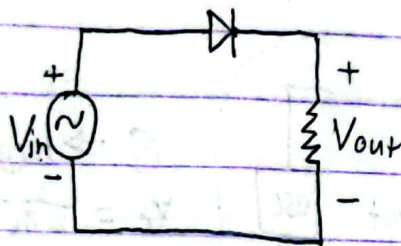


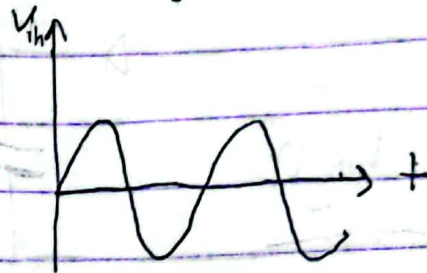
Rectifiers:

- * It is a circuit that converts AC to DC.
- * All electronic devices operates on DC current but current from the power ~~sup~~ supply is AC so here rectifiers are used to convert AC to DC.
- * High voltage DC is more efficient than ^{high} ~~low~~ voltage ~~DC~~ AC.

W-5(L-9)(V-2)

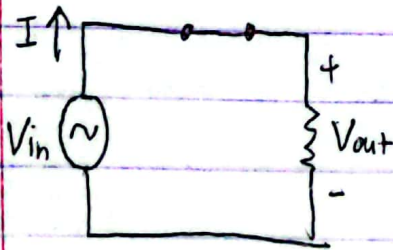


Waveform graph of V_{in} ,



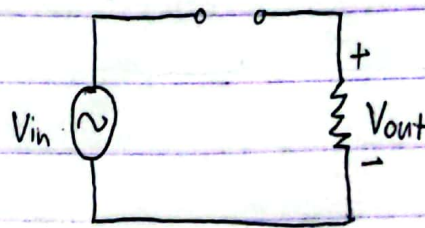
* Halfwave rectifier

For +ve cycle,

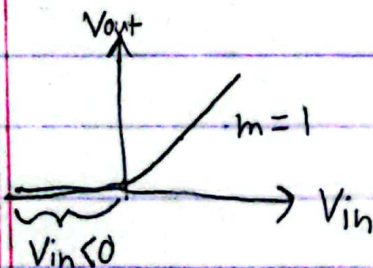


$$V_{in} = V_{out}$$

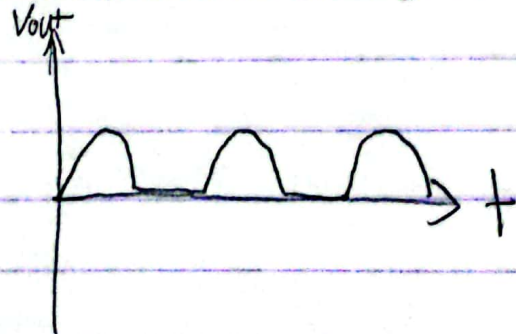
- For -ve cycle,



$$V_{out} = 0$$



Wave form of V_{out} ,

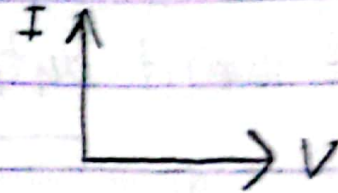


- * There is no power loss in halfwave rectifier, as current is 0 during negative cycle.

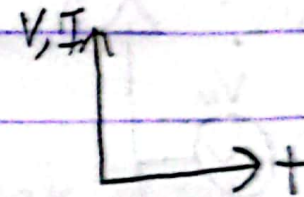
Types of Graphs for this course:

1. IV Graphs / IV - Characteristics

- We do it for devices

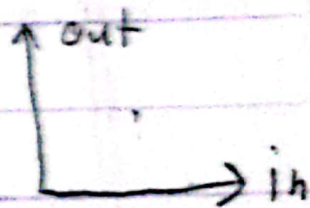


2. Waveform Graphs (V or I vs t)



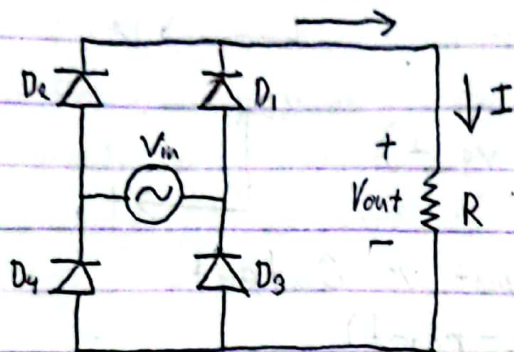
3. Transfer Characteristics (Input vs Output)

- We do it for circuits (2-port)
- (2-port) means comparison between ^{out and in} quantities.
- V_{out} vs V_{in} is called Voltage transfer characteristics (VTC).
- I_{out} vs I_{in} " " Current " " (CTC).
- V_{out} vs I_{in} and I_{out} vs V_{in} is just called - TC.



Full Wave Rectifiers:

* We don't want output to have 2 polarities.

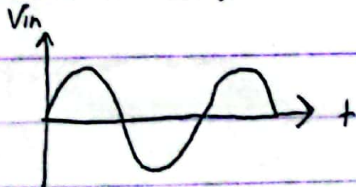


• No matter what cycle (+ve or -ve) it is current will flow in 1 direction only.

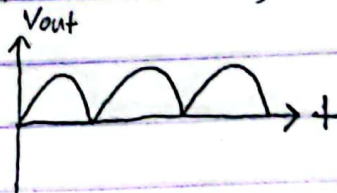
* If $V_{in} = -$ then, current will go through D_1 and return through D_4 .

* If $V_{in} = +$ then, current will go through D_2 and return through D_3 .

* V_{in} waveform,

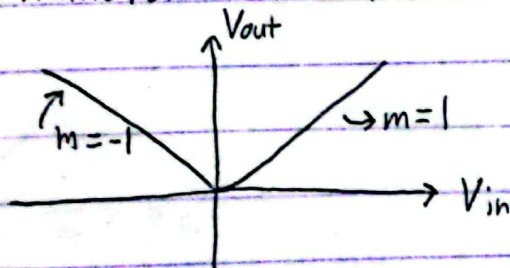


* V_{out} waveform,



* Full wave Rectifier also called Bridge Rectifier.

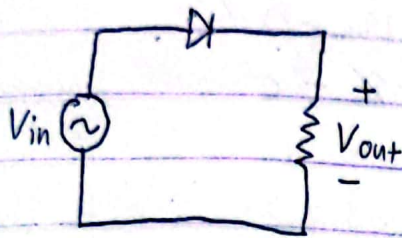
* Voltage Transfer Characteristics (VTC),



* Here all diodes are considered ideal.

Rectifiers with Real Diodes:

* Half wave rectifiers:

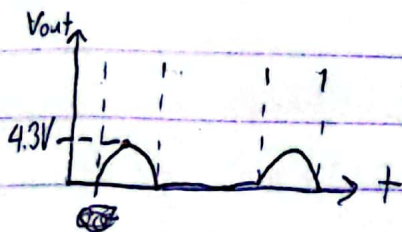
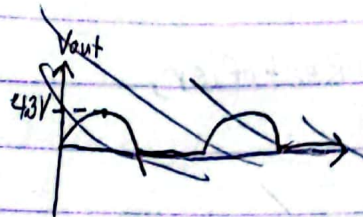
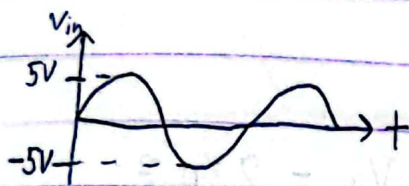


$$I_D = I_S (e^{\frac{V_D}{V_T}} - 1)$$

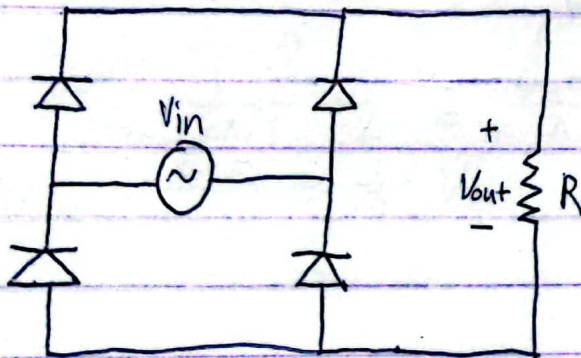
↓

CVD model (0.7V)

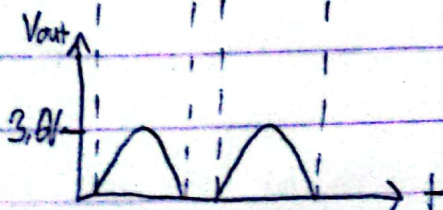
• Peak Voltage, $V_p = V_{in} - 0.7V$



* Full wave rectifiers:



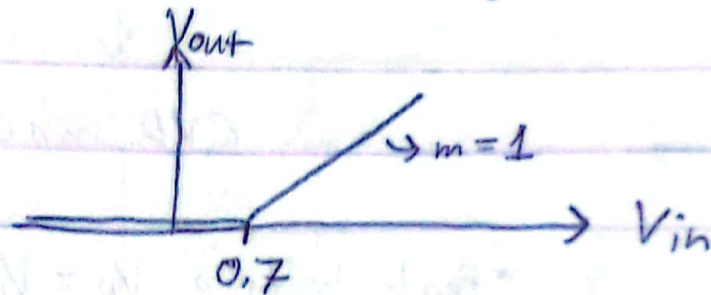
• It will turn ON when $V_{in} \geq 2 \times 0.7 = 1.4V$.
Because 2 diode are ON in each cycle.



• Peak Voltage $V_p = V_{in} - 2 \times 0.7$
 $= V_{in} - 1.4V$

* Transfer Characteristics with Real Diodes:

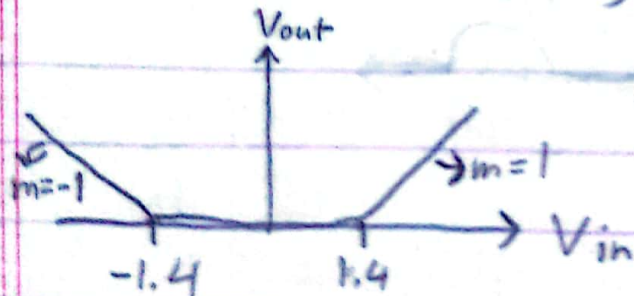
* Half Wave Rectifier,



$$V_{out} = V_{in} - 0.7$$
$$y = x - c$$

Annotations: V_p and V_m are marked with upward arrows pointing to the V_{out} and V_{in} terms in the equation respectively.

* Full Wave Rectifier,



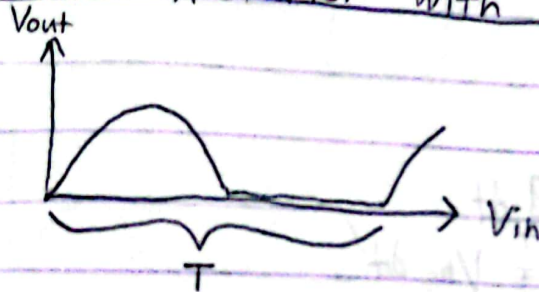
$$V_{out} = V_{in} - 2 \times 0.7$$

V_{00}

* Average Value/DC Value of a periodic signal is the area divided by time period.

$$V_{Avg} = \frac{1}{T} \int_0^T V(t) dt, \quad T = \text{Time period.}$$

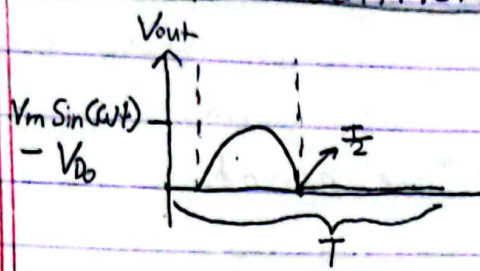
* Half Wave Rectifier with Ideal diode:



$$\begin{aligned} V_{in} &= V_{max} \sin(\omega t) \\ &= V_{max} \sin(2\pi f t) \end{aligned}$$

$$\begin{aligned} \text{Area} &= \int_0^T V_{out}(t) dt \\ &= \int_0^{\frac{T}{2}} V_{out}(t) dt + \int_{\frac{T}{2}}^T \cancel{V_{out}(t) dt} \\ &= \int_0^{\frac{T}{2}} V_m \sin(\omega t) dt \\ &= \left[-V_m \frac{\cos(\omega t)}{\omega} \right]_0^{\frac{T}{2}} \\ &= V_m \cdot \frac{1}{\omega} [-\cos(\frac{\omega T}{2}) + \cos(0)] \quad , \quad \omega = \frac{2\pi}{T} \\ &= V_m \cdot \frac{1}{\omega} \cdot 2 \quad , \quad \frac{\omega T}{2} = \pi, \cos \pi = -1 \\ &= V_m \cdot \frac{1}{2\pi/T} \cdot 2 = \frac{V_m T}{\pi} \\ \therefore V_{Avg} &= \frac{\text{Area}}{T} = \frac{1}{\pi} V_m \end{aligned}$$

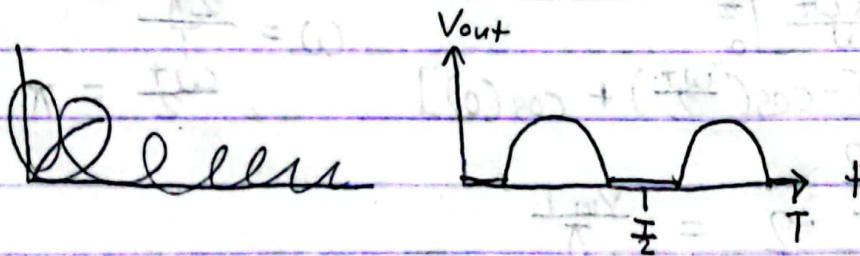
* Half wave rectifier with Real diode:



V_{Do} = diode activation voltage (0.7V)

$$\begin{aligned}
 V_{Avg} &= \frac{1}{T} \int_0^T V_{out}(t) dt \\
 &= \frac{1}{T} \int_0^{\frac{T}{2}} V_{out}(t) dt \\
 &= \frac{1}{T} \int_0^{\frac{T}{2}} [V_m \sin(\omega t) - V_{Do}] dt \\
 &= \frac{1}{T} \left[\int_0^{\frac{T}{2}} V_m \sin(\omega t) dt - \int_0^{\frac{T}{2}} V_{Do} dt \right] \\
 &= \frac{1}{T} \left[\frac{2}{\pi} V_m - V_{Do} \cdot \frac{T}{2} \right] \\
 &= \frac{1}{\pi} V_m - \frac{1}{2} V_{Do}
 \end{aligned}$$

* Full wave rectifier with Real Diode:



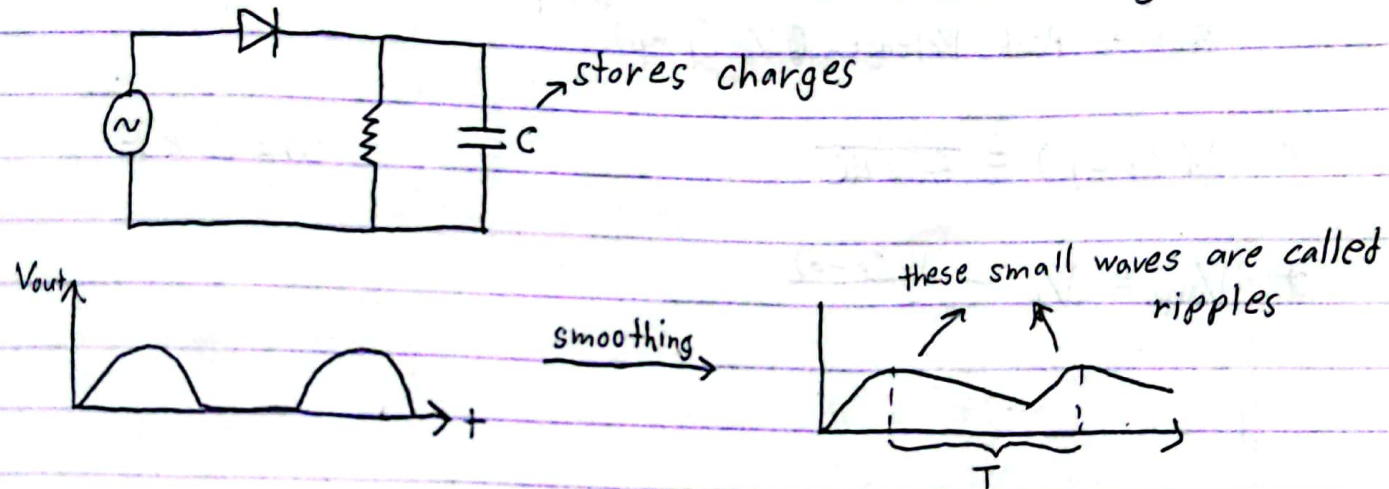
$$V_{out}(t) = V_m \sin(\omega t) - 2V_{Do}$$

$$\begin{aligned}
 \text{Area} &= \int_0^T V_{out}(t) dt \\
 &= 2 \int_0^{\frac{T}{2}} V_{out}(t) dt \\
 &= 2 \int_0^{\frac{T}{2}} [V_m \sin(\omega t) - 2V_{Do}] dt \\
 &= 2 \left[\frac{2}{\pi} V_m - 2V_{Do} \cdot \frac{T}{2} \right]
 \end{aligned}$$

$$\begin{aligned}
 \therefore V_{Avg} &= \frac{\text{Area}}{T} \\
 &= \frac{2}{\pi} V_m - 2V_{Do}
 \end{aligned}$$

* $V_{Avg} = \frac{2}{\pi} V_m$, for FWR with Ideal Diode.

- * Rectifiers convert a AC signal to Pulsating DC Signal.
- * But we need to smooth these pulsating signal in order to make them actual DC current and it is done using a capacitor.



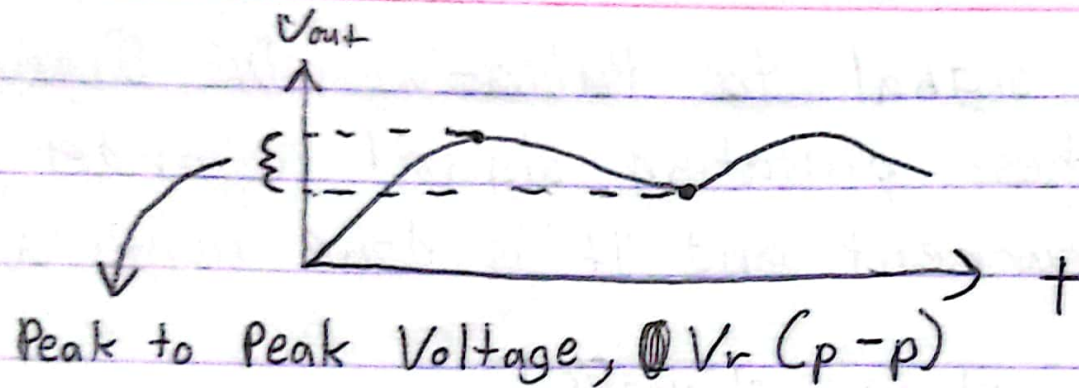
- * Higher the capacitance of the capacitor more ~~of~~ smoothing will occur (higher capacitance will discharge more slowly).

W-5 (L-10) (V-3)

- * ~~Time~~ Time period of the ripple (T_r) is equal to the time period of the signal (T_s), $T_r = T_s$, $\therefore f_r = f_s = \frac{1}{T_s}$, for half wave rectifier.

- * For Full wave rectifier, $T_r = \frac{1}{2} T_s$, $\therefore f_r = 2f_s$

*



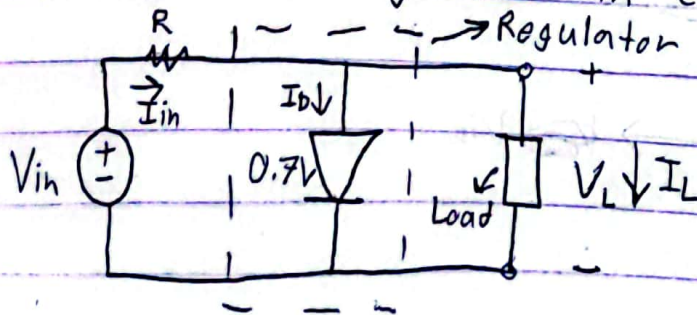
* $V_r(p-p) = \frac{V_p}{f_r \times RC}$ $\omega = 2\pi f$

* $V_{avg} = V_p - \frac{V_r(p-p)}{2}$

Regulators:

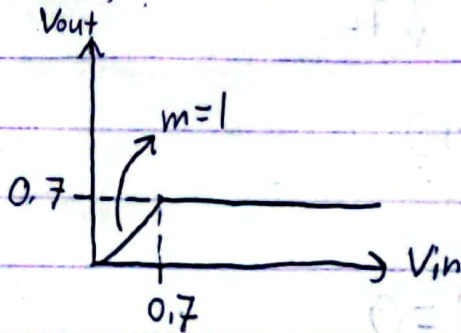
* It is used to further smooth the DC Voltage.

* Diode is used as regulator in circuits.



$$* V_L = V_{in} - R I$$

* For CVD



$$F.B \rightarrow I_D > 0$$

$$R.B \rightarrow I_D = 0$$

* The Diode needs to be in Forward Bias to act as a Voltage Regulator.

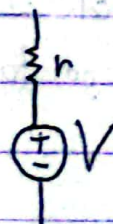
* Because if the diode is in R.B the Voltage across the load would fluctuate if the V_{in} fluctuates.

* The value of I_L needs to be low and I_D needs to be high for the diode to ^{stay} in F.B.

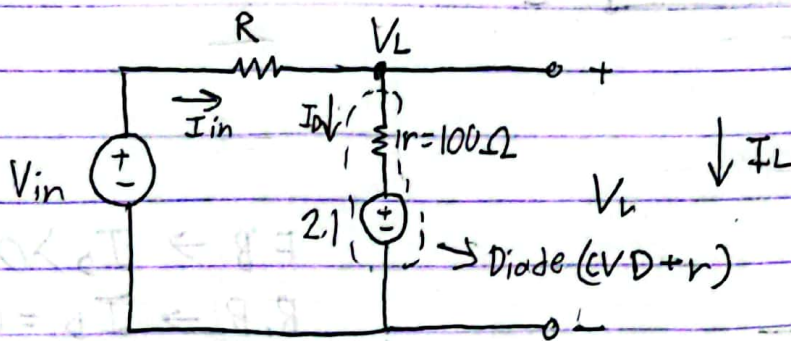
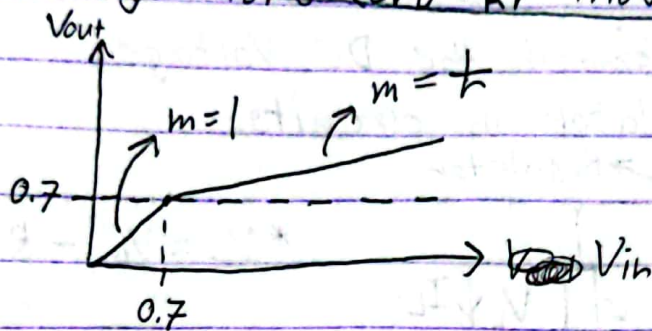
* V_{in} should be high also, for the above reason.

* Multiple diodes can be connected in series to each other in order to ~~in~~ increase Voltage across the load (V_L)

* Regulator Equivalent Circuit:



Real Regulators (CVD + R_r model diode):



$$V_L \left(\frac{1}{R} + \frac{1}{r} \right) - V_{in} \left(\frac{1}{R} \right) - 2.1 \left(\frac{1}{r} \right) = 0$$

$$V_L = \left(\frac{r}{R+r} \right) V_{in} + 2.1 \quad \text{--- (1)}$$

* From eqn - (1), It is visible that V_L depends on $\left(\frac{r}{R+r} \right)$ and V_{in} , but V_{in} is not constant so $\left(\frac{r}{R+r} \right)$ is what mainly keeps V_L constant.

* $\left(\frac{r}{R+r} \right)$ needs to be very small to maintain a constant V_L . To do this the value of r needs to be small and the value of R needs to be big.

* However, keeping R big may cause problems because it will decrease the value of I_{in} which in turn may lower I_D and the diode may go to R.B.

Performance Measure:

① Line Regulation

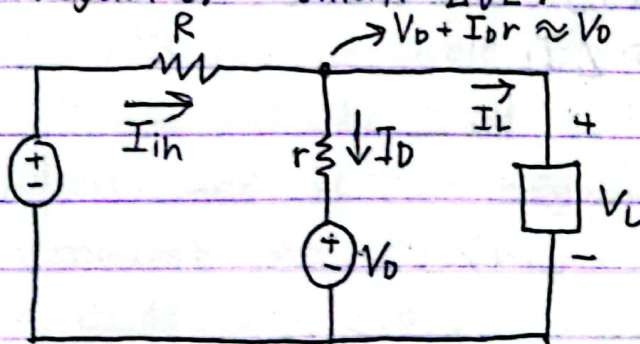
② Load "

* Line Regulation:

- It measures the change in Load Voltage (ΔV_L) if V_{in} changes by 1V.
- If the regulator is good ΔV_L would be very small.

* Load Regulation:

- It measures the change in Load ^{Voltage} ~~Current~~ ($\frac{\Delta V_L}{\Delta I_L}$) if I_L changes by 1 mA.
- Good regulator = small ΔV_L .



* For the above circuit,

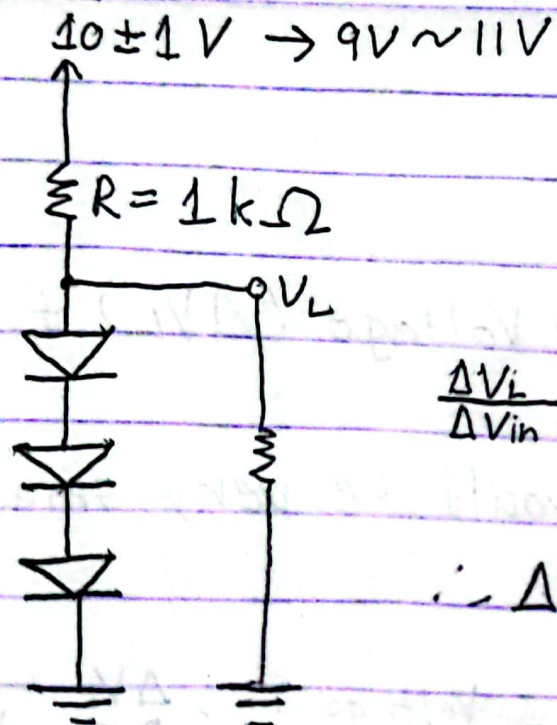
* Line Regulation eqn,

$$\frac{\Delta V_L}{\Delta V_{in}} = \frac{r}{R+r}$$

* Load Regulation eqn,

$$\frac{\Delta V_L}{\Delta I_L} = - \frac{Rr}{R+r}$$

* Example:



Each diode res = 3.2Ω , $V_D = 0.7V$
Calc Line and Load regulation.

Line Regulation,

$$\frac{\Delta V_L}{\Delta V_{in}} = \frac{r}{R+r} = \frac{3 \times 3.2}{1000 + 3 \times 3.2} = 9.5 \times 10^{-3}$$

$$\therefore \Delta V_L = 9.5 \times 10^{-3} \times \Delta V_{in}$$

$$I_L = \frac{V_L}{R_L} = \frac{2.1}{1000} = \Delta I_L = 2.1 \text{ mA}$$

Load Regulation,

$$\frac{\Delta V_L}{\Delta I_L} = -\frac{R_r}{R+r} = \frac{-1000 \times 3 \times 3.2}{1000 + 3 \times 3.2} = -9.51$$

$$\therefore \Delta V_L = -9.51 \times \Delta I_L$$