COMS3008A: Parallel Computing Introduction to OpenMP: Part I

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Contents

OpenMP Overview

- OpenMP Core Features
 - Parallel Region Construct
 - Synchronization



Outline

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 - Parallel Region Construct
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What is OpenMP?

Open specifications for Multi Processing

- An Application Program Interface (API) that may be used to explicitly direct multi-threaded, shared memory parallelism.
- Comprised of three primary API components:
 - Compiler Directives
 - Runtime Library Routines
 - Environment Variables
- API is specified for C, C++ and Fortran.
- Portable
- Easy to use



OpenMP Programming Model

 OpenMP is designed for multi-processor/core, shared memory machines.

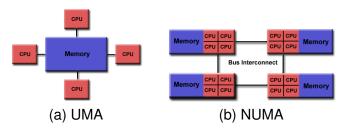


Figure: The shared memory model of parallel computation.



OpenMP Programming Model Cont.

Thread Based Parallelism:

- OpenMP programs accomplish parallelism exclusively through the use of threads.
- A thread of execution is the smallest unit of processing that can be scheduled by an operating system.
- Threads exist within the resources of a single process. Without the process, they cease to exist.
- Typically, the number of threads match the number of processors/cores of a machine, but it can differ.



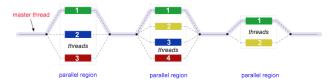
OpenMP Programming Model Cont.

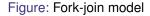
- Explicit Parallelism:
 - OpenMP is an explicit (not automatic) programming model, offering the programmer full control over parallelization.
- Compiler Directive Based: Most OpenMP parallelism is specified through the use of compiler directives which are embedded in C/C++ or Fortran source code.



OpenMP Programming Model Cont.

- Fork Join Model: OpenMP programs begin as a single process: the master thread. The master thread executes sequentially until the first parallel region construct is encountered.
 - FORK:
 - The master thread then creates a team of parallel threads;
 - Becomes the master of this group of threads;
 - Assigned the thread number 0 within the group.
 - JOIN: When the team threads complete the statements in the parallel region construct, they synchronize and terminate, leaving only the master thread.







OpenMP API Overview

- Three components: Compiler Directives, Runtime Library Routines, Environment Variables.
 - Compiler Directives: Appear as comments in your source code to guide the compilers.
 - The OpenMP API includes an ever-growing number of run-time library routines.
 - OpenMP provides several environment variables for controlling the execution of parallel code at run-time.



OpenMP API Overview Cont.

- OpenMP core syntax:
 - Most of the constructs in OpenMP are compiler directives:
 #pragma omp (construct name) [clause [clause]...]
 - OpenMP code structure: Structured block. A block of one or more statements with one point of entry and one point of exit at the end.
 - Function prototypes and types in the file: #include (omp.h)



OpenMP API Overview Cont.

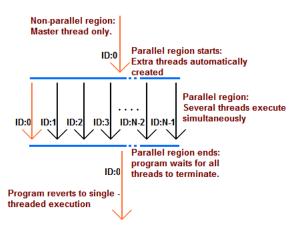


Figure: OpenMP parallel construct execution model



Compiling OpenMP Programs

Exercise 1: Write a multi-threaded C program that prints "Hello World!". (hello omp.c)



Compiling OpenMP Programs Cont.

- To compile, type gcc -fopenmp hello_omp.c -o hello_omp.
- To run, type ./hello_omp



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Parallel Region Construct

A parallel region is a block of code that will be executed by multiple threads. This is the fundamental OpenMP parallel construct.

Syntax:

```
#pragma omp parallel [clause[[,] clause] ... ]
structured block
```



Typical clauses in clause list:

Degree of concurrency:

```
num_threads(<integer expression>)
```

- Data scoping:
 - private(<variable list>)
 - firstprivate(<variable list>)
 - shared(<variable list>)
 - default (<data scoping specifier>) (shared or none)
- Conditional parallelization:if (<scalar expression>),
 determines whether the parallel construct creates threads.



Interpreting an OpenMP parallel directive

```
int b, a=10, c=5;
#pragma omp parallel if (is_parallel==1) \
num_threads(8) shared(b) private(a) \
firstprivate(c) default(none)
{
/* structured block */
}
```



• Create threads in OpemMP using the parallel construct.

Example 1

Create a 4-thread parallel region using *num_threads* clause.

```
#include <stdio.h>
#include <omp.h>
3 int main()
4 {
   //Parallel region with 'num threads' clause to set
       number of threads
   #pragma omp parallel num_threads(4)
6
   //Start of the parallel region
     //Runtime library function to return a thread number
9
      int ID = omp_get_thread_num();
     printf("Hello World! (Thread %d) \n", ID);
11
    }//End of the parallel region
12
13
```

Example 2

Create a 4-thread parallel region using runtime library routine.

```
#include <stdio.h>
2 #include <omp.h>
 int main()
   //Runtime library function to request the number of
       threads in the parallel region
   omp set num threads (4);
   #pragma omp parallel
      int ID = omp get thread num();
     printf("Hello World! (Thread %d)\n", ID);
12
```

Different ways to set the number of threads in a parallel region:

- Using runtime library function omp_set_num_threads().
- Setting clause num_threads, e.g.,
 #pragma omp parallel num_threads (8).
- Specify at runtime using environment variable OMP_NUM_THREADS,
 e.g., export OMP_NUM_THREADS=8.



Computing the π Using Integration

Example 3

Compute the number $\boldsymbol{\pi}$ using

numerical integration:
$$\int_{0}^{1} \frac{4.0}{1+x^2} = \pi.$$

- Write a serial program for the problem.
- Parallelize the serial program using OpenMP directive.
- Compare the results from 1 and 2.

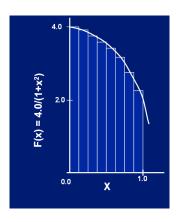


Figure: Approximating the π using numerical integration



Serial Program for Computing Π

10

12

```
static long num_steps = 1000000;
double step;
int main () {
   int i;
   double x, pi, sum = 0.0;
   step = 1.0/(double) num_steps;
   for (i=0;i< num_steps;i++) {
        x = (i+0.5)*step;
        sum = sum + 4.0/(1.0+x*x);
   }
   pi = step * sum;
}</pre>
```



Parallel Program for Computing Π — Method I

```
static long num steps = 1000000;
    double step;
    #define NUM THREADS 2
    int main () {
      int i, nthreads;
      double pi, sum[NUM_THREADS];
      step = 1.0/(double) num_steps;
      omp set num threads (NUM THREADS);
      #pragma omp parallel
9
10
         int i, id, tthreads; double x;
        tthreads = omp_get_num_threads();
12
         id = omp_get_thread_num();
13
         if (id==0) nthreads=tthreads;
14
         for (i=id, sum[id]=0.0;i< num_steps; i=i+tthreads) {</pre>
15
           x = (i+0.5)*step;
16
           sum[id] = sum[id] + 4.0/(1.0+x*x);
18
19
      for (i=0, pi=0.0; i < nthreads; i++)</pre>
20
        pi += step * sum[i];
21
```



False Sharing

If independent data elements happen to sit on the same cache line, each update will cause the cache lines to "slosh back and forth" between threads...this is called **false sharing**.

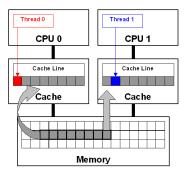


Figure: False sharing



Cache

- Processors usually execute operations faster than they access data in memory.
- To address this problem, a block of relatively fast memory is added to a processor — cache.
- The design of cache considers the temporal and spatial locality.
- For example, x is a shared variable and x = 5, my_y, my_z are private variable, what will be the value of my_z?

```
if myId==0 {
    my_y = x;
    x++;
}else if myId==1 {
    my_z = x;
}
```



Cache Coherence

Example 4

Suppose x = 2 is a shared variable, y0, y1, z1 are private variable. If the statements in Table 1 are executed at the indicated times, then x = ?, y0 = ?, y1 = ?, z1 = ?

Time	Core 0	Core 1
0	y0 = x;	y1 = 3 * x;
1	x = 7;	Statements not involving <i>x</i>
2	Statements not involving <i>x</i>	z1=4*x;

Table: Example - cache coherence



Cache Coherence cont.

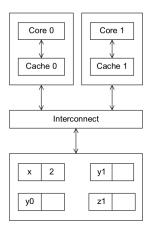


Figure: Example - cache coherence cont.



Cache Coherence cont.

Cache coherence problem - When the caches of multiple processors store the same variable, an update by one processor to the cached variable is 'seen' by the other processors. That is, the cached value stored by the other processors is also updated.



False Sharing

- Suppose two threads with separate caches access different variables that belong to the same cache line. Further suppose at least one of the threads updates its variable.
- Even though neither thread has written to a shared variable, the cache controller invalidates the entire cache line and forces the other threads to get the values of the variables from main memory.
- The threads aren't sharing anything (except a cache line), but the behaviour of the threads with respect to memory access is the same as if they were sharing a variable. Hence the name false sharing.
- Avoiding false sharing having each thread use its own private storage, and then update the shared variable when they are done.



Parallel Program for Computing Π — Method II

```
static long num_steps = 1000000;
2 int main () {
    int i, tthreads, id;
    double step, pi = 0.0, sum = 0.0, x;
    step = 1.0/(double) num_steps;
    #pragma omp parallel
      tthreads = omp_get_num_threads();
8
      id = omp_get_thread_num();
      for (i=id; i<num_steps; i+=tthreads) {</pre>
10
        x = (i+0.5)*step;
        sum = sum + 4.0/(1.0+x*x);
13
14
    pi += step * sum;
15
16
```



Race Condition

- When multiple threads update a shared variable, the computation exhibits non-deterministic behaviour — race condition. That is, two or more threads attempt to access the same resource.
- If a block of code updates a shared resource, it can only be updated by one thread at a time.



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Synchronization

- Synchronization: Bringing one or more threads to a well defined and known point in their execution. Barrier and mutual exclusion are two most often used forms of synchronization.
 - Barrier: Each thread wait at the barrier until all threads arrive.
 - Mutual exclusion: Define a block of code that only one thread at a time can execute.
- Synchronization is used to impose order constraints and to protect access to shared data.
- In Method II of computing π ,

```
sum = sum + 4.0/(1.0+x*x); is called a critical section.
```

 Critical section - a block of code executed by multiple threads that updates a shared variable, and the shared variable can only be updated by one thread at a time.

High level synchronizations in OpenMP

 critical construct: Mutual exclusion. Only one thread at a time can enter a *critical* section.

```
#pragma omp critical
```

```
float result;
   #pragma omp parallel
      float B; int i, id, nthrds;
      id = omp get thread num();
      nthrds = omp_get_num_threads();
      for (i = id; i < nthrds; i+= nthrds) {</pre>
8
        B = biq job(i);
10
      #pragma omp critical
        result += calc(B);
12
```

High level synchronizations in OpenMP Cont.

- atomic construct: Basic form. Provides mutual exclusion but only applies to the update of a memory location.
- #pragma omp atomic

The statement inside the *atomic* must be one of the following forms:

```
• x op = expr, where op \in (+ =, - =, * =, / =, % =)
```

- \bullet X++
- \bullet + + x
- \bullet --x

```
#pragma omp parallel

{

    .....

    double tmp, B;

    B = calc();

    tmp = big_calc(B);

    #pragma omp atomic

    X += tmp;

    ....

    WITS
```

High level synchronizations in OpenMP Cont.

• barrier construct: Each thread waits until all threads arrive.

#pragma omp barrier

```
#pragma omp parallel

int id=omp_get_thread_num();

A[id]=calc1(id);

#pragma omp barrier

B[id]=calc2(id, A);

.....

}
```



'Summary

- OpenMP execution model
- Create a parallel region in OpenMP programs
- We have studied the following constructs:
 - parallel
 - critical
 - atomic
 - barrier
- Usage of OpenMP library functions and environment variables
- False sharing and race condition

