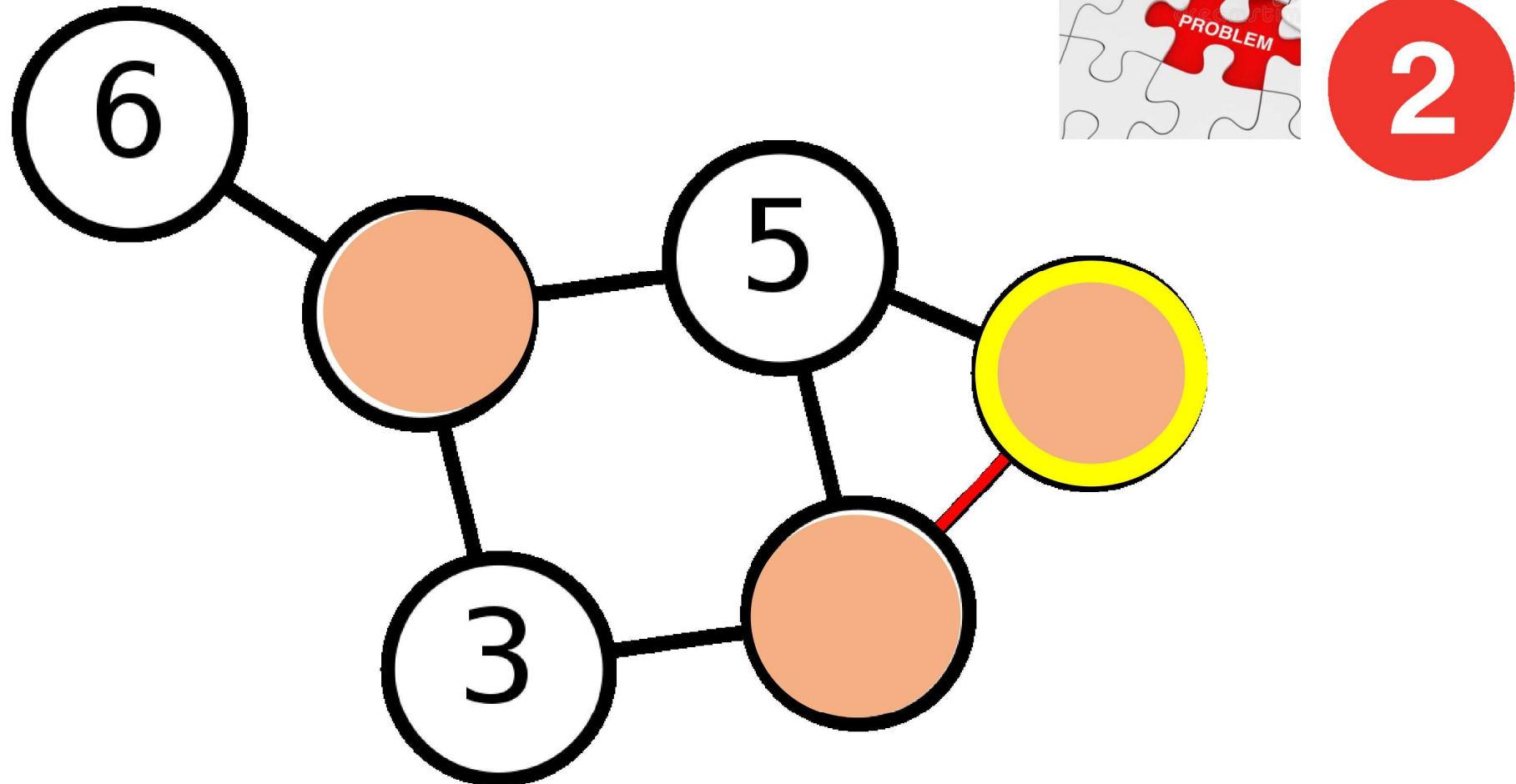


רוויזיה ריבוחית הדרודוידית



2

רוויזיה ריבוחית הדרודוידית





כעיהת כיסוי קודקודים

כיסוי על ידי קודקודים (*vertex cover*) של גרף בchner
מכוון ($G = (V, E)$) הוא

תת קבוצה $V \subseteq V$ כך שאם $v, u \in V$, אז $(v, u) \in E$ או $(u, v) \in E$.
(או שניהם).

NP שלמה

מציאת הכיסוי המינימלי



כעית כיסוי קודקודים

כיסוי על ידי קודקודים (vertex cover) של גרף בchner
מכוון ($G = (V, E)$) הוא

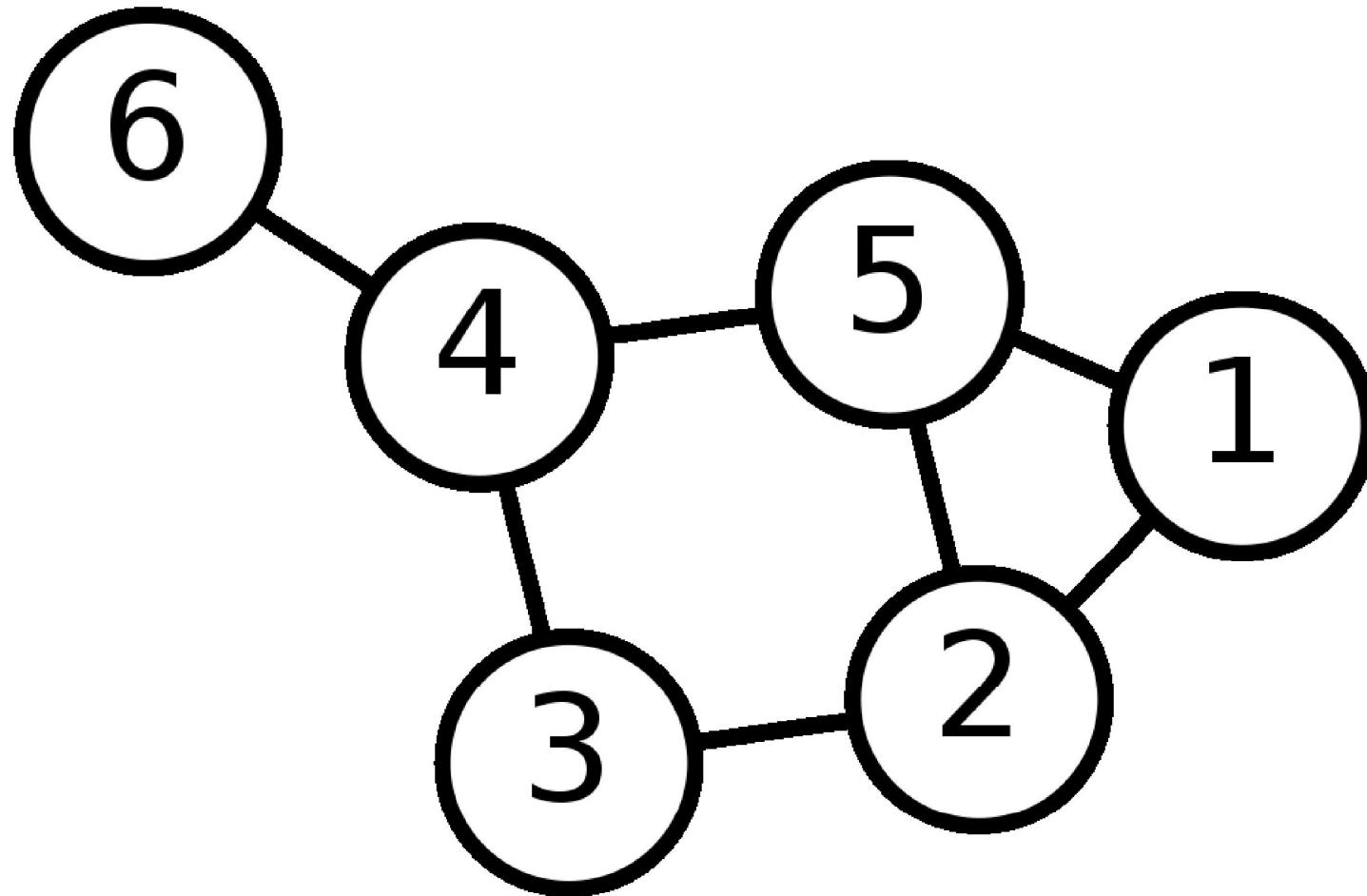
תת קבוצה $V \subseteq V$ כך שאם $v, u \in V$, אז $(v, u) \in E$ או $(u, v) \in E$
(או שניהם).

NP שלמה

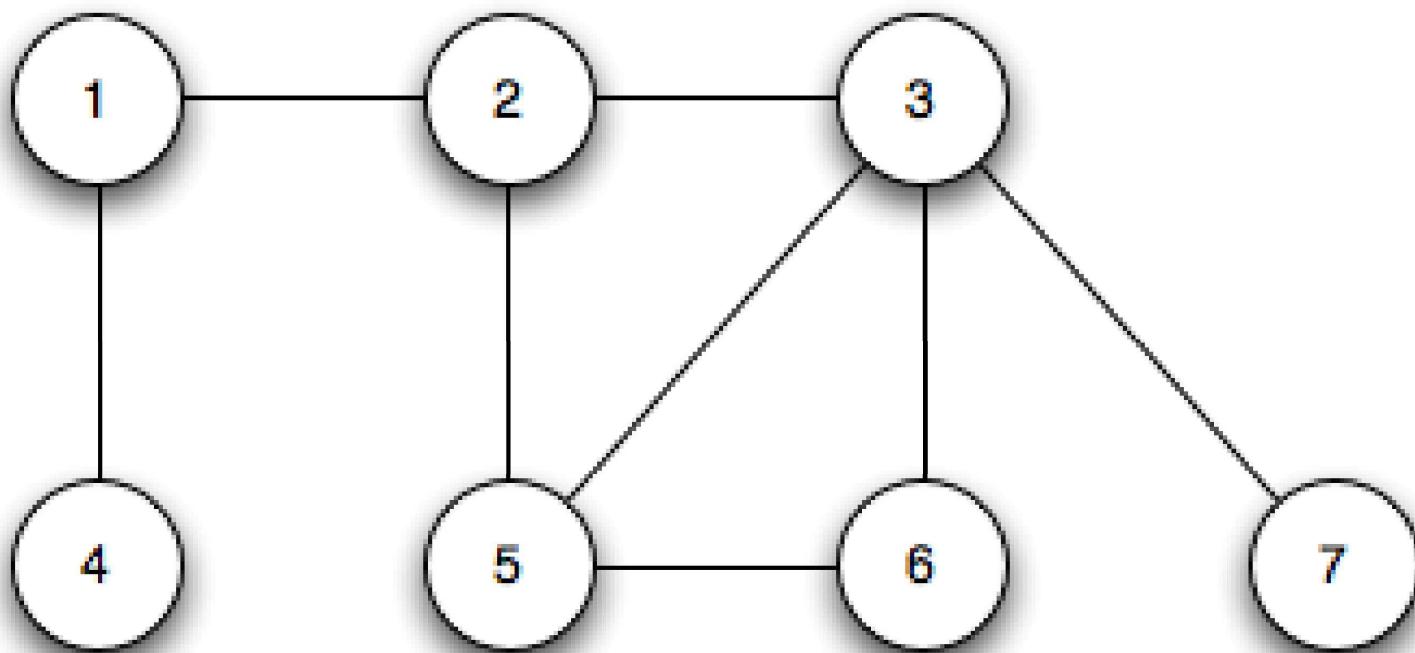
מציאת הכיסוי המינימלי



אלגוריתם הירולר לרשייה ריבוי הודהות

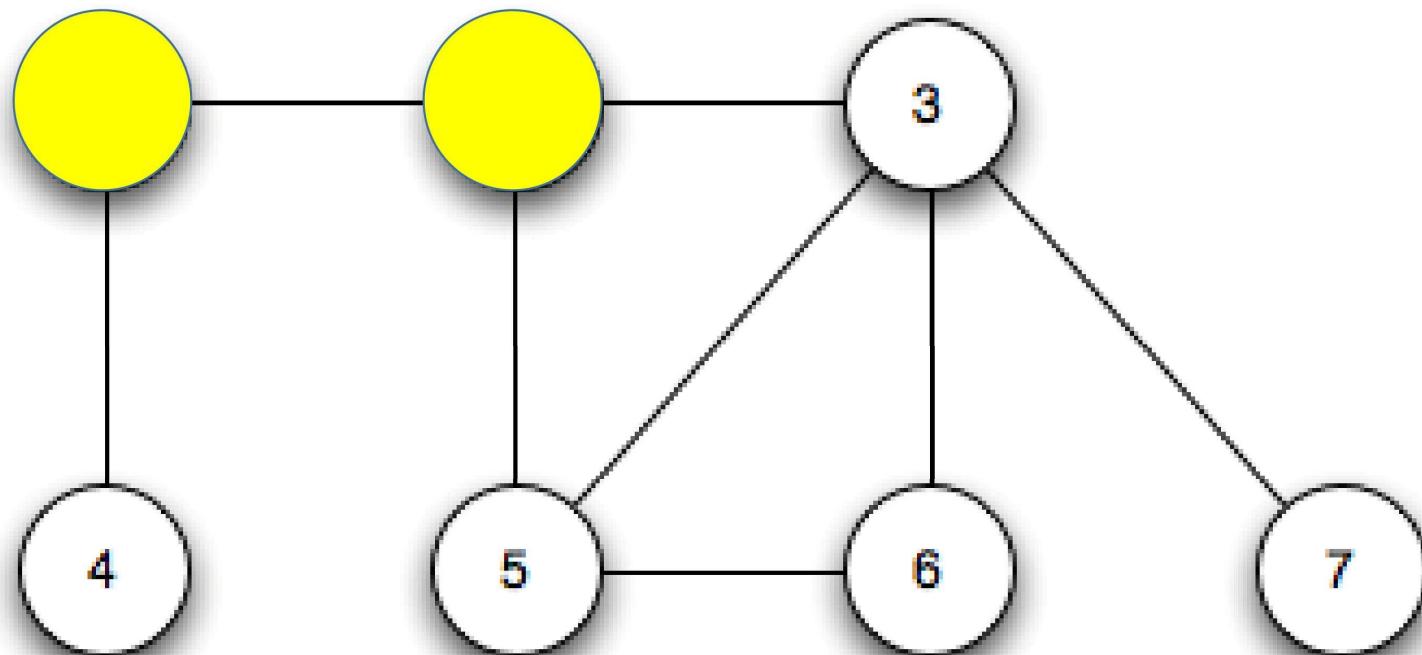


אתחול אלגוריתם קירוב לביעית כיסוי קודקודים



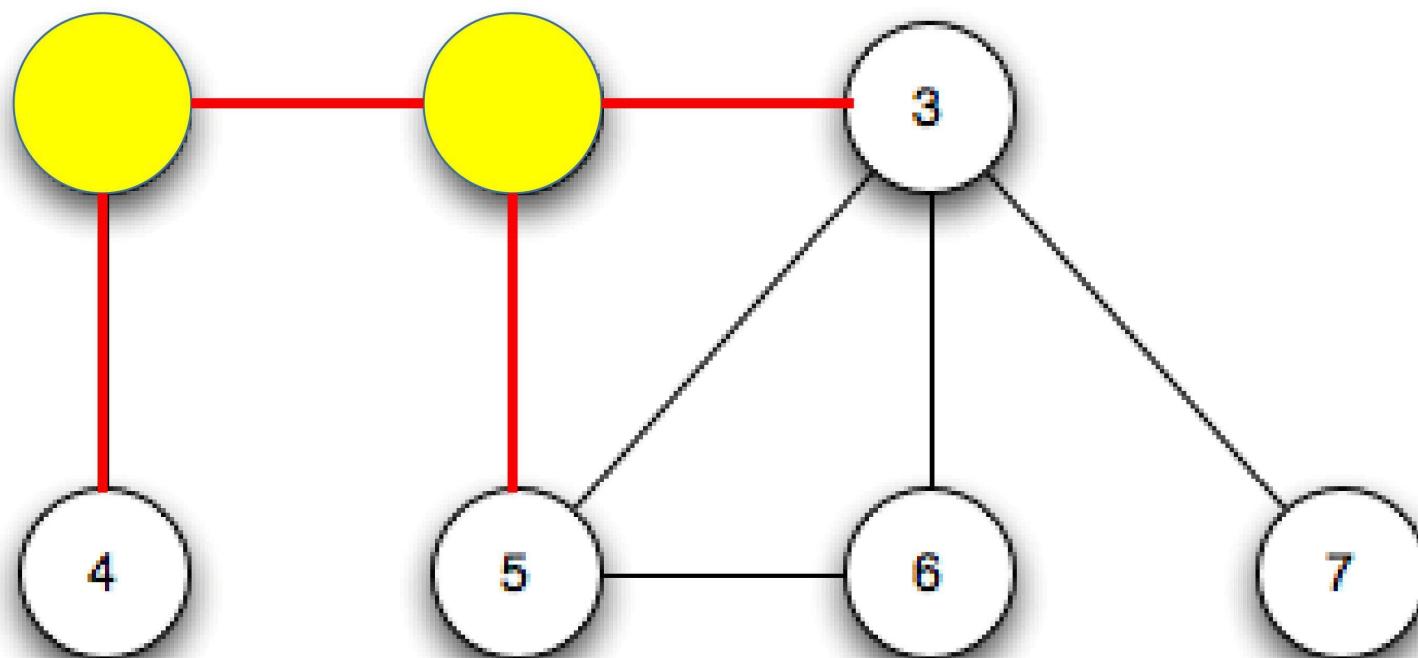
E'	C
(1,4)	
(1,2)	
(2,5)	
(2,3)	
(3,5)	
(3,6)	
(3,7)	
(5,6)	

בחר צלע מהקבוצה E' - הכנס את קדקודיה ל- C
אלגוריתם קירוב לביעית כיסוי קודקודים



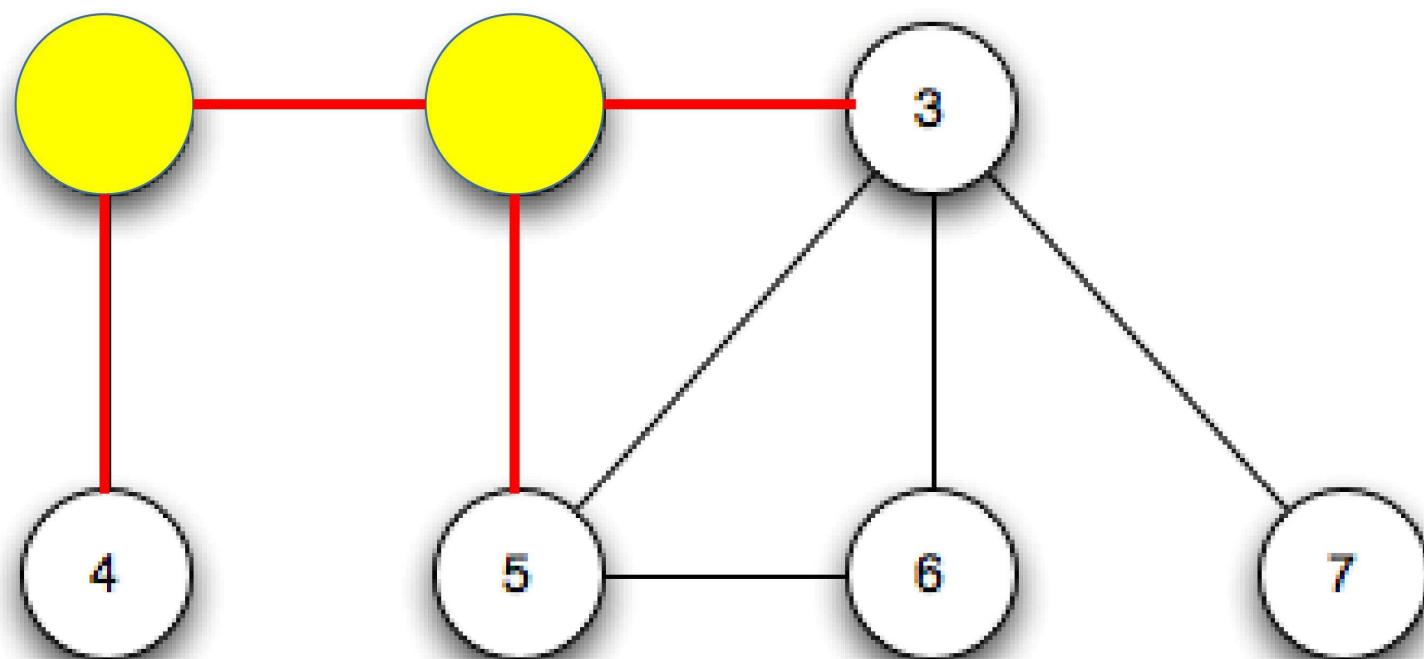
E'	C
(1,4)	1
(1,2)	2
(2,5)	
(2,3)	
(3,5)	
(3,6)	
(3,7)	
(5,6)	

הסר את הצלעות מ- E' המכוסות על ידי הקודקודים שנוספו ל- C
אלגוריתם קירוב לביעית כיסוי קודקודים



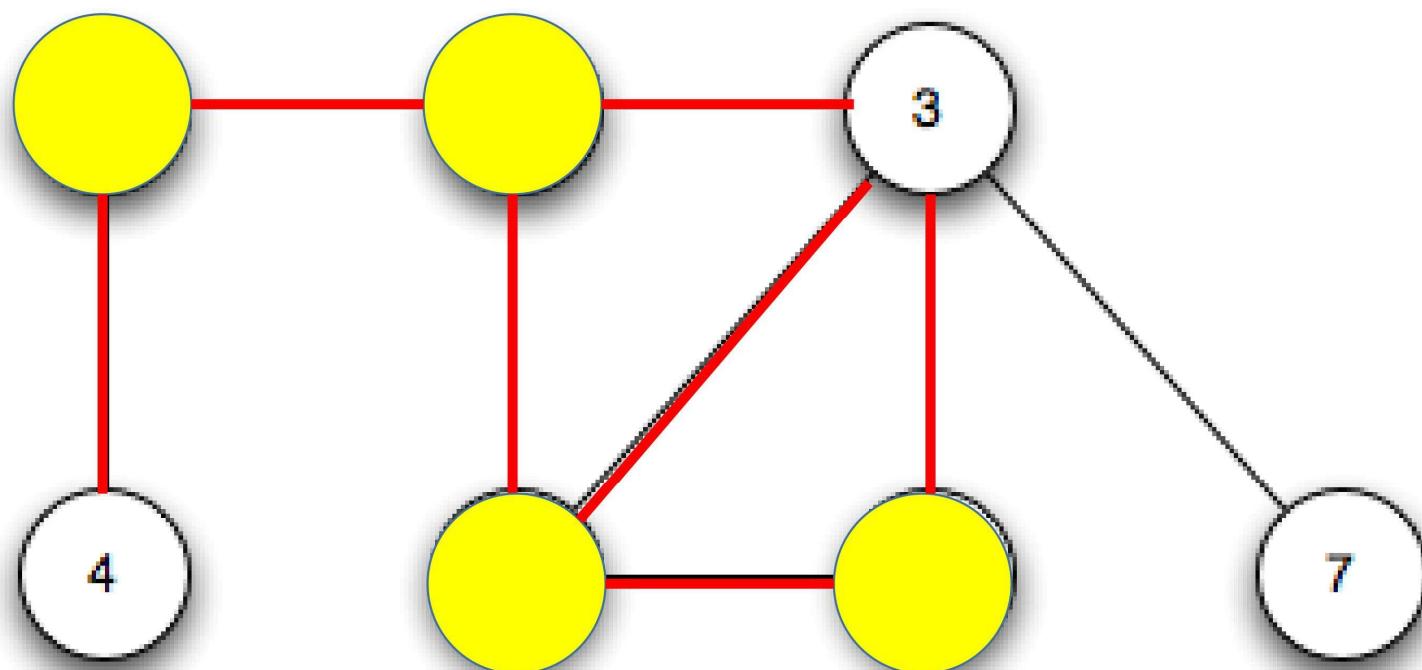
E'	C
(1,4)	1
(1,2)	2
(2,5)	
(2,3)	
(3,5)	
(3,6)	
(3,7)	
(5,6)	

אלגוריתם קירוב לביעית כיסוי קודקודים



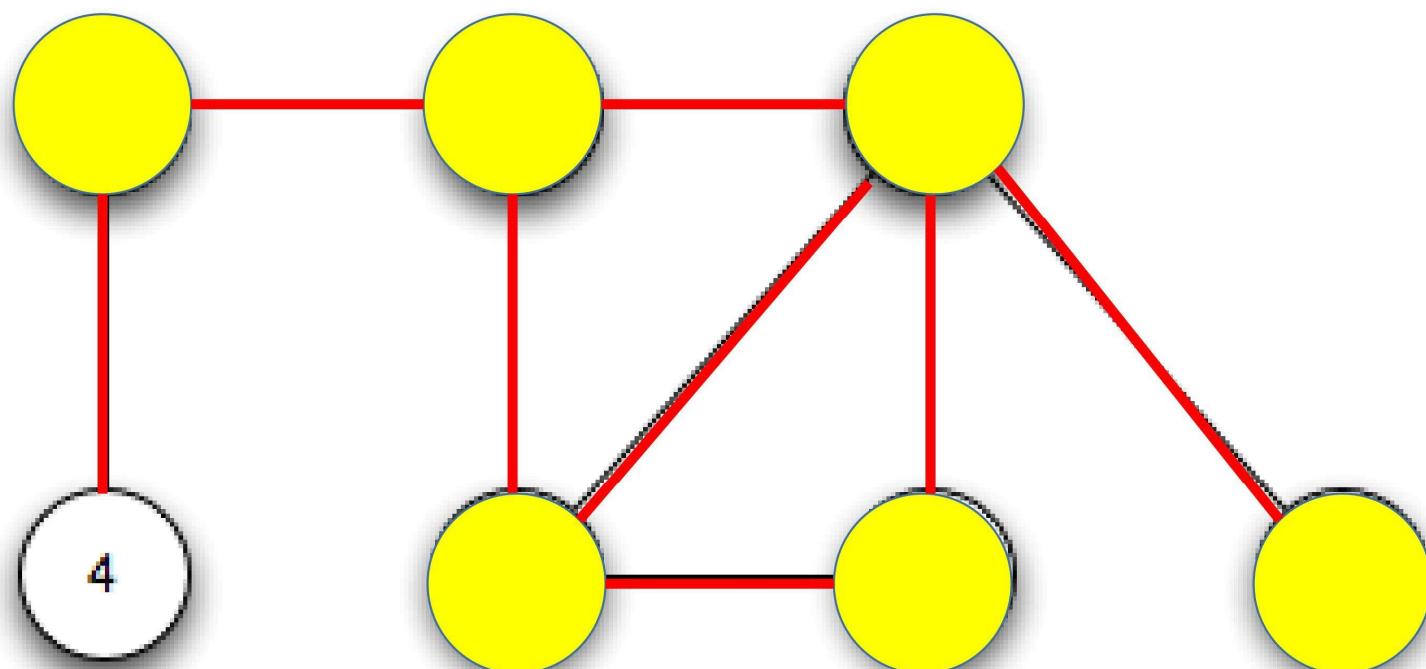
E'	C
	1
(1,2)	2
(3,5)	
(3,6)	
(3,7)	
(5,6)	

אלגוריתם קירוב לביעית כיסוי קודקודים



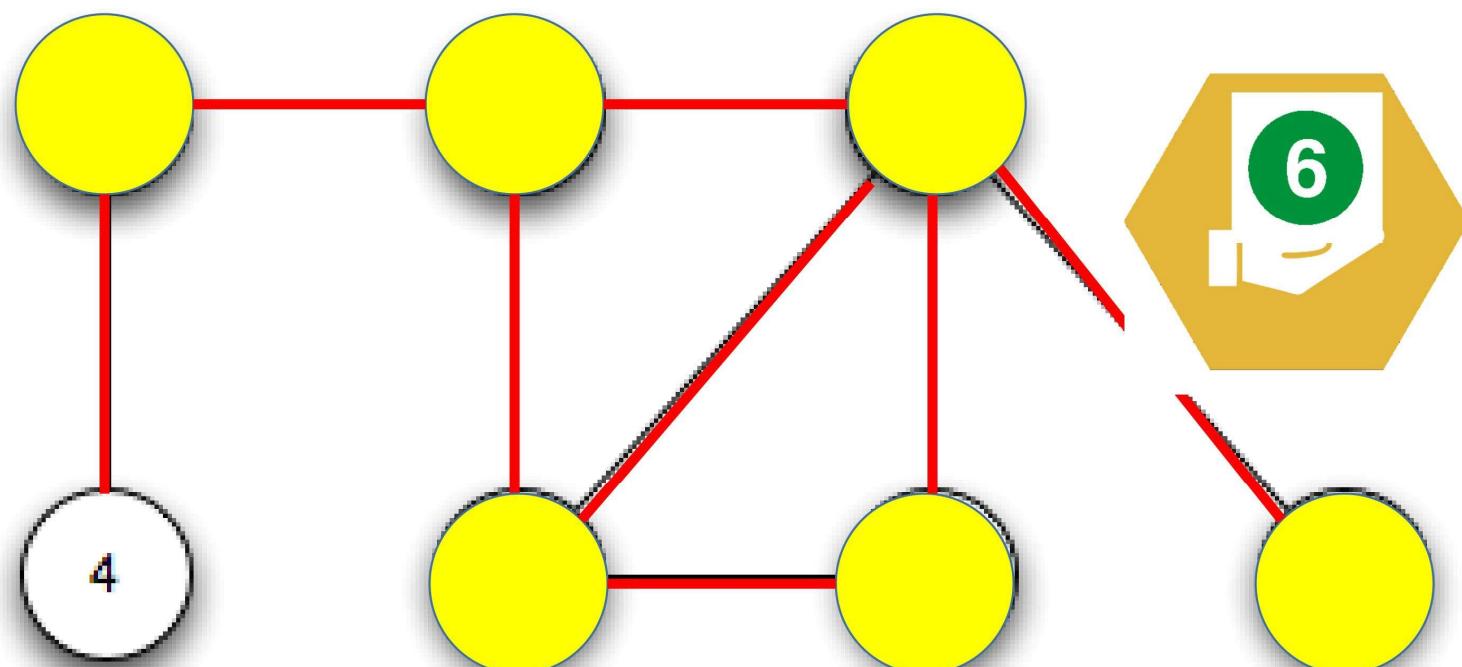
E'	C
	1
(1,2)	2
	5
	6
(3,7)	
(5,6)	

אלגוריתם קירוב לביעית כיסוי קודקודים



E'	C
	1
(1,2)	2
	5
	6
	3
	7
(3,7)	
(5,6)	

אלגוריתם קירוב לביעית כיסוי קודקודים

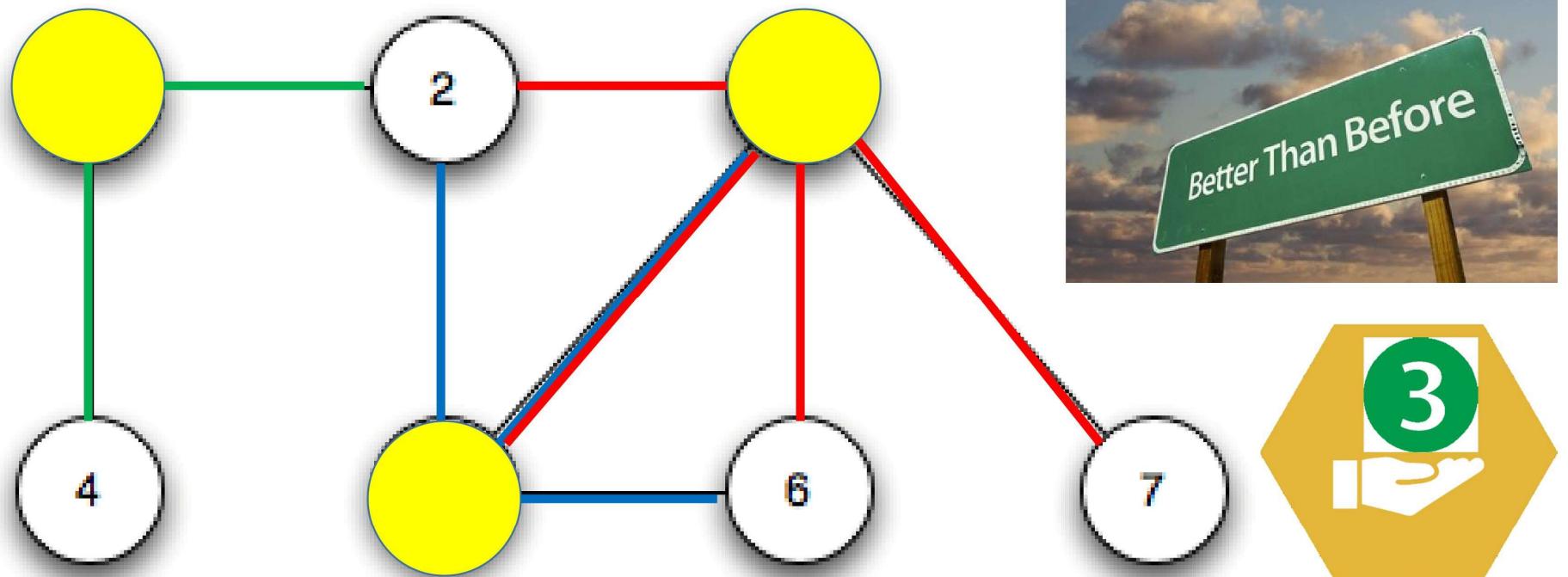


E'	C
	1
(1,2)	2
	5
	6
	3
	7
(3,7)	
(5,6)	

APROX-VERTEX COVER(G)

1. $C \leftarrow \emptyset$
2. $E' \leftarrow E$
3. **while** $E' \neq \emptyset$
4. **do let** (u, v) **be an arbitrary edge of** E'
5. $C \leftarrow C \cup \{u, v\}$
6. **remove from** E' **every edge incident on either**
 u **or** v
7. **return** C

אלגוריתם קירוב לביעית כיסוי קודקודים



האלגוריתם קירוב לבעיית CISI קודקודים הוא בעל
יחס קירוב 2

שלב ראשון: מדוּ האלגוריתם מוצא CISI ?

האלגוריתם קירוב לבעית CISI קודקודים הוא בעל
יחס קירוב 2

שלב שני: מדוע האלגוריתם מוצא CISI ?

הקבוצה C שמחזיר האלגוריתם היא CISI קודקודים, כיון
שהאלגוריתם חוזר ומבצע את הלולאה עד שכל קשת ב- G
מכוסה על ידי איזשהו קודקוד ב- C

האלגוריתם קירוב לבעיית CISCO קודקודים הוא בעל
יחס קירוב 2

שלב ראשון: מדוּק קירוב הוא ?

נסמן ב- A את קבוצת הקשתות (v, u) שנבחרה בשורה 4.
קבוצת זו אינה מכילה קשתות שלhn צמתים משותפים,
לכן $|A| \cdot 2 = |C|$.

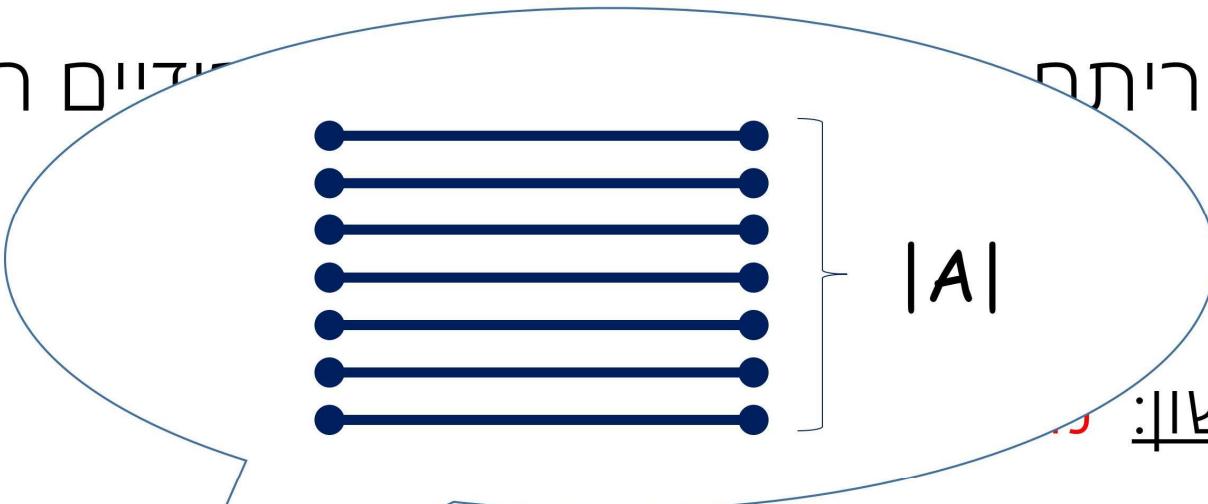
יעדיים הוא בעל

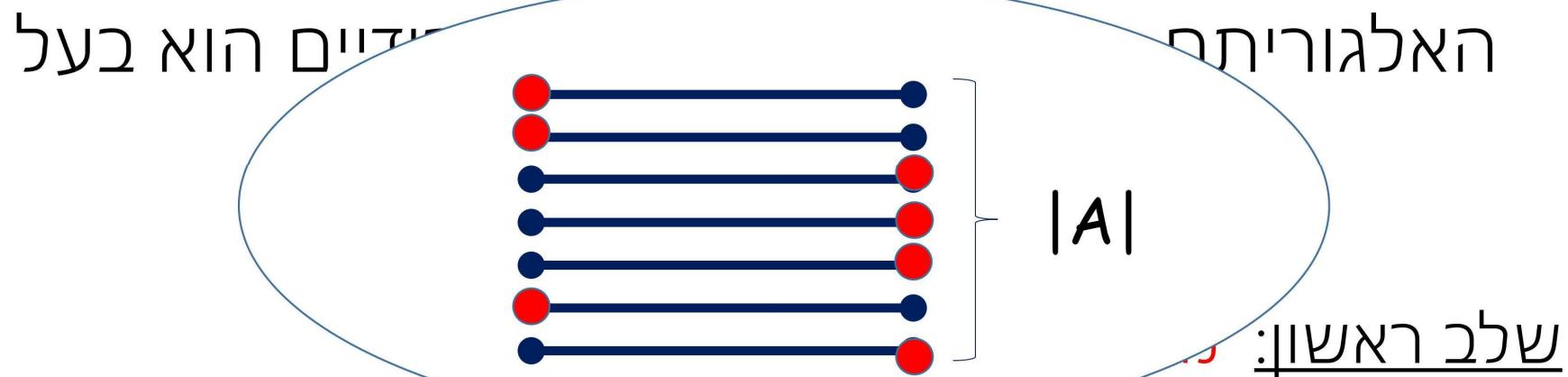
האלגוריתם

$|A|$

שלב ראשון:

נסמן ב- A את קבוצת הקשתות (v, u) שנבעו מה בשורה 4.
קבוצת זו אינה מכילה קשתות שלhn צמתים משותפים,
לכן $|A| \cdot 2 = |C|$.





נסמן ב- C את קבוצת הקשתות (v, u) שנקבעו בה בשורה 4.
קבוצת זו אינה מכילה קשתות שלhn צמתים משותפים,
לכן $|C| = 2 \cdot |A|$.

צמתי הפתרון האופטימלי C^* מכסים את קשתות A ולקן
מכילים לפחות צומת אחד לכל קשת ומוכאן $|C^*| \geq |A|$.
ולכן נקבל, $|C^*| \geq |A|$

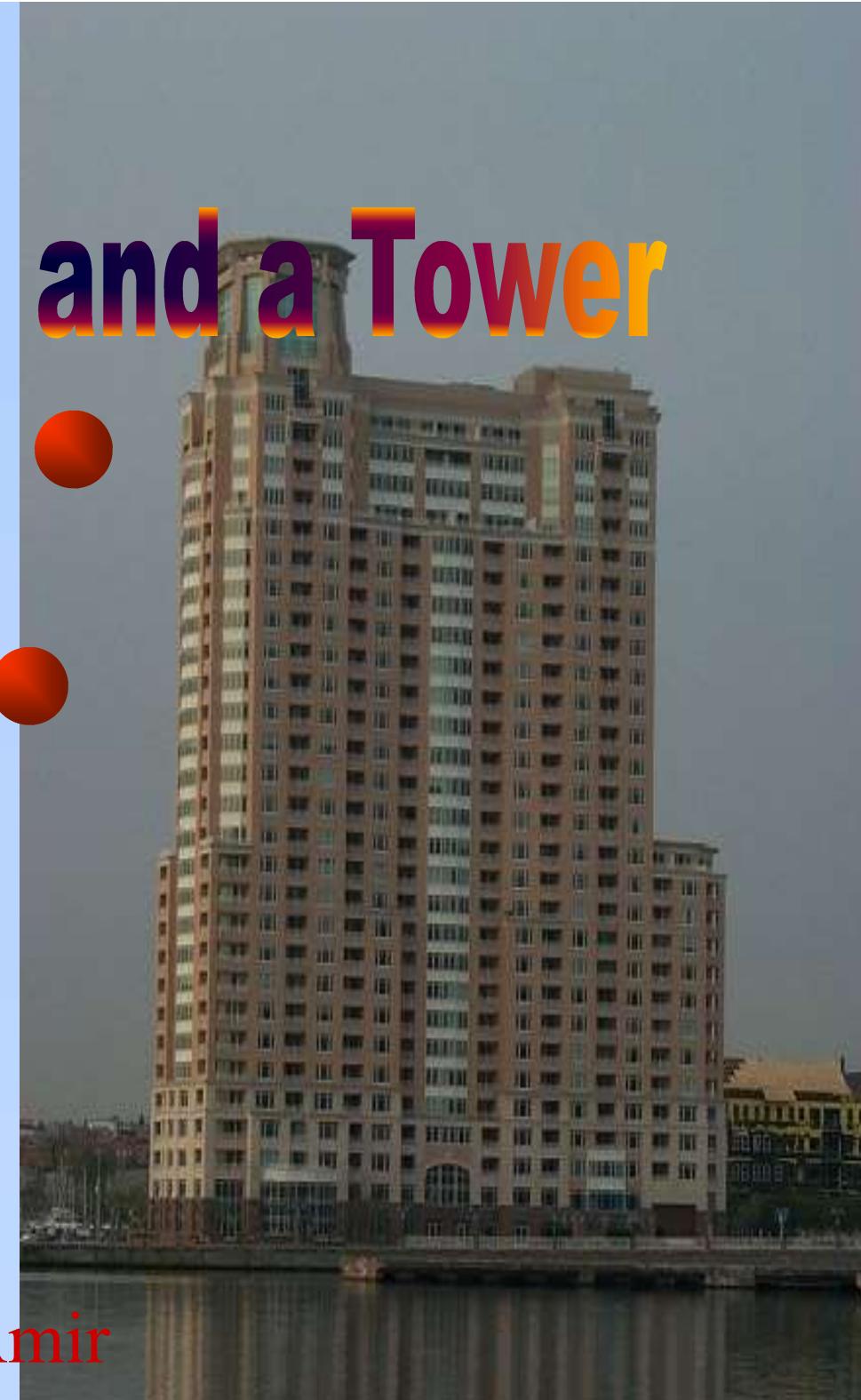
Two Glass Balls and a Tower

Amihood Amir

**Bar Ilan University
And
Georgia Tech**

**Costas Iliopoulos
Oren Kapah
Ely Porat**

Artistic Consultant: Aviya Amir



Given: A glass ball.

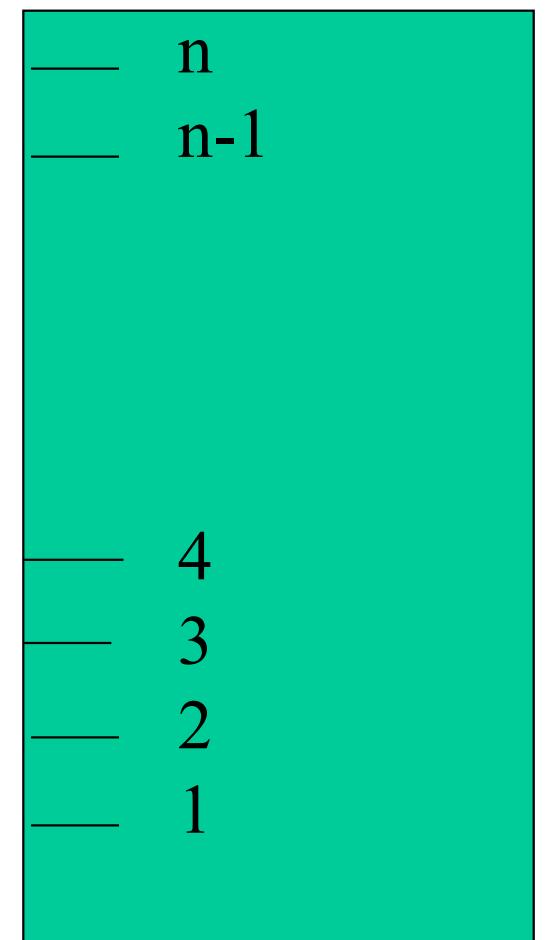
An n storied building.

Find: The floor k such that the ball breaks when dropped from it, but does not break if dropped from floor $k-1$.



KABLOOIE!!!

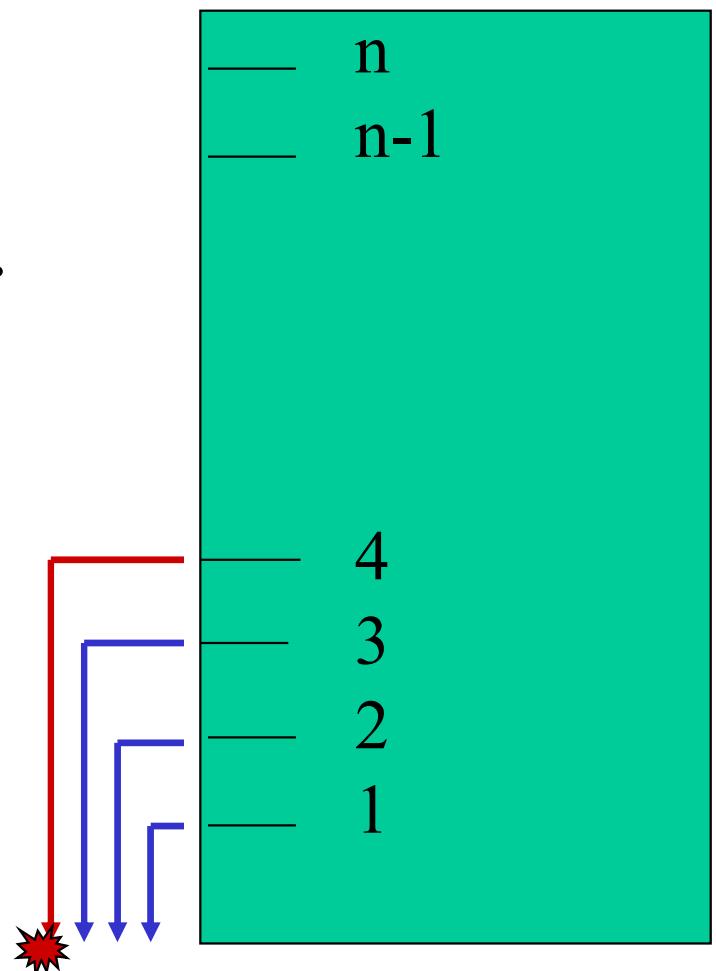
STRATEGY 1: Only *one* ball given to experiment with.



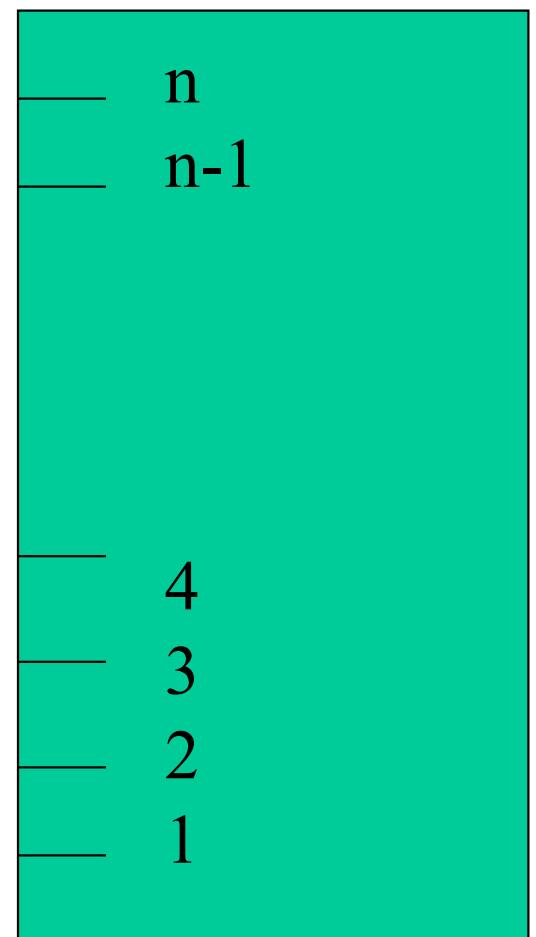
STRATEGY 1: Only *one* ball given to experiment with.

$O(n)$ experiments necessary.

Sequential search.



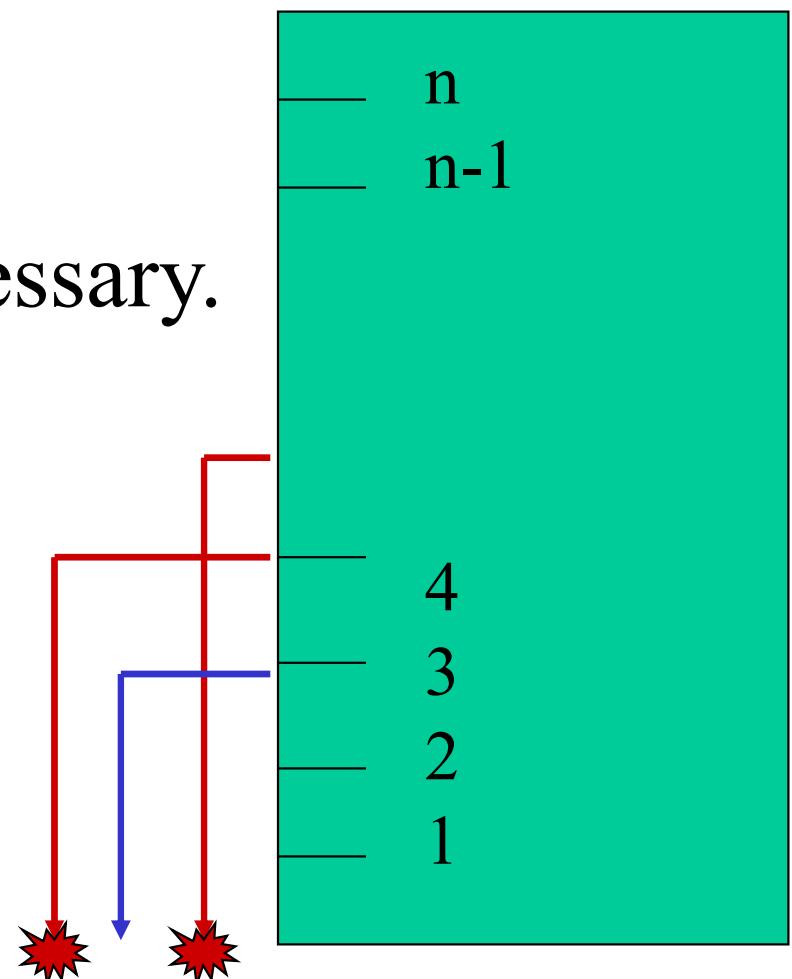
STRATEGY 2: As many balls as necessary are given to experiment with.



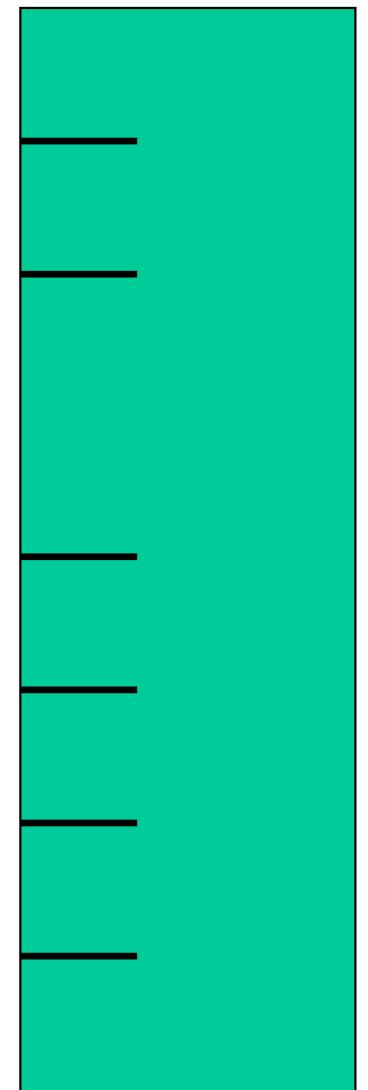
STRATEGY 2: As many balls as necessary are given to experiment with.

$O(\log n)$ experiments necessary.

Binary search.



STRATEGY 3: Only *two* balls given to experiment with.



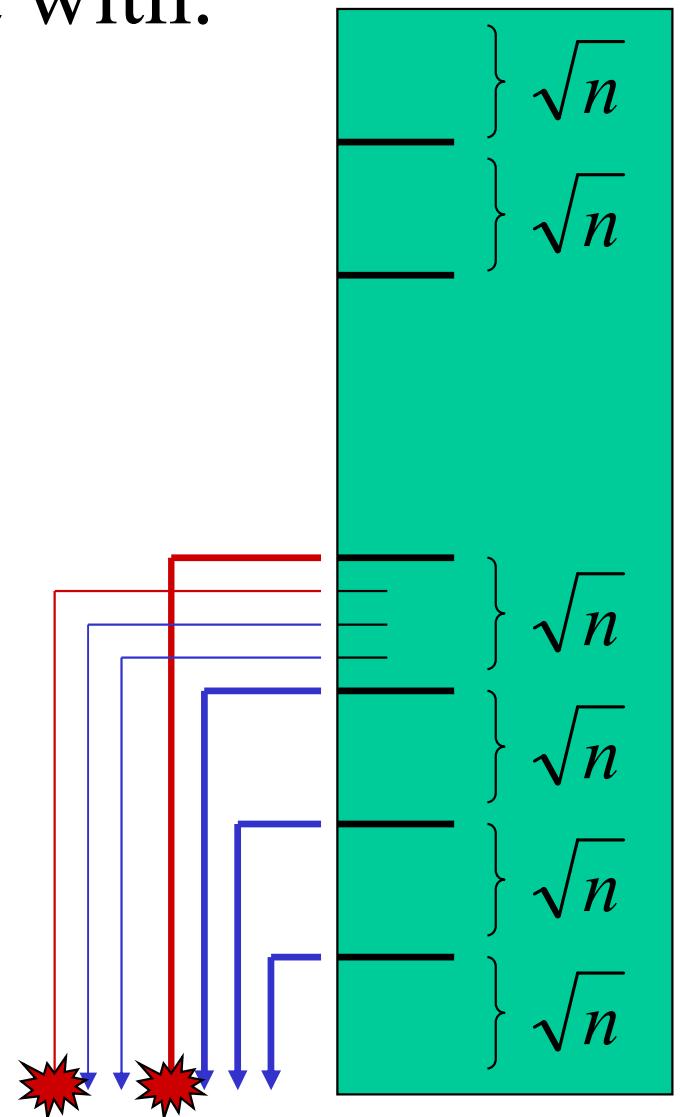
STRATEGY 3: Only *two* balls given to experiment with.

$O(\sqrt{n})$ experiments necessary.

Bounded divide-and-conquer

$O(\sqrt{n})$ Experiments 1st ball

$O(\sqrt{n})$ Experiments 2nd ball



Meaning of two Balls

“Bounded” Divide-and-Conquer.

In reality: Different paradigms.

1. Works on large groups.
2. Works within a group.

In Pattern Matching

1. Works on large groups:

Convolutions:

	b_0	b_1	b_2	b_3	b_4
	a_0	a_1	a_2	a_3	a_4
		b_2	b_1	b_0	
	$a_0 b_0$	$a_1 b_0$	$a_2 b_0$	$a_3 b_0$	$a_4 b_0$
	$a_0 b_1$	$a_1 b_1$	$a_2 b_1$	$a_3 b_1$	$a_4 b_1$
	$a_0 b_2$	$a_1 b_2$	$a_2 b_2$	$a_3 b_2$	$a_4 b_2$
		r_0	r_1	r_2	

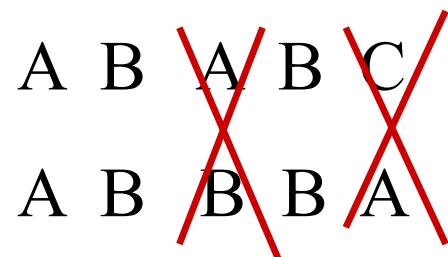
$O(n \log m)$ using FFT

Problem: $O(n \log m)$ only in algebraically closed fields, e.g. \mathbb{C} .

Solution: Reduce problem to
(Boolean/integer/real) multiplication.

This reduction costs!

Example: Hamming distance.



Counting *mismatches* is equivalent to Counting *matches*

Example:

1	0	0	0	1
1	0	0	0	0
1	0	0	1	0
1	0	0	0	0
1	0	0	1	0
<hr/>				
1	0	0	0	0
1	0	0	1	0
1	0	0	0	0
1	0	0	1	0
<hr/>				
1	1	0	0	0
1	1	0	0	0
1	1	0	0	0
1	1	0	0	0
<hr/>				
1	1	0	0	0
1	1	0	0	0
1	1	0	0	0
1	1	0	0	0

Count all “hits” of 1 in pattern and 1 in text.

For $a \in \Sigma$

Define:

$$\chi_a(b) = \begin{cases} 1 & \text{if } a=b \\ 0 & \text{o/w} \end{cases}$$

$$\chi_a(S_1S_2S_3\dots S_n) = \chi_a(S_1)\chi_a(S_2)\chi_a(S_3)\dots\chi_a(S_n)$$

Example:

$$\chi_a(abbaabb) = 1001100$$

For $\Sigma = \{a, b, c\}$

Do:

$$\begin{array}{r} \chi_a(T) \times \chi_a(P^R) \\ + \chi_b(T) \times \chi_b(P^R) \\ + \chi_c(T) \times \chi_c(P^R) \\ \hline \end{array}$$

Result: The number of times a in pattern matches a in text + the number of times b in pattern matches b in text + the number of times c in pattern matches c in text.

So for alphabet with a symbols (a fixed) the time is:

$$O(n a \log m) = O(n \log m)$$

Problem: Infinite alphabets.

Without loss of generality:

$$|\Sigma| = m + 1$$

Since every element of T not in P is replaced by some symbol x not in P .

Example:

ABCDEFGH

same number of errors as

ABBBBBGH

ABXXXXGH

ABBBB BGH

Needed: Fast way to compute matches of x to itself.

Such a method exists if x appears in the pattern a very **small** number of times.

Assume: x appears in pattern c times.

For every occurrence of x in text, update just the appropriate counters of the c occurrences of x in the pattern.

Text:

A horizontal line representing text with three 'X's. A red circle highlights the fourth 'X' from the left, which is part of a sequence of four 'X's.

Pattern:

A horizontal line representing a pattern with four slots. The first slot is empty. The second slot contains two 'X's. The third slot contains one 'X'. The fourth slot contains a bolded 'X'. Below the pattern, there are four green triangles pointing upwards, corresponding to the positions of the 'X's in the pattern.

Time: $O(nc)$.

Problem: In general it could be that x occurs in the pattern $O(m)$ times, then total time becomes $O(nm)$. BAD again.

Tradeoff: If x appears in the pattern **more** than c times, count matches by FFT, in time $O(n \log m)$, per x .

For all x 's that appear in the pattern **less** than c times, count matches (simultaneously) in time $O(nc)$.

How many elements appear at least c times?

$$\frac{m}{c}$$

For these elements , time: $O((m/c) n \log m)$.

For all other elements, time: $O(nc)$.

The optimal case is when they equal, i.e.

$$\frac{mn \log m}{c} = cn$$
$$m \log m = c^2$$

$$\sqrt{m \log m} = c$$

Total Time:

$$O(n\sqrt{m \log m})$$

(A-87,K-87)