

МИНИСТЕРСТВО ОБРАЗОВАНИЯ И НАУКИ РОССИЙСКОЙ
ФЕДЕРАЦИИ МОСКОВСКИЙ АВИАЦИОННЫЙ ИНСТИТУТ
(НАЦИОНАЛЬНЫЙ ИССЛЕДОВАТЕЛЬСКИЙ УНИВЕРСИТЕТ)

ЛАБОРАТОРНАЯ РАБОТА №4 по курсу объектно-ориентированное программирование I семестр, 2019/20 уч. год

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Условие

Задание №1: написать программу, которая реализует работу с фигурами:

1. Ввод фигуры
2. Ввод фигуры как tuple

Описание программы

Код программы состоит из 4-ти файлов:

1. app/main.cpp: исходный код с точкой входа
2. include/algorithm.hpp: объявление и реализация generic структур
3. include/polygon.hpp: объявление и реализация generic структур
4. include/point.hpp: объявление и реализация generic структур

Выводы

Шаблоны Visual C++ не полностью совместимы с шаблонами из GCC.

Исходный код

algorithm.hpp

```
#pragma once
```

```
#include <type_traits>
```

```
#include <tuple>
```

```
#include <utility>
```

```
#include <ostream>
```

```
#include <cmath>
```

```
#include "point.hpp"
```

```
namespace detail {
```

```
    template<size_t _Off, size_t ... _Ix>
```

```
    std::index_sequence<(_Off + _Ix)...> add_offset(std::index_sequence<_Ix...>) {  
        return {};
```

```
    }
```

```
    template<size_t _Off, size_t _N>
```

```
    auto make_index_sequence_with_offset() {  
        return add_offset<_Off>(std::make_index_sequence<_N>{});  
    }
```

```
    template<typename _T, size_t... _Ix>
```

```
    double area2d(const _T& tuple, std::index_sequence<_Ix...>) {  
        using vertex = std::remove_const_t<std::remove_reference_t<decltype(std::get<0>(tuple))>>;  
        static_assert(std::is_same_v<vertex, point2d>, "incorrect type");
```

```
        auto constexpr tuple_size = std::tuple_size<_T>{}();
```

```
        auto constexpr x = 0;
```

```
        auto constexpr y = 1;
```

```
        using std::get;
```

```
        double result = ((get<_Ix>(tuple)[x] * (get<_Ix + 1>(tuple)[y] - get<_Ix - 1>(tuple)[y])
```

```
        auto constexpr first = 0;
```

```
        auto constexpr last = tuple_size - 1;
```

```
        result += get<first>(tuple)[x] * (get<first + 1>(tuple)[y] - get<last>(tuple)[y])
```

```
        result += get<last>(tuple)[x] * (get<first>(tuple)[y] - get<last - 1>(tuple)[y])
```

```
        result /= 2;
```

```

        return std::abs(result);
    }

    template<typename _T, std::size_t... _Ix>
    auto center2d(const _T& tuple, std::index_sequence<_Ix...>) {
        using vertex = std::remove_const_t<std::remove_reference_t<decltype(std::get<0>(tuple))>>>;
        static_assert(std::is_same_v<vertex, point2d>, "incorrect type");

        auto constexpr tuple_size = std::tuple_size<_T>{}();
        auto constexpr x = 0;
        auto constexpr y = 1;

        vertex result = (std::get<_Ix>(tuple) + ...);
        result[x] /= tuple_size;
        result[y] /= tuple_size;

        return result;
    }

    template<typename _T, std::size_t... _Ix>
    auto print_points2d(std::ostream& out, const _T& tuple, std::index_sequence<_Ix...>) {
        auto constexpr tuple_size = std::tuple_size<_T>{}();
        (out << ... << std::get<_Ix>(tuple));
    }
}

template<typename _T>
double area2d(const _T& tuple) {
    auto constexpr tuple_size = std::tuple_size<_T>{}();
    using vertex = std::remove_reference_t<decltype(std::get<0>(tuple))>>;
    return detail::area2d(tuple, detail::make_index_sequence_with_offset<1, tuple_size - 1>());
}

template<typename _T>
auto center2d(const _T& tuple) {
    auto constexpr tuple_size = std::tuple_size<_T>{}();
    return detail::center2d(tuple, std::make_index_sequence<tuple_size>{});
}

template<typename _T>
auto print2d(std::ostream& stream, const _T& tuple) {
    auto constexpr tuple_size = std::tuple_size<_T>{}();

```

```

using std::endl;

stream << "\ntype:  ";
switch (tuple_size) {
case 4:
    stream << "rhombus" << endl; break;
case 5:
    stream << "pentagon" << endl; break;
case 6:
    stream << "hexagon" << endl; break;
default:
    stream << "unknown" << endl;
}

stream << "center: " << center2d(tuple) << endl
    << "area:  " << area2d(tuple) << endl
    << "points: ";
detail::print_points2d(stream, tuple, std::make_index_sequence<tuple_size>{});
stream << endl << endl;
}

```

polygon.hpp

```
#pragma once

#include <cstdint> // size_t
#include <tuple>
#include <type_traits>
#include <istream>
#include <ostream>
#include <stdexcept>

/*
    basic_polygon traits
*/
template<typename _Vertex>
struct basic_polygon_traits {
    using vertex          = _Vertex;
    using pointer         = vertex*;
    using const_pointer   = const vertex*;
    using reference       = vertex&;
    using const_reference = const vertex&;

    using iterator        = pointer;
    using const_iterator  = const_pointer;
};

/*
    basic_polygon class
    tuple-like
    structured binding is available
*/
template<typename _Vertex, size_t _NumOfPoints>
class basic_polygon {
    static_assert(_NumOfPoints >= 3, "can not create polygon from points when there are");
    using traits = basic_polygon_traits<_Vertex>;

    struct tag_prepare_initializer{};
    struct tag_emplace_initializer{};
public:
    using vertex          = typename traits::vertex;
    using pointer         = typename traits::pointer;
    using const_pointer   = typename traits::const_pointer;
    using reference       = typename traits::reference;
```

```

using const_reference = typename traits::const_reference;

using iterator        = typename traits::iterator;
using const_iterator  = typename traits::const_iterator;

// constructors
basic_polygon() = default;
basic_polygon(std::istream& stream) {
    for (auto& point : points) {
        stream >> point;
    }
    if (stream.fail()) {
        throw std::runtime_error("bad polygon initialization");
    }
}
basic_polygon(const vertex& v) noexcept {
    for (auto& point : points) {
        point = v;
    }
}

// element getters
reference at(size_t ix) {
    return points[ix];
}
const_reference at(size_t ix) const {
    return const_cast<basic_polygon&>(*this).at(ix);
}

reference operator[](size_t ix) {
    return at(ix);
}
const_reference operator[](size_t ix) const {
    return const_cast<basic_polygon&>(*this)[ix];
}

// iterators

```

```

iterator begin() {
    return &points[0];
}

const_iterator begin() const {
    // cast const to mutable and use non-const begin
    return const_cast<basic_polygon*>(*this).begin();
}

/* NEVER DEREFERENCE */
iterator end() {
    return &points[_NumOfPoints];
}

/* NEVER DEREFERENCE */
const_iterator end() const {
    // cast const to mutable and use non-const end
    return const_cast<basic_polygon*>(*this).end();
};

// structured binding
template<size_t _Ix>
constexpr auto& get() & {
    // check out of bounds
    if constexpr (_Ix < _NumOfPoints) {
        return points[_Ix];
    }
    else {
        // generate compile-time error
        static_assert(_Ix < _NumOfPoints, "ix is out of range");
    }
}

template<size_t _Ix>
constexpr auto const& get() const& {
    // cast const to mutable and use non-const get
    // which does no effect on storage
    return const_cast<basic_polygon*>(*this).get<_Ix>();
}

template<size_t _Ix>
constexpr auto&& get() && {

```



```

        // cast lvalue reference to rvalue and return it
        return std::move(this->get<_Ix>());
    }

    constexpr size_t size() const {
        return _NumOfPoints;
    }

private:
    vertex points[_NumOfPoints];

    template<size_t _Ix, typename _V, size_t _N>
    friend constexpr auto std::get(const basic_polygon<_V, _N>& polygon);
};

// std types spetializations for structured binding of basic_polygon
namespace std {
    template<size_t _Ix, typename _Vertex, size_t _NumOfPoints>
    constexpr auto get(const basic_polygon<_Vertex, _NumOfPoints>& polygon) {
        return polygon.points[_Ix];
    }

    template<typename _Vertex, size_t _NumOfPoints>
    struct tuple_size<::basic_polygon<_Vertex, _NumOfPoints>>
        : integral_constant<size_t, _NumOfPoints> {};

    template<size_t _Ix, typename _Vertex, size_t _NumOfPoints>
    struct tuple_element<_Ix, ::basic_polygon<_Vertex, _NumOfPoints>> {
        using type = typename basic_polygon_traits<_Vertex>::vertex;
    };
} // namespace std

```

point.hpp

```
#pragma once

#include <iostream>
#include <cstdint>
#include <cassert>
#include <cmath>

template<typename _Type, size_t _Dimensions>
struct point {
    static_assert(_Dimensions != 0, "can not create 0d point");

    using type = _Type;
    using reference = type&;
    using const_reference = const type&;
    using pointer = type*;
    using const_pointer = const type*;

    using iterator = pointer;
    using const_iterator = const_pointer;

    type dots[_Dimensions];

    type& operator[](size_t ix) noexcept {
        return dots[ix];
    }

    const type& operator[](size_t ix) const noexcept {
        return const_cast<point&>(*this).operator[](ix);
    }

    iterator begin() noexcept {
        return &dots[0];
    }

    const_iterator begin() const noexcept {
        return const_cast<point&>(*this).begin();
    }

    iterator end() noexcept {
        return &dots[_Dimensions];
    }
}
```

```

const_iterator end() const noexcept {
    return const_cast<point*>(*this).end();
}

static constexpr size_t size() noexcept {
    return _Dimensions;
}

point operator+(const point& other) const {
    point result = *this;

    for (size_t i = 0; i < result.size(); i++) {
        result[i] += other[i];
    }

    return result;
}

point operator-(const point& other) const {
    point result = *this;

    for (size_t i = 0; i < result.size(); i++) {
        result[i] -= other[i];
    }

    return result;
}
};

template<typename _Type, size_t _Dims>
std::ostream& operator<<(std::ostream& stream, const point<_Type, _Dims>& p) {
    stream << "{ ";
    for (const auto& d : p) {
        stream << d << " ";
    }
    stream << "}";

    return stream;
}

template<typename _Type, size_t _Dims>

```

```

std::istream& operator>>(std::istream& stream, point<_Type, _Dims>& p) {
    for (auto& d : p) {
        stream >> d;
    }

    return stream;
}

// Examples:
using point2d = point<double, 2>;

inline double distance(const point2d& left, const point2d& right) {
    double x = left[0] - right[0];
    double y = left[1] - right[1];
    return std::sqrt((x * x) + (y * y));
}

```