

MACHINE LEARNING

Learning from Data

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|00 INTRODUCTION

Pattern Recognition Study Correlations Between Data Domains Tune a Parametric Model with Data





|00 INTRODUCTION

H

SUPERVISED

Learn parameters from Labeled Data

Regression

Classification

UNSUPERVISED

Learn parameters from Unlabeled Data

Clustering

Latent Space

REINFORCEMENT

Autonomous Agent Learning from **Experience**

Q-Learning





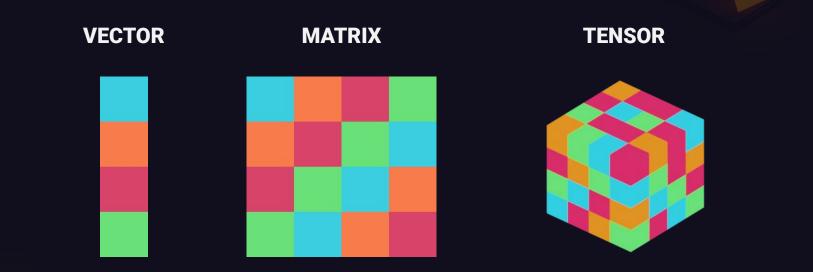


01

LINEAR ALGEBRA

The Last Space Bender







01 LINEAR ALGEBRA



LENGTH

$$ec{v} = \left(egin{array}{c} v_x \ v_y \end{array}
ight)$$

$$\|ec{v}\|=\sqrt{v_x^2+v_y^2}$$





ADDITION / SUBTRACTION



$$ec{v} = \left(egin{array}{c} v_x \ v_y \end{array}
ight)$$

$$ec{u} = \left(egin{array}{c} u_x \ u_y \end{array}
ight)$$

$$ec{v}+ec{u}=\left(egin{array}{c} v_x+u_x\ v_y+u_y \end{array}
ight)$$



01 LINEAR ALGEBRA



SCALAR (DOT) PRODUCT



$$ec{v} = \left(egin{array}{c} v_x \ v_y \end{array}
ight)$$

$$ec{u} = \left(egin{array}{c} u_x \ u_y \end{array}
ight)$$

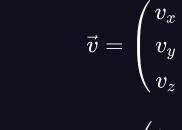
$$ec{v}.\,ec{u}=v_xu_x+v_yu_y=|v|\,|u|\,cos heta$$



01 LINEAR ALGEBRA

VECTOR





$$ec{u} = egin{pmatrix} u_x \ u_y \ u_z \end{pmatrix}$$

$$ec{v} imes ec{u} = egin{pmatrix} v_y u_z - v_z u_y \ v_z u_x - v_x u_z \ v_x u_y - v_y u_x \end{pmatrix}$$





ADDITION / SUBTRACTION



$$A=\left(egin{array}{cc} a_{1,1} & a_{1,2}\ a_{2,1} & a_{2,2} \end{array}
ight)$$

$$B = egin{pmatrix} b_{1,1} & b_{1,2} \ b_{2,1} & b_{2,2} \end{pmatrix}$$

$$A+B=egin{pmatrix} a_{1,1}+b_{1,1} & a_{1,2}+b_{1,2}\ a_{2,1}+b_{2,1} & a_{2,2}+b_{2,2} \end{pmatrix}$$





HADAMARD PRODUCT



$$A=\left(egin{array}{cc} a_{1,1} & a_{1,2} \ a_{2,1} & a_{2,2} \end{array}
ight)$$

$$B = egin{pmatrix} b_{1,1} & b_{1,2} \ b_{2,1} & b_{2,2} \end{pmatrix}$$

$$A\odot B=egin{pmatrix} a_{1,1}b_{1,1} & a_{1,2}b_{1,2}\ a_{2,1}b_{2,1} & a_{2,2}b_{2,2} \end{pmatrix}$$





MATRIX MULTIPLICATION



$$A = egin{pmatrix} a_{1,1} & a_{1,2} \ a_{2,1} & a_{2,2} \end{pmatrix}$$

$$B = egin{pmatrix} b_{1,1} & b_{1,2} \ b_{2,1} & b_{2,2} \end{pmatrix}$$

$$A\cdot B = egin{pmatrix} a_{1,1}b_{1,1} + a_{1,2}b_{2,1} & a_{1,1}b_{1,2} + a_{1,2}b_{2,2} \ a_{2,1}b_{1,1} + a_{2,2}b_{2,1} & a_{2,1}b_{1,2} + a_{2,2}b_{2,2} \end{pmatrix}$$







EYE

$$\begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$



MATRIX



SCALE

$$egin{pmatrix} s_x & 0 & 0 & 0 \ 0 & s_y & 0 & 0 \ 0 & 0 & s_z & 0 \ 0 & 0 & 0 & 1 \end{pmatrix}$$



MATRIX



ROTATION

$$R_x(heta) = egin{pmatrix} 1 & 0 & 0 & 0 \ cos(heta) & -sin(heta) & 0 & 0 \ sin(heta) & cos(heta) & 1 & 0 \ 0 & 0 & 0 & 1 \end{pmatrix}$$

$$R_y(heta) = egin{pmatrix} cos(heta) & 0 & sin(heta) & 0 \ 0 & 1 & 0 & 0 \ -sin(heta) & 0 & cos(heta) & 0 \ 0 & 0 & 0 & 1 \end{pmatrix}$$

$$R_z(heta) = egin{pmatrix} cos(heta) & -sin(heta) & 0 & 0 \ sin(heta) & cos(heta) & 0 & 0 \ 0 & 0 & 1 & 0 \ 0 & 0 & 0 & 1 \end{pmatrix}$$



MATRIX



SHEAR

$$\begin{pmatrix} 1 & 0 & \lambda & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$







REFLECTION

$$egin{pmatrix} 1 & 0 & 0 & 0 \ 0 & -1 & 0 & 0 \ 0 & 0 & 1 & 0 \ 0 & 0 & 0 & 1 \ \end{pmatrix}$$







TRANSLATION

$$egin{pmatrix} 1 & 0 & 0 & t_x \ 0 & 1 & 0 & t_y \ 0 & 0 & 1 & t_z \ 0 & 0 & 0 & 1 \end{pmatrix}$$



02

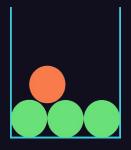


Roll the Dice









RANDOM VARIABLES

$$B = egin{cases} r & ext{if Box is red} \ b & ext{if Box is blue} \end{cases}$$

$$F = egin{cases} a & ext{if Fruit is an apple} \ o & ext{if Fruit is an orange} \end{cases}$$



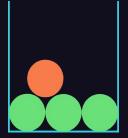








$$p(B=r)=rac{ ext{\# red boxes picked}}{ ext{\# total boxes picked}} \in [0;1]$$



$$p(B=r) + p(B=b) = 1$$





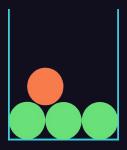






Joint probabilties p(B=r, F=a)

Marginal probabilty p(B=r)=p(B=r,F=a)+p(B=r,F=o)



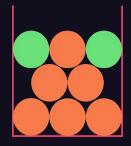
Product Rule

Conditional probabilties p(B = r | F = o)

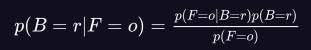
$$p(B=r,F=o)=p(F=o|B=r)\;p(B=r)$$

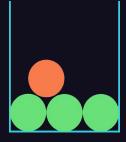


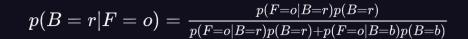






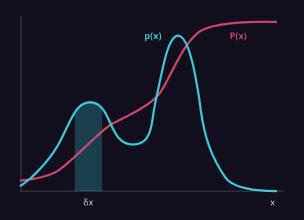










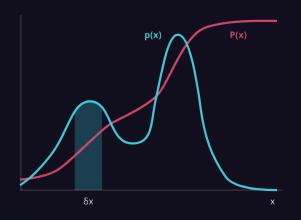


DENSITY

$$p(x\in(a,b))=\int_a^b p(x)dx$$
 $\int_{-\infty}^{+\infty} p(x)dx=1$ $p(x)\geq 0$







EXPECTATION & COVARIANCE

$$egin{aligned} \mathbb{E}[f] &= \int p(x)f(x)dx \ var[f] &= \mathbb{E}[(f(x) - \mathbb{E}[f(x)])^2] \ var[f] &= \mathbb{E}[f(x)^2] - \mathbb{E}[f(x)]^2 \ cov[x,y] &= \mathbb{E}_{x,y}[xy] - \mathbb{E}[x]\mathbb{E}[y] \end{aligned}$$







03

OPTIMIZATION

One Method to Rule them All



f(x+h) f(x-h) Δx $x-h \quad x+h \quad x$

DERIVATIVES

$$f'(x) = \lim_{h o 0} rac{\Delta f}{\Delta x} = \lim_{h o 0} rac{f(x+h) - f(x-h)}{2h}$$

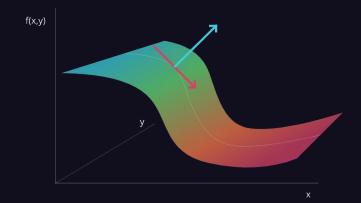
First order Derivative

Direction of the Slope

Second order Derivative

Rate of Changes in the Slope



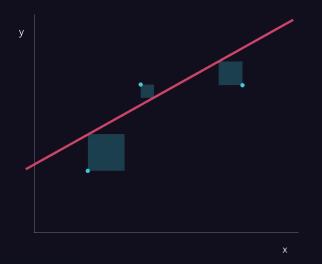


GRADIENTS

$$abla f = \left(rac{rac{\partial f}{\partial x}}{rac{\partial f}{\partial y}}
ight)$$



103 OPTIMIZATION



LEAST SQUARES

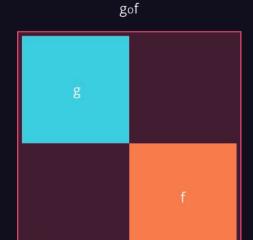
Objective Function

Minimize Squared Distances from Expected Value

$$\hat{y} = ax + b$$

$$\sum_i (y_i - \hat{y}_i)^2 = 0$$





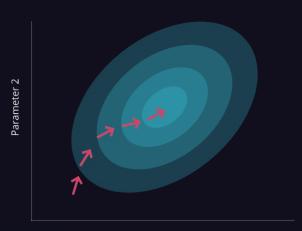
CHAIN RULE

$$h=g\circ f$$

$$h'(x) = g'(f(x))f'(x)$$



Error Landscape



Parameter 1

GRADIENT DESCENT

Steps

-) Forward Propagate Through the Chain
- 2) Compute Output **Error**
- 3) **Backpropagate** Error Through the Chain
- 4) **Update** Weights w/ Learning Rate
- 5) Repeat Until Convergence Threshold



Test

/alid

ain

DATASET SPLIT

Training Set

Samples used to Fit/Train the Model

Validation Set

Samples used to provide an Unbiased Evaluation of the Model Becomes Biased during Training

Testing Set

Samples used to provide an Unbiased Evaluation of the Model after Training







CROSS-VALIDATION

Method

- 1) Split Dataset into **k-Folds**
- 2) Train on k-1 Folds and Validate w/ Last
- 3) **Repeat** k-times
- Use Ensemble Method for Inference or Retrain on all Dataset



04

DIMENSIONALITY REDUCTION

Small Worlds are Filled with Things to See

Paul Safranek



|04 DIMENSIONALITY REDUCTION





PCA

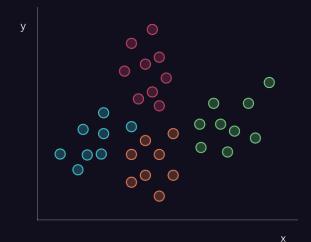
$$C = egin{pmatrix} Var(x) & Cov(x,y) & Cov(x,z) \ Cov(y,x) & Var(y) & Cov(y,z) \ Cov(z,x) & Cov(z,y) & Var(z) \end{pmatrix}$$

$$egin{array}{cccc} v_1 & \lambda_1 & & \mathsf{Big} \ v_2 & \lambda_2 & & & \ v_3 & \lambda_3 & & \mathsf{Small} \end{array}$$





|04 DIMENSIONALITY REDUCTION





Steps

- Use Normal Distribution to Estimate Similarity b/ Data Points
- Create another Distribution
 (t-distribution) Capturing the Same
 Similarity Between Data Points using
 Gradient Descent on KL-divergence





05

SUPERVISED LEARNING

Keep Calm & Label them All





$$Y = f(X)$$

Classification



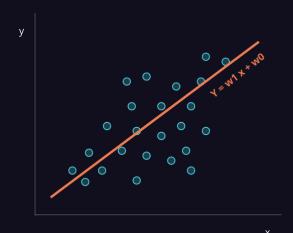
Regression











LINEAR REGRESSION

$$Y=f(W,X)=XW^t+oldsymbol{\epsilon}$$

$$\mathcal{L} = MSE(\hat{Y},Y) = rac{1}{N} \sum_i (w_i x_i - y_i)^2$$

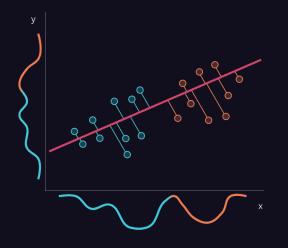
$$rac{\partial \mathcal{L}}{\partial W} = rac{2}{N}(X^tXW - X^tY) = 0$$







LINEAR DISCRIMINANT ANALYSIS



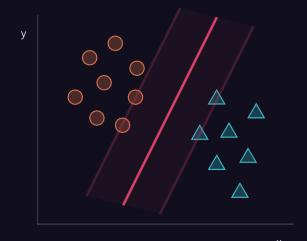
$$Y=f(W,X)=XW^t+oldsymbol{\epsilon}$$

$$Objective(W) = rac{| ilde{\mu_1} - ilde{\mu_2}|}{ ilde{s_1^2} + ilde{s_2^2}}$$









SUPPORT VECTOR MACHINE

$$Y_i(WX+b)-1\geq 0$$

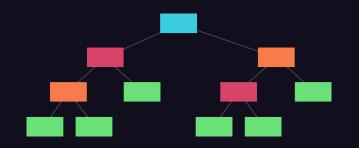
$$margin = (X_+ - X_-) rac{W}{\|W\|}$$

$$J(W) = rac{1}{2} \|W\|^2 + C(rac{1}{N} \sum_i max(0, 1 - y_i(wx_i + b)))$$









DECISION TREE

Steps

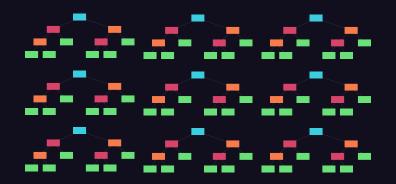
- 1) Compute all **Gini Impurity** Scores
- 2) Lowest Impurity Score Becomes a Leaf
- 3) Else **if Improvement** pick the Separation with the **Lowest Score**

$$Gini(K) = \sum_i P_{i,K} (1-P_{i,K}) = 1 - \sum_i P_{i,K}^2$$









RANDOM FOREST

Intuition

Forest of **Dense Decision Trees**Like **Cross Validation Ensemble Methods** give Better Results
Use Voting, Max or Average









Steps

- Start from a Single Leaf of the Average Prediction
- Build a New Tree to Predict the Residual Error from the Previous Tree and Weight its Contribution by a Learning Rate
- 3) Do **Until Convergence** Condition



