

# 人工智能

第7讲:深度学习Ⅱ

卷积神经网络、自注意力机制与模型训练策略

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#### 2025年春季

● 参考资料: 吴飞,《人工智能导论:模型与算法》,高等教育出版社

● 在线课程: <a href="https://www.icourse163.org/course/ZJU-1003377027?from=searchPage">https://www.icourse163.org/course/ZJU-1003377027?from=searchPage</a>

● 本部分参考: 李宏毅, 《机器学习》课程, 台湾大学

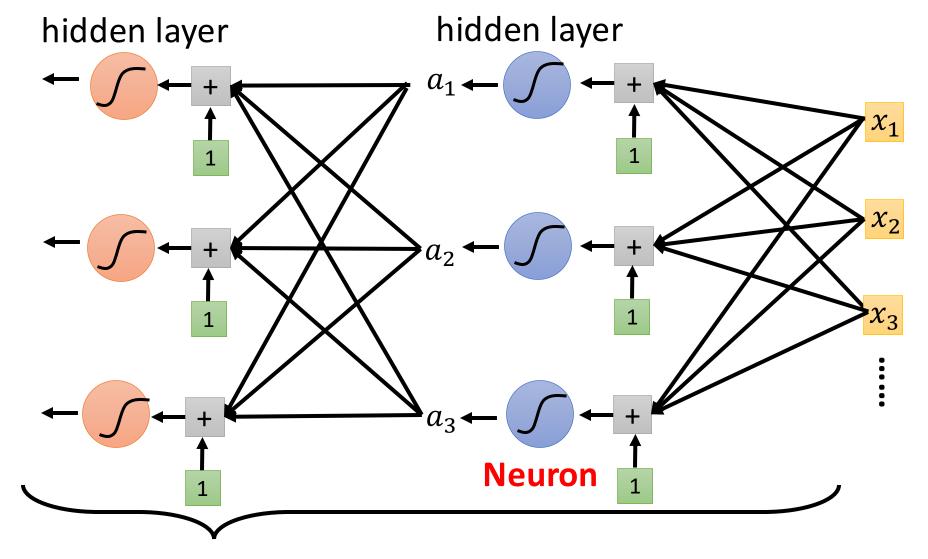


- 一、线性回归与梯度下降
- 二、前馈神经网络
- 三、卷积神经网络
- 四、序列数据模型
- 五、深度学习应用



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神经网络 Neural Network

Many layers means **Deep 一**深度学习Deep Learning



#### 前馈神经网络

- 输入层、输出层和至少一层的隐藏层构成。网络中各个隐藏层中神经元可接收相邻前序隐藏层中所有神经元传递而来的信息,经过加工处理后将信息输出给相邻后续隐藏层中所有神经元。
- 各个神经元接受前一级的输入,并输出到下一级,模型中没有反馈
- 层与层之间通过"全连接"进行链接,即两个相邻层之间的神经元完全成对连接,但层内的神经元不相互连接。
- 也被称为全连接网络,或多层感知机。



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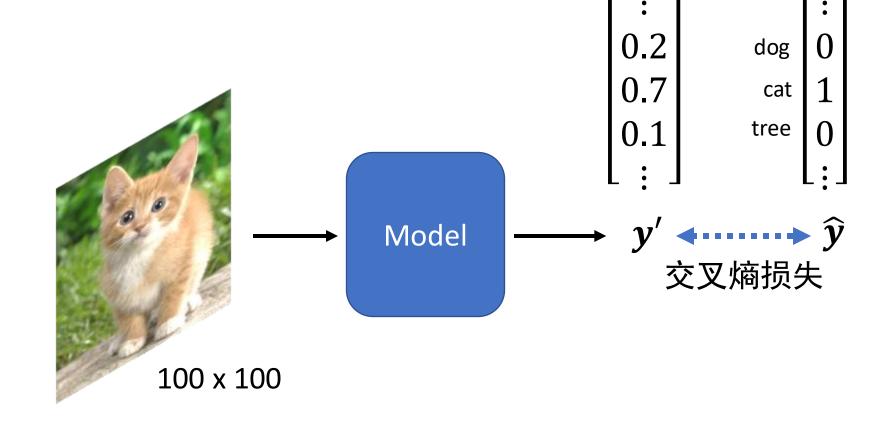


# Convolutional Neural Networks 卷积神经网络

Network architecture designed for image



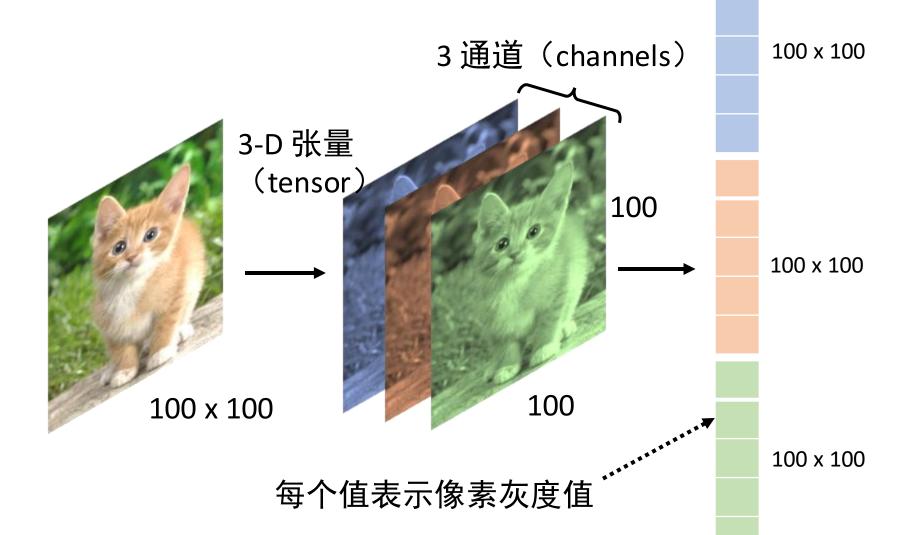
# 图像分类



(待分类图像具有相同尺寸)



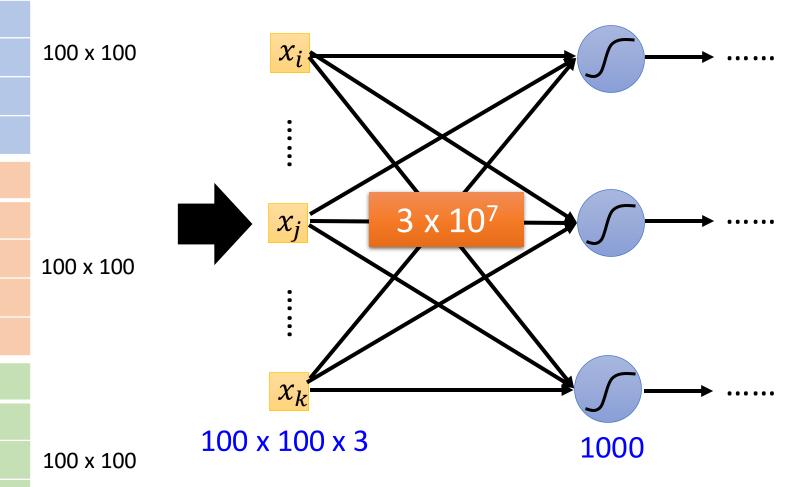
# 图像分类



假设输入图像大小为3 x 100 x 100, 分类类别数为1000个, 如果用一层全连接网络实现分类,需要多少参数? [填空1]



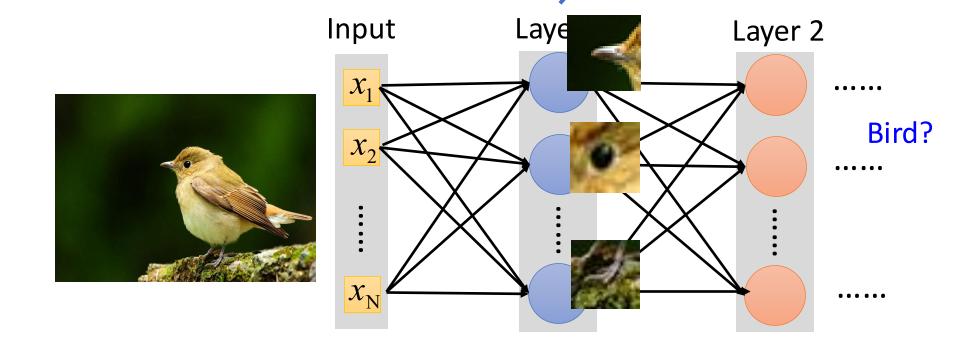
#### 全连接网络



是否需要全连接网络来处理图像?



根据特定的模式(pattern)进行识别

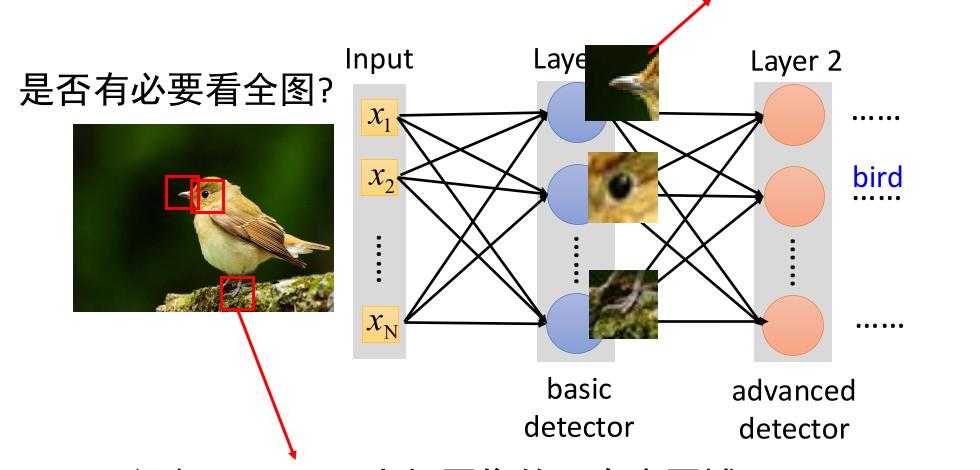


人也许用的是同样的方式实现鸟的识别… ②



### 观察1

#### 每个神经元无需覆盖整个图像.

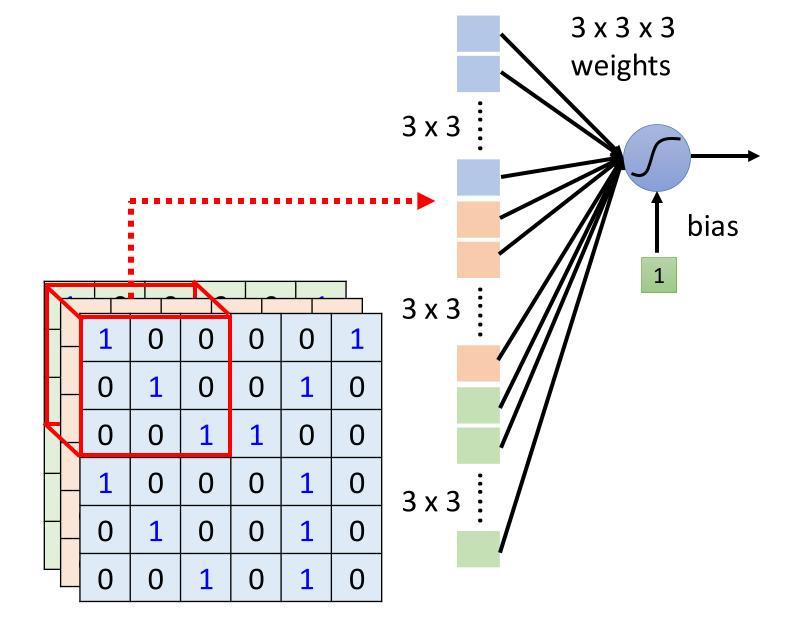


很多patterns只占据图像的一个小区域.



# 简化1

Receptive field 感受野

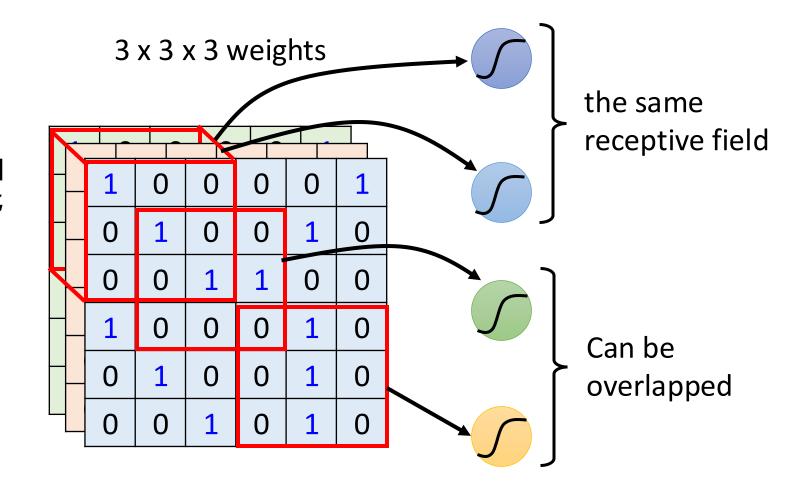




## 简化1

- 不同神经元覆盖不同感受野大小?
- 只覆盖部分通道?
- 非正方形感受野?

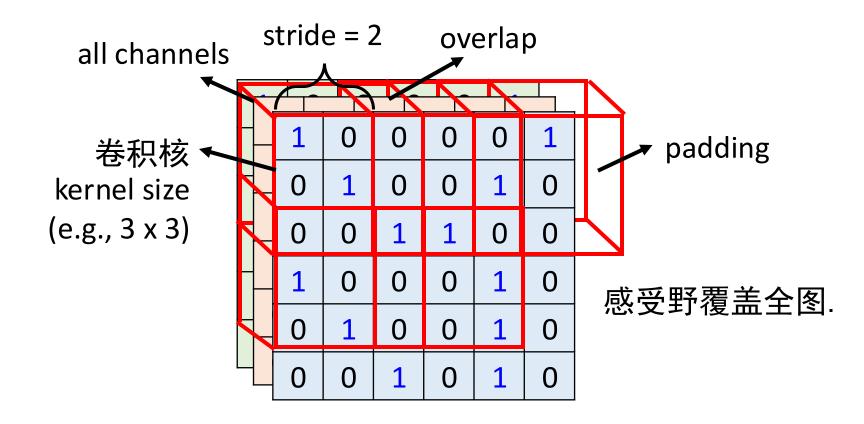
Receptive field 感受野





### 简化1-典型设置

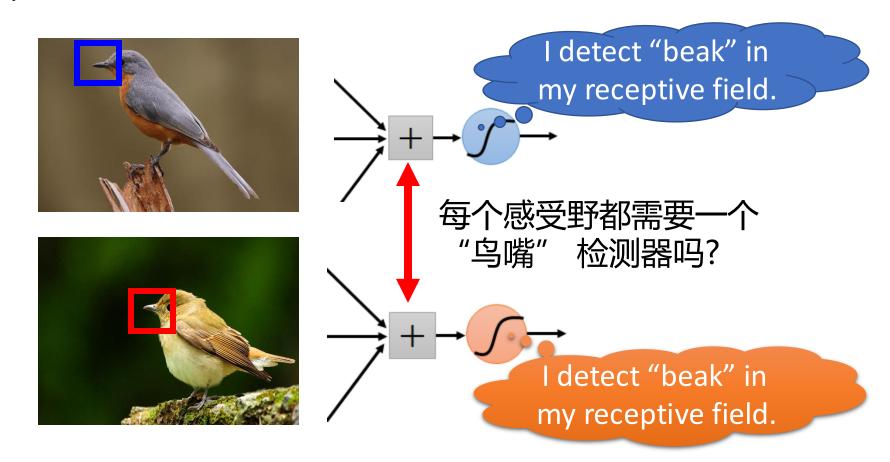
每个感受野覆盖一组神经元 (e.g., 64 neurons).





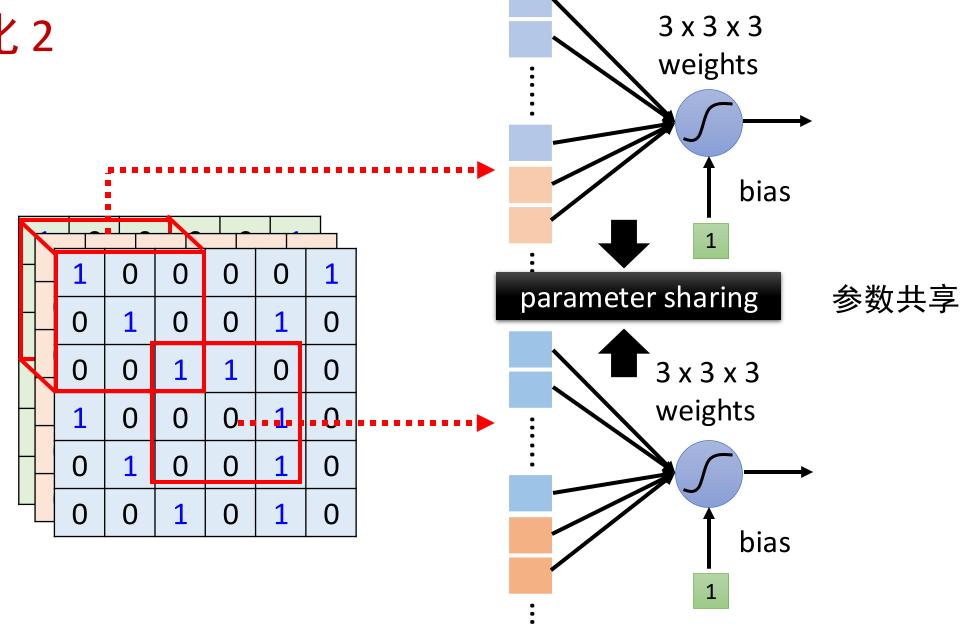
## 观察 2

• 同一pattern可能出现在不同图像的不同区域



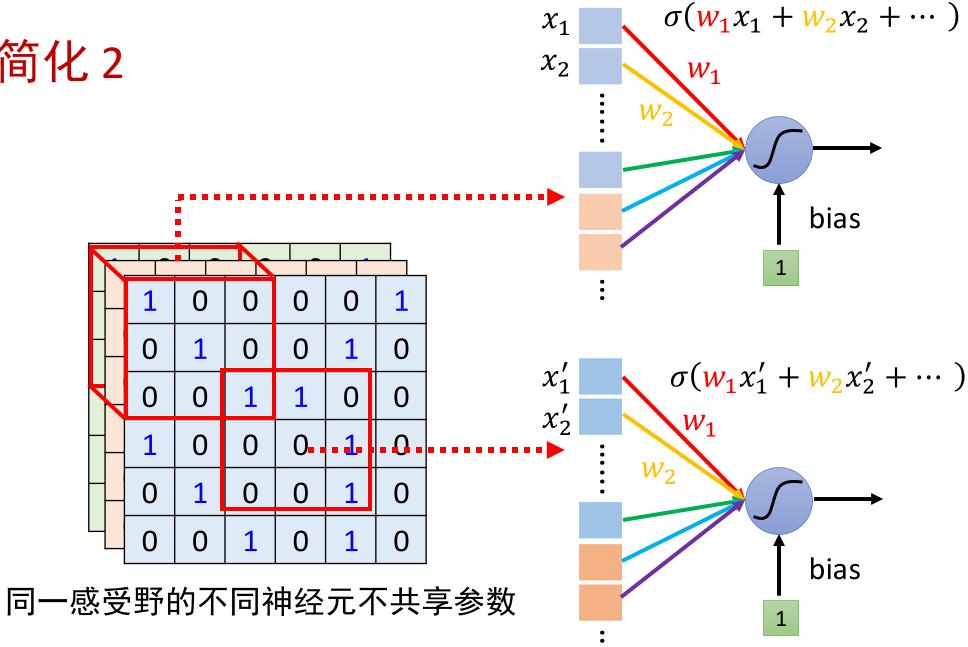


# 简化 2





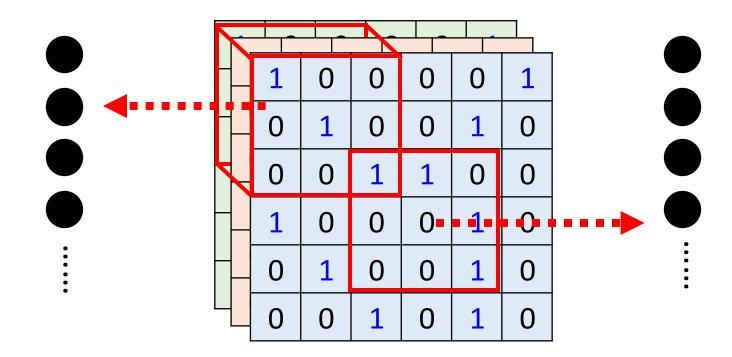
## 简化 2





## 简化2-典型设置

每个感受野有多个神经元 (e.g., 64 个神经元).

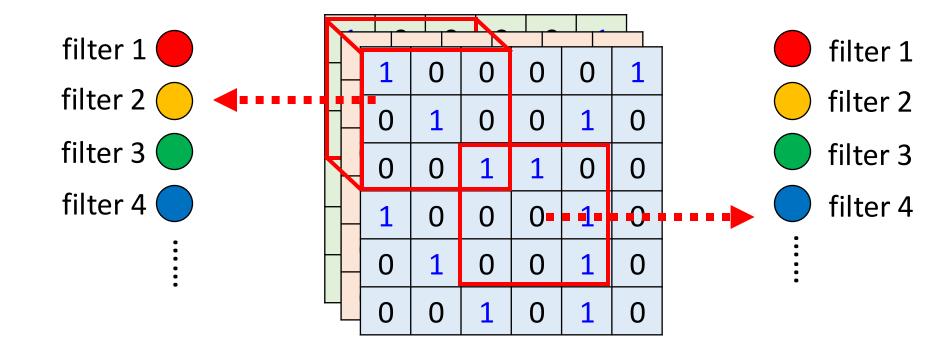




#### 简化2-典型设置

每个感受野有多个神经元 (e.g., 64 个神经元).

不同感受野的神经元共享参数(filter,滤波器)

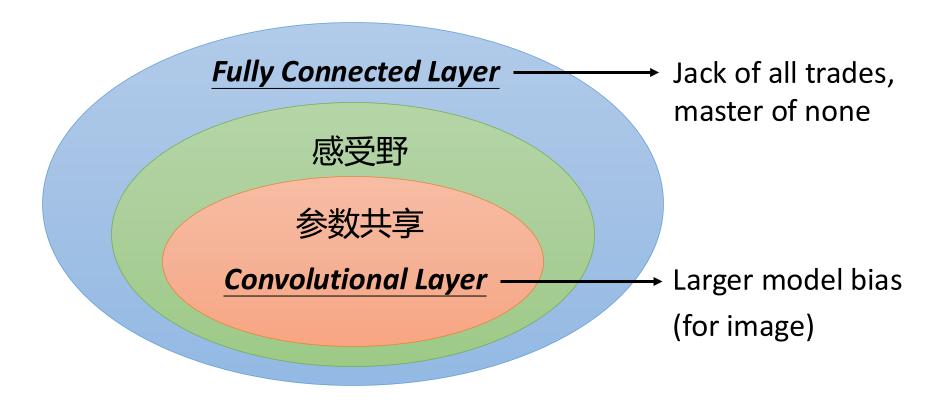


请思考,一层卷积神经网络的参数与哪些因素有关? [填空1]

请思考,卷积神经网络与全连接网络相比,参数量有什么变化?为什么卷积神经网络优于全连接网络?



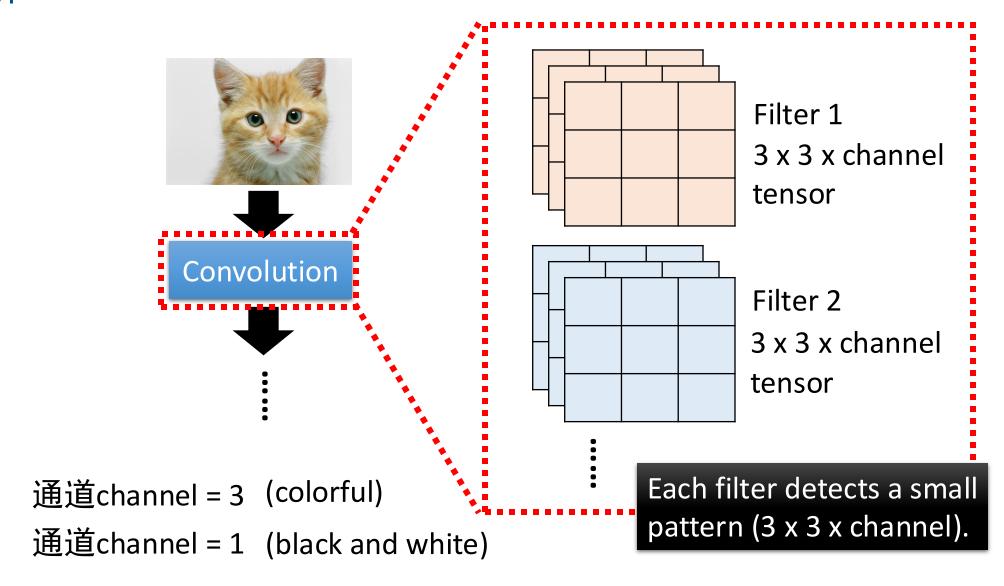
#### 卷积层的优势



- 通常pattern会远小于整图大小
- 同样的pattern会出现在图上不同区域



#### Another story based on *filter* ©





#### Consider channel = 1 (假设黑白图)

| 1 | 0 | 0 | 0 | 0 | 1 |
|---|---|---|---|---|---|
| 0 | 1 | 0 | 0 | 1 | 0 |
| 0 | 0 | 1 | 1 | 0 | 0 |
| 1 | 0 | 0 | 0 | 1 | 0 |
| 0 | 1 | 0 | 0 | 1 | 0 |
| 0 | 0 | 1 | 0 | 1 | 0 |

| 1  | -1 | -1 |
|----|----|----|
| -1 | 1  | -1 |
| -1 | -1 | 1  |

Filter 1

| -1 | 1 | -1 |
|----|---|----|
| -1 | 1 | -1 |
| -1 | 1 | -1 |

Filter 2

6 x 6 image

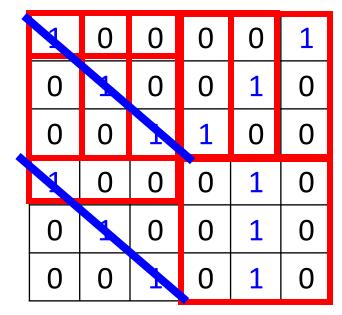
(filters 中的数值即为待学习的未知参数)



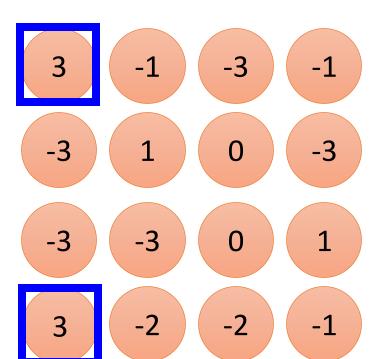
# 1 -1 -1 -1 1 -1 -1 -1 1

Filter 1

#### stride=1



6 x 6 image





# -1 1 -1 -1 1 -1 -1 1 -1 -1 1 -1

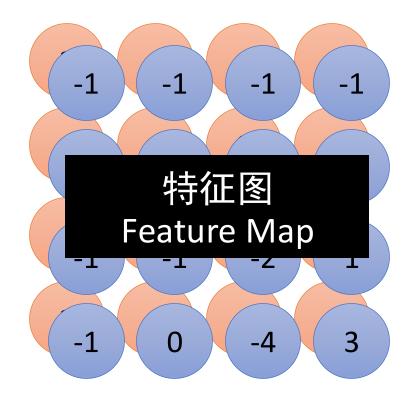
Filter 2

#### stride=1

| 1 | 0 | 0 | 0 | 0 | 1 |
|---|---|---|---|---|---|
| 0 | 1 | 0 | 0 | 1 | 0 |
| 0 | 0 | 1 | 1 | 0 | 0 |
| 1 | 0 | 0 | 0 | 1 | 0 |
|   |   |   |   |   |   |
| 0 | 1 | 0 | 0 | 1 | 0 |

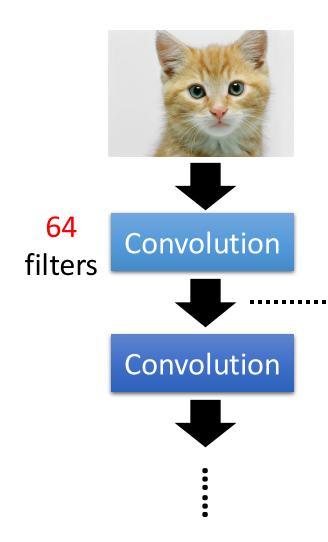
6 x 6 image

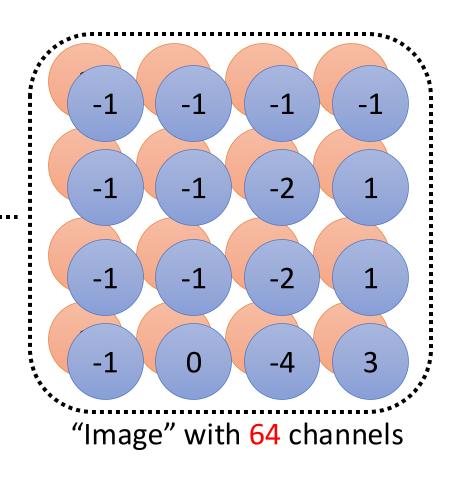
#### 对每个filter重复此过程



请思考,如果想捕捉图像中较大感受野的pattern,比如鸟嘴,3x3大小的卷积核是否足够?为什么?

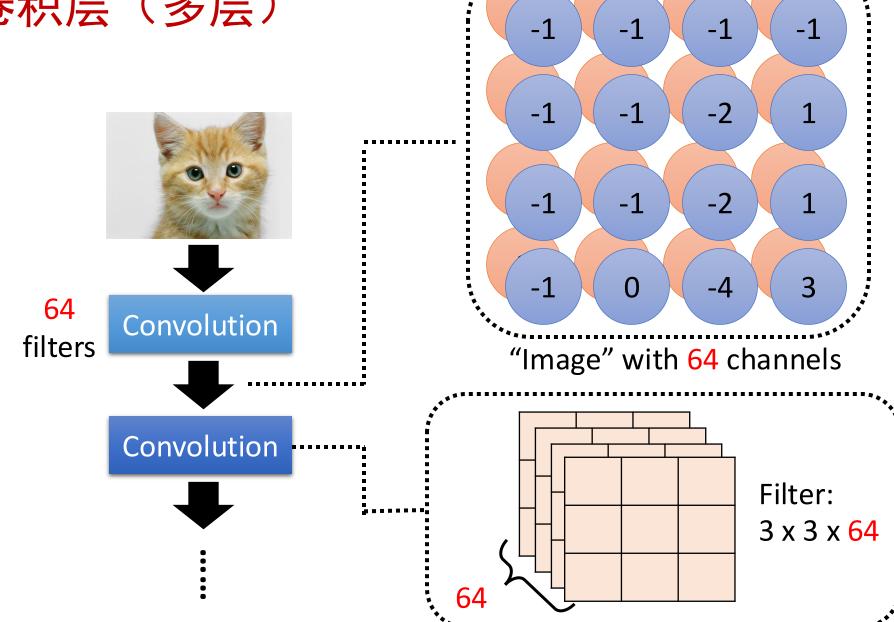






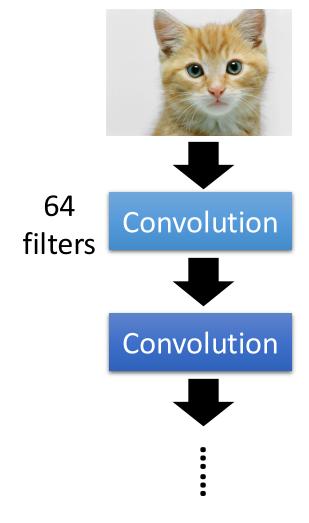


## 卷积层(多层)

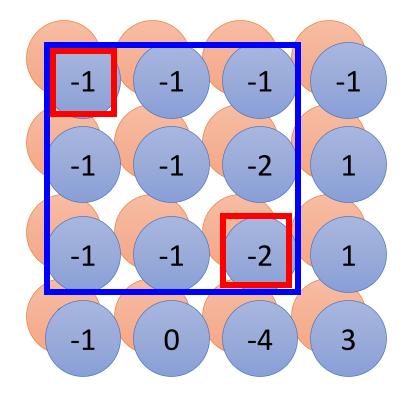




# 卷积层(多层)



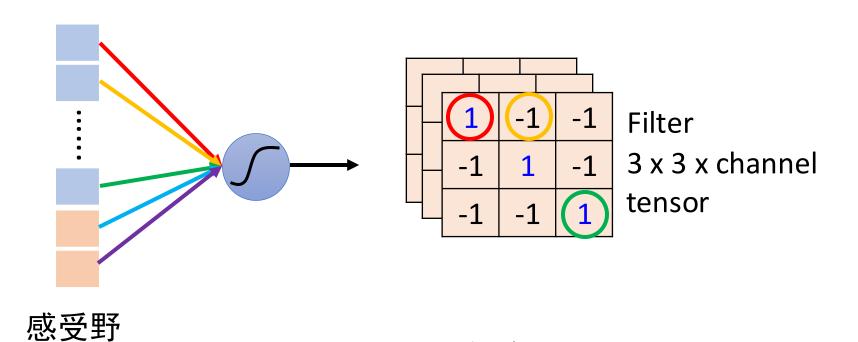
| 1 | 0 | 0 | 0 | 0 | 1 |
|---|---|---|---|---|---|
| 0 | 1 | 0 | 0 | 1 | 0 |
| 0 | 0 | 1 | 1 | 0 | 0 |
| 1 | 0 | 0 | 0 | 1 | 0 |
|   |   |   |   | _ |   |
| 0 | 1 | 0 | 0 | 1 | 0 |





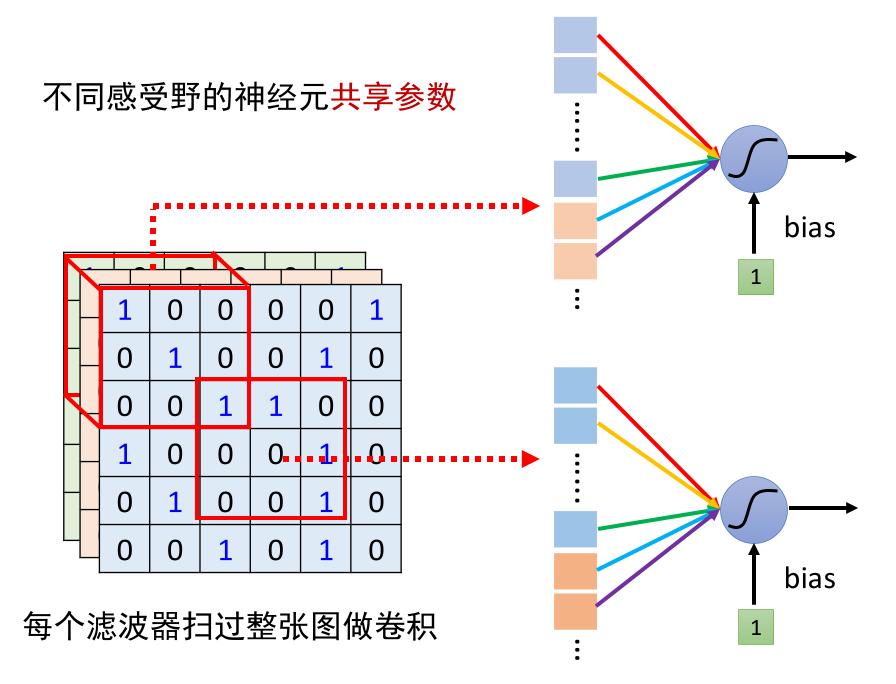
## 两种解释的对比

(Receptive field)



(忽略bias项)







| Neuron Version Story | Filter Version Story   |
|----------------------|------------------------|
| 每个神经元只考虑一个感受野.       | 一系列的滤波器检测小的图案(pattern) |
| 不同感受野的神经元共享参数        | 每个滤波器以卷积的形式扫过整张图       |

They are the same story.



• 对像素降采样不影响物体类别语义





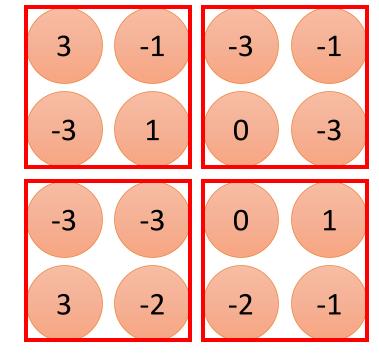
# 池化-最大池化

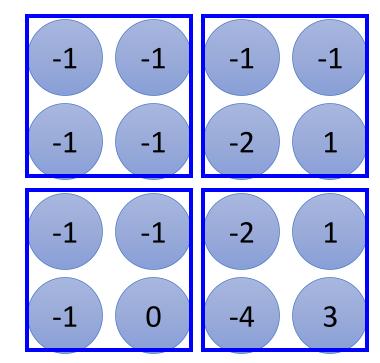
| 1  | -1 | -1 |
|----|----|----|
| -1 | 1  | -1 |
| -1 | -1 | 1  |

Filter 1

| -1 | 1 | -1 |
|----|---|----|
| -1 | 1 | -1 |
| -1 | 1 | -1 |

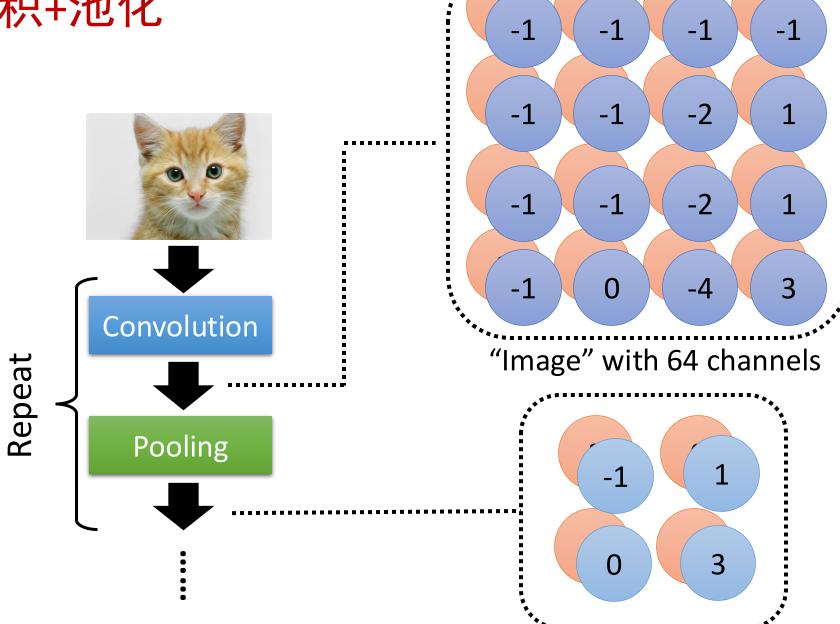
Filter 2





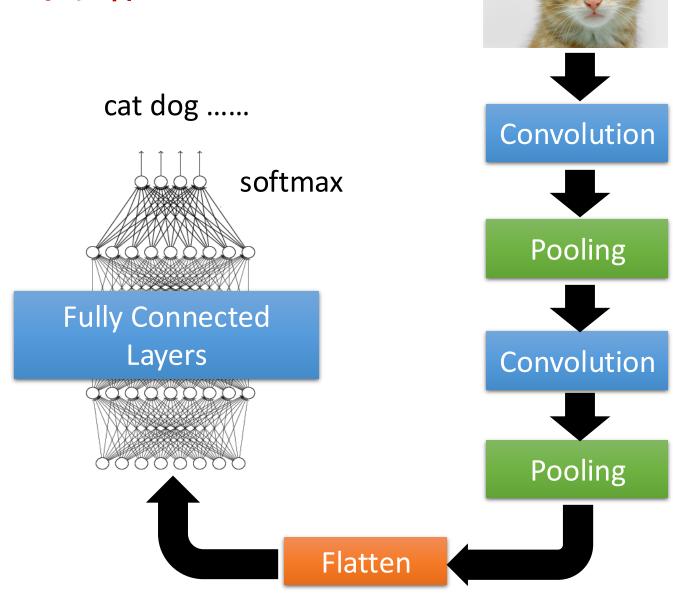


# 卷积+池化





# 卷积神经网络





# 问题和不足

• CNN中的卷积操作不满足尺度和旋转不变性 (需要数据增广◎)





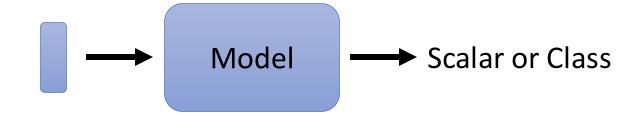


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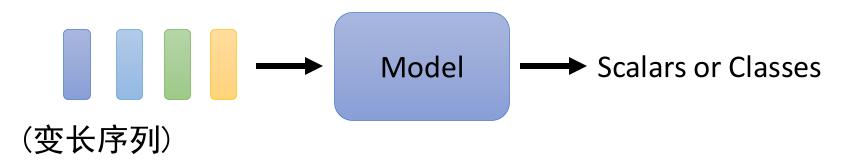


## 复杂输入数据

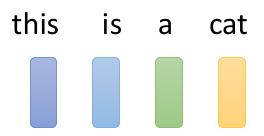
• 向量输入(vector input)



• 向量集输入(vector set input)







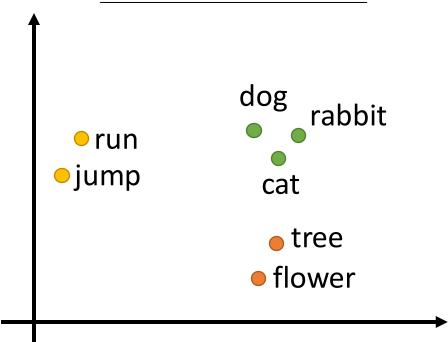
#### **One-hot Encoding**

cat = 
$$[0 \ 0 \ 1 \ 0 \ 0 \dots]$$

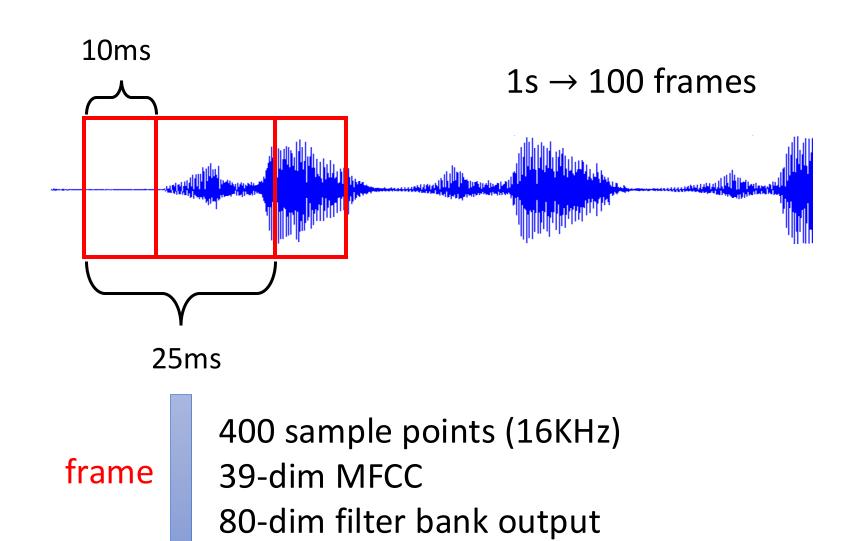
$$dog = [0 \ 0 \ 0 \ 1 \ 0 \dots]$$

elephant = 
$$[0 \ 0 \ 0 \ 1 \dots]$$

#### Word Embedding

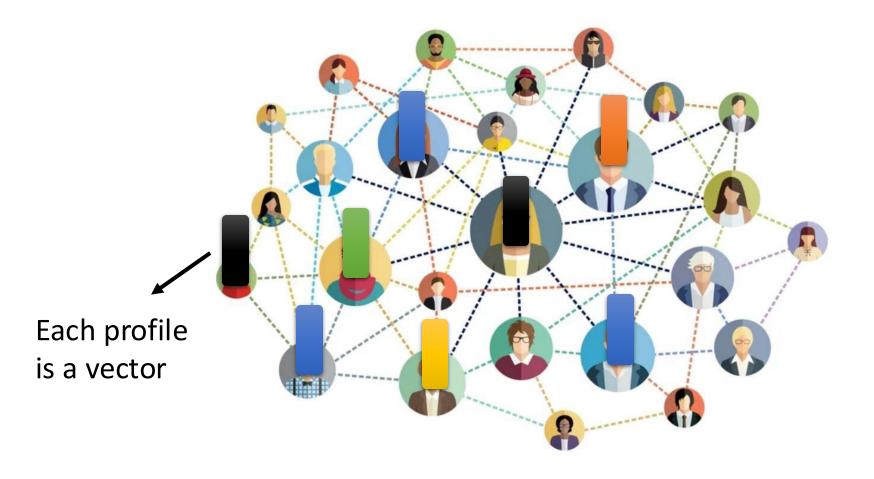








• 图数据(Graph)也可以看做向量集 (每个结点看做一个向量)



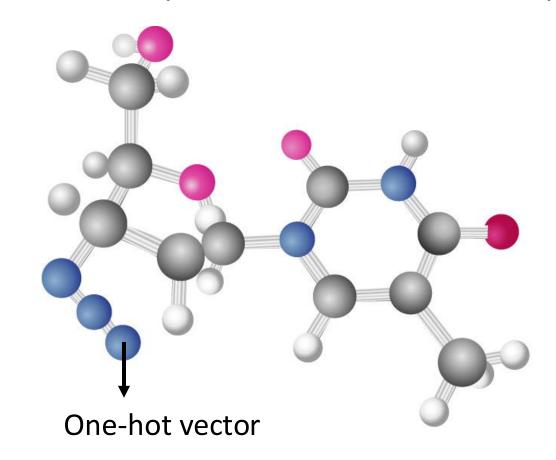


• 图数据(Graph)也可以看做向量集 (每个结点看做一个向量)

$$H = [1 \ 0 \ 0 \ 0 \ \dots]$$

$$C = [0 \ 1 \ 0 \ 0 \ 0 \dots]$$

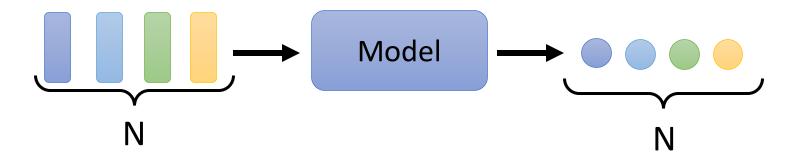
$$O = [0 \ 0 \ 1 \ 0 \ 0 \dots]$$



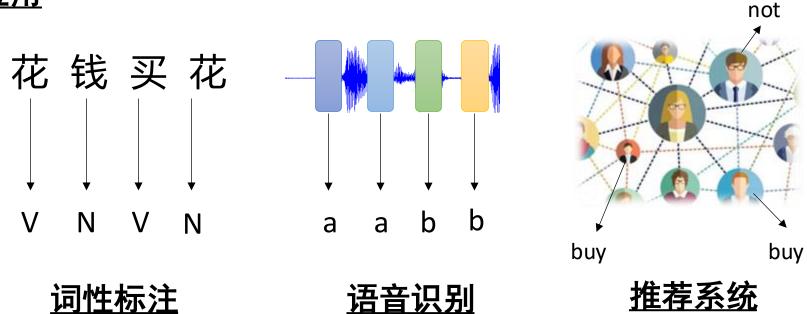


## <u>输出形式</u>

• 一对一输出









## <u>输出形式</u>

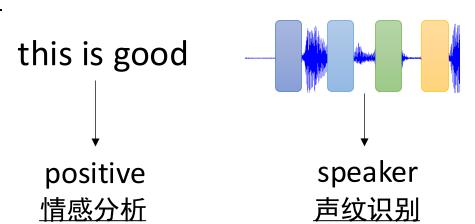
• 一对一输出

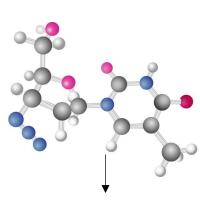


• 多对一输出



#### 应用





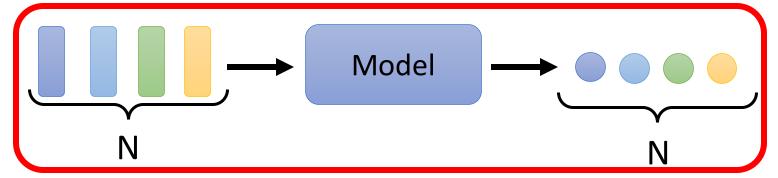
hydrophilicity 分子性质识别



### <u>输出形式</u>

• 一对一输出

Focus on this first!



• 多对一输出



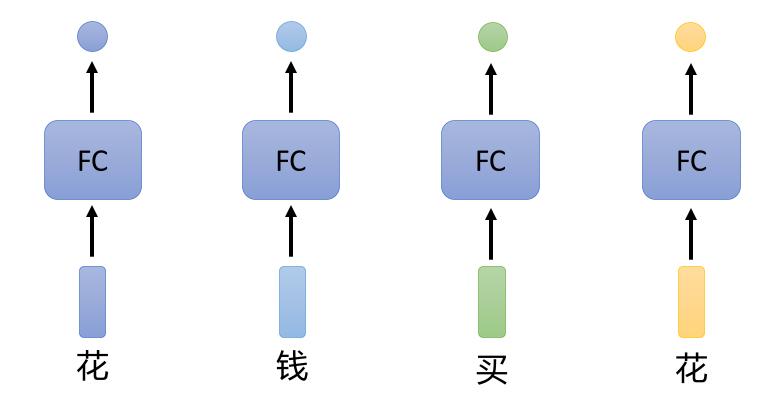
• 多对多输出 seq2seq



请思考,给定向量集输入,如何建模上下文信息

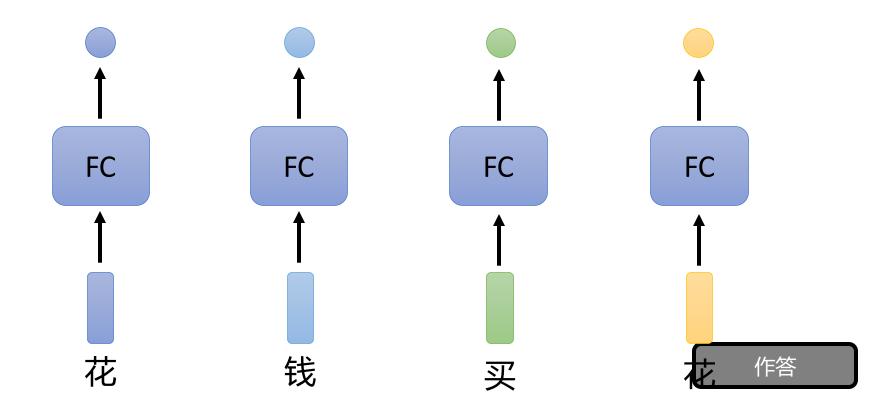


FC Fully-connected



#### 如何考虑上下文信息?

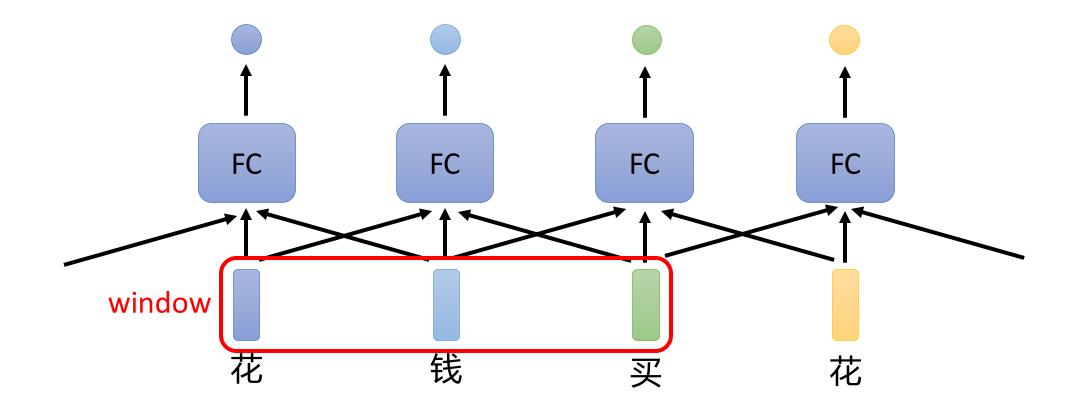
FC Fully-connected





- 如何考虑上下文信息?
  - FC 可以考虑邻域信息
- 如何考虑整个序列的上下文信息?
  - 覆盖整个序列的窗口?

Fully-connected

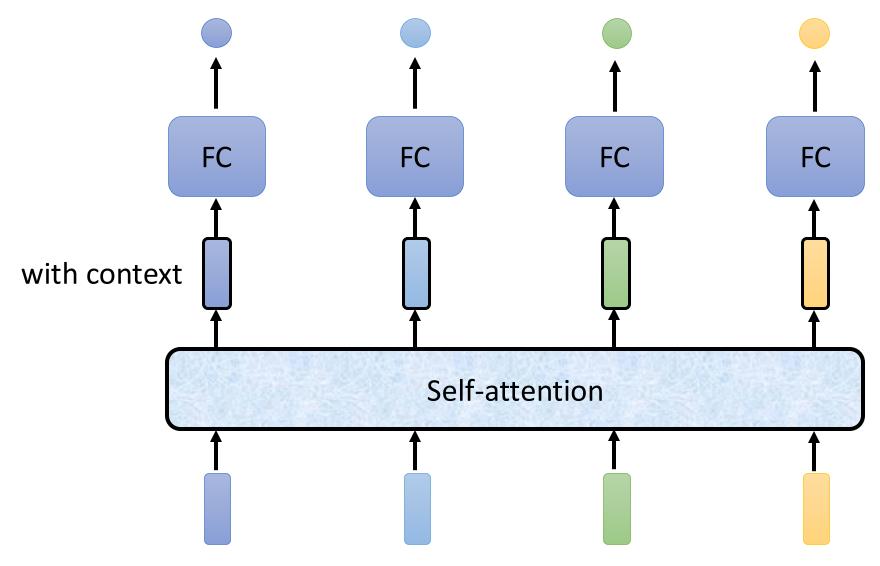


FC

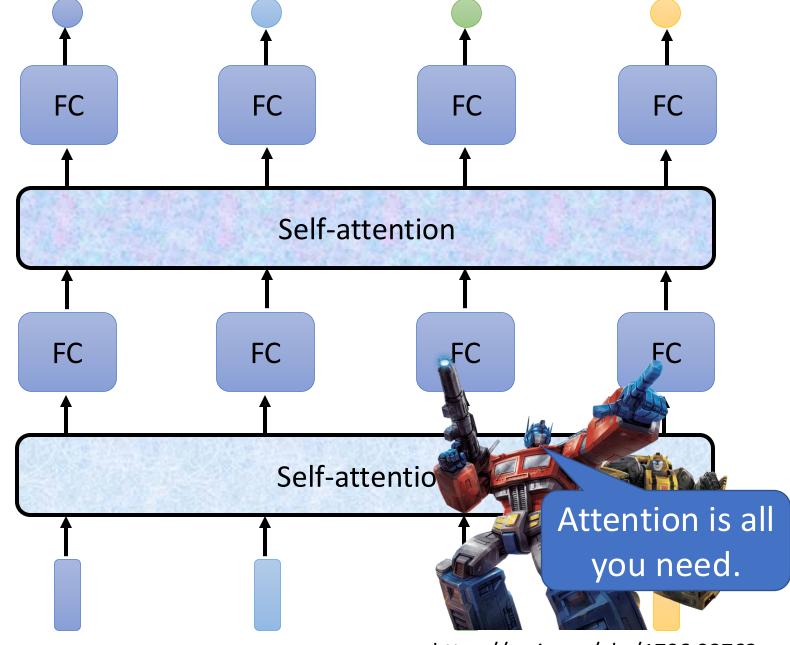


Self-attention 自注意力机制



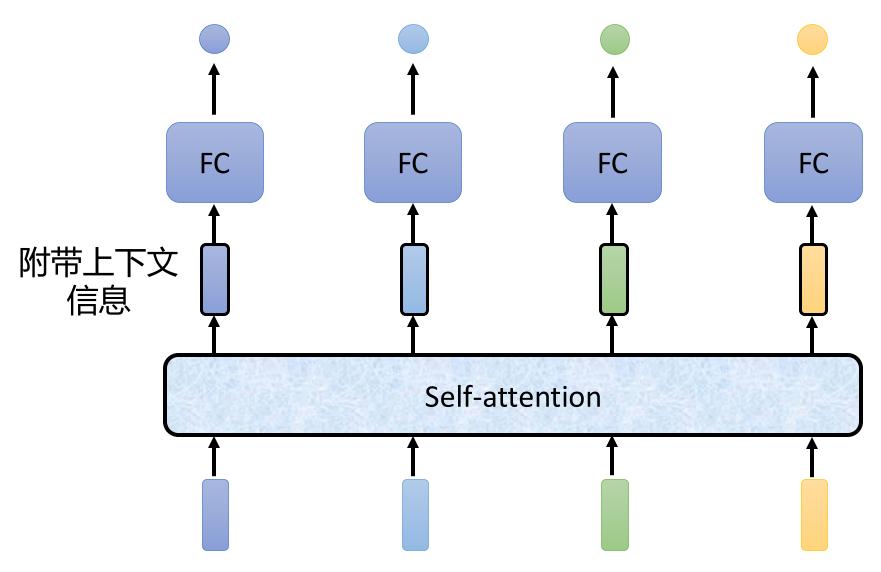




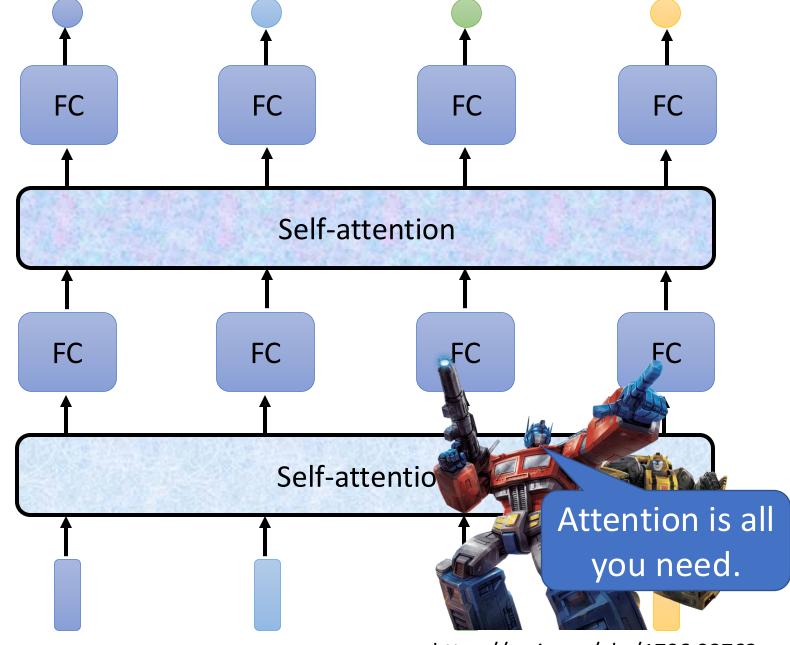


https://arxiv.org/abs/1706.03762



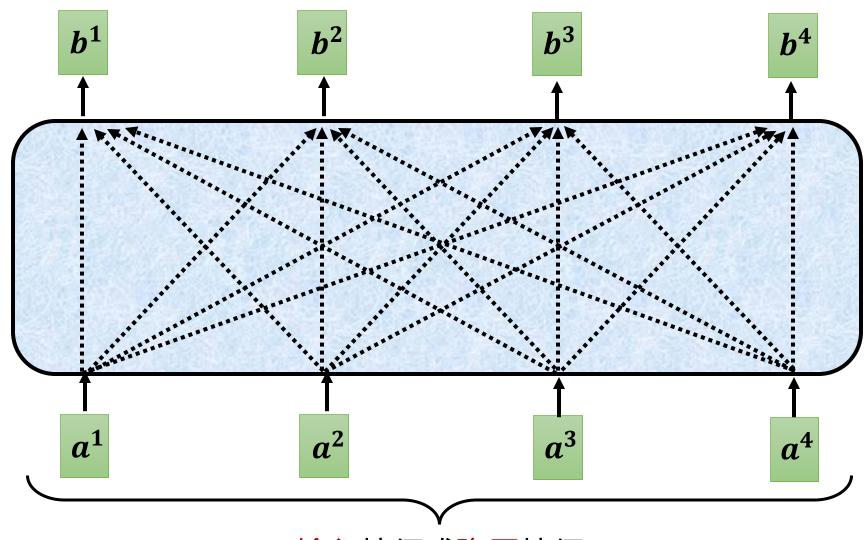






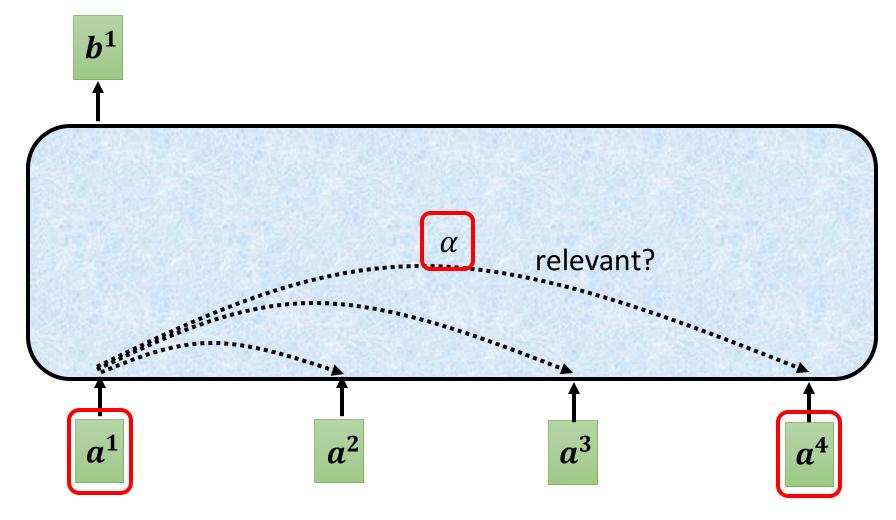
https://arxiv.org/abs/1706.03762





输入特征或隐层特征





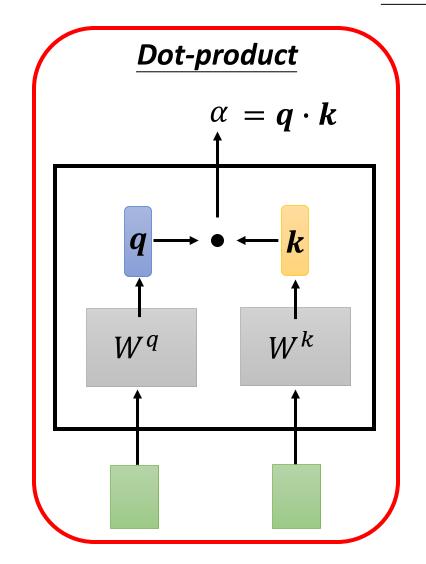
在序列中找到相关向量

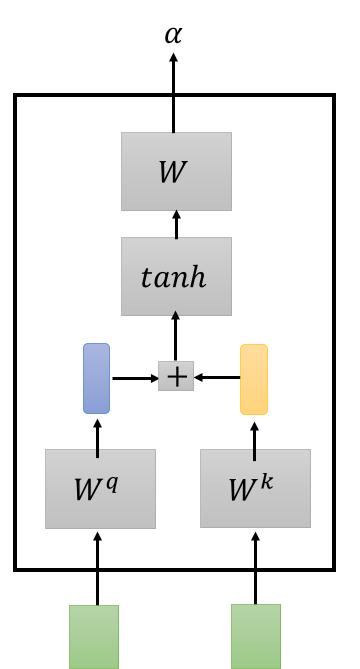


- 想象你在图书馆(输入序列)找书:
  - Query(查询): 就像你的借书需求("我想找一本关于深度学习的入门书")
  - Key(键): 就像每本书的索引标签(书名、分类标签等)
  - Value(值): 就是书籍本身的实际内容
- 具体过程
  - 匹配阶段:你的Query(需求)会与所有书的Key(标签)进行比较,计算匹配程度(注意力分数)
  - ■加权求和:根据匹配程度,从Value(书籍内容)中提取信息
  - 得到结果: 最终你得到的是各种书籍内容的加权组合, 其中与你的需求 最相关的书贡献最大

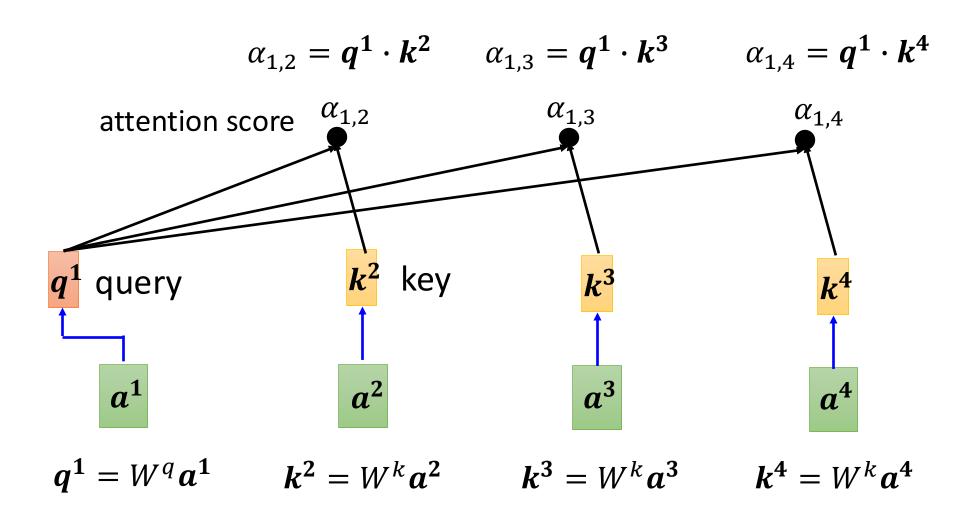


#### **Additive**





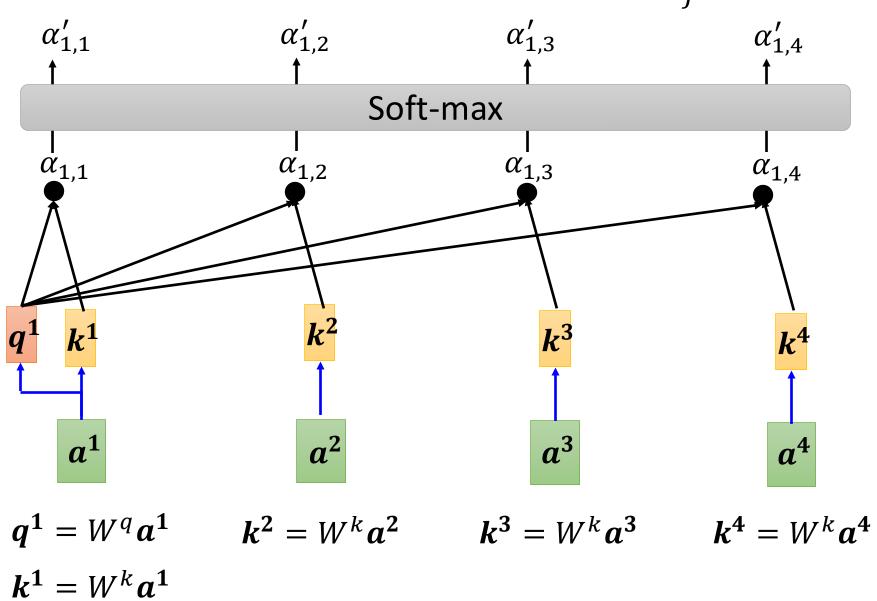






$$\alpha'_{1,i} = exp(\alpha_{1,i}) / \sum_{j} exp(\alpha_{1,j})$$

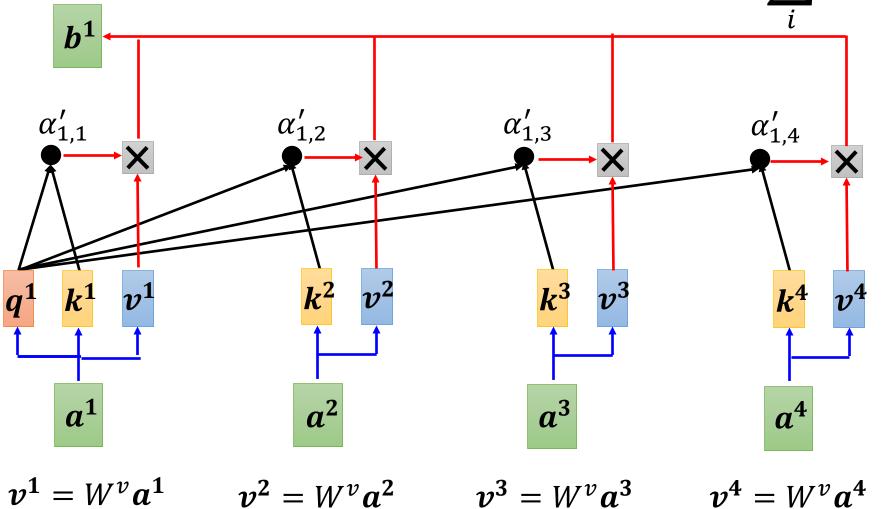
$$\alpha'_{1,3} \qquad \alpha'_{1,4}$$





根据attention scores来抽取信息  $b^1 = \sum \alpha'_{1,i} v^i$ 

$$\boldsymbol{b^1} = \sum_i \alpha'_{1,i} \boldsymbol{v}$$



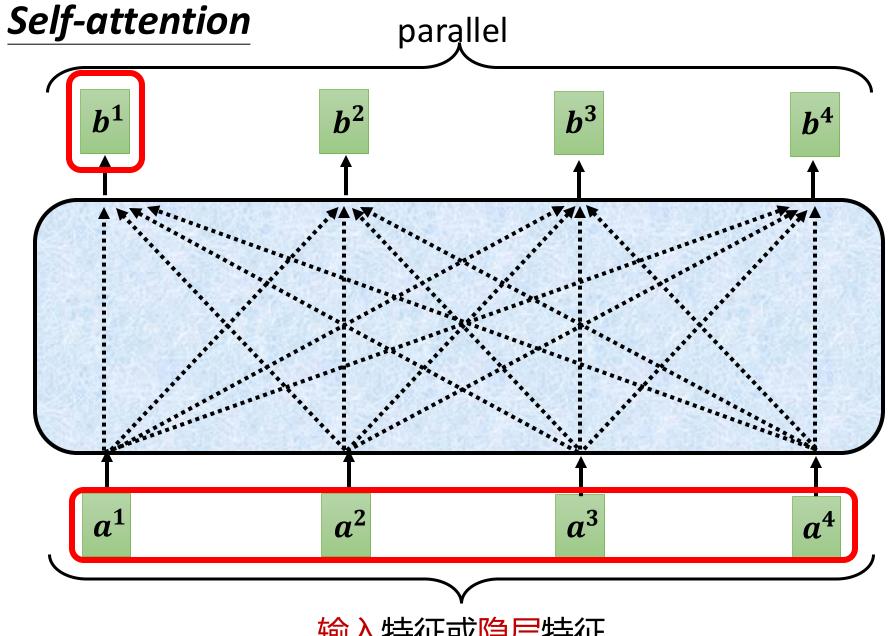
$$v^1 = W^v a^1$$

$$v^2 = W^v a^2$$

$$v^3 = W^v a^3$$

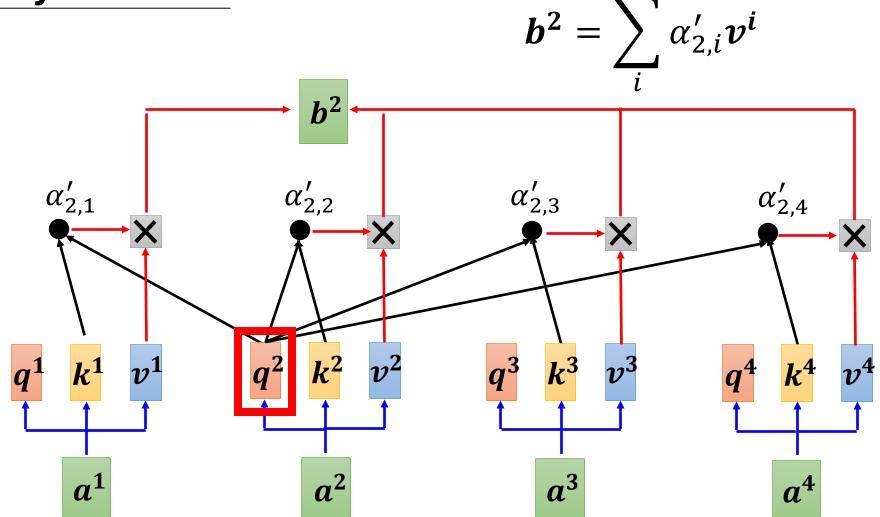
$$v^4 = W^v a^4$$





输入特征或隐层特征







$$q^i = W^q a^i$$

$$q^i = W^q a^i \qquad q^1 q^2 q^3 q^4 = W^q \qquad a^1 a^2 a^3 a^4$$

$$W^q$$

$$a^1a^2a^3a^4$$

$$k^i = W^k a^i$$

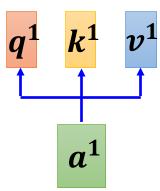
$$k^{i} = W^{k} a^{i}$$
  $k^{1} k^{2} k^{3} k^{4} = W^{k} a^{1} a^{2} a^{3} a^{4}$ 

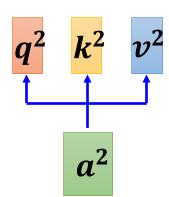
$$W^k a^1 a$$

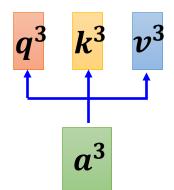
$$a^1a^2a^3a^4$$

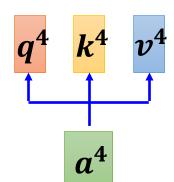
$$v^{i} = W^{v}a^{i} \quad v^{1}v^{2}v^{3}v^{4} = W^{v} \quad a^{1}a^{2}a^{3}a^{3}$$

$$V$$





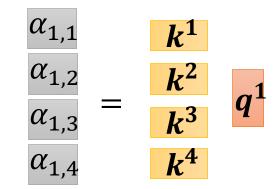


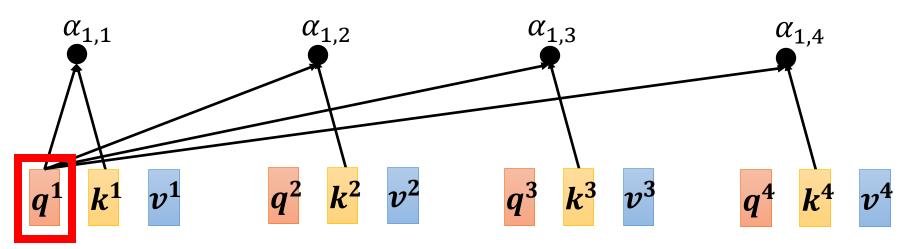




$$\alpha_{1,1} = \mathbf{k^1} \mathbf{q^1} \quad \alpha_{1,2} = \mathbf{k^2} \mathbf{q^1}$$

$$\alpha_{1,3} = k^3 q^1 \alpha_{1,4} = k^4 q^1$$

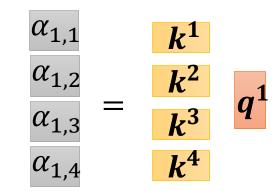


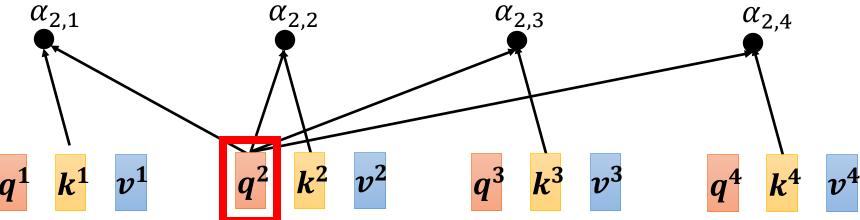




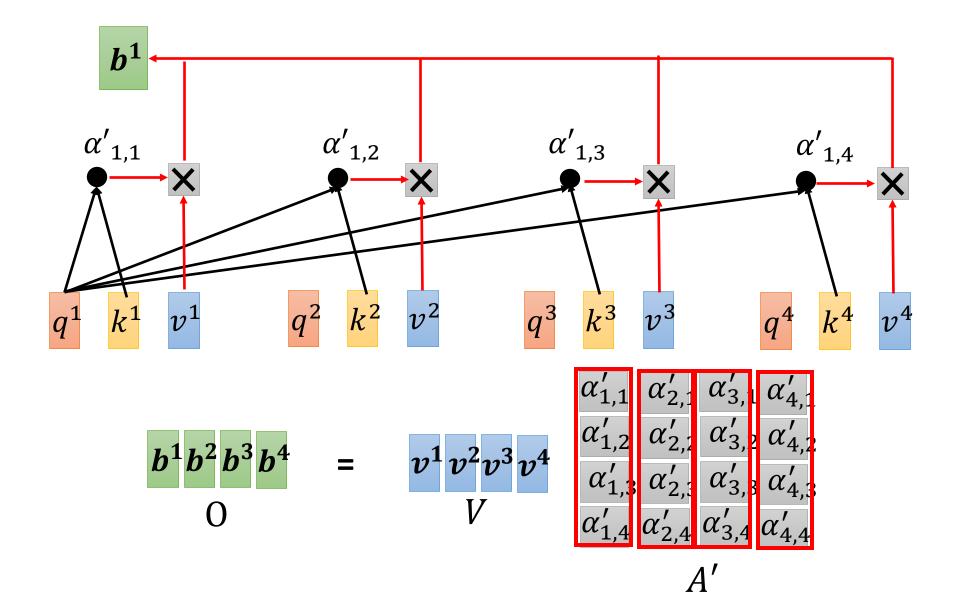
$$\alpha_{1,1} = \begin{bmatrix} \mathbf{k^1} & \mathbf{q^1} & \alpha_{1,2} = \begin{bmatrix} \mathbf{k^2} & \mathbf{q^1} \end{bmatrix}$$

$$\alpha_{1,3} = \mathbf{k^3} \mathbf{q^1} \quad \alpha_{1,4} = \mathbf{k^4} \mathbf{q^2}$$

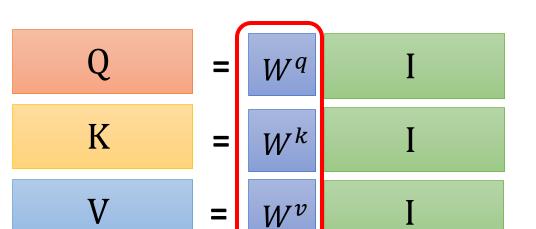




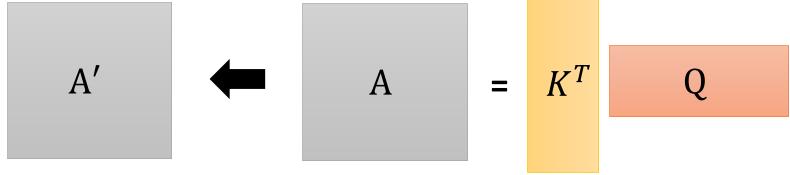








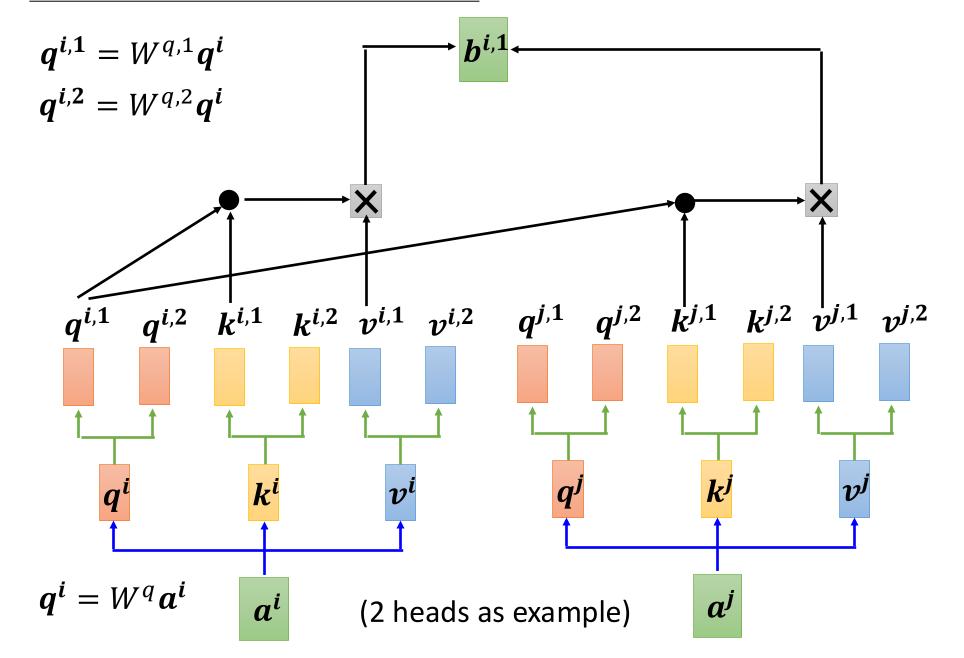
Parameters
to be learned



**Attention Matrix** 

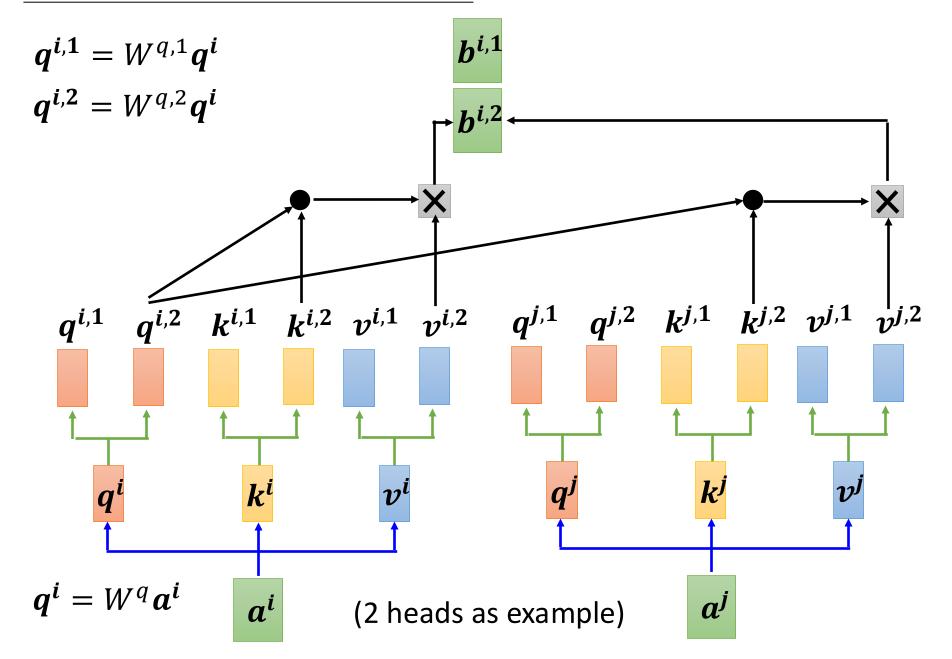


#### Multi-head Self-attention Different types of relevance





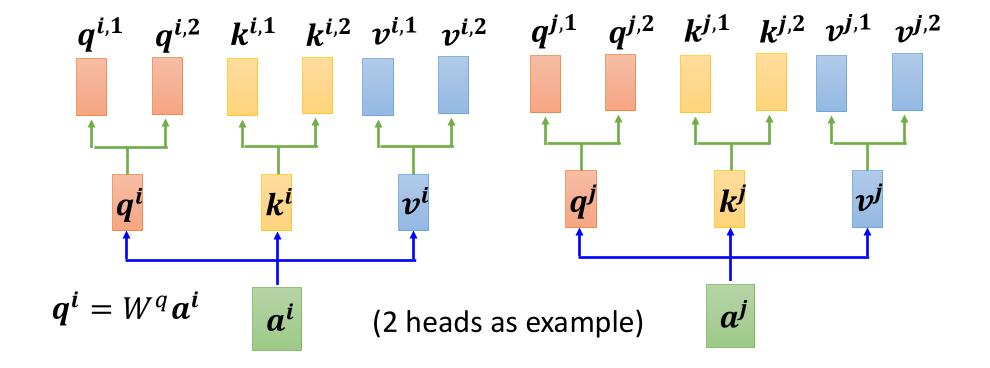
#### Multi-head Self-attention Different types of relevance





#### Multi-head Self-attention Different types of relevance

$$\begin{vmatrix} b^i \\ b^{i,1} \end{vmatrix}$$

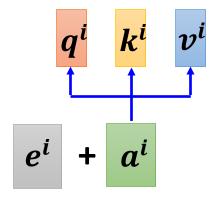


请思考,自注意力机制能否建模序列数据的顺序/位置信息?

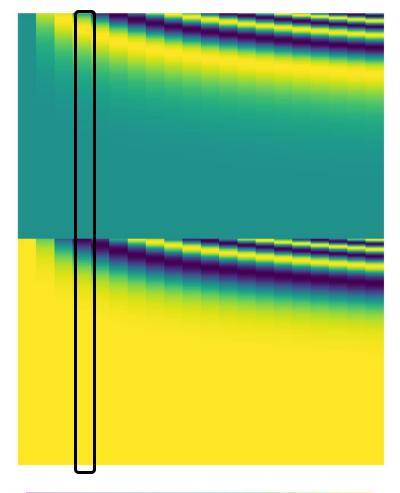


### 位置编码 positional embedding

- self-attention中缺失了位置信息.
- 可以给每个位置赋予一个唯一的位置编码向量(positional vector) $e^i$
- 位置编码可以是手工设计的 hand-crafted
- 也可以是从数据中学习的 learned from data



# Each column represents a positional vector $e^i$

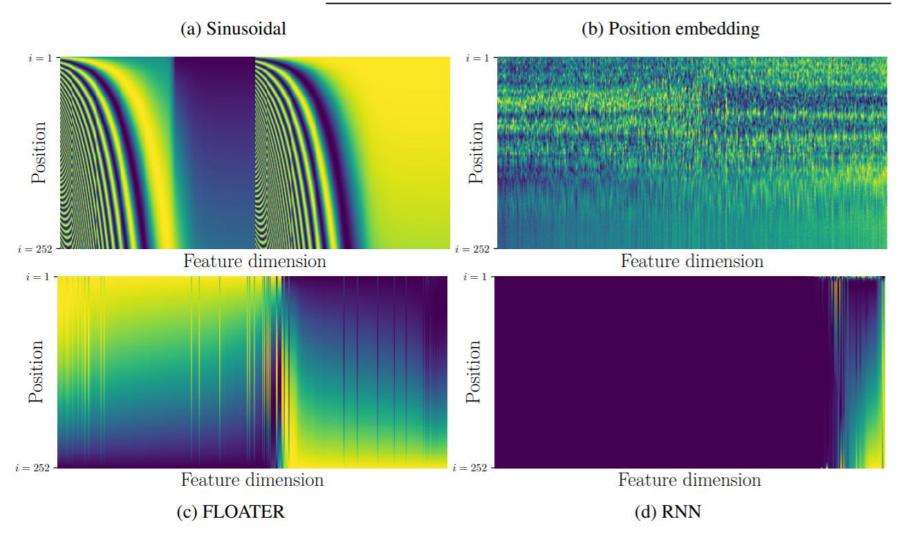




https://arxiv.org/abs/ 2003.09229

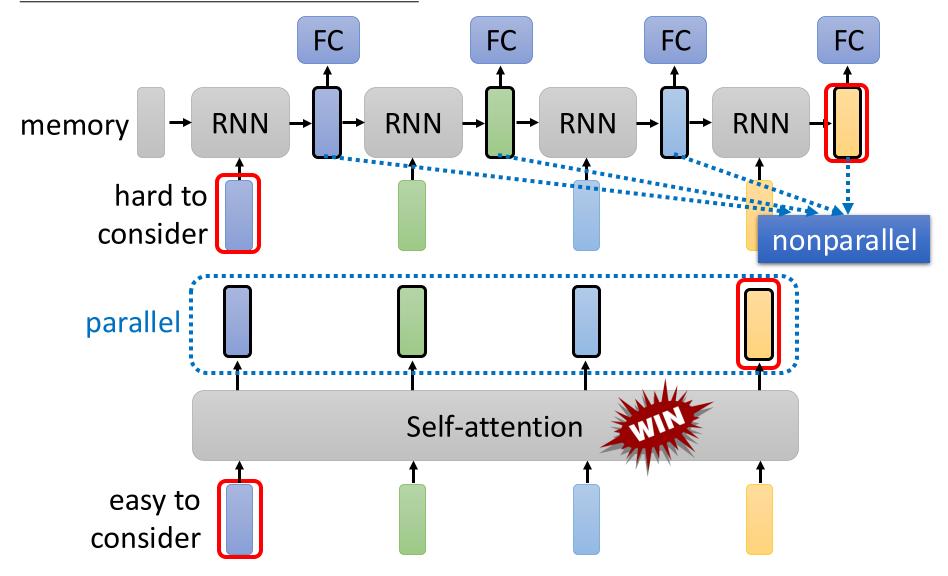
*Table 1.* Comparing position representation methods

| 1 61 1                            |           |             |                     |  |  |
|-----------------------------------|-----------|-------------|---------------------|--|--|
| Methods                           | Inductive | Data-Driven | Parameter Efficient |  |  |
| Sinusoidal (Vaswani et al., 2017) | ✓         | X           | ✓                   |  |  |
| Embedding (Devlin et al., 2018)   | X         | ✓           | X                   |  |  |
| Relative (Shaw et al., 2018)      | X         | ✓           | ✓                   |  |  |
| This paper                        | ✓         | ✓           | ✓                   |  |  |





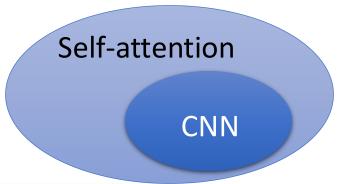
#### Self-attention v.s. RNN

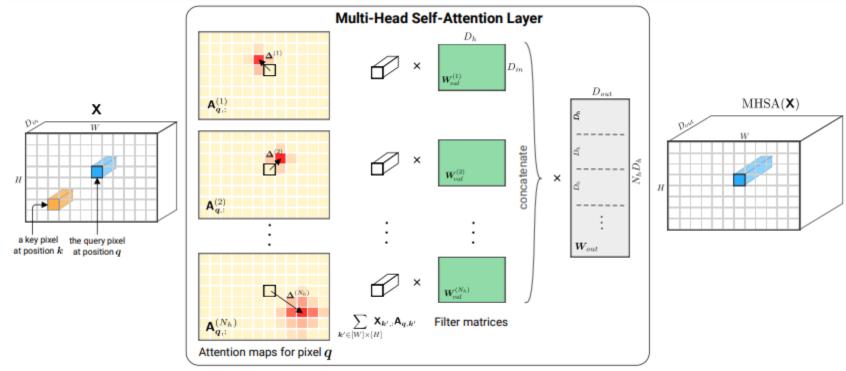


Transformers are RNNs: Fast Autoregressive Transformers with Linear Attention https://arxiv.org/abs/2006.16236



#### Self-attention v.s. CNN





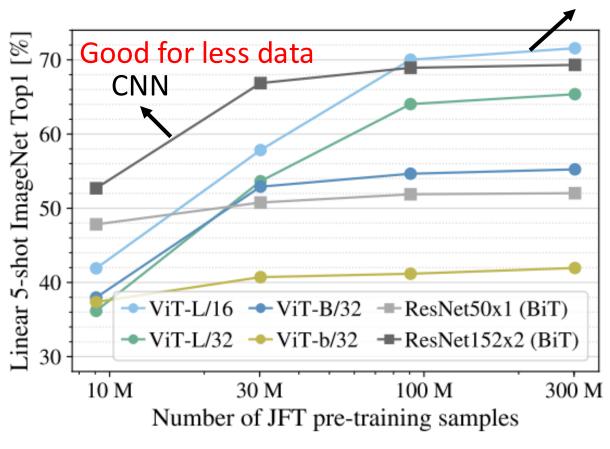
On the Relationship between Self-Attention and Convolutional Layers



#### Self-attention v.s. CNN

#### Good for more data

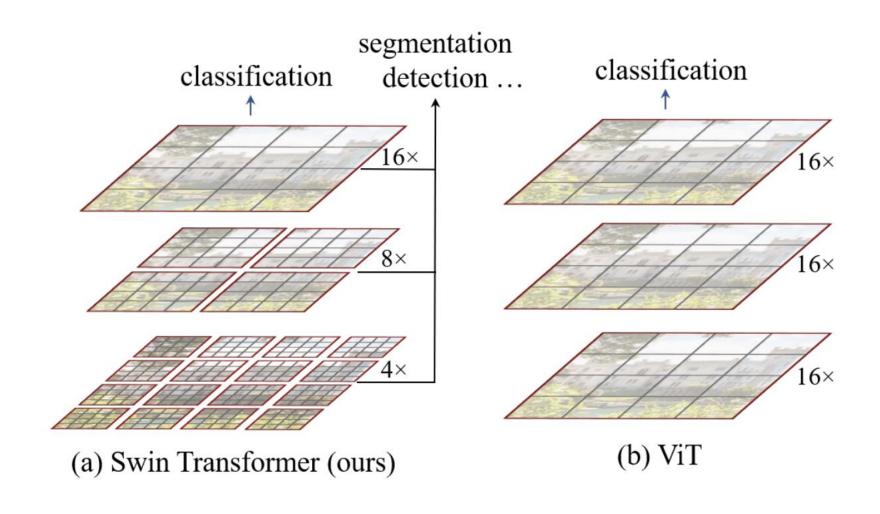
Self-attention



An Image is Worth 16x16 Words: Transformers for Image Recognition at Scale https://arxiv.org/pdf/2010.11929.pdf



#### Self-attention v.s. CNN





- 一、线性回归与梯度下降
- 二、前馈神经网络
- 三、卷积神经网络
- 四、序列数据模型
- 五、深度学习应用



### 深度学习应用

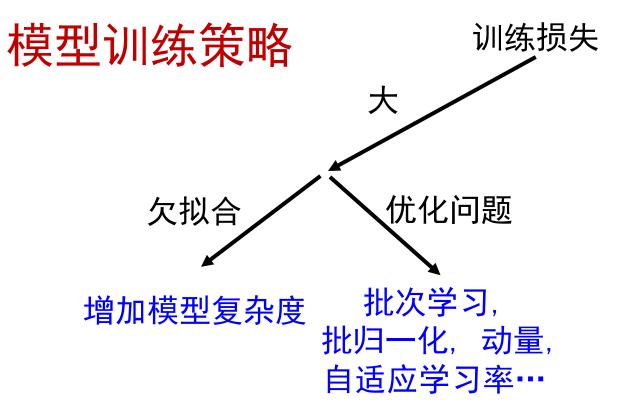
- 深度学习实践
- 卷积神经网络应用
- 自注意力机制应用



### 深度学习应用

- 深度学习实践
  - ■模型训练策略
- 卷积神经网络应用
- 自注意力机制应用







#### 欠拟合

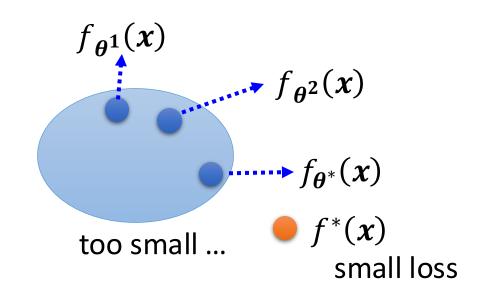
find a needle in a haystack ...
... but there is no needle

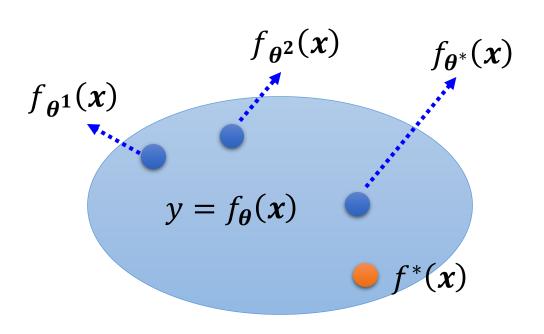
Which one???

#### 优化问题

A needle is in a haystack ...

... Just cannot find it.



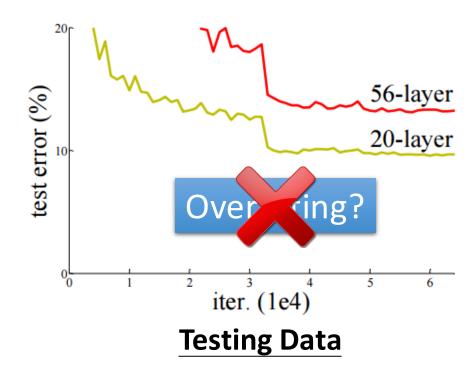


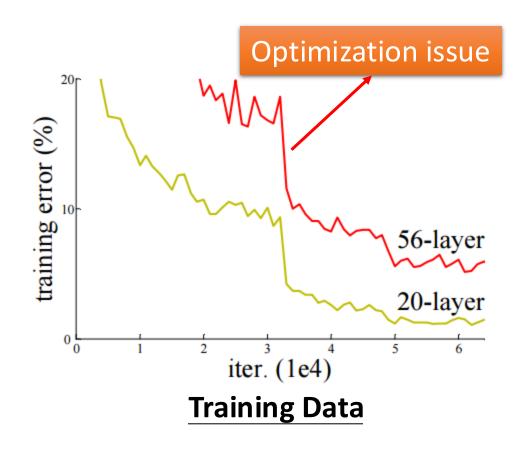
请思考,有哪些方式可以判断模型出现的是欠拟合还是优化问题?



### 欠拟合 v.s. 优化问题

• 实验对比分析







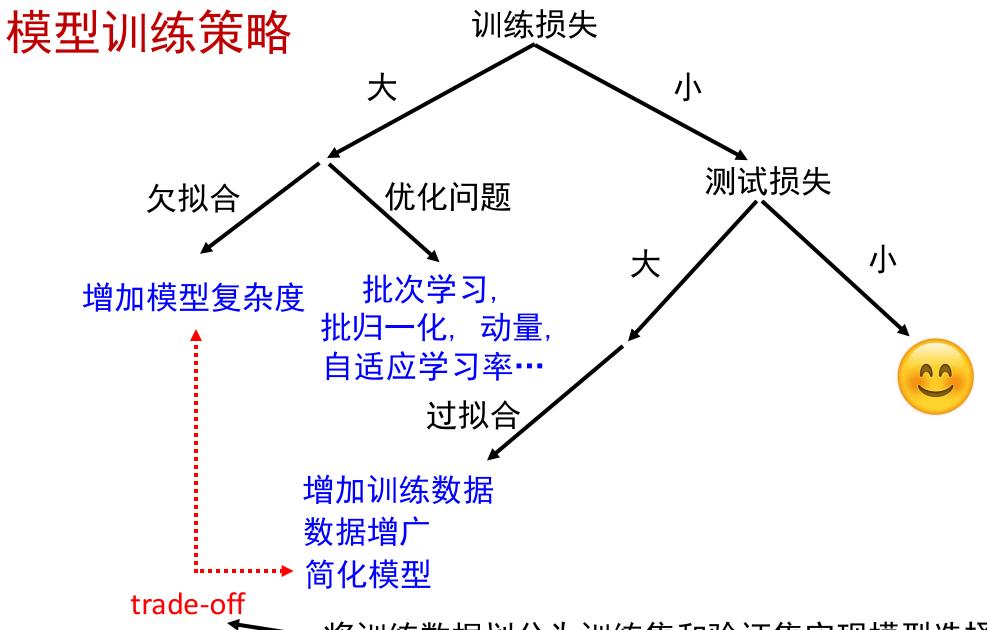
### 优化问题

- 实验对比分析
- 从易优化的浅层网络(或传统方法)开始尝试
- 如果加深网络无法得到更小的训练损失,那么可以认为是优化问题

|             | 1 layer | 2 layer | 3 layer | 4 layer | 5 layer |
|-------------|---------|---------|---------|---------|---------|
| 2017 – 2020 | 0.28k   | 0.18k   | 0.14k   | 0.10k   | 0.34k   |

• 解决方案: 使用更好的优化方法

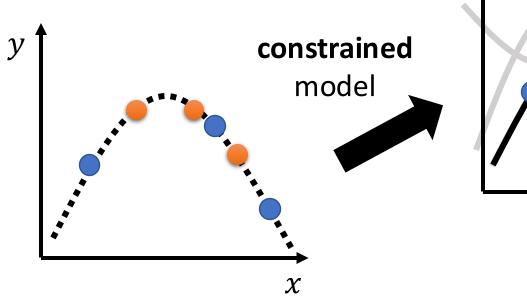


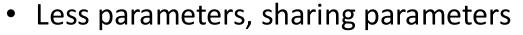


将训练数据划分为训练集和验证集实现模型选择

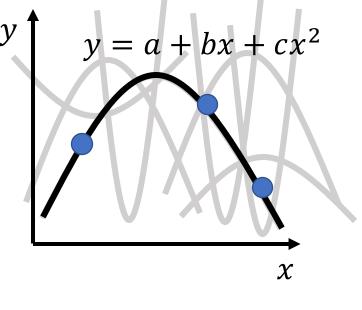


## 过拟合 Overfitting





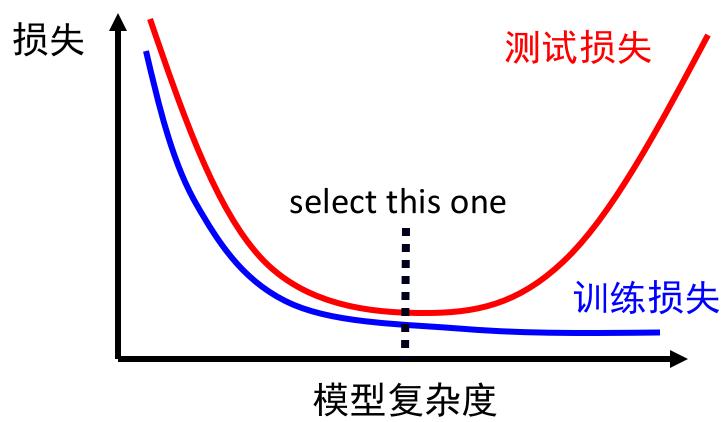
- Less features
- Early stopping
- Regularization
- Dropout



Fully-connected
CNN



### **Bias-Complexity Trade-off**



(e.g. more features, more parameters)



