

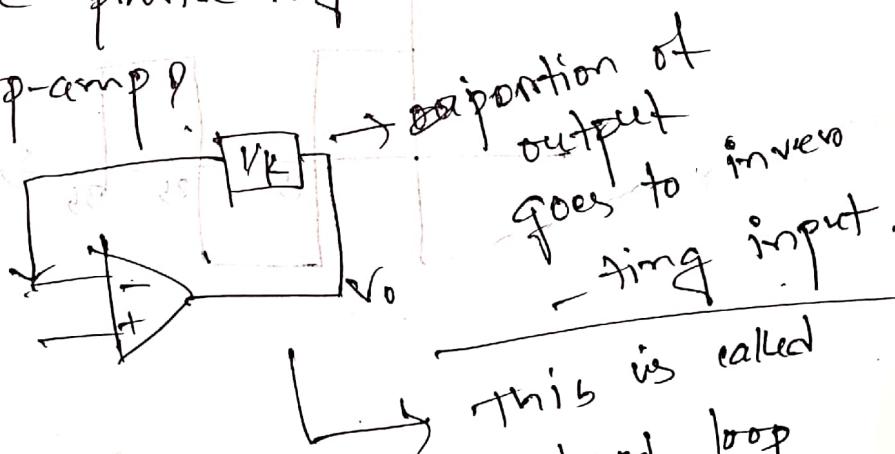
Now if we want to get stable output then
- we need negative feedback.

negative feedback

* This -ve feedback not only use for op-amp. it can be also used for any control device for proper control. [For example, in Following robot]

So, how we provide negative feedback

What happens in op-amp?



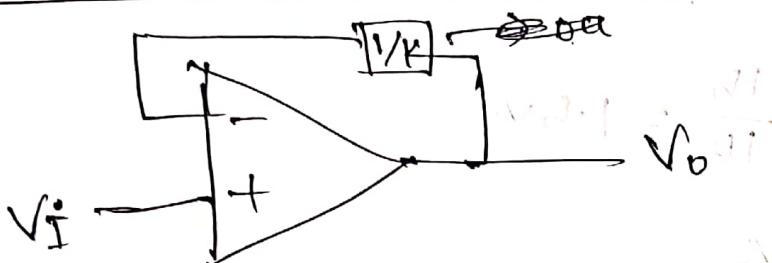
* There's also positive feedback (if its connect to output)

but that's not good

also called transfer ratio

used for pulse generator

with the help of Schmidt trigger

Ex of negative feedback:

Let's assume $A = 1000$, $k = 10$

If $k = 10$
then $\frac{1}{k} = \frac{1}{10}$
of output
is fed back
to -ve
input

if there were no feedback

$$\text{if } \text{out signal } V_b^+ \text{ or } V_b^- \Rightarrow V_I = 5 \text{ V} \quad \therefore V_d = +\text{ve} \\ \therefore V_o = A V_I = 1000 \times 5 = 5000 \text{ V}$$

for feedback $V_b^+ = 5 \text{ V}$ and $V_b^- = 0 \text{ V}$

now

initially, $V_o = 0 \text{ V}$

$$\therefore V_d = \frac{V_o}{10} = 0$$

$$\therefore V_d = V_+ - V_-$$

$$= 5 - 0 = 5$$

$$\therefore V_o = \frac{V_d}{A} = \frac{5}{1000} \times 1000 = 5 \text{ V}$$

Now $V_b^+ = 5 \text{ V}$ and $V_b^- = 5 \text{ V}$

Now $V_d = V_+ - V_- = 5 - 5 = 0 \text{ V}$

Now $V_o = \frac{V_d}{A} = \frac{0}{1000} = 0 \text{ V}$

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$$V_o = 15$$

$$\therefore V_- = \frac{V_o}{10} = \frac{15}{10} = 1.5 \text{ V}$$

$$\therefore V_d = V_+ - V_-$$

$$= 5 - 1.5 = 3.5 \text{ V} \quad (\text{decrease})$$

$$\therefore V_o = 3 \times 3.5 = 10.5 \text{ V}$$

Due to feed back now its gradually going down.

50 ^{negative feedback} here increase output if it decrease and decrease output if it increases.

$$V_o = 10.5 \text{ V}$$

$$\therefore V_- = \frac{V_o + 5}{10} = 1.00 \text{ V}$$

$$\therefore V_d = V_+ - V_- = 5 - 1.00 = 3.95$$

$$\therefore V_o = 3.95 \times 3 = 11.85 \text{ V} \quad (\text{increase})$$

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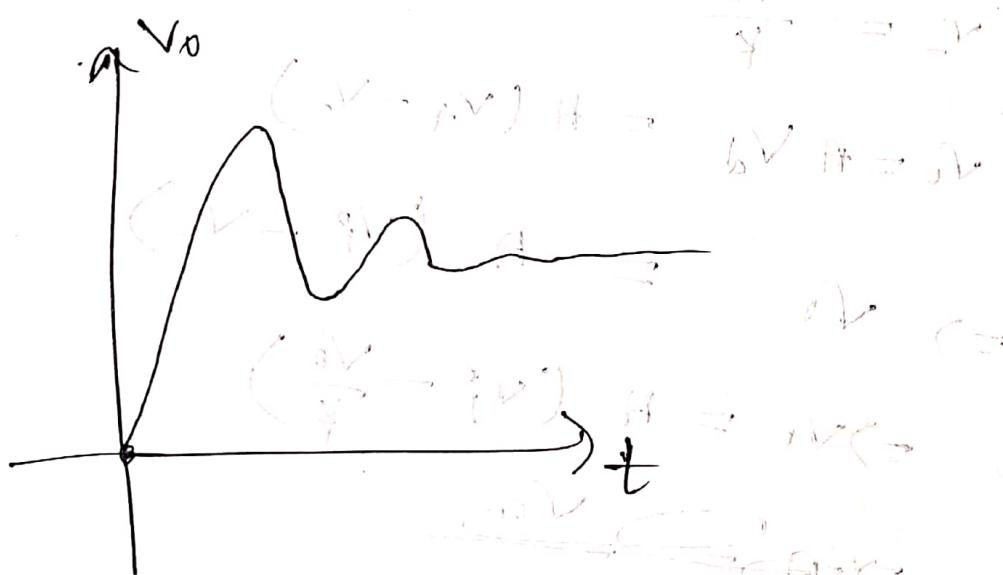
$$V_o = 11.85$$

$$V_f = \frac{11.85}{10} = 1.185 \text{ V}$$

$$\sqrt{A} = 5 - 1.185 = 3.815$$

$$\therefore V_o = 3 \times 3.815 = 11.445$$

hence change difference gap decreasing gradually



this is graph of response of a feedback system. It initially has overshoot then goes gradually get stabled

so it makes the op-amp stable.

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\therefore what's the relation between v_0^o and v_i^o

$$v_0^o = \boxed{2.31} \cdot v_i^o \quad \therefore v_0^o = 2.31 \times 5 \\ \text{Grain} \quad = 11.53$$

$$\therefore v_- = \frac{v_0^o}{k}$$

$$v_0^o = A v_d = A (v_+ - v_-)$$

$$\Rightarrow v_0^o = A (v_i^o - v_-)$$

$$\Rightarrow v_i^o = A \left(v_i^o - \frac{v_0^o}{k} \right)$$

$$\Rightarrow \cancel{A} = \cancel{v_0^o}$$

$$\Rightarrow v_0^o \left(1 + \frac{A}{k} \right) = A v_i^o$$

$$\Rightarrow v_0^o = \boxed{\frac{A}{1 + \frac{A}{k}}} v_i^o$$

Grain

$$\text{For this case } \text{Grain} = \frac{A}{1 + \frac{A}{k}} = \frac{3}{1 + \frac{3}{10}} = \frac{3}{13} = 2.31$$

(A)

Now if $A = \infty$ too large value.

the gain should be $\rightarrow K$

, on that time.

$$\text{Q} V_o = K V_i$$

(B)

so since here gain the internal gain of op-amp is ∞ (too large) we get finite gain of op-amp using negative feedback. following off $\frac{V_o}{V_i}$.

* And using this feedback property we can perform any mathematical operation.

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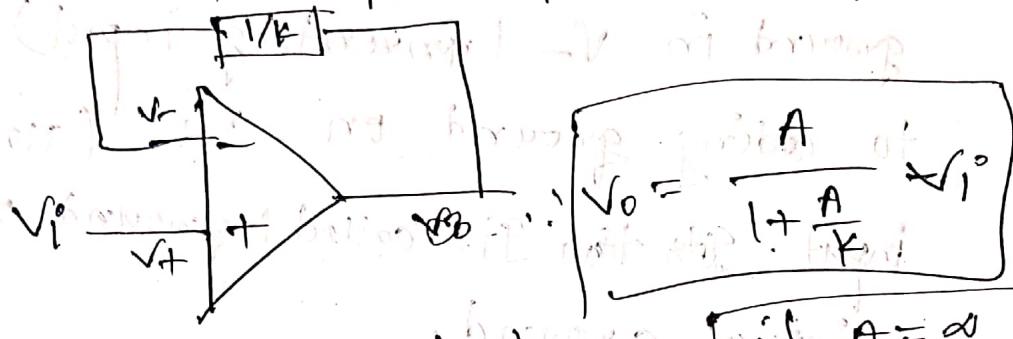
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(Rough)

Feedback [closed loop configuration] (negative feedback)



\Rightarrow provide stable output.

- Now $V_o = \text{stable}$

$$V_o = A V_d$$

$$\therefore V_d = \frac{V_o}{A}$$

now if $V_o = 3V$ $A = \infty$

$$\therefore V_d = \frac{3}{\infty} = 0$$

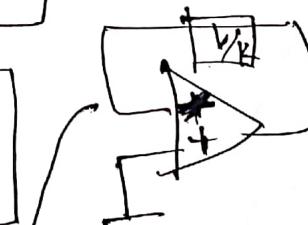
\therefore In negative feedback $V_d = 0$

$$\Rightarrow V_+ - V_- = 0$$

$$\therefore V_+ = V_-$$

so if $V_+ = 0$

$$\therefore V_- = 0$$



\Rightarrow it also becomes zero.

And this is called virtual ground.

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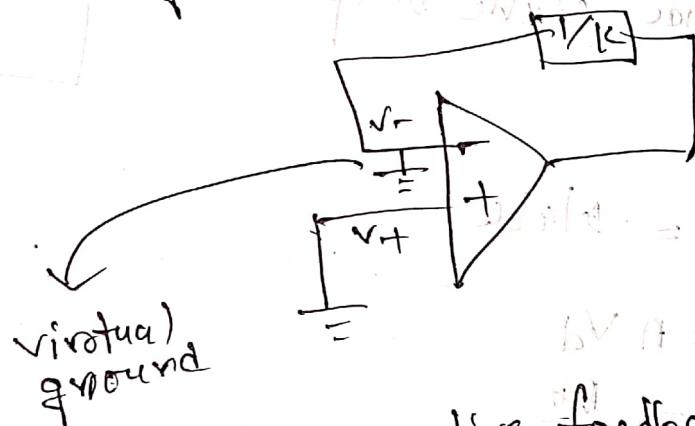
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Practical

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Therefore, when we get zero voltage on ground in V_- (inverting input) due to adding ground on V_+ (non-inverting) input. This is called (ground on V_-) virtual ground.



For negative feedback

$$V_d = 0$$

$$\therefore V_+ - V_- = 0 \Rightarrow \frac{V_+}{V_-} = 1$$

$$V_+ = V_-$$

$$\therefore I_+ = 0, I_- = 0$$

$$I_+ = I_-$$

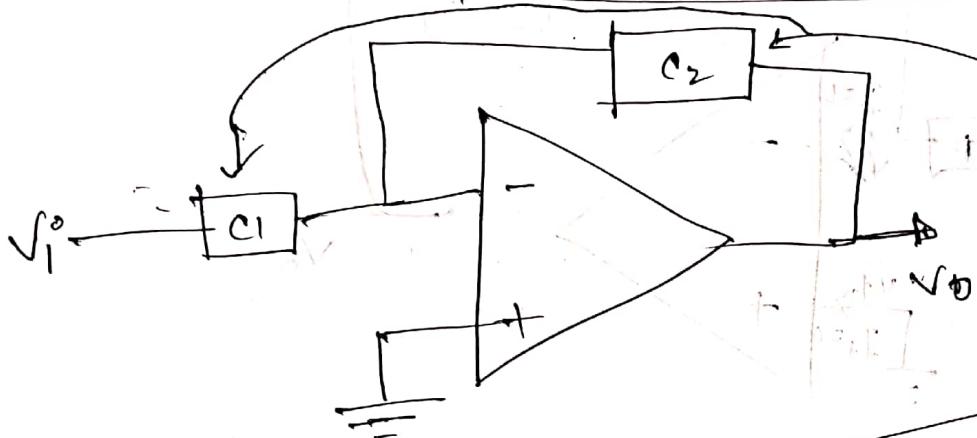
$$0 = V_+ - V_-$$

$$0 = V_+$$



Therefore positive and negative terminals

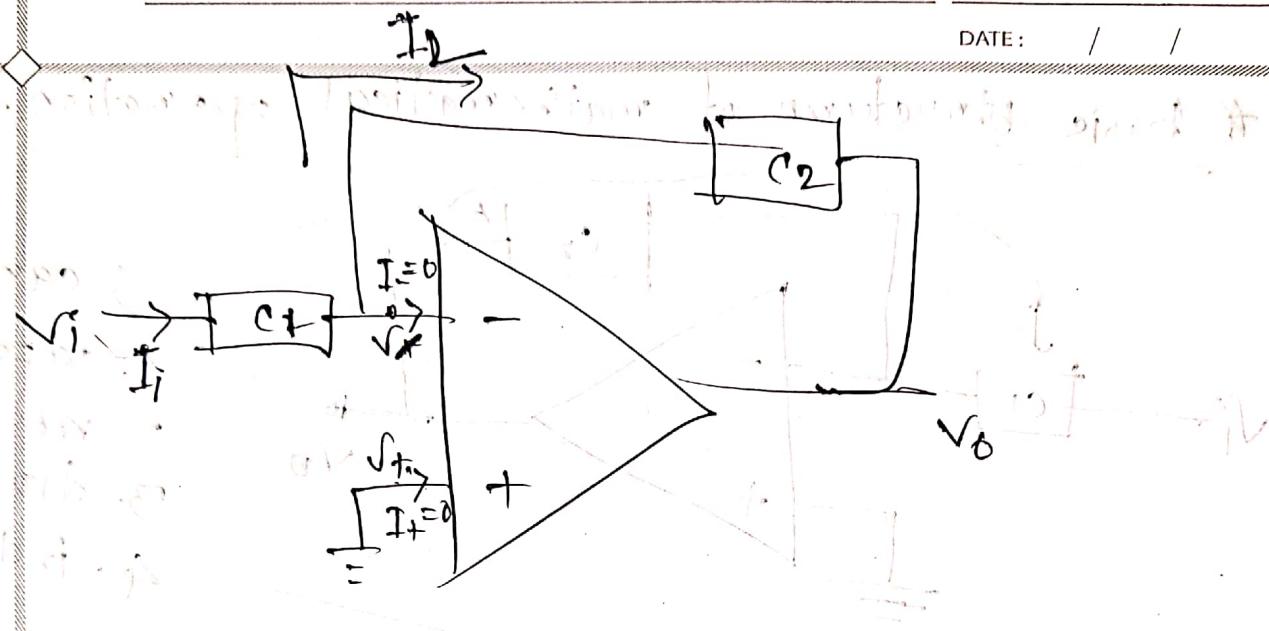
* Basic structure of mathematical operation.



- can be
1. capacitors
 2. resistor
 3. diod
 4. inductors

Hence negative input. because if we provide input in positive ~~then~~ terminal. the term 1 + something will come. that for preventing that we provide input in negative

→ depending on the element the relation between input and output changes.



since $V_+ = 0$

$I_1 = 0$ (no current through virtual ground)

since virtual ground

$I_2 = 0$ (no current through virtual ground)

again $I_f = 0$ (no current through virtual ground)

* Have to remember for equation derivation:

$$\text{step 1. } \textcircled{1} \quad V_d = 0 \Rightarrow V_+ = V_- = ?$$

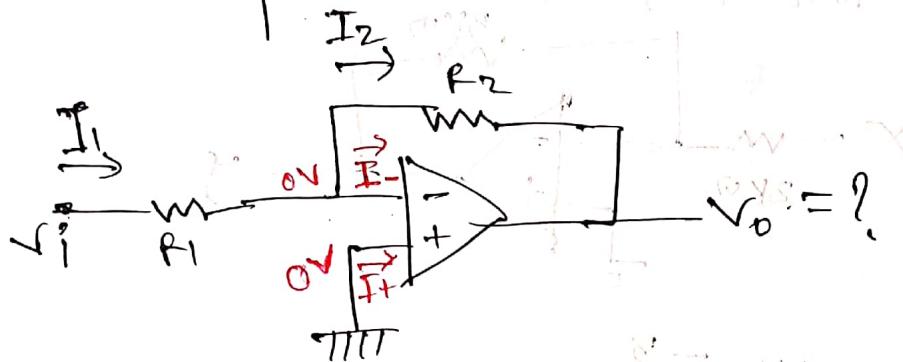
$$\textcircled{2} \quad I_1 = ?$$

$$\text{step 2. } \textcircled{3} \quad I_2 = I_1 \text{ (why?)}$$

$$\text{step 3. } \textcircled{4} \quad V_0 = kV_L \text{ (Ohm's law approach)}$$

(A) # Inverting amplifiers:

If we replace C_1 and C_2 with resistance



$$\therefore I_1 = \frac{V_i - 0}{R_1} = \frac{V_i}{R_1}$$

now since $I_- = 0$

$$\therefore I_2 = I_{in} = \frac{V_i}{R_1}$$

$$\therefore I_2 = \frac{0 - V_o}{R_2}$$

$$\Rightarrow V_o = -I_2 R_2$$

$$= -\frac{V_i}{R_1} \times R_2$$

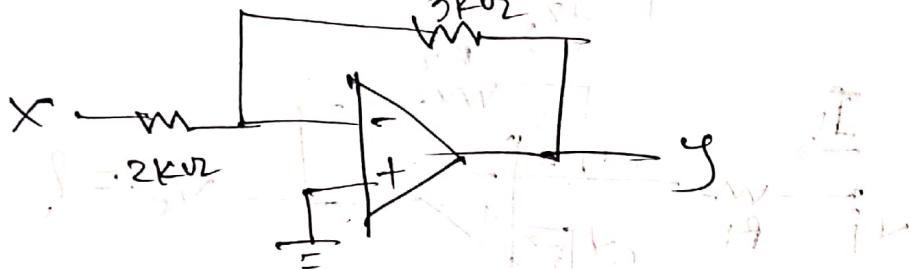
$$= \left(-\frac{R_2}{R_1} \right) V_i$$

$$\boxed{\therefore V_o = \left(-\frac{R_2}{R_1} \right) V_i}$$

amplification & since we're negative that's why
since we're negative that's why
inverting. Gain = $-\frac{R_2}{R_1}$

Q. Now what will be relation between X and y

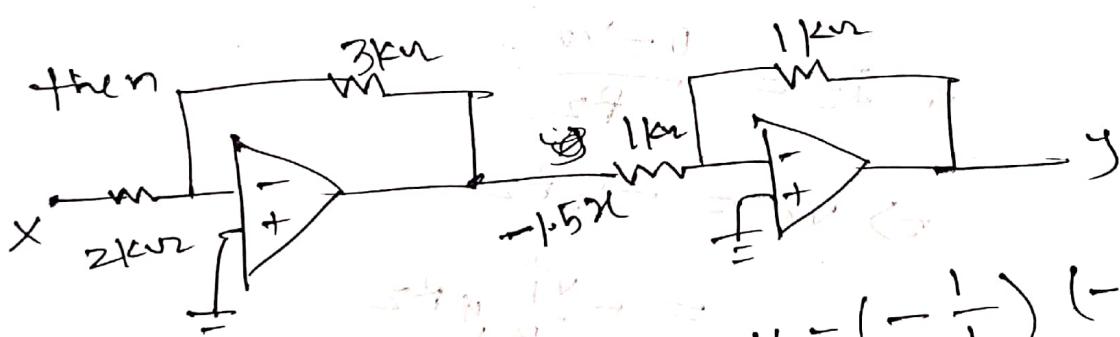
for this circuit.



$$\therefore y = \frac{3}{2}x$$

$$\Rightarrow y = -1.5x$$

Now what if we want $y = 1.5x$



$$y = \left(-\frac{1}{1}\right) (-1.5x)$$

This is called
cascading amplifier.

It provide one amplifier
input to another amplifier

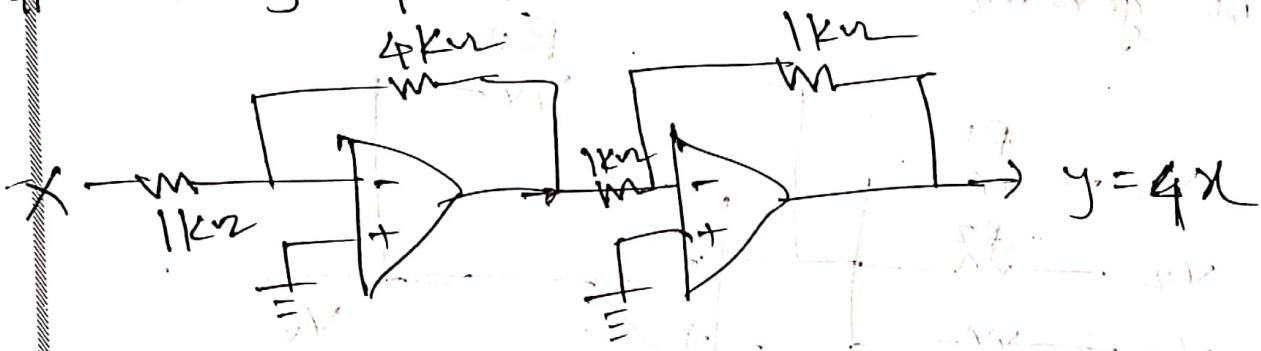
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$$3x + 4y = 5$$

I can achieve
by differentiating
amplifier.

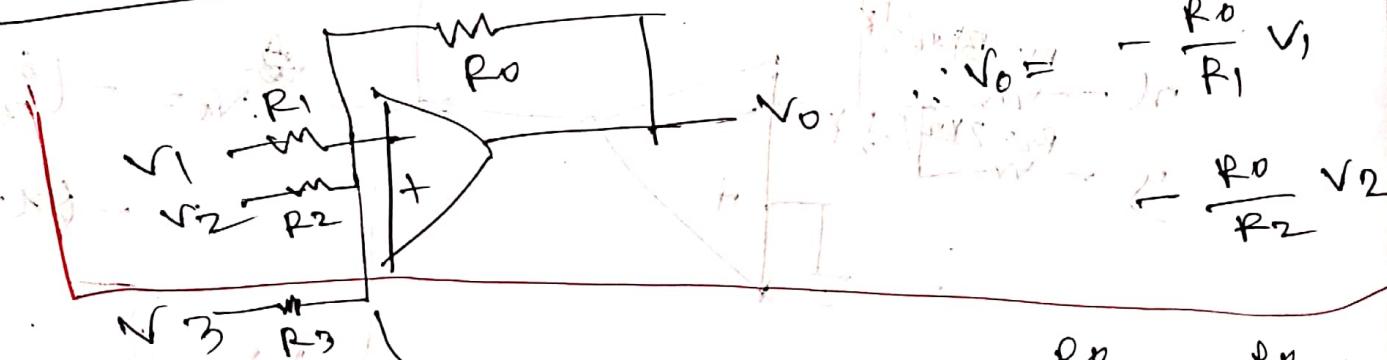
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Do it $y = 4x$?



So, inverting amplifiers basically multiply a input voltage with constant.

(2) Inverting adder (summing amplifier):



$$V_o = - \frac{R_o}{R_1} V_1 - \frac{R_o}{R_2} V_2$$

$$- \frac{R_o}{R_3} V_3$$

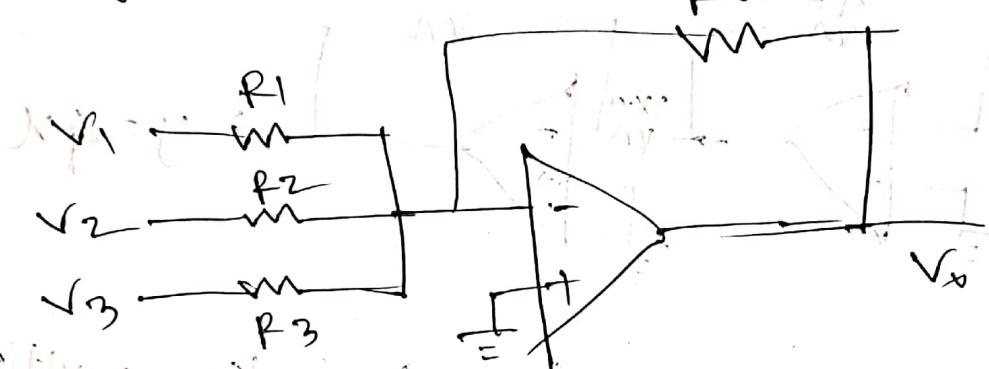
if connect it
can use super
position
theorem
to get understanding

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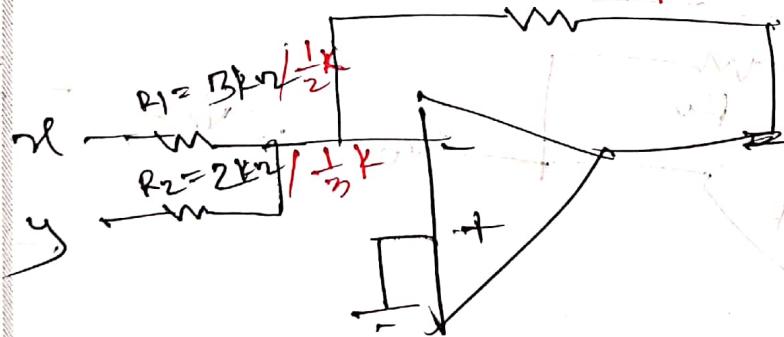
AO general



$\therefore V_x = \frac{R_f}{R_1} V_1 + \frac{R_f}{R_2} V_2 + \frac{R_f}{R_3} V_3$

For example: Ex 1:

$$f(x, y) = -(2x + 3y)$$



$$V_x = -\left(\frac{1}{2}x + \frac{1}{3}y\right)$$

$$= -(2x + 3y)$$

$$V_o = -\left(\frac{1}{2}x + \frac{1}{3}y\right)$$

$$= -(2x + 3y)$$

same output

Sub.: _____

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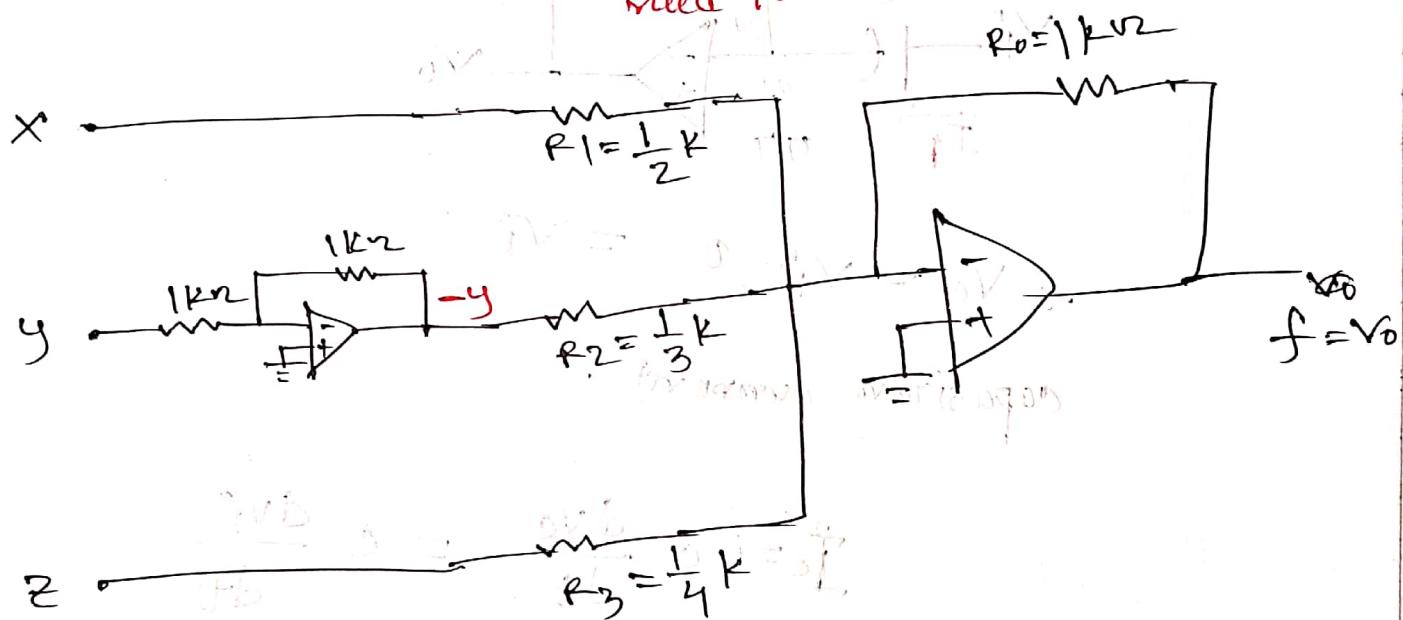
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Ex 2:

$$f = -2x + 3y - 4z \quad \text{from question}$$

$$= -(2x - 3y + 4z)$$

\downarrow
need to invert this first



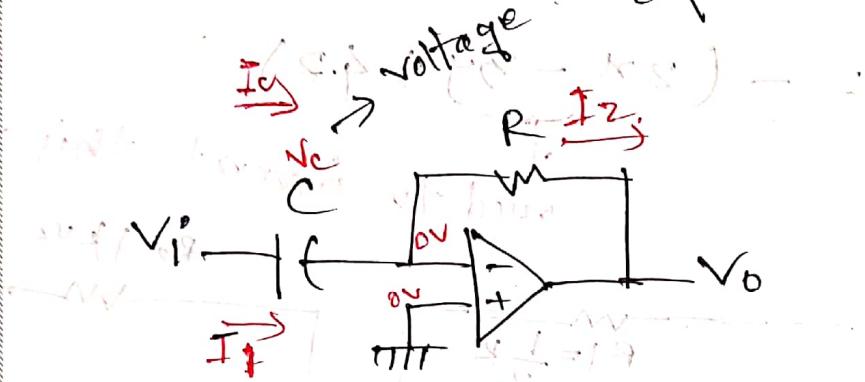
$$f = -2x + 3(-y) - 4z$$

$$\therefore f = 16x - 18y - 4z$$

$$f = 16x - 18y - 4z$$

(3)

Differentiation: Using across capacitor



$$\therefore V_C = V_i - 0 = V_i$$

capacitor current

$$I_c = C \frac{dV_C}{dt} = C \frac{dV_i}{dt}$$

$$\therefore I_2 = I_1 \quad \text{since} \quad I^+ = 0 \\ I^- = 0$$

$$\therefore I_2 = I_1 = I_c$$

$$\therefore I_2 = I_1 = I_c = C \frac{dV_i}{dt}$$

$$\text{now } I_2 = \frac{0 - V_o}{R}$$

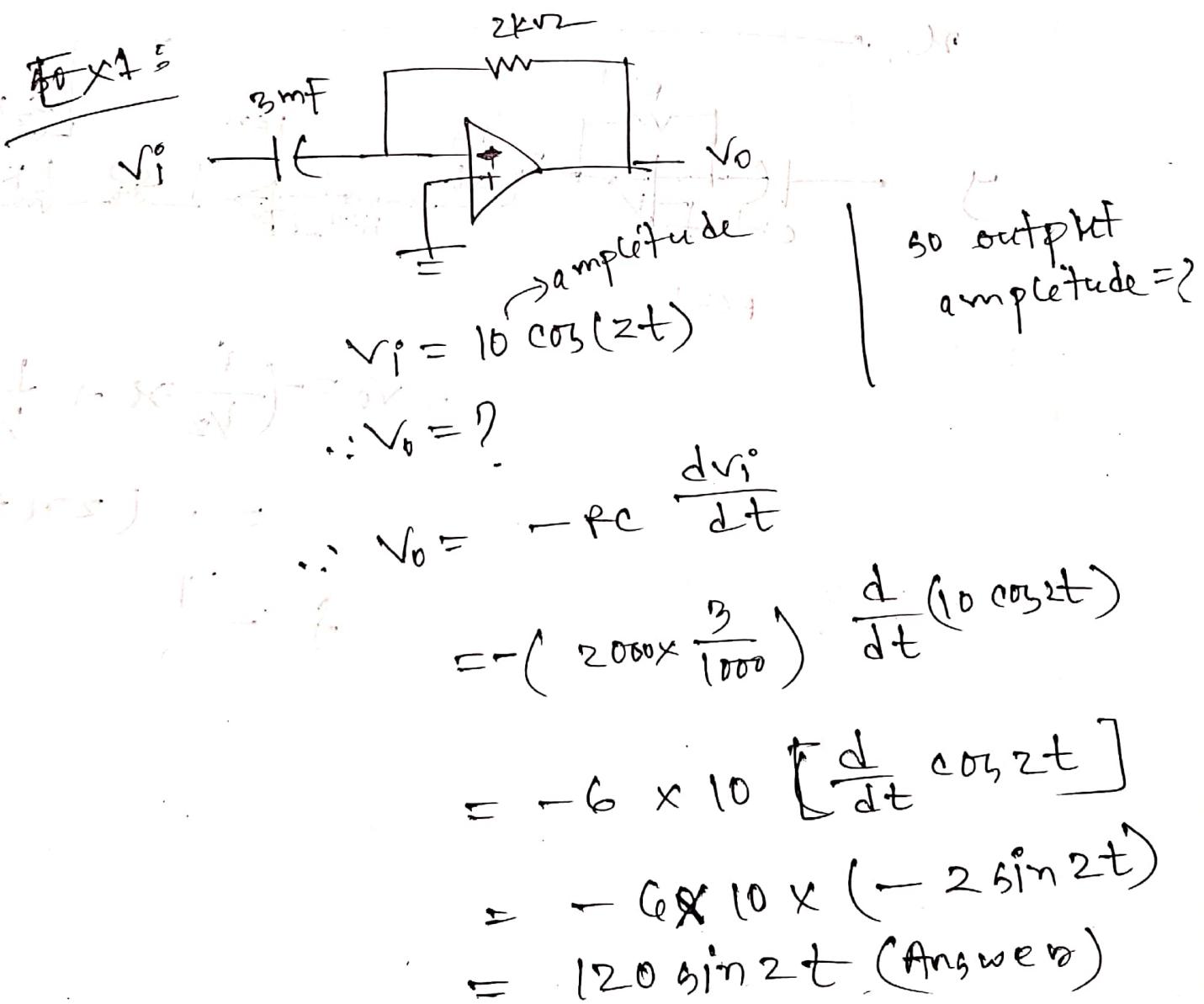
$$\therefore V_o = -I_2 R$$

$$\therefore V_o = -RC \frac{dV_i}{dt}$$

Now what if $\frac{d}{dt} (\sin(100t)) = 100 \cos 100t$

$$\text{if } \frac{d}{dt} e^{5t} = 5e^{5t}$$

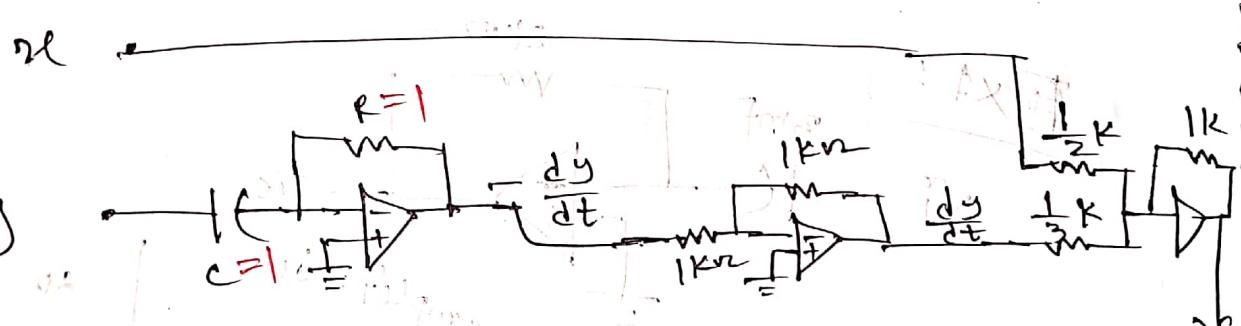
$$\text{if } \frac{d}{dt} \cos(t) = -\sin t$$



* Ques: Design a circuit which it that

$$\text{Ans: } f = -2x - 3 \frac{dy}{dt}$$

$$\text{Ans: } f = -\left(2x + 3 \frac{dy}{dt}\right)$$



$$V_o = -\left(\frac{1}{1/2}x + \frac{1}{1/3} \frac{dy}{dt}\right) \\ = -\left(2x + 3 \frac{dy}{dt}\right)$$

Chennai b
fb (000000) → f ↑

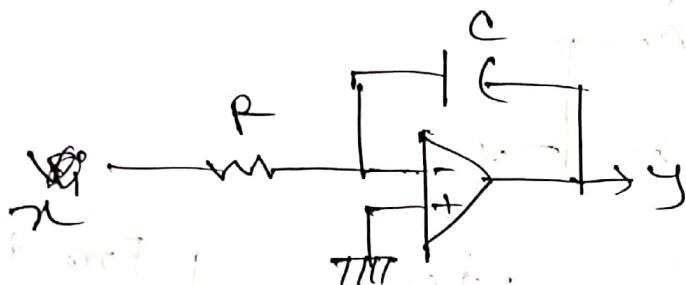
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Integration

Examples. II



Derive it by own

$$\boxed{y = -\frac{1}{RC} \int x dt}$$

Logarithm

(IT block is given) writing part II



$$y = \sqrt[n]{x} = x^{1/n}$$

(x) base logarithm
(x) differentials

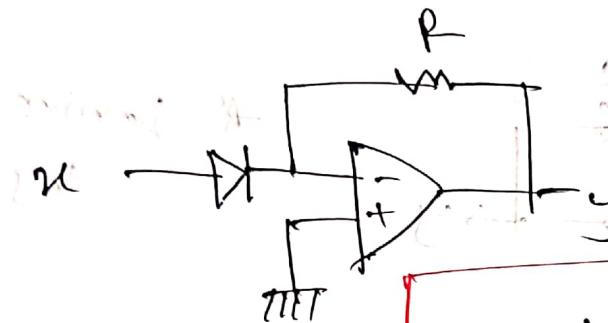
(x) natural log

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Exponential



$$y = -e^x$$

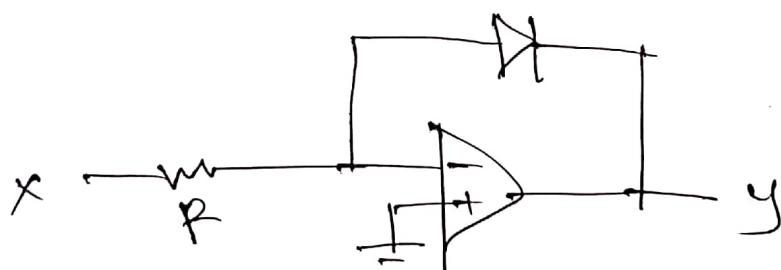
* condition

$$\left. \begin{array}{l} I_S R = 1 \\ V_T = 1 \end{array} \right\}$$

For diod

$$I_D = I_S \exp \left(\frac{V_D}{V_T} \right)$$

Logarithm (Inverse of exponential)



$$\therefore y = -\ln(x)$$

* condition same as exponential operation

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* so addition and subtraction can be done
 by inverting addends.

* And for multiplication and division we can use logarithm and exponential circuit.

For example:

$$\textcircled{1} \quad \ln(\exp(a)) = a \quad | \quad e^{\ln a} = a$$

$$\textcircled{2} \quad \ln(ab) = \ln a + \ln b$$

for $f = xy$, then

$$\begin{aligned} & x \rightarrow \ln x \\ & y \rightarrow \ln y \end{aligned} \quad \cancel{\text{add}} \quad \ln x + \ln y \Rightarrow \ln(xy)$$

$\Downarrow \exp^{\ln(xy)}$

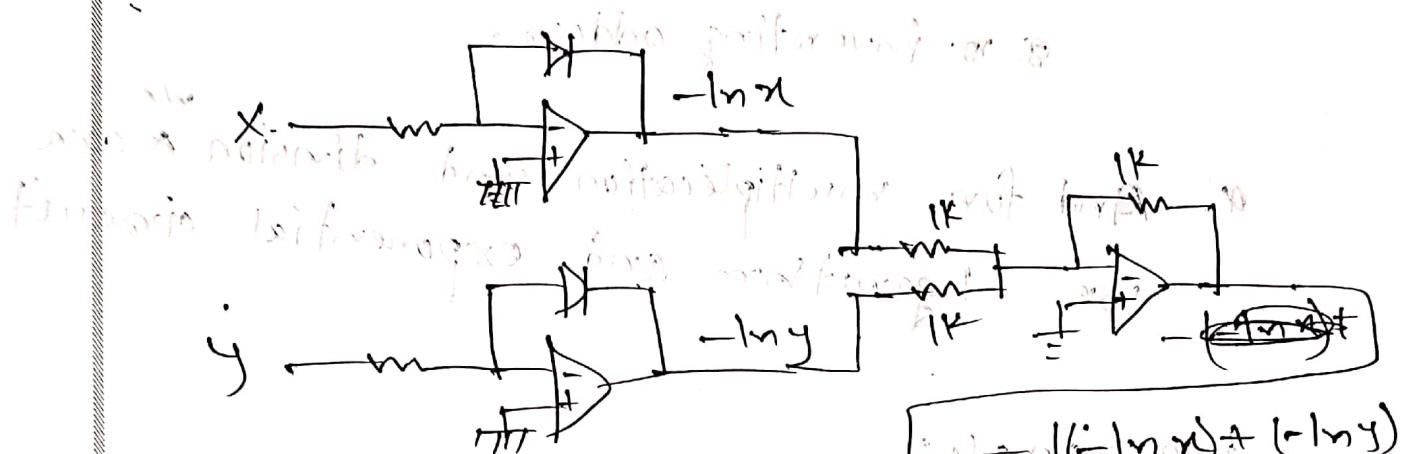
(xy)

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Graph and plot performance of two variables x & y

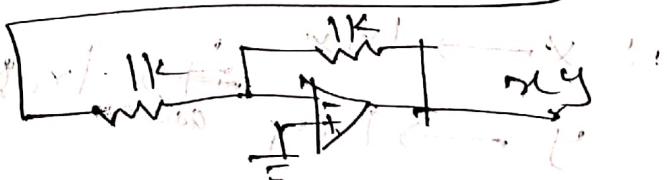
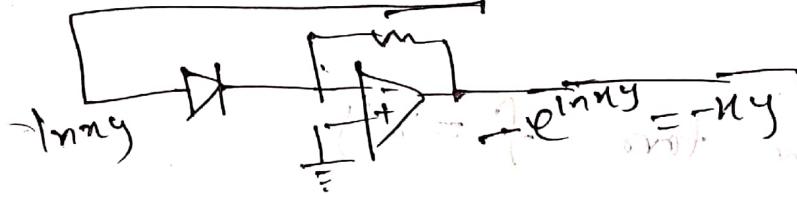


$$\text{Output} = -\ln(x+y)$$

$$\begin{aligned} \text{Output} &= -\ln(x+y) \\ &= -\ln(x) - \ln(y) \end{aligned}$$

$$\begin{aligned} \text{Output} &= -\ln(y) \\ &= \text{Output } (ii) \end{aligned}$$

double loop



(i) and (ii) Plotting

United

(ii)

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Homework:

$$\textcircled{1} \quad \underline{\underline{f}} = -2x + f$$

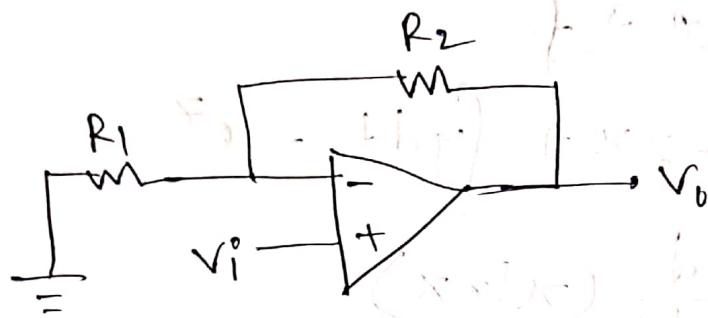
$$\textcircled{1} \quad f = -2x + \int g dt = e^z$$

$$\textcircled{2} \quad f = \frac{d}{dt} (u \ln x)$$

$$u \left(\frac{du}{dt} + 1 \right) = v$$

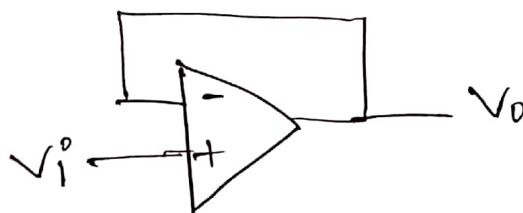


$$[v \ v]$$

Non inverting amplifiers:

$$V_0 = \left(1 + \frac{R_2}{R_1}\right) V_i$$

↓ Gain

Voltage followers:

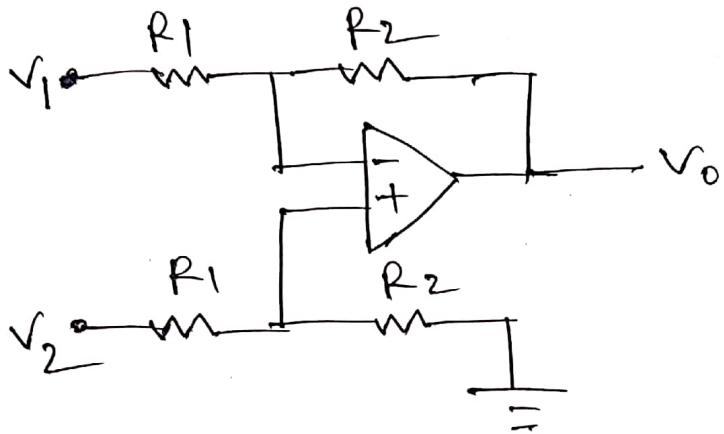
$$V_0 = V_i$$

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Difference amplifier:



$$V_o = \frac{R_2}{R_1} (V_2 - V_1)$$