#### Artificial Intelligence

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Game Theory & Adversarial Search

#### What is game theory?

 Field involving games, answering such questions as:

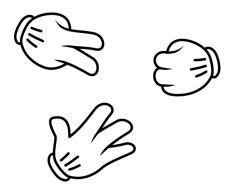
– How should you play games?

– How do most people play games?

– How can you create a game that has certain desirable properties?

# What is a game?











#### What is a game?

- Game is defined by:
  - Initial state
  - -Player(s): decision-making entities
  - -Actions(s): available actions
  - -Result(s, a): successor function or transition model
  - -Terminal(s): is the game over/state terminal
  - Utility(s, p): the value for the game ending in s for player p

#### Why study game theory in AI?

- Making good decisions ⊆ Al
- Making good decisions in games ⊆ Game Theory
- Al often created for situations that can be thought of as games



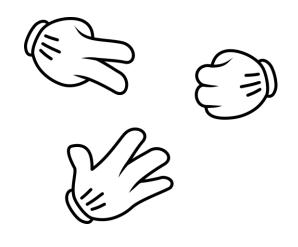
# Types of games

Sequential





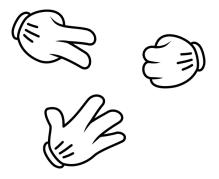
Simultaneous





# Types of games

Constant-sum



Variable-sum











# Classic game theory

• 2-player, one-turn, simultaneous-move games

|   | R                   | P        | S        |
|---|---------------------|----------|----------|
| R | 1/2, 1/2            | 0, 1     | 1, 0     |
| Р | <b>1</b> , <b>0</b> | 1/2, 1/2 | 0, 1     |
| S | 0, 1                | 1, 0     | 1/2, 1/2 |

#### Strategy

- Strategy: A specification of what to do in every single non-terminal state of the game
  - Functions from states to (probability distributions over) legal actions
    - Pure vs. Mixed
- Examples:
  - Trading: I'll accept an offer of R2m or higher, but not lower
  - Chess: Full lookup table of moves and actions to make

#### Best response

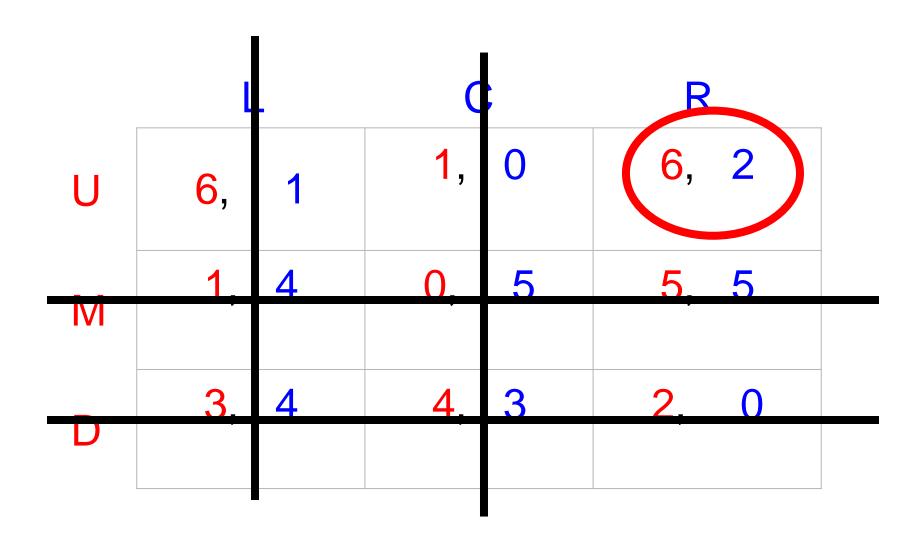
- What's the best strategy in rock-paperscissors?
  - Depends on what the other player is doing!
  - If we knew it, then we could choose the best strategy (optimisation)
  - But we don't know what they want!
    - How to reason when we don't know opponent's strategy

#### Dominated strategies

• Strategy s is dominated by  $s^*$  if  $s^*$  always gives higher payoff

|   | С                   | D    |  |
|---|---------------------|------|--|
| С | 3, 3                | 0, 5 |  |
| D | <b>5</b> , <b>0</b> | 1, 1 |  |

#### Iterated dominance



#### **Iterated Dominance**

 Iterated Elimination of Dominated Strategies (IEDS)

- Won't always produce a unique solution
- Common Knowledge of Rationality (CKR)
- "Faithful Approach"

#### Conservative approach: Maximin

Ensures best worst-case scenario

|   | L    | C    | R                   |
|---|------|------|---------------------|
| U | 6, 1 | 1,0  | <b>6</b> , <b>2</b> |
| M | 1, 4 | 5    | 5, 5                |
| D | 3, 4 | 4, 3 | 2, 0                |

#### Nash equilibrium

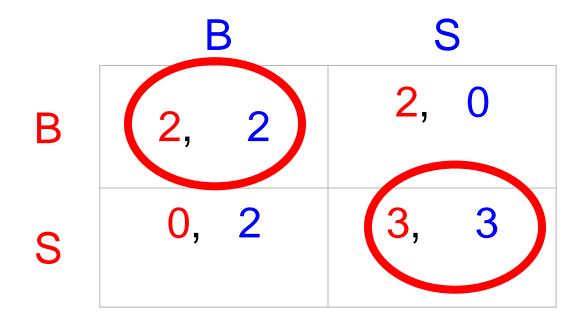
Strategy profile: specification of strategies for all players

 Nash equilibrium: strategy profile such that players are mutually best-responding

 In other words: From a NE, no player can do better by switching strategies alone

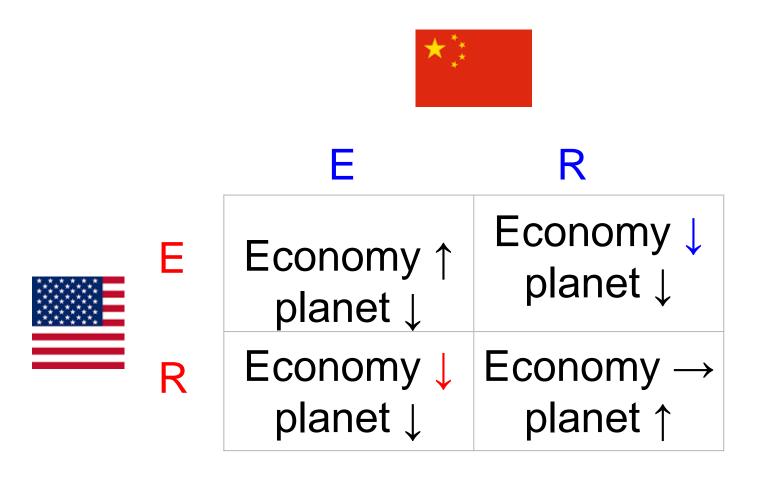
#### Stag hunt

• Strategy s is dominated by  $s^*$  if  $s^*$  always gives higher payoff



Also: play B with prob  $\frac{1}{3}$  is an NE!

#### Diplomacy/Society



#### Properties

- There is always at least one NE
  - Might be mixed

If IEDS produces unique solution, it is a NE

#### Now

Let's consider finding pure strategies in

- Sequential
- Alternating
- Constant-sum (zero-sum)
- Many-turn
- Perfect information

#### Games are big

- Tic-tac-toe  $\sim 10^3$
- Connect Four  $\sim 10^3$
- English draughts  $\sim 10^{23}$
- Othello  $\sim 10^{28}$
- Chess  $\sim 10^{44}$
- Shogi  $\sim 10^{71}$
- # atoms in observable universe  $\sim 10^{82}$
- Twixt  $\sim 10^{140}$
- Go (19x19 board)  $\sim 10^{170}$

Size ox staxe ox staxe space staxes)

#### Zero-sum games

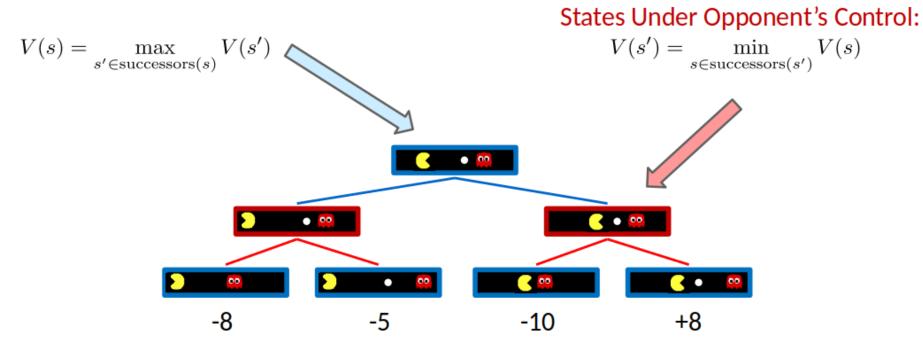
- Assume two players, competitive
  - Player 1 wins, player 2 loses and vice versa
- Game is defined by:
  - Initial state
  - *Player*(s): whose turn it is
  - Actions(s): available actions
  - -Result(s,a): successor function or transition model
  - Terminal(s): is the game over/state terminal
  - Utility(s,p): the value for the game ending in s for player p
- Zero sum game: sum of utilities for all players is constant: e.g. Win = +1, Draw = 0, Loss = -1

#### Two player, zero-sum

- Two players, MAX and MIN
- We are MAX, try to maximise utility
- Opponent is MIN, tries to minimise utility
- Denote V(s) as utility at a given state
  - Utility is known at terminal states
- Start at root node, expand tree
  - Players alternate turns
  - At level 0, us to play. Level 1, them to play, etc
- We want to compute optimal play, assuming our opponent is also optimal

Each level is called a ply

#### Example



#### **Terminal States:**

$$V(s) = known$$

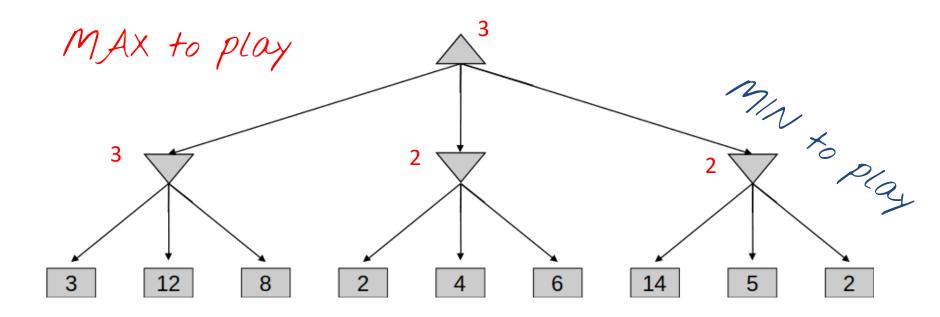
#### Calculating minimax

- Want to calculate V(s) for all s
- If s is terminal, use utility function directly
- else if player to play is MAX:
  - Value is best maximising value at state
- else player to play is MIN:
  - Value is best minimising value at state

# def value(state): if the state is a terminal state: return the state's utility if the next agent is MAX: return max-value(state) if the next agent is MIN: return min-value(state) def max-value(state): initialize v = -∞ for each successor of state: v = max(v, value(successor)) return v def min-value(state): initialize v = +∞ for each successor of state: v = min(v, value(successor)) return v

```
\begin{aligned} & \text{Minimax}(s) = \\ & \begin{cases} & \text{Utility}(s) & \text{if Terminal-Test}(s) \\ & \max_{a \in Actions(s)} \text{Minimax}(\text{Result}(s, a)) & \text{if Player}(s) = \text{max} \\ & \min_{a \in Actions(s)} \text{Minimax}(\text{Result}(s, a)) & \text{if Player}(s) = \text{min} \end{cases} \end{aligned}
```

## Example



#### Game of chance

What if there is stochasticity in the game?

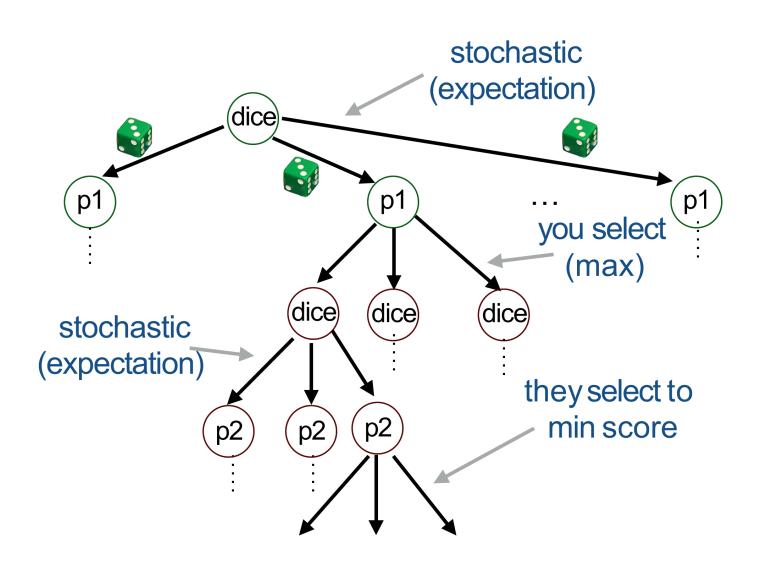


#### Stochasticity

- Be aware of who is choosing at each level
- Sometimes it is:
  - You
  - Opponent
  - Random generator

- We already have min/max nodes
  - So now add chance node

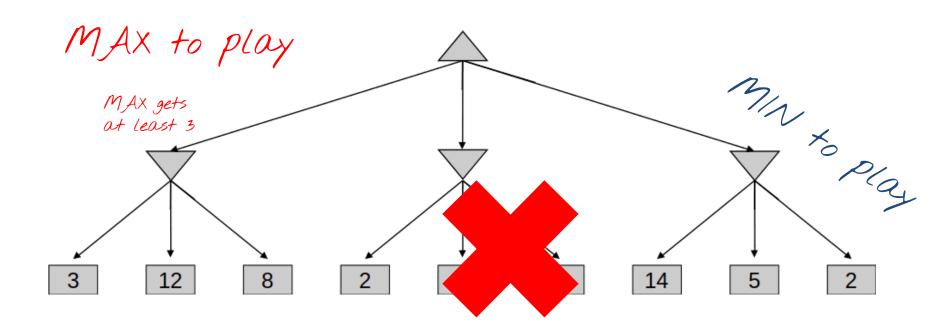
#### Expectimax



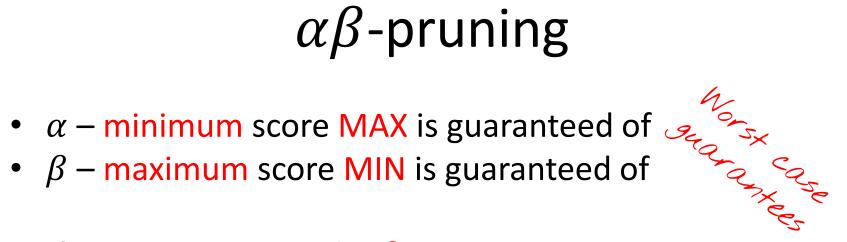
#### Minimax properties

- Like DFS:
  - Time:  $O(b^m)$
  - Space: O(bm)
- But instead of searching for single goal, we need to exhaustively try everything!
  - And we only get value at leaf nodes
- Chess, for e.g.,  $b \sim 20$ ,  $m \sim 70$ 
  - Exact solution infeasible
  - So what do we do?

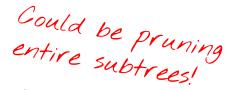
# Pruning the tree



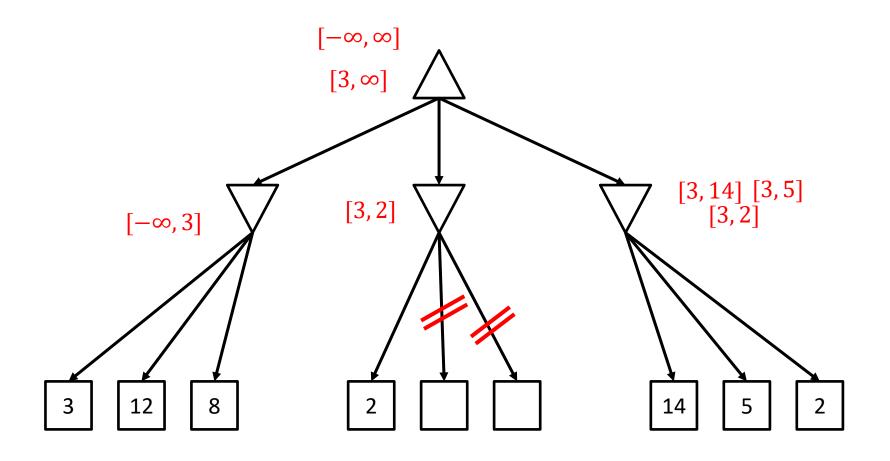
# $\alpha\beta$ -pruning



- If at a given min node,  $\beta < \alpha$ 
  - Then MIN can guarantee a score that makes MAX sad
  - So MAX will never go down this road
  - No need to expand rest of node's children!



- Symmetric argument for other way around
- If children are expanded in optimal order, complexity is halved:  $O(b^{m/2})$



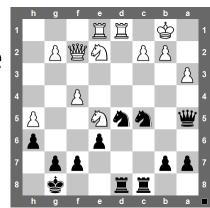
 $\alpha$  – minimum score MAX is guaranteed of  $\beta$  – maximum score MIN is guaranteed of

#### Depth-limited search

- Even with pruning, can't reach leaf nodes in real games
- So must limit depth of search
  - Must replace utility function with estimate (like heuristic in A\*)
  - No longer optimal
- More plies = better performance
- Given time budget, use IDS!

#### **Evaluation functions**

- Estimate of utility of non-terminal state
- Ideally: want actual minimax value of state
  - But this is unknown
- In practice: use domain knowledge
  - E.g. eval(s) =  $w_1(|pawns_w pawns_b|) + w_2(|bishops_w bishops_b|) + \cdots$



- Tradeoff between complexity vs depth
  - More complex eval function may be more accurate, but longer to compute → less time to search deeper
    - Stockfish: fast eval function, huge depth
    - Komodo: slow, complex eval function, less depth

#### Other improvements

- Base algorithm of  $\alpha\beta$  + IDS + eval function
- Transposition tables: stored previous states and their evals
- Aspiration windows: pretend that the  $\alpha\beta$  window is smaller than it is
- Evaluation functions optimised from data (machine learning etc)
- Move ordering: try certain classes of moves first (e.g. captures, then regular moves)

#### Board games

 " ... board games are more or less done and it's time to move on."

