

DeGirum Al Client for C++ Reference Guide

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# **Chapter 1**

# DeGirum Al Client for C++

### 1.1 Introduction

The DeGirum Al Client package referenced in this document is the part of DeGirum Al Software Suite.

Note: Al Client package consists of multiple programming language support packs. This document describes Al Client for C++. Al client packs for other languages are described in separate documents.

The DeGirum Al Software Suite provides means to perform fast and efficient Al model inferencing on locally installed Al hardware accelerator platforms.

The list of supported hardware accelerator platforms includes all DeGirum Orca Al hardware accelerators and Google Edge TPU accelerators. Al inferencing on local host CPU is also supported.

The DeGirum Al Software Suite consists of DeGirum Al Server package, Al Model Zoo, and DeGirum Al Client package.

#### 1.1.1 Al Server Package

The Al Server package is installed on a computer system where Al hardware accelerators are connected to. The purpose of the Al Server is the following:

- · It controls AI hardware accelerators
- It provides distributed and concurrent access of multiple AI clients to AI inferencing functionality of AI hardware accelerators over the TCP/IP network
- It maintains local AI model zoo with AI models to be used for AI inferencing
- · It provides Web-based GUI to manage local model zoo

The following computer platforms are currently supported for the server installation:

- Intel x64 with Linux 64-bit OS
- · ARM64 with Linux 64-bit OS

The support for following computer platforms is currently under development:

- · Intel x64 with Windows 10 OS
- Intel x64 with MacOS
- · ARM64 with MacOS

The AI Server for Linux is distributed as fully configured Docker container (refer to  $https://hub.docker. \leftarrow com/r/degirum/aiserver$ ), which simplifies AI Server deployment to the variety of Linux platforms.

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#### 1.1.2 Al Model Zoo

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The Al Model Zoo is the place where Al models reside.

The local AI Model Zoo of DeGirum AI Server is implemented as the directory on the AI Server local file system. It contains files of all locally deployed AI models. Only models in the local Model Zoo can be used for AI inferencing on particular AI server installation.

Currently, AI Server supports the following AI model types:

- N2X models: models in proprietary DeGirum N2X format compiled for DeGirum Orca AI accelerator hardware and CPU
- TFLite Edge TPU models: models in Google TFLite format compiled for Google Edge TPU Al accelerator hardware
- · TFLite CPU models: models in Google TFLite format compiled for execution on CPU
- · OpenVINO models

The deployment of the local Model Zoo is performed using PySDK server module (please refer to PySDK documentation available on <a href="https://degirum.github.io">https://degirum.github.io</a>).

# 1.1.3 Al Client Package

The AI Client package is installed on a computer system, where client-side ML software runs. It can be the same computer system, where the AI Server is deployed, or it can be any other computer system, which has TCP/IP network access to the AI Server computer system.

Al Client Package includes the following components:

- · Al Client library
- Al Client examples
- · Build scripts

Al Client library provides APIs to control and use the Al Server. It includes the following functionality:

- · List all AI models with their attributes available for AI inferencing in particular AI Server local Model Zoo
- Find Al model in that local Model Zoo matching particular model attributes
- Open and configure streaming connection to particular AI Server for inferencing using particular AI model from local Model Zoo
- · Stream data frames to the that streaming connection to perform AI inferencing on these data frames

Al Client library provides integration into the C++ programming language. This document describes Al Client for C++. Al client packs for other languages are described in separate documents.

All Al Client Package software is distributed in the source code and requires compilation.

The following computer platforms are currently supported for the client installation:

- Intel x64 with Linux 64-bit OS
- Intel x64 with Windows 10 OS
- · ARM64 with Linux 64-bit OS
- Intel x64 with MacOS
- · ARM64 with MacOS

# 1.2 Al Client Package Installation and Build

# 1.2.1 Installation Pre-Requisites

For Linux OS the following software packages need to be installed in order to build Al Client package software:

- Git
- CMake
- · GCC compiler
- · Thread building blocks library

To install all these component use the following commands:

```
sudo apt install git-all cmake g++ libtbb-dev
```

For Windows OS the following software packages need to be installed in order to build AI Client package software:

- Git
- CMake
- · Visual Studio 2019 (Community Edition would suffice)

# 1.2.2 Al Client Package Installation

The AI Client library is distributed in source code and is available on GitHub at the following link:

```
https://github.com/DeGirum/CppSDK
```

You clone the Al Client library repo by executing command:

```
git clone https://github.com/DeGirum/CppSDK
```

The repo directory contains the Al Client library collaterals. The subdirectory structure is as follows:

Directory	Contents
/client	Al Client library code
/doc	documentation
/examples	sample applications
/extern	third-party libraries
/images	sample images to be used for AI inference
/inc	Al Client library C++ include files

# 1.2.3 Al Client Package Build

The CMakeLists.txt file is provided for the CMake build. It builds AI Client C++ library, and C++ examples.

To perform the build under Linux OS, execute the following commands:

```
cd client
mkdir build
cd build
cmake ..
cmake --build .
```

For Windows OS and Visual Studio, CMake will create the Visual Studio project files and AICLIENTLIB.sln solution.

For Linux OS, CMake will create make files (unless otherwise specified with the -G flag).

After building, the library and example executables are copied into /bin subdirectory.

# 1.3 Al Client C++ API Description

DeGirum Al Client library provides the following functionality:

- · versionGet() function to query the version of the AI Client library
- modelzooListGet() function to list all AI models with their attributes available for AI inferencing in particular AI Server local Model Zoo
- systemInfo() function to obtain AI server system information including information about connected AI devices
- modelFind() function to find AI model in that local Model Zoo matching particular model attributes
- · labelDictionary() function to query the model class label dictionary
- errorCheck() function to check given AI server Json response for run-time errors
- DG::AlModel class to connect to Al server and to perform Al model inference in a simple non-pipelined sequential manner (see AlModel: Synchronous Sequential Al Inferencing API)
- DG::AlModelAsync class to connect to AI server and to perform AI model inference in efficient pipelined asynchronous manner using mechanism of callbacks (see AIModelAsync: Asynchronous Pipelined AI Inferencing API)
- the family of ModelParams classes to handle model parameters (see Model Parameters Management)
- · functions and methods for error handling (see Error Handling)

#### 1.3.1 Al Server Connection and Addressing

The client software communicates with AI server through TCP/IP network using DeGirum proprietary communication protocol based on ASIO library. In order to establish a connection to AI server, the client side must know the host name or IP address of the AI server, and TCP port, which AI server listens.

The server address is passed to Al inference classes as a string in the following format:

If AI server domain name is known, the address string is specified in the form

```
domain_name:port
```

If only IP address of AI server is known, the address string is specified in the form

```
xxx.xxx.xxx.port
```

The port number together with ':' separator can be omitted, in this case default port 8778 is used. When AI server is started without specifying the port, the same default port 8778 is used for the server side. In this case it is safe to omit the port. Otherwise you should match the port on the client side to the port used on the server side.

# 1.3.2 Listing and Searching Models in Local Model Zoo

The AI server can perform AI inferences only on models located either in the local model zoo of that AI server or in the cloud zoo you have access to. This section describes how to deal with local zoo models. The section Working with Cloud Zoo Models describes how to deal with cloud zoo models.

To initiate an inference of a model form the local model zoo on Al server, the client must provide to the server the *model name*, which uniquely identifies the desired model in the local model zoo. There are two ways for the client code to obtain the model name.

- 1. By obtaining the full list of models available in the model zoo using modelzooListGet() function
- 2. By searching the model zoo for a model satisfying certain search attributes using modelFind() function.

Either way you obtain the instance of DG::ModelInfo structure, which contains all necessary model identification information, including:

- DG::ModelInfo::name model string name
- DG::ModelInfo::id unique model ID
- DG::ModelInfo::W input frame width
- DG::ModelInfo::H input frame height
- DG::ModelInfo::C input color depth
- DG::ModelInfo::N input frame depth
- DG::ModelInfo::device type device type on which model runs
- DG::ModelInfo::runtime\_agent runtime agent type on which model runs
- DG::ModelInfo::model quantized 'is model quantized' flag
- DG::ModelInfo::model\_pruned 'is model pruned (not dense)' flag
- DG::ModelInfo::input\_type input data type: "Image", ...
- DG::ModelInfo::input\_tensor\_layout for image inputs, image tensor layout the model expects: "NHWC", "←
  NCHW"
- DG::ModelInfo::input\_color\_space for image inputs, image color-space the model expects: "BGR", "RGB"
- DG::ModelInfo::input\_image\_format for image inputs, image format: "JPEG", "RAW" (this is user-tunable runtime parameter)
- DG::ModelInfo::input\_raw\_data\_type for "RAW" image inputs, image pixel data type: "DG\_FLT", "DG\_UI → NT8" (this is user-tunable runtime parameter)
- DG::ModelInfo::extended\_params extended model parameters (all parameter as listed in model Json configuration file)

Then you pass model name DG::ModelInfo::name to constructors of classes used for AI inference: DG::AIModel or DG::AIModelAsync.

The modelzooListGet() function returns an array of ModelInfo structures listing all models found in the local model zoo. It is then your responsibility to iterate over all elements of this array to find the model you want to use.

The modelFind() function provides simpler means to find the desired model. It accepts the model query: the instance of DG::ModelQuery structure, which contains some model attributes you want to look for. The modelFind() function first obtains the full list of models from the AI server, and then iterates over this list to find a model matching all attributes specified in the model guery. It returns the first model matching all attributes.

You may specify the following attributes:

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 Any part of the model name. Only models which have the specified substring in their model name would be considered.

- Device type to use for inference. Only models which are designed for specified device type would be considered.
- Runtime agent to use for inference. Only models which are designed for specified runtime agent would be considered.
- Model should be quantized flag. Only quantized models would be considered.
- Model should be pruned/sparse flag. Only sparse/pruned models would be considered.

Only the model name substring attribute is mandatory, all other attributes are optional and can be omitted if not needed.

You specify the device type by providing the Device ID string. The following device types are supported:

Device ID	Device	
"ORCA"	DeGirum Orca Al accelerator	
"EDGETPU"	Google Edge TPU Al accelerator	
"MYRIAD"	Intel Myriad Al accelerator	
"CPU"	Al server host computer	

The *runtime agent* is the software module, which controls the device used for AI inference. You specify the runtime agent type by providing the Agent ID string. The following runtime agent types are supported:

Agent ID	Agent
"N2X"	DeGirum N2X runtime agent. Used for all Orca devices and N2X model inference on CPU.
"TFLITE"	Google TFLite runtime agent. Used for Edge TPU devices and direct TFlite model inference on CPU.
"OPENVINO"	Intel OpenVINO runtime agent. Used for Myriad devices and direct OpenVINO model inference on CPU.

Note: the runtime agent attribute is rarely required because in most use cases the AI hardware uniquely defines the runtime agent to use, so it is recommended to avoid setting this attribute.

#### Examples:

Find a model which has 'MobileNet v2' substring in the model name:

```
auto model_id = DG::modelFind( server, { "mobilenet_v2" } );
```

Find a model which has 'mobilenet\_v2' substring in the model name, is designed to run on DeGirum Orca Al accelerator hardware, is quantized, and is sparse/pruned:

#### 1.3.3 Working with Cloud Zoo Models

Starting from release 0.5.0, the AI server supports inference of models from DeGrirum-hosted cloud model zoos. In order to use models from a cloud zoo you need to register at DeGirum Cloud Portal, <a href="https://cs.edegirum.com">https://cs.edegirum.com</a>, and generate API access token. Please refer either to PySDK documentation or General Information section, both available on <a href="https://cs.degirum.com">https://cs.degirum.com</a>, for more details.

To do the inference of a model from some cloud zoo you need to perform the following steps:

- 1. Obtain your **API access token**. You can generate it on DeGirum Cloud Portal site https://cs. ← degirum.com under Management | My Tokens\* main menu item.
- 2. Figure out the **extended model name**. It has the following format: "<organization>/<zoo>/<model>". The "<organization>" field is the name of the zoo owner organization, the "<zoo>" field is the name of the cloud zoo, and the "<model>" field is the name of the model in that cloud zoo. You can obtain the "<organization>/<zoo>" prefix (so-called model zoo path) on DeGirum Cloud Portal site <a href="https://cs.degirum.com">https://cs.degirum.com</a> under *Management* | *Models* main menu item. Just select the model zoo you want to access: the model zoo page opens. Then click the Copy button near the model zoo name to copy the model zoo path into the clipboard. All models available in the cloud zoo are also listed on the model zoo page. Click on particular model: the model page opens. The model name will be displayed at the top of the page. Now concatenate the model zoo path with the model name separated by the slash / to obtain the extended model name.
- 3. Create DG::ModelParamsWriter object and assign CloudToken parameter.
- 4. Create DG::AlModel or DG::AlModelAsync object passing the Al server hostname, extended model name, and DG::ModelParamsWriter object.

For example: const std::string hostname = ""; // specify AI server hostname const std::string ext\_model\_name = ""' specify extended model name const std::string token = ""'; // specify your API access token string

DG::ModelParamsWriter mparams; mparams.CloudToken\_set( token ); DG::AlModel model( hostname, ext\_← model\_name, mparams );

Al server will automatically download the model from the cloud model zoo using provided credentials and store this model in the local model cache to be reused for later inferences.

Each time you create new DG::AlModel or DG::AlModelAsync object and perform the first inference, the checksum of the model in the local cache is compared with the checksum of the model in the cloud zoo, and if they mismatch, the model from the cloud zoo is downloaded into the local cache. This mechanism guarantees that you always perform the inference of the newest model.

# 1.3.4 AlModel: Synchronous Sequential Al Inferencing API

The DG::AlModel class is used to perform AI model inference on AI server in simple non-pipelined sequential manner.

Note: for more efficient (but somewhat more complex to use) asynchronous pipelined inference use DG::AlModelAsync class.

On construction this class performs connection to AI server, selection of AI model, and setting model run-time parameters.

You specify the AI server address as a string as described in the section AI Server Connection and Addressing.

You specify the model name as described in the section Listing and Searching Models in Local Model Zoo.

If you want to modify some of the model parameters (see more on that in the section Model Parameters Management), you define the instance of ModelParamsWriteAccess-derived class, change model parameters you want to adjust by invoking setter methods, and pass this instance as one of DG::AlModel constructor arguments.

For example, you want to change the input frame image type to JPEG. You can pass the following expression to DG::AlModel constructor:

```
DG::ModelParamsWriter().InputImgFmt_set( "JPEG" )
```

Once constructed, it can be used to perform sequential AI inference by invoking DG::AIModel::predict() method. Predict method accepts the input frame data in various formats (see section Format of Data Frames for Image Processing Models for more details) and returns the inference results, which are described in the section Format of Inference Results. This method is blocking method, i.e. it returns the execution only when the inference of an input frame is complete. Working with blocking methods simplifies the programming, but loses some run-time efficiency because (unlike for DG::AIModelAsync class) some actions like sending data to AI server, frame pre-processing, result post-processing, and receiving results from AI server are not pipelined between frames.

#### 1.3.5 Format of Inference Results

The predict() method of DG::AlModel class returns Json array with inference results. The internal structure of this Json array greatly depends on the Al model type: it is different for classification models, detection models, and so on. But in general, that Json array is an array of identical Json objects, and each Json object contains inference results for one detected entity.

The following tables describe Json array format for some model types.

For classification model types each classified object is represented by the following Json object:

Json Field Name	Description	Data Type		
"label"	Classified object class label	string		
"category_id"	Classified object class index	integer		
"score"	Probability of classified object	floating point		

For detection model types each detected object is represented by the following Json object:

Json Field Name	Description	Data Type
"label"	Detected object class label	string
"category_id"	Detected object class index	integer
"score"	Probability of detected object	floating point
"bbox"	Detected object rectangle	four-element Json array [xmin, ymin, xmax, ymax]
"landmarks"	Landmark points (optional)	Json array of two-element arrays [[x1, y1], [x2, y2],]

For pose detection types each detected object is represented by the following Json object:

Json Field Name	Description	Data Type
"score"	Probability of detected pose	floating point
"landmarks"	Pose description landmarks	array of landmark Json objects

The following is the structure of pose description landmark Json object:

Json Field Name	Description	Data Type
"label"	Classified object class label	string
"category_id"	Classified object class index	integer
"score"	Probability of classified landmark	floating point
"landmark"	landmark point	two-element Json array [x, y]
"connect"	list of adjacent landmarks indices	Json array of integers

For hand detection types each detected object is represented by the following Json object:

Json Field Name	Description	Data Type
"score"	Probability of detected hand	floating point
"handedness"	Probability of right hand	floating point
"landmarks"	hand description landmarks	array of landmark Json objects

The following is the structure of hand description landmark Json object:

Json Field Name	Description	Data Type
"label"	Classified object class label	string
"category_id"	Classified object class index	integer
"landmark"	landmark point	three-element Json array [x, y, z]
"world_landmark"	metric world landmark point	three-element Json array [x, y, z]
"connect"	list of adjacent landmarks indices	Json array of integers

When you specify post-processing type as "None" (see section Model Parameters Management) then the inference result Json array contains network output tensors. Each element of that array corresponds to one tensor. Each tensor is represented by the following Json object:

Json Field Name	Description	Data Type
"id"	Tensor numeric ID as specified in network	integer
"name"	Tensor name as specified in network	string
"shape"	Tensor shape: sizes of each dimension	integer array
"quantization"	Tensor quantization parameters	object
"type"	Tensor element type	string
"data"	Tensor linear data buffer contents	binary field

The following tensor data types are supported:

Type String	Type Description
DG_FLT	32-bit floating point
DG_UINT8	8-bit unsigned integer

The following is the structure of quantization Json object:

Json Field Name	Description	Data Type
"axis"	Quantization axis or -1 for global quantization	integer
"scale"	Quantization scale array	floating point array
"zero"	Quantization zero offset	integer array

For convenient handling of tensors the DG::BasicTensor class is provided. You can convert Json array containing a tensor into DG::BasicTensor object by using DG::JsonHelper::tensorDeserialize() static method:

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There is a special case of Json array returned by AI server in case when runtime error happens during inference. In this case the runtime error info object is returned. It is described in details in the Error Handling section.

#### 1.3.6 AlModelAsync: Asynchronous Pipelined Al Inferencing API

The DG::AlModelAsync class is used to perform Al model inference on Al server in efficient pipelined asynchronous manner using the mechanism of callbacks.

Note: for simple (but less efficient) synchronous non-pipelined inference use DG::AlModel class.

On construction this class performs connection to AI server, selection of AI model, setting model run-time parameters, and installation of the client callback function. The client callback function is used to pass the inference results from the AI server to the client code.

You specify the AI server address as a string as described in the section AI Server Connection and Addressing.

You specify the model name as described in the section Listing and Searching Models in Local Model Zoo.

You should define the callback function somewhere in your code in the following form:

```
void MyAiCallback( const json &result, const std::string &info ){}
```

Then you pass your callback name (in this example it is MyAiCallback) as one of DG::AlModelAsync constructor arguments. The callback function has two arguments: the inference result and the frame info string. The inference result is Json array, described in the section Format of Inference Results. The frame info string is the string passed to predict() method along with the frame data. More on that below.

If you want to modify some of the model parameters (see more on that in the section Model Parameters Management), you define the instance of DG::ModelParamsWriteAccess derived class, change model parameters you want to adjust by invoking setter methods, and pass this instance as one of DG::AlModelAsync constructor arguments.

For example, you want to change the input frame image type to JPEG. You can pass the following expression to DG::AIModelAsync constructor:

```
DG::ModelParamsWriter().InputImgFmt_set( "JPEG" )
```

Once constructed, it can be used to perform asynchronous AI inference by invoking DG::AIModelAsync::predict() method. The predict method accept the input frame data in various formats (see section Format of Data Frames for Image Processing for more details) and initiates the inference on the AI server. The method is a non-blocking method, i.e. it returns execution immediately after posting the frame data to the AI server. This allows calling this method in a loop without waiting for the inference results, achieving the maximum AI server utilization.

To simplify matching inference results and corresponding frames in the client callback, additional argument can be passed to predict() method. The frame\_info argument is optional frame information string. It will be passed to the client callback along with the frame result. You can pass arbitrary information as the frame info, for example frame data filenames, or frame numbers, or any other frame identification information, which you need to know in the scope of client callback function in order to interpret inference results in respect to the input frames.

Once the inference of a frame is complete, and the inference result is received from the AI server, the client callback is invoked to dispatch the inference result. Such result handling via callback mechanism is performed in a thread,

separate from the main execution thread. It means that the client callback function is called in asynchronous manner, thus the name of the class.

During construction you may also specify the depth of the internal frame queue. The internal frame queue works the following way. If predict() method is invoked too often and the number of non-processed ("outstanding") frames exceeds the specified queue depth, the consecutive call to predict() method will be blocked until the number of outstanding frames in the queue becomes smaller than the queue depth thus allowing to post one more frame.

The class destructor waits until all outstanding results are received and then closes the connection to AI server. You may use DG::AIModelAsync::waitCompletion() to explicitly wait for completion of all outstanding inferences. It is a blocking call: it returns only when all outstanding frames are processed by AI server and all results are dispatched via client callback.

To monitor the number of outstanding inferences in real-time you use DG::AlModelAsync::outstandingResultsCountGet() method.

To check for runtime errors which happened during inferences you use DG::AlModelAsync::lastError() method. If ever during consecutive calls to predict() method the Al server reported a run-time error, then this method will return the error message string, otherwise it returns an empty string. Alternatively, you may check for runtime errors directly in the callback function by invoking errorCheck() function on inference result argument.

Note: in case of server runtime error, all frames posted after the error was detected, will not be processed.

#### 1.3.7 Model Parameters Management

Each AI model in the model zoo comes with the model parameters file in Json format. This Json file defines all model parameters such as model name, model input dimensions, pre-processing parameters, post-processing parameters, etc. Some of the model parameters are fixed and cannot be altered without breaking the model behavior, and some of the model parameters can be changed to adjust the model behavior. Later parameters are called model runtime parameters and can be adjusted when constructing instances of model inference classes DG::AIModel and DG::AIModelAsync.

To work with model parameters the following classes are provided:

- DG::ModelParamsReadAccess
- DG::ModelParamsWriteAccess
- · DG::ModelParams
- DG::ModelParamsWriter

DG::ModelParamsReadAccess class provides programmatic type-safe read access to model parameters defined in Json model configuration. It keeps non-owning const reference to underlying Json array. For each model parameter it provides getter method, which name matches the parameter name as it appears in Json array.

DG::ModelParamsWriteAccess inherits DG::ModelParamsReadAccess and provides programmatic type-safe read and write access to model parameters defined in Json model configuration. It keeps non-owning non-const reference to underlying Json array. For each model parameter it provides both getter and setter methods. Getter method name matches the parameter name as it appears in Json array. Setter method name is constructed from the parameter name by appending \_set suffix. For example, InputImgFmt\_set() Setter methods return reference to self, so they can be called in a daisy-chain manner, for example:

```
params.InputImgFmt_set( "RAW" ).InputImgRawDataType_set( "DG_UINT8" );
```

DG::ModelParams class provides programmatic type-safe access to model parameters defined in Json model configuration while *owning* that Json array. Access (read or write) is defined by the template parameter, which is used as the base class. You can use any DG::ModelParamsReadAccess-derived base class: it can be DG::ModelParamsReadAccess or DG::ModelParamsWriteAccess.

And finally DG::ModelParamsWriter is DG::ModelParams template instantiation with write access. Instances of this class you typically use to pass adjusted runtime model parameters to constructors of inference classes.

The following table summarizes all runtime parameters which are accessible to the client code:

Parameter Name	Туре	Access	Description	Possible Values	Default Value
CloudToken	string	R/W	Cloud API access to-	Valid cloud API access token	""
EagerBatchSize	size↔ _t	R/W	The size of the batch to be used by device scheduler when inferencing this model. The batch is the number of consecutive frames before this model is switched to another model during batch predict.	180	8
InputImgFmt	string	R/W	Input frame format← : JPEG or raw binary	"JPEG", "RAW"	"JPEG"
InputRawData↔ Type	string	R/W	Data type for raw binary frame format  : byte of 32-bit float	"DG_UINT8", "DG_← FLT"	"DG_UINT8"
InputImg↔ Rotation	int	R/W	Input image rotation angle in degrees, clockwise	0, 90, 180, 270	0
InputColor↔ Space	string	R/W	Input image col- orspace (sequence of colors in C dimen- sion)	"RGB", "BGR"	"RGB"
InputResize↔ Method	string	R/O	Interpolation algo- rithm used for image resizing during model training	"nearest", "bilinear", "area", "bicubic", "lanczos"	"bilinear"
InputPadMethod	string	R/O	How input image is padded when resized during model training	"stretch", "letterbox", "crop-first", "crop-last"	"letterbox"
InputCrop↔ Percentage	double	R/O	How much input image was cropped during model training	01	1
ImageBackend	string	R/O	Graphical package used for image processing during model training	"pil", "opencv", "auto"	"auto"
MaxDetections	int	R/W	Maximum number of objects to report for detection models	> 0	20
Max↔ Detections↔ PerClass	int	R/W	Maximum number of objects to report for each class for detection models	> 0	100
MaxClasses↔ PerDetection	int	R/W	Maximum number of classes to report for detection models	> 0	30
MeasureTime	bool	R/W	Enable inference time measurements	true/false	false
Output↔ Postprocess↔ Type	string	R/W	Post-processor type	see below	"None"
OutputConf↔ Threshold	double	R/W	Confidence threshold	01	0.1

Parameter Name	Туре	Access	Description	Possible Values	Default Value
OutputNMS←	double	R/W	Threshold for non-	01	0.6
Threshold			max suppression		
OutputTopK	size↩	R/W	Number of classes	0,1	0
	_t		with biggest scores to		
			report for classifica-		
			tion models		
UseRegularNMS	bool	R/W	Use regular (per-	true/false	true
			class) NMS algorithm		
			as opposed to global		
			(class-ignoring) N←		
			MS algorithm for		
			detection models		

If you do not specify a runtime parameter, then the value for this parameter will be taken from the model Json configuration file from the local model zoo. If the model Json configuration file also does not specify this parameter, then the default value will be used.

The following table lists currently available post-processor types.

Post-Processor Name	Applicability	Description
"None"	All models	Pass-through post-processor. Network output tensors are sent without any post-processing
"Classification"	Classification models	Classification post-processor for all classification models
"Segmentation"	Segmentation models	Semantic segmentation post-processor for all segmentation models
"TFLiteDetection"	TFlite detection models	Object detection post-processor for TF← Lite detection models
"DetectionYolo"	Yolov5-based models	Object detection post-processor for De ← Girum Yolov5-based models
"Detection"	Other detection models	Object detection post-processor for all other DeGirum general object detection models
"DetectionYoloPlates"	Yolov5-based license plate detection models	DeGirum license plate detection model post-processor
"FaceDetection"	Face detection models	Face detection post-processor for all DeGirum face detection models
"PoseDetection"	Pose detection models	Person pose detection post-processor for all DeGirum pose detection models
"HandDetection"	Hand detection models	Hand landmark detection post-processor for all DeGirum hand detection models

Note: not all post-processors are compatible with all models. Special care should be taken when specifying post-processor type other than "None".

Notes of Input\* parameters.

DG::ModelParamsReadAccess::InputImgFmt parameter is used to tell pre-processor what input frame format to expect. The value of this parameter should match the frame data type you pass to predict() methods. You may change it to match the format of your input frames.

DG::ModelParamsReadAccess::InputRawDataType parameter is used to tell pre-processor what data element type to expect for raw data frames (InputImgFmt is "RAW"). Again, the value of this parameter should match the frame data element type you pass to predict() methods. You may change it to match the format of your input frames.

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DG::ModelParamsReadAccess::InputImgRotation parameter is used to ask pre-processor to perform input image rotation by certain angle. It is convenient when your input frames are coming from your camera which is mounted on a side or upside down.

DG::ModelParamsReadAccess::InputColorSpace defines the colorspace (pixel order) which the AI model expects (was trained to). In case when the input image format is "RAW", you should provide raw image frame with correct pixel order corresponding to the input colorspace parameter value. In case when the input image format is "JPEG", the pre-processor will perform the conversion to the proper pixel order when decoding the JPEG image. Usually you do not change this parameter, otherwise the model performance will degrade.

# 1.3.8 Format of Data Frames for Image Processing Models

The Al Client package supports two formats of the input data frames for image processing models: JPEG images and binary bitmaps, where binary format is used by default and typically set in Json model configuration files for all DeGirum models.

In any case the HxW dimension of the input data frame must match the input dimension of the AI model used for the inference. The input dimensions of the AI model are stored in the DG::ModelInfo data structure fields DG::ModelInfo::W and DG::ModelInfo::H, returned by either modelzooListGet() or modelFind() functions (see section Listing and Searching Models in Local Model Zoo).

The frame data in the binary bitmap format should be arranged as HWC three-dimensional dense array, meaning that color dimension 'C' is the fastest dimension, while the vertical dimension 'H' is the slowest. The color order is dependent on how the model was originally trained. The pixel data type can be either 8-bit unsigned integer number or 32-bit floating point number.

You specify input frame type when you construct instances of model inference classes DG::AlModel and DG::AlModelAsync, passing instance of ModelParams class as the constructor parameter (see more details in the section Model Parameters Management).

To specify JPEG frame type you need to set InputImgFmt parameter to "JPEG".

To specify binary frame type you need to set both InputImgFmt and InputImgRawDataType parameters. For example, the byte binary frame type you set this way:

#### 1.3.9 Error Handling

There are two mechanisms of error handling employed in Al Client package: using standard library exceptions and using specially formatted Json inference results.

All runtime errors *except errors happened during inference*, are handled by throwing standard library exceptions - objects of std::exception type. To handle such errors the recommended practice is to place all the code which interacts with the Al Client library into one try/catch block, and then catch exceptions of std::exception type:

```
try
{
    ...
}
catch( std::exception &e )
{
    std::cout << e.what(); // handle exception
}</pre>
```

Errors which happened during the inference are handled special way. Instead of throwing an exception, the special Json runtime error info object is returned by DG::AlModel::predict() method in case you use synchronous API, and that Json object is passed as an argument into your callback in case you use asynchronous API.

The Json runtime error info object has the following structure:

Json Field Name	Description
"success"	Boolean field containing "false" in case of error
"msg"	Error message string

If you want to check that the inference result actually defines runtime error, you use <a href="error">error Check</a>() function. If the Al server Json response contains the run-time error, then this function will return the error message string, otherwise it returns an empty string. The following code demonstrates the typical use case for synchronous API:

```
json result;
model.predict( frame, result );
auto possible_error = DG::errorCheck( result );
if( !possible_error.empty() )
    throw std::runtime_error( possible_error );
```

The following code demonstrates the typical use case for asynchronous API:

```
void MyAiCallback( const json &result, const std::string &info )
{
   auto possible_error = DG::errorCheck( result );
   if( possible_error.empty() )
   {
      ... accept inference result
   }
   else // do not throw exception, since it will be ignored by AI Client thread
}
```

Note: do not throw any exceptions in your callback, since the Al Client callback thread, which handles user callback invocation, suppresses all exceptions thrown in callbacks to not to terminate the callback thread unexpectedly.

Another approach for the inference error handling for asynchronous API would be to check for inference errors at the very end of the inference sequence. You can use DG::AlModelAsync::lastError() method: if ever during consecutive calls to predict() method the inference errors are detected, then this method will return the error message string, otherwise it returns an empty string. To guarantee that all outstanding frames are processed before the error check, you can use DG::AlModelAsync::waitCompletion() method:

```
model.waitCompletion();
auto possible_error = model.lastError();
if( !possible_error.empty() )
    throw std::runtime_error( possible_error );
```

Note: in case of inference error in asynchronous client, all frames posted after the error was detected, will not be processed.

# Chapter 2

# **Hierarchical Index**

# 2.1 Class Hierarchy

This inheritance list is sorted roughly, but not completely, alphabetically:

DG::AlModel	
DG::AlModelAsync	7
DG::BasicTensor	C
DG::JsonHelper	8
DG::ModelInfo	2
DG::ModelParamsReadAccess	6
DG::ModelParams< Base, >	3
DG::ModelParamsWriteAccess	1
DG::ModelParams< ModelParamsWriteAccess >	3
DG::ModelParamsSection	C
DG::ModelQuery	5
DG::BasicTensor::quant_params_t	6
DG::BasicTensor::quant_params_t::scale_t	9
DG::ServerAddress	9

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# **Chapter 3**

# **Class Index**

# 3.1 Class List

Here are the classes, structs, unions and interfaces with brief descriptions:

DG::AlModel	
AlModel is DeGirum Al client API class for simple non-pipelined sequential inference	35
DG::AlModelAsync	
AlModelAsync is DeGirum Al client API class for efficient pipelined asynchronous inference	37
DG::BasicTensor	40
DG::JsonHelper	
Json helper class: contains assorted static methods to operate with Json configurations	48
DG::ModelInfo	
ModelInfo is the model identification structure. It keeps AI model key attributes	52
DG::ModelParams< Base, >	
ModelParams is model parameters collection with user-defined access rights	53
DG::ModelParamsReadAccess	
ModelParamsReadAccess is read-only accessor to model parameters	56
DG::ModelParamsSection	
Model parameters section descriptor	60
DG::ModelParamsWriteAccess	
ModelParamsWriteAccess is read/write accessor to model parameters	61
DG::ModelQuery	
Model query structure used to search models on AI server which match a set of provided model	
attributes	65
DG::BasicTensor::quant_params_t	
Quantization parameters (how to convert from integer/quantized data back to floating point)	66
DG::BasicTensor::quant_params_t::scale_t	69
DG::ServerAddress	
ServerAddress is the server address structure. It keeps AI server TCP/IP address	69

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# **Chapter 4**

# File Index

# 4.1 File List

Here is a list of all documented files with brief descriptions:

dg_client_structs.h	
DG client API data types	73
dg_json_helpers.h	
DG Core JSON helper classes and functions	75
dg_model_api.h	
DG Client API for model inference	77
dg_model_parameters.h	
DG centralized handling of Json model parameters	78
dg_tensor_structs.h	
DG tensor container classes	80

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# **Chapter 5**

# **Namespace Documentation**

# 5.1 DG Namespace Reference

DG is DeGirum namespace which groups all DeGirum software declarations.

#### **Classes**

class AlModel

AlModel is DeGirum Al client API class for simple non-pipelined sequential inference.

· class AlModelAsync

AlModelAsync is DeGirum Al client API class for efficient pipelined asynchronous inference.

- class BasicTensor
- · class JsonHelper

Json helper class: contains assorted static methods to operate with Json configurations.

• struct ModelInfo

ModelInfo is the model identification structure. It keeps AI model key attributes.

class ModelParams

ModelParams is model parameters collection with user-defined access rights.

class ModelParamsReadAccess

ModelParamsReadAccess is read-only accessor to model parameters.

struct ModelParamsSection

Model parameters section descriptor.

· class ModelParamsWriteAccess

ModelParamsWriteAccess is read/write accessor to model parameters.

struct ModelQuery

Model query structure used to search models on Al server which match a set of provided model attributes.

struct ServerAddress

ServerAddress is the server address structure. It keeps AI server TCP/IP address.

# **Typedefs**

using BasicTensorVector = std::vector < BasicTensor >

Collection of tensors.

• using json = nlohmann::json

Json library.

typedef struct DG::ModelInfo ModelInfo

ModelInfo is the model identification structure. It keeps AI model key attributes.

using ModelParamsWriter = ModelParams
 ModelParamsWriteAccess >

ModelParamsWriter is ModelParams template instantiation with write access.

typedef struct DG::ServerAddress ServerAddress

ServerAddress is the server address structure. It keeps AI server TCP/IP address.

#### **Enumerations**

enum DetectionStatus { DetectionStatus::OK, DetectionStatus::ProtocolMismatch, DetectionStatus::HostAlive }

Enumerator showing server status as detected by the below function.

```
    enum RUNTIME_AGENT_TYPES {
        RUNTIME_AGENT_TYPES::DEFAULT, RUNTIME_AGENT_TYPES::N2X, RUNTIME_AGENT_TYPES::TFLITE,
        RUNTIME_AGENT_TYPES::ONNX,
        RUNTIME_AGENT_TYPES::OPENVINO, RUNTIME_AGENT_TYPES::DUMMY }
```

Runtime agent types.

#### **Functions**

- std::vector< std::tuple< std::string, DG::DetectionStatus > > detectHostnameServers (const std::string &prefix, const int range\_start, const int range\_end, const int numeral\_width=3)
- std::vector< std::tuple< std::string, DetectionStatus >> detectSubnetServers (const std::string &root\_ip, const std::string &subnet\_mask)
- std::string errorCheck (const json &json\_response)
- template<typename T >

T jsonGetMandatoryValue (const json &json\_params, const std::string &section, int index, const std::string &key)

• template<typename T >

T jsonGetOptionalValue (const json &json\_params, const std::string &section, int index, const std::string &key, const T &default\_value)

- static bool jsonKeyExist (const json &json params, const std::string &section, int index, const std::string &key)
- template<typename T >

void jsonSetOptionalValue (json &json\_params, const std::string &section, int index, const std::string &key, const T &value)

- json labelDictionary (const std::string &server, const std::string &model\_name)
- static std::string messagePrepare (const json &in)
- static json messagePrepareJson (const json &in)
- ModelInfo modelFind (const std::string &server, const ModelQuery &query)
- void modelzooListGet (const std::string &server, std::vector < ModelInfo > &modelzoo\_list)
- json modelZooManage (const std::string &server, const json &req)
- bool operator< (const ServerAddress &lhs, const ServerAddress &rhs)</li>

Comparison operator for server address.

std::ostream & operator<< (std::ostream &os, const BasicTensor &t)</li>

Print tensor to stream.

bool operator== (const ServerAddress &lhs, const ServerAddress &rhs)

Comparison operator for server address.

- bool serverPing (const std::string &server)
- void shutdown (const std::string &server)
- json systemInfo (const std::string &server)
- json traceManage (const std::string &server, const json &req)
- std::string versionGet ()

#### **Variables**

• const int CURRENT PROTOCOL VERSION = 4

current client-server protocol version

const int DEFAULT\_CONNECTION\_TIMEOUT\_MS = 10000

Default connection timeout, ms.

• const int DEFAULT FRAME QUEUE DEPTH = 8

Default frame queue depth.

const int DEFAULT\_INFERENCE\_TIMEOUT\_MS = 180000

Default inference timeout, ms.

• const int DEFAULT\_PORT = 8778

Default TCP port of AI server.

• const int MIN\_COMPATIBLE\_PROTOCOL\_VERSION = 4

minimum compatible client-server protocol version

- const int MODEL\_PARAMS\_CURRENT\_VERSION = 8
- const int MODEL\_PARAMS\_MIN\_COMPATIBLE\_VERSION = 1
- constexpr const char \* PROTOCOL\_VERSION\_TAG = "VERSION"

client-server protocol version tag

constexpr ModelParamsSection SECT\_DEVICE = { "DEVICE", true }

device parameters section

constexpr ModelParamsSection SECT\_INTERNAL = { "INTERNAL", true }

internal parameters section

- constexpr ModelParamsSection SECT\_MODEL\_PARAMETERS = { "MODEL\_PARAMETERS", true }
   model parameters section
- constexpr ModelParamsSection SECT\_POST\_PROCESS = { "POST\_PROCESS", true }

post-processing parameters section

• constexpr ModelParamsSection SECT\_PRE\_PROCESS = { "PRE\_PROCESS", false }

pre-processing parameters section

constexpr ModelParamsSection SECT\_TOP = { "", true }

Json file top-level sections.

# 5.1.1 Detailed Description

DG is DeGirum namespace which groups all DeGirum software declarations.

#### 5.1.2 Enumeration Type Documentation

#### 5.1.2.1 DetectionStatus

```
enum DG::DetectionStatus [strong]
```

Enumerator showing server status as detected by the below function.

#### Enumerator

OK	Server fully operational.
ProtocolMismatch	Server is up, but is outdated.
HostAlive	Hardware is alive, but no server found. Unimplemented!

# 5.1.2.2 RUNTIME\_AGENT\_TYPES

```
enum DG::RUNTIME_AGENT_TYPES [strong]
```

Runtime agent types.

#### Enumerator

DEFAULT	default runtime agent
N2X	DeGirum nnExpress runtime agent.
TFLITE	TF-Lite runtime agent.
ONNX	Onnx runtime agent.
OPENVINO	OpenVINO runtime agent.
DUMMY	dummy agent (for DeGirum internal use only)

## 5.1.3 Function Documentation

## 5.1.3.1 detectHostnameServers()

Detect all ORCA servers with hostnames generated from a prefix and a range

in	prefix	is a string prefix, formatted as "nnnn[:port]". This will be used to generate two sets of hostnames, one with the pattern "nnnn#", and one "nnnn###". For example, the prefix "farm", range_start 1, range_end 2 and numeral_width 3 will scan the hosts "farm1", "farm001", "farm2", "farm002". Setting numeral_width to 0 disables pattern generation, and will just scan the prefix. The port part is optional. If included, all servers will be scanned on the port. If omitted, the default port 8778 will be used.
in	range_start	is the lowest numeral to be applied to the pattern
in	range_end	is the highest numeral to be applied to the pattern, inclusive
in	numeral_width	is the width of the numeral in the padded set. This is optional, set to 3 by default. Set to 0 to disable pattern generation.

#### Returns

Vector of strings containing hostnames of ORCA servers on the network.

#### 5.1.3.2 detectSubnetServers()

Detect all ORCA servers on a given subnet

#### **Parameters**

in	root_ip	is an IP address in the network, formatted as "xxx.xxx.xxx.xxx[:port]". The port part is optional. If included, all servers will be scanned on the port. If omitted, the default port 8778 will be used.
in	subnet_mask	specifies the subnet with the associated IP, formatted as "xxx.xxx.xxx.xxx", where "xxx"
		is either 255 for fixed bits or 0 for variable bits.

#### Returns

Vector of pairs containing IPs of ORCA servers on the network and their statuses

## 5.1.3.3 errorCheck()

Check given AI server Json response for run-time errors. If AI server reported run-time error in the given Json response, then this function extracts and returns the error message string from the provided Json array, otherwise it returns an empty string.

#### 5.1.3.4 jsonGetMandatoryValue()

Get value from Json array. Raise error, if not there

in	json_params	- Json array
in Generated	Section by Doxygen	- top section name, which contains array of records; if empty, key is taken from topmost level
in	index	- index in array of records
in	key	- key of key-value pair

#### Returns

parameter value

## 5.1.3.5 jsonGetOptionalValue()

Get value from Json array, which may not be present there

#### **Parameters**

in	json_params	- Json array
in	section	- top section name, which contains array of records if empty, key is taken from topmost
		level
in	index	- index in array of records
in	key	- key of key-value pair
in	default_value	- value to return, if no such key is found

#### Returns

parameter value

# 5.1.3.6 jsonKeyExist()

Check if given key exists in Json array

in	json_params	- Json array
in	section	- top section name, which contains array of records if empty, key is checked on topmost
		level
in	index	- index in array of records
in	key	- key of key-value pair

#### Returns

true if such key exists in array

## 5.1.3.7 jsonSetOptionalValue()

Set value to Json array; if it is not present, skip assignment

#### **Parameters**

in	json_params	- Json array
in	section	- top section name, which contains array of records if empty, key is set on topmost level
in	index	- index in array of records
in	in key - key of key-value pair in value - value to set	
in		

## 5.1.3.8 labelDictionary()

## Get model label dictionary

#### Parameters

in	server	is a string specifying server domain name/IP address and port. Format: "domain_name:port" or "xxx.xxx.xxx.xxx:port". If port is omitted, the default port is 8778.
in	model_name	specifies the AI model. To obtain valid model name, either modelFind() or modelzooListGet() functions should be used.

#### Returns

JSON object containing model label dictionary

#### 5.1.3.9 messagePrepare()

prepare client-server response message string from input json

#### **Parameters**

```
in server response json
```

#### Returns

client response string

# 5.1.3.10 messagePrepareJson()

Prepare client-server response message json from input json

#### **Parameters**

```
in server response json
```

#### Returns

client response json

# 5.1.3.11 modelFind()

Find a model on a given Al server which matches given model query.

in	server	is a string specifying server domain name/IP address and port. Format: "domain_name:port" or "xxx.xxx.xxx.xxx:port". If port is omitted, the default port is 8778.
in	query	is the ModelQuery structure of model parameters to look for.

#### Returns

model descriptor to be used in AlModel and AlModelAsync constructors. If the model is not found, the model descriptor contains an empty model name.

### 5.1.3.12 modelzooListGet()

Get a list of supported models from AI server. In case of server connection errors throws std::exception.

### **Parameters**

in	server	is a string specifying server domain name/IP address and port. Format:
		"domain_name:port" or "xxx.xxx.xxx.xxx:port". If port is omitted, the default port is
		8778.
out	modelzoo_list	is the output vector of ModelInfo structures; each structure contains essential model
		attributes such as model ID, model name, input width and input height. The
		ModelInfo structure extracted from this vector can be used as a parameter for
		construction of AlModel and AlModelAsync instances.

### 5.1.3.13 modelZooManage()

Al server model zoo management

# **Parameters**

=	in	server	is a string specifying server domain name/IP address and port. Format: "domain_name:port" or "xxx.xxx.xxx.xxx:port". If port is omitted, the default port is 8778.	
-	in	req	- management request	

#### Returns

results of management request completion (request-specific)

### 5.1.3.14 serverPing()

Ping server with an instantaneous command

#### **Parameters**

in	server	is a string specifying server domain name/IP address and port. Format: "domain_name:port"
		or "xxx.xxx.xxx.xxx:port". If port is omitted, the default port is 8778. return true if no error
		occurred during the ping

### 5.1.3.15 shutdown()

```
void DG::shutdown ( {\tt const\ std::string\ \&\ } {\it server\ } )
```

Send shutdown request to AI server [in] server is a string specifying server domain name/IP address and port. Format: "domain\_name:port" or "xxx.xxx.xxx.xxx:port". If port is omitted, the default port is 8778.

### 5.1.3.16 systemInfo()

Return host system information dictionary.

#### **Parameters**

in	server	is a string specifying server domain name/IP address and port. Format: "domain_name:port" or
		"xxx.xxx.xxx.xxx:port". If port is omitted, the default port is 8778.

### 5.1.3.17 traceManage()

Al server tracing facility management

# **Parameters**

in	server	is a string specifying server domain name/IP address and port. Format: "domain_name:port" or "xxx.xxx.xxx.xxx:port". If port is omitted, the default port is 8778.
in	req	- management request

### Returns

results of management request completion (request-specific)

### 5.1.3.18 versionGet()

```
std::string DG::versionGet ( )
```

Get the version of the library.

#### Returns

library version in the following format: MAJOR.MINOR.REVISION.GIT REVISION

### 5.1.4 Variable Documentation

### 5.1.4.1 MODEL\_PARAMS\_CURRENT\_VERSION

```
const int DG::MODEL_PARAMS_CURRENT_VERSION = 8
```

The most current version of Json model configuration, supported by this version of software. Increment it each time you change any parameter definition or add/remove any parameter

### 5.1.4.2 MODEL\_PARAMS\_MIN\_COMPATIBLE\_VERSION

```
const int DG::MODEL_PARAMS_MIN_COMPATIBLE_VERSION = 1
```

The minimum compatible version of Json model configuration, still supported by this version of software. Increase it when the software is modified such a way, that it stops supporting older Json model configuration versions.

### 5.1.4.3 SECT\_TOP

```
constexpr ModelParamsSection DG::SECT_TOP = { "", true } [constexpr]
```

Json file top-level sections.

top-level section

# **Chapter 6**

# **Class Documentation**

### 6.1 DG::AlModel Class Reference

AlModel is DeGirum Al client API class for simple non-pipelined sequential inference.

```
#include <dg_model_api.h>
```

#### **Public Member Functions**

- AIModel (const std::string &server, const std::string &model\_name, const ModelParamsReadAccess &model\_params=ModelParamsReadAccess({}), size\_t connection\_timeout\_ms=DEFAULT\_CONNECTION\_TIMEOUT\_MS, size\_t inference\_timeout\_ms=DEFAULT\_INFERENCE\_TIMEOUT\_MS)
- void predict (std::vector< std::vector< char > > &data, json &json\_response)
- ∼AlModel ()

Destructor. Closes connection to AI server.

### 6.1.1 Detailed Description

AlModel is DeGirum Al client API class for simple non-pipelined sequential inference.

This class is used to perform AI model inference on AI server in a simple non-pipelined sequential manner. For more efficient (but somewhat more complex) asynchronous pipelined inference use AIModelAsync class.

On construction this class performs connection to Al server, selection of Al model, and setting model run-time parameters.

Once constructed, it can be used to perform sequential AI inference by invoking predict() method. The predict() methods accept the input frame data in various formats and return the inference results. These are blocking methods, i.e. they return execution only when the inference of an input frame is complete.

#### 6.1.2 Constructor & Destructor Documentation

#### 6.1.2.1 AlModel()

Constructor. Performs connection to AI server, selection of AI model, and optionally setting model run-time parameters. In case of server connection errors throws std::exception.

#### **Parameters**

in	server	is a string specifying server domain name/IP address and port. Format: "domain_name:port" or "xxx.xxx.xxx.xxx:port". If port is omitted, the default port is 8778.
in	model_name	specifies the AI model to be used for inference. To obtain valid model name, either modelFind() or modelzooListGet() functions should be used.
in	model_params	is runtime parameter collection, which defines the model runtime behavior. This is optional parameter: if not specified, then default runtime parameters (as defined in the model zoo) are used. ModelParamsWriter class instance can be used to conveniently define runtime parameters.
in	connection_timeout_ms	is the AI server connection timeout in milliseconds. This is optional parameter: by default it is set to 10 sec.
in	inference_timeout_ms	is the AI server inference timeout in milliseconds. This is optional parameter: by default it is set to 180 sec.

### 6.1.3 Member Function Documentation

### 6.1.3.1 predict()

Run the AI inference on provided byte array. The byte array contains the frame data, which depends on selected frame format. It can be either JPEG or bitmap depending on the model parameters. In case of errors throws std  $\leftarrow$  ::exception. This is blocking method, i.e. it returns execution only when the inference of an input frame is complete.

#### **Parameters**

in	data	is a vector of input data for each model input where each data element is a vector of bytes.
out	json_response	is the result of the inference. The response format depends on the model post-processor type.

The documentation for this class was generated from the following file:

• dg\_model\_api.h

# 6.2 DG::AlModelAsync Class Reference

AlModelAsync is DeGirum Al client API class for efficient pipelined asynchronous inference.

```
#include <dq_model_api.h>
```

### **Public Types**

using callback\_t = std::function < void(const json &inference\_result, const std::string &frame\_info) >

#### **Public Member Functions**

- std::string lastError () const
- · int outstandingResultsCountGet () const

Get the number of outstanding inference results posted so far.

- void predict (std::vector < std::vector < char > > &data, const std::string &frame\_info="")
- void setCallback (callback\_t callback)
- void waitCompletion ()
- ∼AlModelAsync ()

### 6.2.1 Detailed Description

AlModelAsync is DeGirum Al client API class for efficient pipelined asynchronous inference.

This class is used to perform AI model inference on AI server in efficient pipelined asynchronous manner using the mechanism of callbacks. For simple (but less efficient) synchronous non-pipelined inference use AIModel class.

On construction this class performs connection to AI server, selection of AI model, setting model run-time parameters, and installation of the client callback function. The client callback function is used to pass the inference results from the AI server to the client code.

Once constructed, it can be used to perform asynchronous AI inference by invoking predict() method. The predict() methods accept the input frame data and initiate the inference on the AI server. Each of those methods is a non-blocking method, i.e. it returns execution immediately after posting the frame data to the AI server. This allows calling those methods in a loop without waiting for the inference results, achieving the maximum AI server utilization. Once the inference of a frame is complete, and the inference result is received from the AI server, the client callback is invoked to dispatch the inference result. Such result handling via callback mechanism is performed in a thread, separate from the main execution thread. It means that the client callback function is called in asynchronous manner, thus the name of the class.

### 6.2.2 Member Typedef Documentation

#### 6.2.2.1 callback\_t

```
using DG::AIModelAsync::callback_t = std::function< void( const json &inference_result, const
std::string &frame_info ) >
```

User callback type. The callback is called asynchronously from the main execution thread as soon as prediction result is ready. Consecutive prediction result in a form of Json array is passed as the inference\_result argument. Corresponding frame info string (provided to predict() call) is passed as the frame info argument.

# 6.2.3 Constructor & Destructor Documentation

### 6.2.3.1 AlModelAsync()

Constructor. Performs connection to AI server, selection of AI model, installing client callback, and optionally setting model run-time parameters. In case of server connection errors throws std::exception.

### **Parameters**

in	server	is a string specifying server domain name/IP address and port. Format: "domain_name:port" or "xxx.xxx.xxx.xxx:port". If port is omitted, the default port is 8778.
in	model_name	specifies the AI model to be used for inference. To obtain valid model name, either modelFind() or modelzooListGet() functions should be used.
in	callback	is user callback functional, which will be called asynchronously from the main execution thread as soon as prediction result is ready.
in	model_params	is runtime parameter collection, which defines the model runtime behavior.  This is optional parameter: if not specified, then default runtime parameters (as defined in the model zoo) are used. ModelParamsWriter class instance can be used to conveniently define runtime parameters.
in	frame_queue_depth	is the depth of the internal frame queue. If <a href="mailto:predict">predict()</a> methods are invoked too often and the number of non-processed (aka "outstanding") frames exceeds this parameter, the consecutive call to any <a href="mailto:predict(">predict(")</a> method will be blocked until the number of outstanding frames in the queue becomes smaller than the queue depth thus allowing to post one more frame. This is optional parameter: by default it is set to 8 frames.
in	connection_timeout_ms	is the AI server connection timeout in milliseconds. This is optional parameter: by default it is set to 10 sec.
in	inference_timeout_ms	is the AI server inference timeout in milliseconds. This is optional parameter: by default it is set to 180 sec.

#### 6.2.3.2 ∼AlModelAsync()

```
DG::AIModelAsync::~AIModelAsync ( )
```

Destructor. Waits until all outstanding results are received and then closes the connection to AI server. Note: in case of server runtime error, all frames posted after that error was detected, will not be processed.

#### 6.2.4 Member Function Documentation

#### 6.2.4.1 lastError()

```
std::string DG::AIModelAsync::lastError ( ) const
```

If ever during consecutive calls to predict() methods AI server reported a run-time error, then this method will return the error message string, otherwise it returns an empty string. Note: in case of server runtime error, all frames posted after that error was detected, will not be processed.

#### 6.2.4.2 predict()

Start the inference on given byte data vector. The byte vector contains the frame data, which depends on selected frame format. It can be either JPEG or bitmap depending on the model parameters. In case of errors throws std :: exception. This is non-blocking call meaning that it returns execution immediately after posting the frame data to the AI server.

### **Parameters**

in	data	is a vector of input data for each model input where each data element is a vector of bytes.
in	frame_info	is optional frame information string to be passed to the client callback along with the frame result. You can pass arbitrary information as frame info. This simplifies matching results to frames in the client callback.

### 6.2.4.3 setCallback()

Set user callback

#### **Parameters**

in	callback	is user callback functional, which will be called asynchronously from the main execution
		thread as soon as prediction result is ready.

#### 6.2.4.4 waitCompletion()

```
void DG::AIModelAsync::waitCompletion ( )
```

Wait for completion of all outstanding inferences. This is blocking call: it returns when all outstanding frames are processed by AI server and all results are dispatched via client callback. You can continue calling predict() after call to this method - frame processing will restart automatically.

The documentation for this class was generated from the following file:

· dg model api.h

### 6.3 DG::BasicTensor Class Reference

```
#include <dg_tensor_structs.h>
```

### **Classes**

• struct quant\_params\_t

Quantization parameters (how to convert from integer/quantized data back to floating point)

### **Public Types**

using shape\_t = std::vector < size\_t >
 Tensor shape vector type.

#### **Public Member Functions**

- template < class CONTAINER >
   auto alloc (const CONTAINER & source, bool do\_copy=true, int32\_t id=0, const std::string &name="", const shape\_t &shape={}, const quant\_params\_t &quant\_params={}) -> decltype(source.data(), source.size(), void())
- template<typename T >
   void alloc (int32\_t id, const std::string &name, const shape\_t &shape, const quant\_params\_t &quant\_
   params={}, T \*ext\_lin\_buffer=nullptr)
- void alloc (int32\_t id, const std::string &name, const shape\_t &shape, DGType data\_type, const quant\_params\_t &quant\_params={}, void \*ext\_lin\_buffer=nullptr)
- BasicTensor () noexcept

Default constructor.

BasicTensor (BasicTensor &&move) noexcept

Move constructor.

• BasicTensor (const BasicTensor &)=delete

Deleted copy constructor.

template < class CONTAINER >

BasicTensor (const CONTAINER &source, bool do\_copy=true, int32\_t id=0, const std::string &name="", const shape\_t &shape={}, const quant\_params\_t &quant\_params={})

• template<typename T >

BasicTensor (int32\_t id, const std::string &name, const shape\_t &shape, const quant\_params\_t &quant\_← params={}, T \*ext\_lin\_buffer=nullptr)

- BasicTensor (int32\_t id, const std::string &name, const shape\_t &shape, DGType data\_type, const quant\_params\_t &quant\_params={}, void \*ext\_lin\_buffer=nullptr)
- · BasicTensor clone () const

Create and return exact copy of itself.

• template<typename T >

BasicTensor convert () const

- BasicTensor convert (DGType to type) const
- · BasicTensor copy () const
- template<typename T >

T \* data ()

• template<typename T >

const T \* data () const

DGType dataTypeGet () const

Get DG data type of tensor element.

void dealloc ()

Deallocate tensor data and clear tensor.

- template<typename T\_IN, typename T\_OUT > void dequantize ()
- size\_t elementSizeGet () const

Get tensor element size in bytes.

· bool empty () const

Check if tensor is empty.

int32\_t id () const

Get id

- FloatCompareResult< double > isEqualData (const BasicTensor &rhs, double maxRelDiff) const
- template<typename T >

FloatCompareResult< double > isEqualData (const std::vector< T > &rhs, double maxRelDiff) const

- bool isEqualDataShape (const BasicTensor &rhs) const
- bool isEqualStruct (const BasicTensor &rhs) const
- bool isExternal () const

Is external buffer?

bool isNull () const

Check if tensor is null.

• size\_t linearSizeGet () const

Get tensor linear size in elements of current type.

• size\_t linearSizeGet\_bytes () const

Get tensor linear size in bytes.

• const std::string & name () const

Get name.

std::string numpyTypeGet () const

Return numpy-compatible type string.

BasicTensor & operator= (BasicTensor &&move)

Move assignment operator.

BasicTensor & operator= (const BasicTensor &)=delete

```
Deleted copy assignment operator.
```

```
    template<typename T_IN, typename T_OUT > void quantize ()
```

· const quant params t & quantParams () const

Get quantization parameters.

- void reshapeTo (size\_t dim)
- void reshapeToNHWC ()

Reshape tensor to 4-D NHWC shape.

· const shape\_t & shape () const

Get shape vector.

• const std::type\_info & typeInfo () const

Return type info.

• template<typename T = void>

T \* untypedData ()

Return raw data buffer.

• template<typename T = void>

T \* untypedData () const

Return raw data buffer.

∼BasicTensor ()

Destructor.

#### **Static Public Member Functions**

static std::string numpyTypeGet (const std::string &dg\_type)
 Return numpy-compatible type string from given DG type string.

### 6.3.1 Detailed Description

Basic tensor container class. Based on "linear buffer with dimension array" approach. Dynamically-typed. Supports both internally or externally allocated buffers.

### 6.3.2 Constructor & Destructor Documentation

### 6.3.2.1 BasicTensor() [1/3]

Constructor: allocate or assign tensor memory according to dimension vector (static typing version)

#### **Parameters**

in	id	- tensor ID
in	name	- tensor name
in	shape	- tensor shape vector, which defines dimensions of new tensor
in	quant_params	- tensor quantization parameters
in	ext_lin_buffer	- optional external linear buffer pointer; if nullptr, buffer will be allocated internally

### 6.3.2.2 BasicTensor() [2/3]

```
DG::BasicTensor::BasicTensor (
    int32_t id,
    const std::string & name,
    const shape_t & shape,
    DGType data_type,
    const quant_params_t & quant_params = {},
    void * ext_lin_buffer = nullptr ) [inline]
```

Constructor: allocate or assign tensor memory according to dimension vector (dynamic typing version)

#### **Parameters**

in	id	- tensor ID
in	name	- tensor name
in	shape	- tensor shape vector, which defines dimensions of new tensor
in	data_type	- tensor element data type id
in	quant_params	- tensor quantization parameters
in	ext_lin_buffer	- optional external linear buffer pointer; if nullptr, buffer will be allocated internally

### 6.3.2.3 BasicTensor() [3/3]

Constructor: allocate tensor memory and copy data from given linear container. CONTAINER type should have value\_type, data(), and size() methods. If shape is empty, 1-D tensor the size of the linear container will be allocated. The size of the data copied is the minimum of the linear container size and the shape dimensions product.

#### **Parameters**

in source - linear container (such as string or vector) with tensor data
--

#### **Parameters**

in	do_copy	- when true, copy data from container into tensor-owned buffer, otherwise assign	
		pointer to container data	
in	id	- tensor ID	
in	name	- tensor name	
in	shape	- tensor shape vector, which defines dimensions of new tensor	
in	quant_params	- tensor quantization parameters	

### 6.3.3 Member Function Documentation

### 6.3.3.1 alloc() [1/3]

Allocate tensor memory and copy data from given linear container. CONTAINER type should have value\_type, data(), and size() methods. If shape is empty, 1-D tensor the size of the linear container will be allocated. The size of the data copied is the minimum of the linear container size and the shape dimensions product.

#### **Parameters**

in	source	- linear container (such as string or vector) with tensor data	
in	do_copy	- when true, copy data from container into tensor-owned buffer, otherwise assign pointer to container data	
in	id	- tensor ID	
in	name	- tensor name	
in	shape	- tensor shape vector, which defines dimensions of new tensor	
in	quant_params	- tensor quantization parameters	

### 6.3.3.2 alloc() [2/3]

```
const quant_params_t & quant_params = {},
T * ext_lin_buffer = nullptr ) [inline]
```

Allocate or assign tensor memory according to dimension vector (static typing version)

#### **Parameters**

in	id	- tensor ID	
in	name	- tensor name	
in	shape	- tensor shape vector, which defines dimensions of new tensor	
in	quant_params	- tensor quantization parameters	
in	n ext_lin_buffer - optional external linear buffer pointer; if nullptr, buffer will be allocated intern		

### 6.3.3.3 alloc() [3/3]

```
void DG::BasicTensor::alloc (
    int32_t id,
    const std::string & name,
    const shape_t & shape,
    DGType data_type,
    const quant_params_t & quant_params = {},
    void * ext_lin_buffer = nullptr ) [inline]
```

Allocate or assign tensor memory according to dimension vector (dynamic typing version)

### **Parameters**

in	id	- tensor ID	
in	name	- tensor name	
in	shape	- tensor shape vector, which defines dimensions of new tensor	
in	data_type	- tensor element data type id	
in	quant_params	- tensor quantization parameters	
in	ext_lin_buffer - optional external linear buffer pointer; if nullptr, buffer will be allocated internal		

### 6.3.3.4 convert() [1/2]

```
template<typename T >
BasicTensor DG::BasicTensor::convert ( ) const [inline]
```

Convert tensor to new element type with casting and copying data

#### **Template Parameters**

output	data type T

#### Returns

new owning tensor of type T

### 6.3.3.5 convert() [2/2]

Convert tensor to new element type with casting and copying data

### **Parameters**

```
in to_type - new element type
```

#### Returns

new owning tensor

# 6.3.3.6 copy()

```
BasicTensor DG::BasicTensor::copy ( ) const [inline]
```

Create and return deep copy of itself. External buffer data will be duplicated.

# 6.3.3.7 data() [1/2]

```
template<typename T >
T* DG::BasicTensor::data ( ) [inline]
```

Return non-const typed pointer to underlying linear buffer. Returns nullptr if template type does not match actual runtime tensor element type

### 6.3.3.8 data() [2/2]

```
template<typename T >
const T* DG::BasicTensor::data ( ) const [inline]
```

Return const typed pointer to underlying linear buffer. Returns nullptr if template type does not match actual runtime tensor element type

#### 6.3.3.9 dequantize()

```
template<typename T_IN , typename T_OUT > void DG::BasicTensor::dequantize ( ) [inline]
```

Dequantize tensor according to current quantization settings from type T\_IN to type T\_OUT New linear buffer will be internally allocated to receive dequantized data.

### 6.3.3.10 isEqualData() [1/2]

Check, if this object and given object have equal data contents

### **Parameters**

in	rhs	- object to compare with	
in	maxRelDiff	- maximum relative difference for floating point comparison (ignored for integer data)	

# 6.3.3.11 isEqualData() [2/2]

Check, if this object and given vector have equal data contents

### **Parameters**

in	rhs	- vector to compare with	
in	maxRelDiff - maximum relative difference for floating point comparison (ignored for integer date)		

# 6.3.3.12 isEqualDataShape()

Check, if this object and given object have equal shape, element size and number of elements

#### **Parameters**

in	rhs	- object to compare with

#### 6.3.3.13 isEqualStruct()

Check, if this object and given object have equal structure

#### **Parameters**

```
in rhs - object to compare with
```

#### 6.3.3.14 quantize()

```
template<typename T_IN , typename T_OUT >
void DG::BasicTensor::quantize ( ) [inline]
```

Quantize tensor according to current quantization settings from type T\_IN to type T\_OUT New linear buffer will be internally allocated to receive quantized data.

### 6.3.3.15 reshapeTo()

Reshape tensor to given shape When new shape is bigger than current, shape is appended with unity values When new shape is smaller than current, shape is reduced, and last shape dimension is multiplied by product of reduced dimensions

The documentation for this class was generated from the following file:

• dg\_tensor\_structs.h

# 6.4 DG::JsonHelper Class Reference

Json helper class: contains assorted static methods to operate with Json configurations.

```
#include <dg_json_helpers.h>
```

### **Public Types**

using serial\_container\_t = json::binary\_t::container\_type
 Container type for serialized Json array (it is std::vector< unit8\_t >)

#### **Static Public Member Functions**

- static std::string errorCheck (const json &response, const std::string &source, bool do\_throw=true)
- static json jsonDeserialize (const serial\_container\_t &v)
- static serial container t jsonSerialize (const json &j)
- static json parse (const std::string &json\_cfg, const char \*file, const char \*line, const char \*func)
- static json parse\_ignore\_errors (const std::string json\_cfg)
- static BasicTensor tensorDeserialize (const json &j)
- static json tensorSerialize (const BasicTensor &t)

### 6.4.1 Detailed Description

Json helper class: contains assorted static methods to operate with Json configurations.

#### 6.4.2 Member Function Documentation

#### 6.4.2.1 errorCheck()

Check server Json response for errors and throw exception, if any

#### **Parameters**

in	response	- Json response from server/core
in	source	- description of the server command initiator
in	do_throw	- if true, throws exception in case of error

### Returns

original error string, if error is detected, empty string otherwise

### 6.4.2.2 jsonDeserialize()

Deserialize given byte vector with msgpack data into Json array

#### **Parameters**

in	V	- byte vector with msgpack data to deserialize	Ì
----	---	--	---

### Returns

Json array

### 6.4.2.3 jsonSerialize()

```
static serial_container_t DG::JsonHelper::jsonSerialize ( const json & j ) [inline], [static]
```

Serialize given Json array into byte vector using conversion to msgpack

### **Parameters**

```
in j - Json array to serialize
```

#### Returns

byte vector with Json array contents converted to msgpack representation

### 6.4.2.4 parse()

Parse given Json string with proper exception handling

### **Parameters**

in	json_cfg	- Json string to parse
in	file	- file where parsing happens
in	line	- line in file where parsing happens
in	func	- function where parsing happens

### Returns

Json array

### 6.4.2.5 parse\_ignore\_errors()

Parse given Json string with swallowing exceptions

**Parameters** 

```
in | json_cfg | - Json string to parse
```

#### Returns

Json array or empty array, if parsing failed

### 6.4.2.6 tensorDeserialize()

Convert Json array to basic tensor

#### **Parameters**

```
in j - Json array
```

# Returns

basic tensor

#### 6.4.2.7 tensorSerialize()

Convert basic tensor to Json array

#### **Parameters**

```
in t - basic tensor
```

### Returns

Json array

The documentation for this class was generated from the following file:

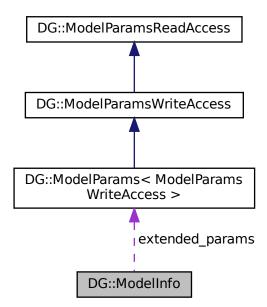
• dg\_json\_helpers.h

# 6.5 DG::ModelInfo Struct Reference

ModelInfo is the model identification structure. It keeps AI model key attributes.

```
#include <dg_client_structs.h>
```

Collaboration diagram for DG::ModelInfo:



# **Public Attributes**

• int C

input color depth

• std::string device\_type

device type on which model runs

DG::ModelParamsWriter extended\_params

extended model parameters

• int H

input height

size\_t id

unique model ID

• std::string input\_color\_space

for image inputs, image color-space the model expects: "BGR", "RGB"

· std::string input\_image\_format

for image inputs, image format: "JPEG", "RAW" (this is user-tunable runtime parameter)

std::string input\_raw\_data\_type

for "RAW" image inputs, image pixel data type: "DG\_FLT", "DG\_UINT8" (this is user-tunable runtime parameter)

std::string input\_tensor\_layout

for image inputs, image tensor layout the model expects: "NHWC", "NCHW"

· std::string input\_type

input data type: "Image", ...

· bool model pruned

'is model pruned (not dense)' flag

bool model\_quantized

'is model quantized' flag

int N

input frame depth

· std::string name

model string name

• std::string runtime\_agent

runtime agent type on which model runs

int W

input width

# 6.5.1 Detailed Description

ModelInfo is the model identification structure. It keeps AI model key attributes.

The documentation for this struct was generated from the following file:

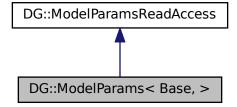
dg\_client\_structs.h

# 6.6 DG::ModelParams < Base, > Class Template Reference

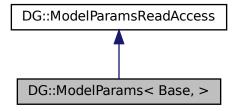
ModelParams is model parameters collection with user-defined access rights.

```
#include <dg_model_parameters.h>
```

Inheritance diagram for DG::ModelParams< Base, >:



Collaboration diagram for DG::ModelParams< Base, >:



#### **Public Member Functions**

- ModelParams (const char \*json text="{}")
- ModelParams (const json &json\_cfg)
- ModelParams (const std::string &json\_text)
- ModelParams (ModelParams &&rhs)

Move constructor.

ModelParams (ModelParams const &rhs)

Copy constructor.

ModelParams & operator= (ModelParams &&rhs)

Move assignment.

ModelParams & operator= (ModelParams const &rhs)

Copy assignment.

#### **Additional Inherited Members**

### 6.6.1 Detailed Description

ModelParams is model parameters collection with user-defined access rights.

This class provides programmatic type-safe access to model parameters defined in Json model configuration while owning that Json array. Access (read or write) is defined by the Base template parameter, which is used as the base class.

### **Template Parameters**

Base	- ModelParamsReadAccess-derived base class: it can be ModelParamsReadAccess or	
	ModelParamsWriteAccess	

### 6.6.2 Constructor & Destructor Documentation

#### 6.6.2.1 ModelParams() [1/3]

Constructor. Creates model parameter collection by parsing Json text in character array

#### **Parameters**

in	json text	- Json text with model parameters. It will be parsed and stored in internal Json array.
	J	the contract of the contract o

### 6.6.2.2 ModelParams() [2/3]

Constructor. Creates model parameter collection by parsing Json text in std::string

#### **Parameters**

in	ison text	- Json text with model parameters. It will be parsed and stored in internal Json array.

#### 6.6.2.3 ModelParams() [3/3]

Constructor. Creates model parameter collection from given Json array

#### **Parameters**

in	json_cfg	- Json array with model parameters. It will be copied into internal Json array.
----	----------	---

The documentation for this class was generated from the following file:

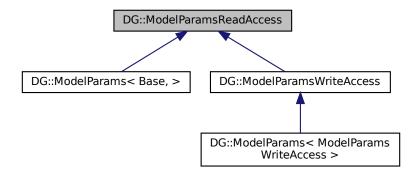
· dg\_model\_parameters.h

### 6.7 DG::ModelParamsReadAccess Class Reference

ModelParamsReadAccess is read-only accessor to model parameters.

```
#include <dg_model_parameters.h>
```

Inheritance diagram for DG::ModelParamsReadAccess:



### **Public Member Functions**

- · const json & jsonGet () const
- ModelParamsReadAccess (const json &config)
- template<typename T >

T None (size t idx=0) const

Stub for empty getter fallback.

bool None\_exist (size\_t idx=0) const

Stub for empty existence checker fallback.

• template<typename T >

T None\_get (size\_t idx=0) const

Stub for empty getter fallback.

- · operator const json & () const
- operator std::string () const
- const json & sectionGet (const std::string &section, size\_t idx=0) const
- size\_t sectionHashGet (const std::string &section, size\_t idx=0) const
- size\_t sectionSizeGet (const std::string &section) const

#### **Protected Member Functions**

- template<typename T >

T paramGet (const char \*section, const char \*key, bool is\_mandatory, const T &default\_value, size\_t idx, T(ModelParamsReadAccess::\*fallback)(size\_t) const) const

### **Protected Attributes**

• const json & m\_cfg\_ro

non-owning reference to Json array with model configuration

### 6.7.1 Detailed Description

ModelParamsReadAccess is read-only accessor to model parameters.

This class provides programmatic type-safe read access to model parameters defined in Json model configuration. It keeps non-owning const reference to underlying Json array. For each model parameter it provides getter method, which name matches the parameter name as it appears in Json array.

#### 6.7.2 Constructor & Destructor Documentation

#### 6.7.2.1 ModelParamsReadAccess()

Constructor. Attaches model parameter read-only accessor to Json array

#### **Parameters**

in	config	- Json array with model configuration
----	--------	---------------------------------------

#### 6.7.3 Member Function Documentation

# 6.7.3.1 jsonGet()

```
const json& DG::ModelParamsReadAccess::jsonGet ( ) const [inline]
```

Access to underlying Json array

#### Returns

constant non-owning reference to Json array with model configuration

### 6.7.3.2 operator const json &()

```
DG::ModelParamsReadAccess::operator const json & ( ) const [inline]
```

Access to underlying Json array

#### Returns

constant non-owning reference to Json array with model configuration

### 6.7.3.3 operator std::string()

```
DG::ModelParamsReadAccess::operator std::string ( ) const [inline]
```

Access to underlying Json array as string

#### Returns

Json text with model configuration

### 6.7.3.4 paramExist()

Check parameter for existence

### **Template Parameters**

```
T - parameter type
```

#### **Parameters**

	in	section	- top section name; if empty, key is taken from topmost level
Ī	in	key	- key of key-value pair
ſ	in	idx	- array index inside section object
Ī	in	fallback	- existence checker for fallback parameter

### Returns

parameter value

### 6.7.3.5 paramGet()

### Get parameter from Json array

#### **Template Parameters**

```
T - parameter type
```

#### **Parameters**

in	section	- top section name; if empty, key is taken from topmost level
in	key	- key of key-value pair
in	is_mandatory	- if parameter mandatory
in	default_value	- value to return, if no such key is found
in	idx	- array index inside section object
in	fallback	- fallback parameter getter

#### Returns

parameter value

### 6.7.3.6 sectionGet()

Access to underlying Json sub-array for particular section

#### **Parameters**

in	section	- section name to access (one of SECT_xxx constants)
in	idx	- array index inside section object

#### Returns

constant non-owning reference to Json array with particular model section configuration

### 6.7.3.7 sectionHashGet()

Compute the hash of the parameter values in a given section

#### **Parameters**

in	section	- section name to compute hash for
in	idx	- array index inside section object

#### Returns

std::hash for a given section

# 6.7.3.8 sectionSizeGet()

Get size of underlying Json sub-array for particular section

#### **Parameters**

j	in	section	- section name to access (one of SECT_xxx constants)
---	----	---------	--

#### Returns

section sub-array size in elements

The documentation for this class was generated from the following file:

· dg\_model\_parameters.h

# 6.8 DG::ModelParamsSection Struct Reference

Model parameters section descriptor.

```
#include <dg_model_parameters.h>
```

### **Public Attributes**

bool is\_scalar

scalar vs vector flag: vector sections contain more than one element

· const char \* label

section name string

# 6.8.1 Detailed Description

Model parameters section descriptor.

The documentation for this struct was generated from the following file:

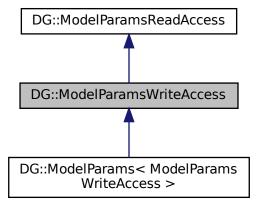
• dg\_model\_parameters.h

# 6.9 DG::ModelParamsWriteAccess Class Reference

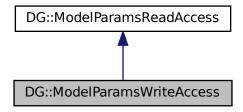
ModelParamsWriteAccess is read/write accessor to model parameters.

```
#include <dg_model_parameters.h>
```

Inheritance diagram for DG::ModelParamsWriteAccess:



Collaboration diagram for DG::ModelParamsWriteAccess:



#### **Public Member Functions**

- · bool is\_dirty () const
  - Check if dirty: at least one of the parameters was changed.
- ModelParamsWriteAccess & merge (const json &config)
- ModelParamsWriteAccess (json &config)
- void set\_dirty (bool state)

#### **Protected Member Functions**

template < typename T >
 ModelParamsWriteAccess & paramSet (const char \*section, const char \*key, const T &value, size\_t idx)

# **Protected Attributes**

- · json & m\_cfg\_rw
  - non-owning reference to Json array with model configuration
- bool m\_dirty

'some parameter was changed' flag

# 6.9.1 Detailed Description

ModelParamsWriteAccess is read/write accessor to model parameters.

This class provides programmatic type-safe read and write access to model parameters defined in Json model configuration. It keeps non-owning non-const reference to underlying Json array. For each model parameter it provides both getter and setter methods. Getter method name matches the parameter name as it appears in Json array. Setter method name is constructed from the parameter name by appending \_set suffix. For example, Input lmgFmt\_set()

### 6.9.2 Constructor & Destructor Documentation

# 6.9.2.1 ModelParamsWriteAccess()

```
\label{eq:decess:ModelParamsWriteAccess:ModelParamsWriteAccess} \mbox{ (} \\ \mbox{json & } config \mbox{ ) [inline]}
```

Constructor. Attaches model parameter read-write accessor to Json array

### **Parameters**

in <i>config</i>	- Json array with model configuration
------------------	---------------------------------------

### 6.9.3 Member Function Documentation

# 6.9.3.1 merge()

Merge given model configuration Json array with self Note: only runtime parameters will be merged

### **Parameters**

```
in config - model configuration Json array to be merged
```

### 6.9.3.2 paramSet()

Set parameter to Json array

### **Template Parameters**

```
T - parameter type
```

#### **Parameters**

in	section	- top section name; if empty, key is placed in topmost level
in	key	- key of key-value pair
in	value	- value to set
in	idx	- array index inside section object

#### 6.9.3.3 set\_dirty()

### Set dirty flag

#### **Parameters**

```
in state - dirty flag value to set
```

The documentation for this class was generated from the following file:

· dg model parameters.h

# 6.10 DG::ModelQuery Struct Reference

Model query structure used to search models on AI server which match a set of provided model attributes.

```
#include <dg_model_api.h>
```

## **Public Types**

enum TriState { Yes, No, Dont\_care }
 Tri-state boolean enum.

### **Public Attributes**

std::string device\_type

device type to use for inference (optional, can be empty if don't care)

• std::string model\_name

any part of the model name (mandatory parameter)

TriState model\_pruned = Dont\_care

model should be pruned/sparse (not dense)

TriState model\_quantized = Dont\_care

model should be quantized

std::string runtime\_agent

runtime agent to use for inference (optional, can be empty if don't care)

### 6.10.1 Detailed Description

Model query structure used to search models on Al server which match a set of provided model attributes.

### 6.10.2 Member Enumeration Documentation

### 6.10.2.1 TriState

enum DG::ModelQuery::TriState

Tri-state boolean enum.

#### Enumerator

Yes	yes / true
No	no / false
Dont_care	not set / don't care

The documentation for this struct was generated from the following file:

• dg\_model\_api.h

# 6.11 DG::BasicTensor::quant\_params\_t Struct Reference

Quantization parameters (how to convert from integer/quantized data back to floating point)

```
#include <dg_tensor_structs.h>
```

#### Classes

· struct scale\_t

#### **Public Member Functions**

- bool isEqualData (const quant\_params\_t &rhs, double maxRelDiff) const
- bool isEqualStruct (const quant\_params\_t &rhs) const
- int quant\_axis () const

Get quantization axis (-1 means global quantization)

• const std::vector< scale\_t > & quant\_params () const

Get quantization parameters.

• quant\_params\_t ()

Default constructor.

- quant\_params\_t (const scale\_t &global\_qparam)
- quant\_params\_t (int axis, const std::vector< scale\_t > &qparams)
- template<typename SCALE\_T, typename ZERO\_T >
   quant\_params\_t (int axis, const std::vector< SCALE\_T > &scales, const std::vector< ZERO\_T > &zeros)

template<typename T >

```
std::vector < T > quant\_scales \ () \ const
```

Get array of scales.

• template<typename T >

```
std::vector< T> quant_zeros () const
```

Get array of zero offsets.

### 6.11.1 Detailed Description

Quantization parameters (how to convert from integer/quantized data back to floating point)

# 6.11.2 Constructor & Destructor Documentation

# 6.11.2.1 quant\_params\_t() [1/3]

Constructor for global quantization

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#### **Parameters**

in	alobal aparam	- global quantization parameters	1
	9.0.00	ground quantiment parameters	1

### 6.11.2.2 quant\_params\_t() [2/3]

Constructor for per-axis quantization

#### **Parameters**

in	axis	- quantization axis
in	qparams	- vector of per-axis quantization parameters

#### 6.11.2.3 quant\_params\_t() [3/3]

Alternative constructor for per-axis quantization

#### **Parameters**

in	axis	- quantization axis
in	scales	- vector of per-axis scales
in	zeros	- vector of per-axis zero offsets

# 6.11.3 Member Function Documentation

# 6.11.3.1 isEqualData()

Check, if this object and given object have equal data contents

#### **Parameters**

in	rhs	- object to compare with
in	maxRelDiff	- maximum relative difference for floating point comparison

#### 6.11.3.2 isEqualStruct()

Check, if this object and given object have equal structure

#### **Parameters**

in <i>rhs</i>
---------------

The documentation for this struct was generated from the following file:

• dg\_tensor\_structs.h

# 6.12 DG::BasicTensor::quant\_params\_t::scale\_t Struct Reference

```
#include <dg_tensor_structs.h>
```

#### **Public Attributes**

double m\_scale scale factorint64\_t m\_zero

zero offset

# 6.12.1 Detailed Description

Single quantization parameter: scale and zero offset Scaling formula is real\_value = m\_scale \* (int\_value - m\_zero)

The documentation for this struct was generated from the following file:

• dg\_tensor\_structs.h

# 6.13 DG::ServerAddress Struct Reference

ServerAddress is the server address structure. It keeps Al server TCP/IP address.

```
#include <dg_client_structs.h>
```

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# **Public Member Functions**

- const bool is\_valid () const
- ServerAddress ()

Default constructor.

ServerAddress (std::string ip, int port=DEFAULT\_PORT)

# **Public Attributes**

```
    std::string ip
server domain name or IP address string
```

int port

server TCP port number

# 6.13.1 Detailed Description

ServerAddress is the server address structure. It keeps AI server TCP/IP address.

#### 6.13.2 Constructor & Destructor Documentation

#### 6.13.2.1 ServerAddress()

#### Constructor

#### **Parameters**

in	ip	- server domain name or IP address	
in	port	- server TCP port	

# 6.13.3 Member Function Documentation

# 6.13.3.1 is\_valid()

```
const bool DG::ServerAddress::is_valid ( ) const [inline]
```

Check server address validity

# Returns

true if server address is valid

The documentation for this struct was generated from the following file:

• dg\_client\_structs.h

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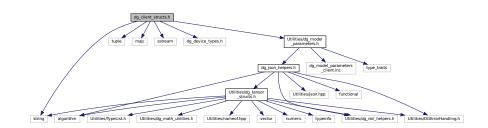
# **Chapter 7**

# **File Documentation**

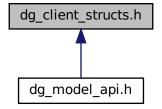
# 7.1 dg\_client\_structs.h File Reference

DG client API data types.

```
#include <string>
#include <tuple>
#include <map>
#include <sstream>
#include "dg_device_types.h"
#include "Utilities/dg_model_parameters.h"
Include dependency graph for dg_client_structs.h:
```



This graph shows which files directly or indirectly include this file:



#### **Classes**

struct DG::ModelInfo

ModelInfo is the model identification structure. It keeps AI model key attributes.

struct DG::ServerAddress

ServerAddress is the server address structure. It keeps AI server TCP/IP address.

# **Namespaces**

• DG

DG is DeGirum namespace which groups all DeGirum software declarations.

# **Typedefs**

typedef struct DG::ModelInfo DG::ModelInfo

ModelInfo is the model identification structure. It keeps Al model key attributes.

• typedef struct DG::ServerAddress DG::ServerAddress

ServerAddress is the server address structure. It keeps AI server TCP/IP address.

#### **Enumerations**

```
    enum DG::RUNTIME_AGENT_TYPES {
        DG::RUNTIME_AGENT_TYPES::DEFAULT, DG::RUNTIME_AGENT_TYPES::N2X, DG::RUNTIME_AGENT_TYPES::TFLITE
        DG::RUNTIME_AGENT_TYPES::ONNX,
        DG::RUNTIME_AGENT_TYPES::OPENVINO, DG::RUNTIME_AGENT_TYPES::DUMMY }
        Runtime agent types.
```

#### **Functions**

- static std::string DG::messagePrepare (const json &in)
- static json DG::messagePrepareJson (const json &in)
- bool DG::operator< (const ServerAddress &lhs, const ServerAddress &rhs)

Comparison operator for server address.

• bool DG::operator== (const ServerAddress &lhs, const ServerAddress &rhs)

Comparison operator for server address.

#### **Variables**

```
• const int DG::CURRENT_PROTOCOL_VERSION = 4
```

current client-server protocol version

const int DG::DEFAULT CONNECTION TIMEOUT MS = 10000

Default connection timeout, ms.

• const int DG::DEFAULT\_FRAME\_QUEUE\_DEPTH = 8

Default frame queue depth.

const int DG::DEFAULT\_INFERENCE\_TIMEOUT\_MS = 180000

Default inference timeout, ms.

const int DG::DEFAULT\_PORT = 8778

Default TCP port of AI server.

const int DG::MIN COMPATIBLE PROTOCOL VERSION = 4

minimum compatible client-server protocol version

constexpr const char \* DG::PROTOCOL VERSION TAG = "VERSION"

client-server protocol version tag

# 7.1.1 Detailed Description

DG client API data types.

This file contains declarations of various data types of DG client API:

- · device types
- · runtime agent types
- · model parameters, etc.

# 7.2 dg\_json\_helpers.h File Reference

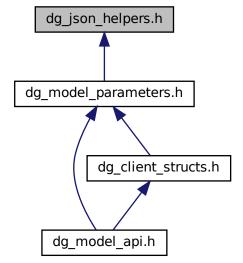
DG Core JSON helper classes and functions.

```
#include "Utilities/DGErrorHandling.h"
#include "Utilities/dg_tensor_structs.h"
#include "Utilities/dg_raii_helpers.h"
#include "Utilities/json.hpp"
#include <functional>
#include <algorithm>
```

Include dependency graph for dg\_json\_helpers.h:



This graph shows which files directly or indirectly include this file:



#### **Classes**

class DG::JsonHelper

Json helper class: contains assorted static methods to operate with Json configurations.

#### **Namespaces**

• DG

DG is DeGirum namespace which groups all DeGirum software declarations.

#### **Macros**

#define DG\_JSON\_PARSE(json\_cfg) DG::JsonHelper::parse( json\_cfg, \_\_FILE\_\_, TOSTRING(\_\_LINE\_\_), FUNCTION\_NAME )

Parse given Json string with proper exception handling.

# **Typedefs**

using DG::json = nlohmann::json
 Json library.

# **Functions**

- template<typename T >
   T DG::jsonGetOptionalValue (const json &json\_params, const std::string &section, int index, const std::string &key, const T &default value)
- static bool DG::jsonKeyExist (const json &json\_params, const std::string &section, int index, const std::string &key)
- template<typename T >
   void DG::jsonSetOptionalValue (json &json\_params, const std::string &section, int index, const std::string &key, const T &value)

# 7.2.1 Detailed Description

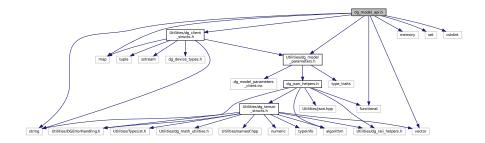
DG Core JSON helper classes and functions.

This file contains declaration of various helper classes and helper functions enhancing Json handling

# 7.3 dg\_model\_api.h File Reference

DG Client API for model inference.

```
#include <string>
#include <memory>
#include <vector>
#include <set>
#include <map>
#include <functional>
#include <cstdint>
#include "Utilities/dg_client_structs.h"
#include "Utilities/dg_model_parameters.h"
Include dependency graph for dg_model_api.h:
```



#### **Classes**

• class DG::AlModel

AlModel is DeGirum Al client API class for simple non-pipelined sequential inference.

· class DG::AlModelAsync

AlModelAsync is DeGirum Al client API class for efficient pipelined asynchronous inference.

struct DG::ModelQuery

Model query structure used to search models on AI server which match a set of provided model attributes.

# **Namespaces**

• DG

DG is DeGirum namespace which groups all DeGirum software declarations.

#### **Enumerations**

• enum DG::DetectionStatus { DG::DetectionStatus::OK, DG::DetectionStatus::ProtocolMismatch, DG::DetectionStatus::HostAliv

Enumerator showing server status as detected by the below function.

#### **Functions**

- std::vector< std::tuple< std::string, DG::DetectionStatus >> DG::detectHostnameServers (const std::string &prefix, const int range\_start, const int range\_end, const int numeral\_width=3)
- std::vector < std::tuple < std::string, DetectionStatus > > DG::detectSubnetServers (const std::string &root ← \_ip, const std::string &subnet\_mask)
- std::string DG::errorCheck (const json &json\_response)
- json DG::labelDictionary (const std::string &server, const std::string &model name)
- ModelInfo DG::modelFind (const std::string &server, const ModelQuery &query)
- void DG::modelzooListGet (const std::string &server, std::vector< ModelInfo > &modelzoo\_list)
- json DG::modelZooManage (const std::string &server, const json &req)
- bool DG::serverPing (const std::string &server)
- void DG::shutdown (const std::string &server)
- json DG::systemInfo (const std::string &server)
- json DG::traceManage (const std::string &server, const json &req)
- std::string DG::versionGet ()

# 7.3.1 Detailed Description

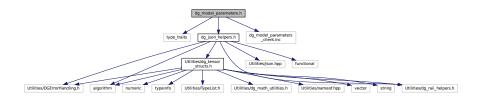
DG Client API for model inference.

This file contains declaration of DG Client API functions and classes for model inference

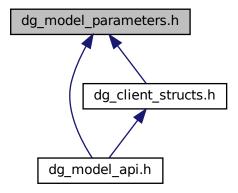
# 7.4 dg\_model\_parameters.h File Reference

DG centralized handling of Json model parameters.

```
#include <type_traits>
#include "dg_json_helpers.h"
#include "dg_model_parameters_client.inc"
Include dependency graph for dg model parameters.h:
```



This graph shows which files directly or indirectly include this file:



#### **Classes**

class DG::ModelParams< Base, >

ModelParams is model parameters collection with user-defined access rights.

class DG::ModelParamsReadAccess

ModelParamsReadAccess is read-only accessor to model parameters.

• struct DG::ModelParamsSection

Model parameters section descriptor.

• class DG::ModelParamsWriteAccess

ModelParamsWriteAccess is read/write accessor to model parameters.

#### **Namespaces**

• DG

DG is DeGirum namespace which groups all DeGirum software declarations.

# **Typedefs**

• using DG::ModelParamsWriter = ModelParams< ModelParamsWriteAccess > ModelParamsWriter is ModelParams template instantiation with write access.

# **Variables**

- const int DG::MODEL PARAMS CURRENT VERSION = 8
- const int DG::MODEL\_PARAMS\_MIN\_COMPATIBLE\_VERSION = 1
- constexpr ModelParamsSection DG::SECT\_DEVICE = { "DEVICE", true } device parameters section
- constexpr ModelParamsSection DG::SECT\_INTERNAL = { "INTERNAL", true }
  internal parameters section

```
    constexpr ModelParamsSection DG::SECT_MODEL_PARAMETERS = { "MODEL_PARAMETERS", true }
    model parameters section
```

```
    constexpr ModelParamsSection DG::SECT_POST_PROCESS = { "POST_PROCESS", true }
    post-processing parameters section
```

```
    constexpr ModelParamsSection DG::SECT_PRE_PROCESS = { "PRE_PROCESS", false }
    pre-processing parameters section
```

```
    constexpr ModelParamsSection DG::SECT_TOP = { "", true }
    Json file top-level sections.
```

### 7.4.1 Detailed Description

DG centralized handling of Json model parameters.

This file implements classes for centralized handling of Json model parameters. Each AI model in DG framework is accompanied with Json configuration file, which defines all model configuration parameters. Class list: Model ← ParamsReadAccess - read-only model parameters accessor ModelParamsWriteAccess - read/write model parameters accessor ModelParams - model parameters collection with access type defined by the template parameter

# 7.5 dg\_tensor\_structs.h File Reference

DG tensor container classes.

```
#include <vector>
#include <string>
#include <algorithm>
#include <numeric>
#include <typeinfo>
#include "Utilities/DGErrorHandling.h"
#include "Utilities/TypeList.h"
#include "Utilities/dg_math_utilities.h"
#include "Utilities/dg_raii_helpers.h"
#include "Utilities/nameof.hpp"
Include dependency graph for dg_tensor_structs.h:
```



This graph shows which files directly or indirectly include this file:



# **Classes**

- class DG::BasicTensor
- struct DG::BasicTensor::quant\_params\_t

Quantization parameters (how to convert from integer/quantized data back to floating point)

• struct DG::BasicTensor::quant\_params\_t::scale\_t

# **Namespaces**

• DG

DG is DeGirum namespace which groups all DeGirum software declarations.

# **Typedefs**

using DG::BasicTensorVector = std::vector < BasicTensor >
 Collection of tensors.

# **Functions**

std::ostream & DG::operator<< (std::ostream &os, const BasicTensor &t)</li>
 Print tensor to stream.

# 7.5.1 Detailed Description

DG tensor container classes.

This file contains declaration of tensor container classes

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