

Table 1: Global Parameters and Notations

Notation	Description
$\Phi$	Set of DAGs (Directed Acyclic Graphs) with tasks and dependencies
$D$	Set of deadlines $\{D_1, D_2, \dots, D_n\}$ for each DAG
$C$	Set of heterogeneous cores with voltage-frequency levels
$P$	Power consumption profiles for tasks on different cores
$TDP_{chip}$	Thermal Design Power limit for the entire chip
$TDP_{core}$	Thermal Design Power limit per core
$W$	Task workload matrix containing execution times for each task
$T_{i,k}$	Task instance to be scheduled
$arrival\_time_{i,k}$	Arrival time of task instance $(i, k)$
$deadline_{i,k}$	Deadline of task instance $(i, k)$
$S$	Current schedule state
$partitions$	Available time slots per core
$PPL$	Power profile list tracking chip-level power usage

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**Algorithm 1** Schedule multiple DAGs on multicore environment

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1: Inputs:  $\Phi, D = \{D_1, D_2, \dots, D_n\}, C, P, TDP_{\text{chip}}, TDP_{\text{core}}, W$ 
2: Outputs:  $S$  or FAILURE
3: function SCHEDULEDAGS
4:    $(\text{schedule}, \text{free\_slots}, \text{power\_usage}, \text{all\_tasks}, \text{hyperperiod}) \leftarrow \text{SetupDAGEnvironment}()$ 
5:   while  $\text{all\_tasks} \neq \emptyset$  do
6:      $\text{current\_task} \leftarrow \text{select\_highest\_priority}(\text{all\_tasks})$ 
7:      $\text{allocated} \leftarrow \text{ScheduleTask}(\text{current\_task})$ 
8:     if  $\text{allocated} = 0$  then
9:       return FAILURE # Task could not be scheduled
10:    end if
11:     $\text{all\_tasks.remove}(\text{current\_task})$ 
12:  end while
13:  return  $\text{schedule}$  # Successfully scheduled all tasks
14: end function
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**Algorithm 2** Setup DAG Environment

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1: Inputs:  $\Phi, D, C, P, TDP_{\text{chip}}, TDP_{\text{core}}, W$ 
2: Outputs:  $S$ 
3: function SETUPDAGENVIRONMENT
4:    $\text{hyperperiod} \leftarrow \text{LCM}(D_1, D_2, \dots, D_n)$  # Calculate hyperperiod
5:    $\text{all\_tasks} \leftarrow \emptyset$  # Store all task instances
6:   for each DAG  $\phi \in \Phi$  do
7:      $\text{repeat\_count} \leftarrow \text{hyperperiod} / D_\phi$  # Number of repetitions
8:     for all tasks  $i$  in  $\phi$  do
9:       for  $k \leftarrow 1$  to  $\text{repeat\_count}$  do
10:         $\text{task\_start} \leftarrow (k - 1) \times D_\phi$ 
11:         $\text{task\_deadline} \leftarrow k \times D_\phi$ 
12:         $\text{all\_tasks.add}((i, k, \text{task\_start}, \text{task\_deadline}))$ 
13:      end for
14:    end for
15:  end for
16:   $\text{schedule} \leftarrow [\emptyset] \times |C|$  # Initialize empty schedule
17:   $\text{free\_slots} \leftarrow \{c : [(0, \text{hyperperiod})] \text{ for } c \in C\}$  # Track free slots
18:   $\text{power\_usage} \leftarrow [0] \times \text{hyperperiod}$  # Track power consumption
19:  return  $(\text{schedule}, \text{free\_slots}, \text{power\_usage}, \text{all\_tasks}, \text{hyperperiod})$ 
20: end function
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**Algorithm 3** Allocate Core for Task with Power-Aware Scheduling

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1: Inputs:  $\Phi, D = \{D_1, D_2, \dots, D_n\}, C, P, TDP_{\text{chip}}, TDP_{\text{core}}, W$ 
2: Outputs:  $S$ 
3: function SCHEDULETASK( $T_{i,k}$ )
4:    $start\_time \leftarrow \max(arrival\_time_{i,k}, predecessor\_finish(T_{i,k}))$ 
5:    $cores\_sorted \leftarrow \text{sort\_cores\_by\_execution\_time}(C, T_{i,k})$ 
6:    $scheduled \leftarrow false$ 
7:   while not  $scheduled$  do
8:      $found\_valid\_slot \leftarrow false$ 
9:      $selected\_core \leftarrow null$ 
10:     $selected\_partition \leftarrow null$ 
11:    for all core  $c$  in  $cores\_sorted$  do
12:      if  $found\_valid\_slot$  then
13:        break
14:      end if
15:      for all partition  $p$  in  $partitions[c]$  do
16:        if  $found\_valid\_slot$  then
17:          break
18:        end if
19:        if  $start\_time \geq p.start$  and  $start\_time + W_i \leq p.end$  then
20:          if  $start\_time + W_i \leq deadline_{i,k}$  then
21:             $can\_schedule \leftarrow true$ 
22:            for  $t \leftarrow start\_time$  to  $start\_time + W_i - 1$  do
23:              if  $PPL[t] + P_{i,c} > TDP_{\text{chip}}$  or  $P_{i,c} > TDP_{\text{core}}$  then
24:                 $can\_schedule \leftarrow false$ 
25:                break
26:              end if
27:            end for
28:            if  $can\_schedule$  then
29:               $selected\_core \leftarrow c$ 
30:               $selected\_partition \leftarrow p$ 
31:               $found\_valid\_slot \leftarrow true$ 
32:              break
33:            end if
34:          end if
35:        end if
36:      end for
37:    end for
38:    if  $found\_valid\_slot$  then
39:       $finish \leftarrow start\_time + W_i$ 
40:      Add  $(start\_time, finish, T_{i,k})$  to  $S[selected\_core]$ 
41:      for  $t \leftarrow start\_time$  to  $finish - 1$  do
42:         $PPL[t] \leftarrow PPL[t] + P_{i,c}$ 
43:      end for
44:       $p \leftarrow selected\_partition$ 
45:      if  $start\_time > p.start$  and  $finish < p.end$  then
46:        Remove  $p$  from  $partitions[selected\_core]$ 
47:        Add  $(p.start, start\_time)$  to  $partitions[selected\_core]$ 
48:        Add  $(finish, p.end)$  to  $partitions[selected\_core]$ 
49:      else if  $start\_time = p.start$  and  $finish < p.end$  then
50:        Set  $p.start$  to  $finish$ 
51:      else if  $start\_time > p.start$  and  $finish = p.end$  then
52:        Set  $p.end$  to  $start\_time$ 
53:      else
54:        Remove  $p$  from  $partitions[selected\_core]$ 
55:      end if
56:      return 1 # Successfully allocated
57:    else
58:      if  $start\_time + W_i \leq deadline_{i,k}$  then
59:        return 0 # Failed to allocate within deadline
60:      end if
61:       $start\_time \leftarrow start\_time + 1$ 
62:    end if
63:  end while
64: end function
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