

EXPERIMENT – 3.3

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Aim of the practical Write a program to demonstrate the traversal of graph using

Breadth first search

Depth first search

Algorithm:

Breadth First search

Step 1: SET STATUS = 1 (ready state) for each node in G.

Step 2: Enqueue the starting node A and set its STATUS = 2 (waiting state)

Step 3: Repeat Steps 4 and 5 until QUEUE is empty

Step 4: Dequeue a node N. Process it and set its STATUS = 3 (processed state).

Step 5: Enqueue all the neighbours of N that are in the ready state (whose STATUS = 1) and set their STATUS = 2 (waiting state) [END OF LOOP]

Step 6: EXIT

Depth First Search

Step 1: SET STATUS = 1 (ready state) for each node in G

Step 2: Push the starting node A on the stack and set its STATUS = 2 (waiting state)

Step 3: Repeat Steps 4 and 5 until STACK is empty

Step 4: Pop the top node N. Process it and set its STATUS = 3 (processed state)

Step 5: Push on the stack all the neighbors of N that are in the ready state (whose STATUS = 1) and set their STATUS = 2 (waiting state) [END OF LOOP]

Step 6: EXIT

Program code:

Breadth first Search

```
#include <iostream>
#include <list> using
namespace std; class
Graph {
    int numVertices;
    list<int>* adjLists;
    bool* visited; public:
    Graph(int vertices); void
    addEdge(int src, int dest);
    void BFS(int startVertex);
};
```

```
Graph::Graph(int vertices) {
    numVertices = vertices; adjLists =
    new list<int>[vertices];
}
void Graph::addEdge(int src, int dest) {
    adjLists[src].push_back(dest);
    adjLists[dest].push_back(src);
}
void Graph::BFS(int startVertex) {
    visited = new bool[numVertices]; for
    (int i = 0; i < numVertices; i++)
    visited[i] = false; list<int>
    queue; visited[startVertex] =
    true;
    queue.push_back(startVertex)
    ; list<int>::iterator i; while
    (!queue.empty()) {
        int currVertex = queue.front(); cout << "Visited " << currVertex << " ";
        queue.pop_front(); for (i = adjLists[currVertex].begin(); i !=
        adjLists[currVertex].end(); ++i) {
            int adjVertex = *i; if
            (!visited[adjVertex]) {
                visited[adjVertex] = true;
                queue.push_back(adjVertex);
            }
        }
    }
} int main()
{ Graph
g(5);
g.addEdge(0, 1);
g.addEdge(0, 2);
g.addEdge(1, 2);
g.addEdge(2, 0);
g.addEdge(2, 3);
g.addEdge(3, 3);
g.BFS(3);
return 0;
}
```

Depth first Search-

```
#include<bits/stdc++.h
> using namespace std;
class Graph { int V;
list<int> *adjList;
public: Graph(int V)
```

```
{ this->V = V; adjList =
new list<int>[V];
} void addEdge(int v,
int w)
{ adjList[v].push_back(w);
} void
DFS();
void DFSUtil(int s, vector<bool> &visited);
};
void Graph::DFSUtil(int s, vector<bool> &visited)
{ stack<int> dfsstack;
dfsstack.push(s); while
(!dfsstack.empty())
{ s = dfsstack.top();
dfsstack.pop();
if (!visited[s])
{ cout << s
<< " ";
visited[s] = true;
} for (auto i = adjList[s].begin(); i !=
adjList[s].end(); ++i)
if (!visited[*i]) dfsstack.push(*i);
}
}

void Graph::DFS()
{ vector<bool> visited(V,
false); for (int i = 0; i < V; i++)
if (!visited[i])
DFSUtil(i, visited);
}
int main()
{
    Graph gidfs(7); gidfs.addEdge(0,
1); gidfs.addEdge(0, 2);
gidfs.addEdge(0, 3);
gidfs.addEdge(1, 2);
gidfs.addEdge(2, 4);
gidfs.addEdge(3, 3);
gidfs.addEdge(4, 4);
cout << "Output of Iterative Depth-first traversal:\n";
gidfs.DFS(); return 0;
}
```



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Output:

Breadth first Search-

```
Visited 3 Visited 2 Visited 0 Visited 1  
PS C:\Codes\cpp> cd "c:\Codes\cpp\" ; if ($?) { g++ graph_bfs.cpp -o graph_bfs } ; if ($?) { .\graph_bfs }  
Visited 3 Visited 2 Visited 0 Visited 1  
PS C:\Codes\cpp> █
```

Depth first Search-

```
PS C:\Codes\cpp> cd "c:\Codes\cpp\" ; if ($?) { g++ graph_dfs.cpp -o graph_dfs } ; if ($?) { .\graph_dfs }  
Output of Iterative Depth-first traversal:  
0 3 2 4 1  
PS C:\Codes\cpp> █
```