

# A4-QA

## Q1

- $G_0 = 4$
- $G_1 = 6$
- $G_2 = 8$
- $G_3 = 4$
- $G_4 = 2$
- $G_5 = 0$

## Q2

1

$$\begin{aligned} V_{\pi}(s) &= E_{\pi} [r_{t+1} + \gamma r_{t+2} + \gamma^2 r_{t+3} \dots | s_t = s] \\ &= E_{a \sim \pi(s, \cdot)} [E_{\pi} [r_{t+1} + \gamma r_{t+2} \dots | s_t = s, A_t = a]] \\ &= \sum_{a \in A} \pi(s, a) \times \vartheta_{\pi}(s, a) \\ &= \sum_{a \in A} \pi(s, a) \vartheta_{\pi}(s, a) \end{aligned}$$
$$\begin{aligned} \vartheta_{\pi}(s, a) &= E_{\pi} [r_{t+1} + \gamma r_{t+2} \dots | s_t = s, A_t = a] \\ &= E_{s' \sim P(\cdot | s, a)} [r(s, a, s') + \gamma E_{\pi} [r_{t+2} + \gamma r_{t+3} \dots | s_{t+1} = s']] \\ &= \sum_{s' \in S} P(s' | s, a) [r(s, a, s') + \gamma \times V_{\pi}(s')] \end{aligned}$$

2

$$\begin{aligned} V_{\pi}(s) &= E[r_{t+1} + \gamma V_{\pi}(s') | s_t = s] \\ &= \sum_{a \in A} \pi(s, a) \sum_{s' \in S} P(s' | s, a) [r(s, a, s') + \gamma V_{\pi}(s')] \\ &= E_{a \sim \pi(s, \cdot)} E_{s' \sim P(\cdot | s, a)} [r(s, a, s') + \gamma V_{\pi}(s')] \\ \vartheta_{\pi}(s) &= E_{\pi} [r_{t+1} + \gamma \vartheta_{\pi}(s', a') | s_t = s, A_t = a] \\ &= \sum_{s' \in S} P(s' | s, a) [r(s, a, s') + \gamma \sum_{a' \in A} \pi(s', a') \vartheta_{\pi}(s', a')] \\ &= E_{s' \sim P(\cdot | s, a)} [r(s, a, s') + \gamma E_{a' \sim \pi(s', \cdot)} [\vartheta_{\pi}(s', a')]] \end{aligned}$$

### Q3

1

$$\begin{aligned}
 V_1 &= \frac{1}{4}(0+rV_3) + \frac{1}{4}(0+rV_2) + \frac{1}{4}(-1+0) + \frac{1}{4}(-1+0) = \frac{r}{4}(V_2+V_3) - \frac{1}{2} \\
 V_2 &= \frac{1}{4}(1+0) + \frac{1}{4}(-1+0) + \frac{1}{4}(-1+0) + \frac{1}{4}(0+V_1) = -\frac{1}{4} + \frac{r}{4}V_1 \\
 V_3 &= -\frac{1}{4} + \frac{r}{4}V_1
 \end{aligned}$$

解得  $\begin{cases} V_1 = \frac{0.7108}{\cancel{0.426}} \\ V_2 = V_3 = \frac{-0.426}{\cancel{0.426}} \end{cases}$

2

$$\begin{aligned}
 f_{\pi}(s_2, \text{向右}) &= 1+r \cdot 0 = 1 \\
 f_{\pi}(s_3, \text{向下}) &= 0+r \cdot V_1 \approx -0.7038 \\
 f_{\pi}(s_3, \text{向左/向上}) &= -1+r \cdot 0 = -1 \\
 \therefore \text{最优为向右. } \pi'(s_3) &= \text{向右.}
 \end{aligned}$$

假设轨迹  $s_1 \xrightarrow{\uparrow} s_3 \xrightarrow{\rightarrow} s_4$

$Q(s_1, \uparrow) = 0.1 \quad r = 0$

$\max_a Q(s_3, a) = 0.1$

TD目标  $y = 0 + 0.1 \times 0.1 = 0.01$

TD误差  $\delta = -0.09$

新值  $Q(s_1, \uparrow) = 0.1 + 0.5 \times (-0.09) = 0.055$

同理更新  $s_3$

$Q(s_3, \rightarrow) = 0 + 0.5 \times 1 = 0.5$

$Q(s_1, \uparrow) = 0.055 \quad Q(s_1, \rightarrow) = 0$

$Q(s_3, \uparrow) = 0.1 \quad Q(s_3, \rightarrow) = 0.5$

最后策略为  $s_1$  时向上,  $s_3$  时向右