COMS3008A: Parallel Computing Lecture 1: Introduction

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School of Computer Science & Applied Mathematics

Semester two 2021



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- Course admin
- Parallel computers
 - Parallel Computing What is it?
 - Why parallelism?
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Objectives

- Understand the basics of parallel computers, parallel computing, the motivation of parallel computing, and the classification of parallel computers.
- Understand and apply the simple quantitative modelling for parallel program performance.



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Course admin

- Relevant course information is given in course outline (uploaded on ulwazi course site).
- Course related communications will be announced primarily through the announcement via ulwazi course site. It is important for you to check such announcements regularly to keep informed timely.



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Parallel computing

- Parallel Computer: A parallel computer is a computer system that uses multiple processing elements simultaneously in a cooperative manner to solve a computational problem.
- Parallel computing (or processing): Parallel processing includes techniques and technologies that make it possible to compute in parallel.
 - Hardware, networks, operating systems, parallel libraries, languages, compilers, algorithms, tools etc.
- Parallel computing is an evolution of serial computing.
 - Parallelism is natural.
 - Computing problems differ in level or type of parallelism.



Serial computing

- A problem is broken into a discrete series of instructions;
- Instructions are executed sequentially one after another;
- Executed on a single processor;
- Only one instruction may execute at any moment in time.

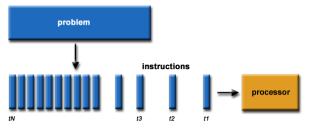


Figure: Serial computing



Parallel computing

- A problem is broken into discrete parts that can be solved concurrently;
- Each part is further broken down to a series of instructions;
- Instructions from each part execute simultaneously on different processors;
- An overall control/coordination mechanism is employed.

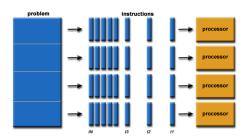


Figure: Parallel computing



Parallel computing cont.

An example of parallelizing an addition of two vectors is shown in Figure 3.

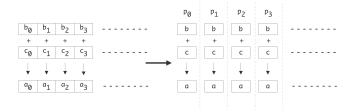


Figure: Parallelization of a vector addition



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Why parallelism?

 In 2004, Intel changed its course from traditional chip design approach (single core processor) to embrace "dual core" processor structure.



Figure: Intel's shift in chip design to multi-core structure.



 What had been happening before multi-processor? – Single-processor machines: they had been getting exponentially faster.

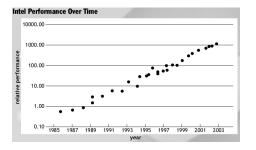


Figure: Intel single processor performance over time

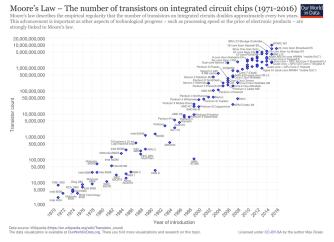


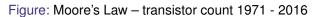
- Wider data paths
 - 4 bit \rightarrow 8 bit \rightarrow 16 bit \rightarrow 32 bit \rightarrow 64 bit
- More efficient pipelining
 - ullet For example, from 3.5 cycles per instruction (CPI) ightarrow 1.1 CPI
- Exploiting instruction level parallelism (ILP)
 - "Superscale" processing: e.g., issues up to 4 instructions/cycle
- Faster clock rates
 - $\bullet \ e.g., \ 10MHz \rightarrow 100MHz \rightarrow 1GHz \rightarrow 3GHz$

During 80s and 90s, computers had large exponential performance gains

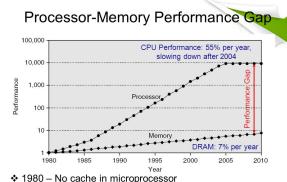


 "The number of transistors on an integrated circuit doubles every two years." — Gordon E. Moore









1995 – Two-level cache on microprocessor

Figure: Processor-memory performance gap



- For example, Intel Itanium II
 - 6-way integer unit < 2% die area;
 - Cache logic > 50% die area.
- Most of chip there to keep these 6 integer units at 'peak' rate.
- Main issue is external DRAM latency (50ns) to internal clock rate (0.25ns) ratio is 200:1.



Figure: Illustration of the die area for integer unit and cache logic for Intel Itanium II.



A brief history of parallel computing

- Greater clock frequency, greater electrical power
- Intel VP Patrick Gelsinger (ISSCC 2001): "If scaling continues at present pace, by 2005, high speed processors would have power density of nuclear reactor, by 2010, a rocket nozzle, and by 2015, surface of sun."

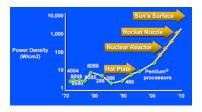
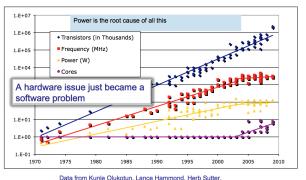


Figure: Intel VP Patrick Gelsinger (ISSCC 2001)

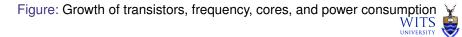


A brief history of parallel computing cont.

 Add multiple cores to add performance, keep clock frequency the same or reduced.



Burton Smith, Chris Batten, and Krste Asanoviç
Slide from Kathy Yelick



A brief history of parallel computing cont.

- What we can do? We can still pack more and more transistors on to a die, but we cannot make the individual transistor faster and faster.
- We have to make better use of those more and more transistors to increase the performance instead of making only the clock speed faster. One solution is to use parallelism.



Why parallelism – summary

- Serial machines have inherent limitations:
 - Processor speed, memory bottlenecks, . . .
- Parallelism has become the future of computing.
- Two primary benefits of parallel computing:
 - Solve fixed size problem in shorter time
 - Solve larger problems in a fixed time
- Other factors motivate parallel processing:
 - Effective use of machine resources;
 - Cost efficiencies;
 - Overcoming memory constraints.
- Performance is still the driving concern.
- Technology push
- Application pull
 - Application performance demands hardware advances;
 - Hardware advances generate new applications;
 - New applications have greater performance demands.



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No 1 Supercomputer in 11/2020 — Fugaku

Site RIKEN Center for Computational Science

Manufacturer Fujitsu (Fugaku; Fugaku virtual tour)

Cores 7.630.848

Linpack Performance (Rmax) 442,010 TFlop/s Theoretical Peak (Rpeak) 537,212 TFlop/s **HPCG** 16,004.5 TFlop/s Nmax 21.288.960

Power

29,899.23 kW (Submitted)

Memory 5.087.232 GB

Processor A64FX 48C 2.2GHz Interconnect Tofu interconnect D

Operating System RHFI

Compiler Fujitsu software technical computing suite v4.0 Math library Fujitsu software technical computing suite v4.0 MPI Fujitsu software technical computing suite v4.0



No 1 Supercomputer in 11/2020 — Fugaku cont.



Figure: Fugaku, a supercomputer from RIKEN and Fujitsu Limited.



No 1 Supercomputer in 11/2019 — Summit

Site DOE/SC/Oak Ridge National Laboratory

Manufacturer IBM

Cores 2,414,592

Linpack Performance (Rmax) 148,600 TFlop/s Theoretical Peak (Rpeak) 200,795 TFlop/s HPCG 2,925.75 TFlop/s

Nmax 16,693,248

Power 9,783.00 kW (Submitted)

Memory 2,801,664 GB

Processor IBM POWER9 AC9 22C 3.07GHz

GPU Nvidia Volta GV100

Interconnect Dual-rail Mellanox EDR Infiniband

Operating System RHEL 7.4
Compiler IBM XLC, nvcc
Math library ESSL, CUBLAS 9.2
MPI Spectrum MPI



No 1 Supercomputer in 11/2019 — Summit cont.



Figure: Summit, a supercomputer from IBM and the US Department of Energy's Oak Ridge National Laboratory (ORNL).



Lengau from CHPC SA — Rank 400 (11/2018)

Site Centre for High Performance Computing

System URL http://www.chpc.ac.za/

Manufacturer Dell Cores 32,856

Linpack Performance (Rmax) 1,029.3 TFlop/s Theoretical Peak (Rpeak) 1,366.8 TFlop/s

Nmax 3,105,408

Power 685 kW (Submitted)

Memory 175,232 GB

Processor Xeon E5-2690v3 12C 2.6GHz

Interconnect Infiniband FDR

Operating System CentOS
Compiler Intel
Math Library Intel MKL
MPI Intel MPI

The same machine was ranked 161 and 165 in 11/2016 and 11/2017 respectively.

Lengau from CHPC SA

CHPC'S LENGAU HANGS-ON IN THE TOP500 LIST

The CHPC's Lengau supercomputer has placed 496th on the computing community's **Top500 List**. The list was announced at the International Supercomputing Conference in Frankfurt, Germany in June 2019.

For the first time, all 500 systems deliver a petallop or more on the High Performance Linpack (HPL) benchmark, with the entry level to the list now at 1.022 petallops. Lengau has appeared on the Top500 List since her launch in June 2015 and is currently at 1.029 petallops. In her first appearance in June 2016, she was at number 121.

The Top SOO List lists computers ranked by their performance on the LINPACK benchmark (The LINPACK Benchmarks measure a system's floating point computing power, introduced by Jack Dongarra, they measure how fast a computer solves a dense in by n system of linear equations, which is a common task in science and engineering). The list is announced in June and in November each year. With over 32000 cores, Lengus remains one of the fastest computers on the Astronomiers, with a utilisation that averagence at 90%.

Lengau continues to put the country in the company of leading supercomputing nations. She has over 1500 registered users, 500 of which are actively engaged in over 200 research programmes.



Figure: Lengau - CHPC



The Clusters at Mathematical Sciences Lab

- stampede: Up to sixteen nodes, each with two Xeon E5-2680 CPUs, two GTX1060 GPUs (6GB per GPU, 12GB per node), and 32GB of system AM. For general purpose use or jobs that can leverage InfiniBand, however, InfiniBand has not yet been enabled yet.
- batch: Up to sixteen nodes each with a single Intel Core i9-10940X CPU (14 cores), NVIDIA RTX3090 GPU (24GB), and 128GB of system RAM. For bigger jobs that can leverage a bigger GPU and additional system RAM.
- biggpu: Each node has two Intel Xeon Platinum 8280L CPUs (28 cores per CPU, 56 cores per node) with two NVIDIA Quadro RTX8000 GPUs (48GB per GPU, 96GB per node), and 1TB of system RAM. For mature code that can meaningfully leverage large amounts of GPU and system RAM. While the system will allow jobs to use all three nodes, please try to use only a single node.

The Clusters at Mathematical Sciences Lab cont.

- ranger: Up to twelve nodes, each with two AMD CPUs, 32GB of RAM, and InfiniBand. No GPUs! For large CPU based jobs.
 Partition only available later in 2021.
- mia: For the exclusive use of researchers in MIA. Up to twelve nodes with InfiniBand.



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Flynn's taxonomy

Flynn's taxonomy is widely used since 1966 for classification of parallel computers. The classification is based on two independent dimensions of *instruction stream* and *data stream* with two possible states: *single* or *multiple*.

 SISD: Single instruction stream single data stream. This is the traditional CPU architecture: at any one time only a single instruction is executed, operating on a single data item.

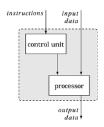


Figure: The SISD architecture



SIMD

SIMD: Single instruction stream multiple data stream. In this
computer type there can be multiple processors, each operating
on its own data item, but they are all executing the same
instruction on that data item. SIMD computers excel at operations
on arrays, such as

$$for(i = 0; i < N; i + +) \quad a[i] = b[i] + c[i];$$

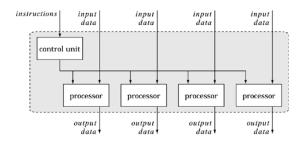


Figure: The SIMD architecture



MIMD

- MISD: Multiple instruction stream single data stream. Each processing unit executes different instruction streams on a single data stream. Very few computers are in this type.
- MIMD: Multiple instruction stream multiple data stream. Multiple processors operate on multiple data items, each executing independent, possibly different instructions. Most current parallel computers are of this type.

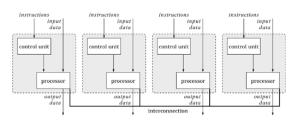


Figure: The MIMD architecture



MIMD cont.

 Most of MIMD machines operate in single program multiple data (SPMD) mode, where the programmers starts up the same executable on the parallel processors.



A Further Decomposition of MIMD

The MIMD category is typically further decomposed according to memory organization: shared memory and distributed memory.

- Shared memory: In a shared memory system, all processes share a single address space and communicate with each other by writing and reading shared variables.
- One class of shared-memory systems is called SMPs(symmetric multiprocessors).

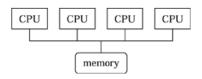


Figure: The SMP architecture



NUMA

- The other main class of shared-memory systems is called non-uniform memory access (NUMA). The memory is shared, it is uniformly addressable from all processors, but some blocks of memory may be physically more closely associated with some processors than others.
- To mitigate the effects of non-uniform access, each processor has a cache, along with a protocol to keep cache entries coherent cache-coherent non-uniform memory access systems (ccNUMA).

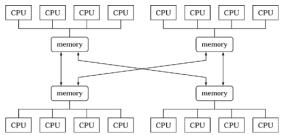




Figure: The NUMA architecture

Distributed memory systems

 Each process has its own address space and communicates with other processes by message passing (sending and receiving messages).

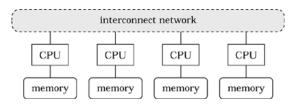


Figure: The distributed memory architecture



Clusters

 Clusters are distributed memory systems composed of off-the-shelf computers connected by an off-the-shelf network.

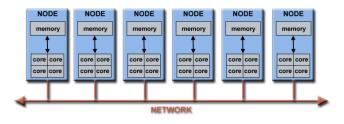


Figure: A cluster



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A simple performance modelling

- Consider a computation consisting of three parts: a setup section, a computation section, and a finalization section.
- The total running time of this program on one processing element (PE) is given as:

$$T_{total}(1) = T_{setup} + T_{compute} + T_{finalization}$$
 (1)

 What happens when we run this computation on a parallel computer with multiple PEs?

$$T_{total}(P) = T_{setup} + \frac{T_{compute}(1)}{P} + T_{finalization}$$
 (2)



Speedup

 An important measure of how much additional PEs help is the relative speedup S, which describes how much faster a problem runs:

$$S(P) = \frac{T_{total}(1)}{T_{total}(P)}$$
 (3)

 A related measure is the efficiency E, which is the speedup normalized by the number of PEs.

$$E(P) = \frac{S(P)}{P} = \frac{T_{total}(1)}{PT_{total}(P)}$$
 (4)

 Ideally, we would want the speedup to be equal to P, the number of PEs. This is sometimes called perfect linear speedup.



Amdahl's Law

• The terms that cannot be run concurrently are called the serial terms. Their running times represent some fraction of the total, called the serial fraction, denoted γ .

$$\gamma = \frac{T_{setup} + T_{finalization}}{T_{total}(1)} \tag{5}$$

• The fraction of time for parallelizable part is then 1 $-\gamma$. The total computation time with P PEs becomes

$$T_{total}(P) = \gamma T_{total}(1) + \frac{(1 - \gamma) T_{total}(1)}{P}$$
 (6)



Amdahl's Law cont.

Then we obtain the well-known Amdahl's law:

$$S(P) = \frac{T_{total}(1)}{T_{total}(P)} = \frac{T_{total}(1)}{\left(\gamma + \frac{1 - \gamma}{P}\right)T_{total}(1)} = \frac{1}{\gamma + \frac{1 - \gamma}{P}}$$
(7)

Taking the limit as P goes to infinity in Eq. 7,

$$S(P) = \frac{1}{\gamma} \tag{8}$$

Eq. 8 gives an upper bound on the speedup.

 Amdahl's Law says the speedup you can achieve is limited by the fraction for serial computation in your problem (i.e., the number of PEs does not determine the upper bound of speedup you can achieve).

Amdahl's Law cont.

Example 1

Suppose we are able to parallelize 90% of a serial program. Further suppose the speedup of this part is P, the number of processes we used (which is a perfect linear speedup). If the serial time is $T_{serial} = 20$ s, then the runtime of the parallelized part is $(0.9 \times T_{serial})/P = 18/P$. The runtime of unparallelized part is $0.1 \times 20 = 2$ s. The overall parallel runtime will be

$$T_{parallel} = 18/P + 2,$$

and the speedup will be

$$S = \frac{T_{serial}}{T_{narallel}} = \frac{20}{18/p + 2}.$$

As P gets larger, 18/P gets close to 0, and the denominator gets close to 2, in turn, S gets close to 10. That means $S \le 10$, no matter how many number of processes you use in your program.

Gustafson's Law

• In contrast to Eq. 2, we obtain $T_{total}(1)$ from the serial and parallel parts when executed on P PEs.

$$T_{total}(1) = T_{setup} + PT_{compute}(P) + T_{finalization}$$
 (9)

• Now, we define the so-called scaled serial fraction, denoted γ_{scaled} , as

$$\gamma_{scaled} = \frac{T_{setup} + T_{finalization}}{T_{total}(P)},$$
 (10)

and then

$$T_{total}(1) = \gamma_{scaled} T_{total}(P) + P(1 - \gamma_{scaled}) T_{total}(P).$$
 (11)



Gustafson's Law cont.

 Using Eq. 11, we obtain the scaled speedup, sometimes known as Gustafson's law.

$$S(P) = \frac{T_{total}(1)}{T_{total}(P)} = \frac{\gamma_{scaled} T_{total}(P) + P(1 - \gamma_{scaled}) T_{total}(P)}{T_{total}(P)}$$

$$= P(1 - \gamma_{scaled}) + \gamma_{scaled} = P + (1 - P)\gamma_{scaled}.$$
(12)

• Suppose we take the limit in P while holding $T_{compute}$ and γ_{scaled} constant. That is, we are increasing the size of the problem so that the total running time remains constant when more processors are added. In this case, the speedup is linear in P.



Gustafson's Law cont.

Example 2

Now, for the previous example, let's assume the scaled serial fraction of the same problem is 0.1, that is $\gamma_{scaled}=0.1$, and p=16. Then the scaled speedup is S=16(1-0.1)+0.1=14.5, which is greater than the upper bound determined by Amdahl's Law (10).



Efficiency

- There are another two performance metrics we frequently use in the process of the course: efficiency and scalability.
- Efficiency:

$$E = \frac{S}{P},\tag{13}$$

where S is the speedup, and P is the number of processes used to achieve the speedup. Note $0 < E \le 1$. Efficiency is better when E is closer to 1, which simply means you utilized the P processors efficiently.



Scalability

- Scalability: In general, a technology is scalable if it can handle ever-increasing problem size.
- In parallel program performance, scalability refers to the following measure. Suppose we run a parallel program using certain number of processors and with a certain problem size, and obtained an efficiency E. Further suppose that now we want to increase the number of processors. In this case, if we can find a rate at which the problem size increases so that we can still maintain the efficiency E, we say the parallel program scalable.



Scalability cont.

Example 3

Suppose $T_{serial}=n,$ where n is also the problem size. Also suppose $T_{parallel}=n/p+1.$ Then

$$E=\frac{n}{p(n/p+1)}=\frac{n}{n+p}.$$

To see if the problem is scalable, we increase p by a factor of k, then we get

$$E = \frac{n}{n+p} = \frac{xn}{xn+kp}.$$

If x = k, then we have the same efficiency. That is, if we increase the problem size at the same rate that we increase the number of processors, then the efficiency remain constant, hence, the program is scalable.

Scalability cont.

- Strong scalability: When we increase the number of processes, we can keep the efficiency fixed without increasing the problem size, the program is strongly scalable.
- Weak scalability: If we can keep the efficiency fixed by increasing the problem size at the same rate as we increase the number of processes, then the program is said to be weakly scalable.



Summary

