COMS3008A: Parallel Computing Introduction to MPI III

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Contents

- MPI Collective Communication
- MPI Derived Datatypes
 - Typemap
 - Creating and Using a New Datatype
 - Contiguous Type
 - Vector Type
 - Indexed Type
 - Struct Type



Outline

- MPI Collective Communication
- 2 MPI Derived Datatypes
 - Typemap
 - Creating and Using a New Datatype
 - Contiguous Type
 - Vector Type
 - Indexed Type
 - Struct Type



Scatters a buffer in parts to all processes in a communicator, which allows different amounts of data to be sent to different processes.

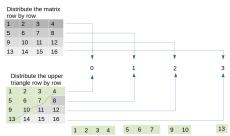
- sendbuf: address of send buffer (significant only at root)
- sendcounts: integer array (of length group size) specifying the number of elements to send to each processor
- displs: integer array (of length group size). Entry i specifies the displacement (relative to sendbuf from which to take the outgoing data to process i
- sendtype: data type of send buffer elements
- recvcount: number of elements in receive buffer (integer)
- recvtype: data type of receive buffer elements
- root: rank of sending process (integer)



Example 1

Given an $N \times N$ matrix, A, of integers, write an MPI program that distributes the first M rows of the upper triangle of A to M processes by rows, where each process gets one row of the upper triangle of A (when M = N, it means each process gets one row of the upper triangle of A).

For this example, we can use MPI_Scatterv.





For Example 1, assuming the matrix is only 4×4 , and we are running the MPI code using 4 processes, then some of the arguments of calling MPI_Scatterv:

- sendcounts[4] = $\{4, 3, 2, 1\};$
- displs[4] = {0, 4, 8, 12} which is with reference to sendbuf; these values can be expressed as N * rank, where rank is the rank of a process.
- note also that recvcount in MPI_Scatterv is a scalar; for process 0, recvcount = 4 (=4-0); for process 1, recvcount = 3 (=4-1); for process 2, recvcount = 2 (=4-2); and for process 3, recvcount = 1 (=4-3); so this value can be obtained as N rank where N is the number of rows in the matrix, and rank is the rank of a process.

scatterv_1.c gives an example code for Example 1.



Sends data from all to all processes; each process may send a different amount of data and provide displacements for the input and output data.

- sendbuf: starting address of send buffer
- sendcounts: integer array equal to the group size specifying the number of elements to send to each processor
- sdispls: integer array (of length group size). Entry j specifies the displacement (relative to sendbuf from which to take the outgoing data destined for process j
- sendtype: data type of send buffer elements
- recvcounts: integer array equal to the group size specifying the maximum number of elements that can be received from each processor
- rdispls: integer array (of length group size). Entry i specifies the displacement (relative to recybuf at which to place the incoming data from process i
- recvtype: data type of receive buffer elements



Example 2

Given the MPI_Alltoallv argument settings shown in the figure (the number of processes is 3), what is the content of recybuf for each process?

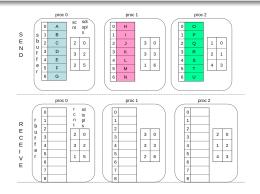


Figure: MPI_Alltoallv example



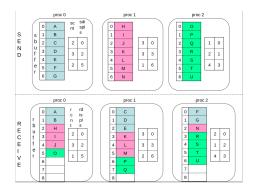


Figure: MPI_Alltoallv example



The following function allows a different number of data elements to be sent by each process by replacing recvcount in MPI_Gather with an array recvcounts

```
int MPI_Gatherv(void *sendbuf, int sendcount, MPI_Datatype sendtype,
void *recvbuf, int *recvcounts, int *displs,
MPI_Datatype recvtype, int target, MPI_Comm comm)
```

- sendbuf: pointer, starting address of send buffer (or the data to be sent)
- sendcount: the number of elements in the send buffer
- sendtype: datatype of send buffer elements
- recvbuf: pointer, starting address of receive buffer (significant only at root)
- recvcounts: integer array (of length group size) containing the number of elements to be received from each process (significant only at root)
- displs: integer array (of length group size). Entry i specifies the displacement relative to recybuf at which to place the incoming data from process i (significant only at root)
- recvtype: the datatype of data to be received (significant only at root)
- target: rank of receiving process (integer)



Gather data from all processes and deliver the combined data to all processes

```
int MPI_Allgatherv(void *sendbuf, int sendcount, MPI_Datatype sendtype,
void *recvbuf, int *recvcounts, int *displs,
MPI_Datatype recvtype, MPI_Comm comm)
```

- sendbuf: pointer, starting address of send buffer (or the data to be sent)
- sendcount: the number of elements in the send buffer
- sendtype: datatype of send buffer elements
- recvbuf: pointer, starting address of receive buffer (significant only at root)
- recvcounts: integer array (of length group size) containing the number of elements to be received from each process (significant only at root)
- displs: integer array (of length group size). Entry i specifies the displacement relative to recybuf at which to place the incoming data from process i (significant only at root)
- recvtype: the datatype of data to be received (significant only at root)



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MPI Derived Datatypes

Example 3

```
double x[10001;
  for (i=0; i<1000; i++) {
    if (my_rank == 0)
          MPI_Send(&x[i], 1, MPI_DOUBLE, 1, 0, comm);
  else
          MPI Recv(&x[i], 1, MPI DOUBLE, 0, 0, comm, &
             status);
/*the following is more efficient than using the for
  if (mv rank == 0)
      MPI_Send(&x[0], 1000, MPI_DOUBLE, 1, 0, comm);
  else
      MPI Recv(&x[0], 1000, MPI DOUBLE, 0, 0, comm, &
         status);
```

In distributed-memory systems, communication can be much more expensive than local computation. Thus, if we can reduce the number of communications, we are likely to improve the performance of programs.

MPI Built-in Datatypes

- The MPI standard defines many built in datatypes, mostly mirroring standard C/C++ or FORTRAN datatypes
- These are sufficient when sending single instances of each type
- They are also usually sufficient when sending contiguous blocks of a single type
- Sometimes, however, we want to send non-contiguous data or data that is comprised of multiple types
- MPI provides a mechanism to create derived datatypes that are built from simple datatypes



MPI Derived Datatypes Contd.

- In MPI, a derived datatype can be used to represent any collection of data items in memory by storing both the types of the items and their relative locations in memory.
- Why use derived datatypes?
 - Primitive datatypes are contiguous;
 - Derived datatypes allow you to specify non-contiguous data in a convenient manner and treat it as though it is contiguous;
 - Useful to
 - Make code more readable
 - Reduce number of messages and increase their size (faster since less latency);
 - Make code more efficient if messages of the same size are repeatedly used.



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Typemap

Formally, a derived datatype in MPI is described by a typemap consists of a sequence of basic MPI datatypes together with a displacement for each of the datatypes. That is,

- a sequence of basic datatypes: {type₀, ..., type_{n-1}}
- a sequence of integer displacements: $\{displ_0, ..., displ_{n-1}\}$.
- Typemap = $\{(type_0, disp_0), \cdots, (type_{n-1}, disp_{n-1})\}$

For example, a typemap might consist of (double,0),(char,8) indicating the type has two elements:

- a double precision floating point value starting at displacement 0,
- and a single character starting at displacement 8.



Typemap Contd.

- Types also have extent, which indicates how much space is required for the type
- The extent of a type may be more than the sum of the bytes required for each component
- For example, on a machine that requires double-precision numbers to start on an 8-byte boundary, the type (double,0),(char,8) will have an extent of 16 even though it only requires 9 bytes



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Creating and Using a New Datatype

Three steps are necessary to create and use a new datatype in MPI:

- Create the type using one of MPI's type construction functions
- Commit the type using MPI_Type_commit().
- Release the datatype using MPI_Type_free () when it is not needed any more.



MPI Derived Datatypes Contd.

MPI provides several methods for constructing derived datatypes to handle a wide variety of situations.

- Contiguous
- Vector
- Indexed
- Struct



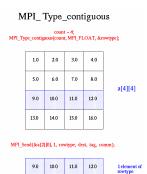
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Contiguous Type

Contiguous: The contiguous datatype allows for a single type to refer to contiguous multiple elements of an existing datatype.



To define the new datatype in this example and release it after finished using it:



Contiguous Type Contd.

To define a new datatype:

- Declare the new datatype as MPI_Datatype.
- Construct the new datatype.
- Before we can use a derived datatype in a communication function, we must first commit it with a call to

```
int MPI_Type_commit(MPI_Datatype* datatype);
```

Commits new datatype to the system. Required for all derived datatypes.

 When we finish using the new datatype, we can free any additional storage used with a call to

```
int MPI_Type_free (MPI_Datatype* datatype)
```



Contiguous Type Contd.

The new datatype is essentially an array of count elements having type oldtype. For example, the following two code fragments are equivalent:

```
MPI_Send (a,n,MPI_DOUBLE,dest,tag,MPI_COMM_WORLD);
and
```

```
MPI_Datatype rowtype;
MPI_Type_contiguous(n, MPI_DOUBLE, &rowtype);
MPI_Type_commit(&rowtype);
MPI_Send(a, 1, rowtype, dest, tag, MPI_COMM_WORLD);
```



Example 4

```
#define STZE 4
    float a[SIZE][SIZE] =
     {1.0, 2.0, 3.0, 4.0, 5.0, 6.0, 7.0, 8.0,
      9.0, 10.0, 11.0, 12.0, 13.0, 14.0, 15.0, 16.0};
    float b[SIZE];
5
    MPI_Status stat;
    MPI Datatype rowtype;
    MPI_Init (&argc, &argv);
    MPI Comm rank (MPI COMM WORLD, &rank);
    MPI Comm size (MPI COMM WORLD, &numtasks);
10
    MPI_Type_contiguous (SIZE, MPI_FLOAT, &rowtype);
    MPI Type commit (&rowtype);
12
    if (numtasks == SIZE) {
      if (rank == 0)
14
        for (i=0; i<numtasks; i++)</pre>
15
          MPI_Send(&a[i][0], 1, rowtype, i, tag,
16
              MPI COMM WORLD);
      /*the datatype rowtype can also be used in the
          following function*/
      MPI Recv (b, SIZE, MPI FLOAT, source, tag, MPI COMM WORLD, &
18
          stat);
19
      //MPI_Recv(b, 1, rowtype, source, tag, MPI_COMM_WORLD, &
      printf("rank= %d b= %3.1f %3.1f %3.1f %3.1f\n",
20
            rank,b[0],b[1],b[2],b[3]);
21
22
    MPI_Type_free (&rowtype);
    MPI Finalize();
24
```

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Vector Type

Vector: The vector datatype is similar to the contiguous datatype but allows for a constant non-unit stride between elements.

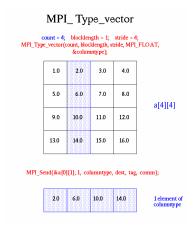
```
int MPI_Type_vector(
  int count,
  int blocklength,
  int stride,
  MPI_Datatype oldtype,
  MPI_Datatype *newtype)
```

- Input parameters
 - count: number of blocks (nonnegative integer)
 - blocklength: number of elements in each block (integer)
 - stride: number of elements between each block (integer)
 - oldtype: old datatype

Vector Type Contd.

Output parameter

newtype: new datatype





Vector Type Contd.

For example, the following two types can be used to communicate a single row and a single column of a matrix $(ny \times nx)$:

```
MPI_Datatype rowType, colType;
MPI_Type_vector(nx, 1, 1, MPI_DOUBLE, &rowType);
MPI_Type_vector(ny, 1, nx, MPI_DOUBLE, &colType);
MPI_Type_commit(&rowType);
MPI_Type_commit(&colType);
```



Example 5

```
#define SIZE 4
    float a[SIZE][SIZE] =
2
      {1.0, 2.0, 3.0, 4.0, 5.0, 6.0, 7.0, 8.0,
3
      9.0, 10.0, 11.0, 12.0, 13.0, 14.0, 15.0, 16.0};
4
    float b[SIZE];
5
6
    MPI_Status stat;
    MPI Datatype coltype;
7
    MPI Init (&argc, &argv);
8
    MPI Comm rank (MPI COMM WORLD, &rank);
9
    MPI Comm size (MPI COMM WORLD, &numtasks);
10
    MPI Type vector(SIZE, 1, SIZE, MPI FLOAT, &coltype);
    MPI_Type_commit(&coltype);
12
    if (numtasks == SIZE) {
13
      if(rank == 0){
14
        for (i=0; i<numtasks; i++)</pre>
15
          MPI_Send(&a[i][0], 1, coltype, i, tag,
16
              MPI COMM WORLD):
      MPI_Recv(b, SIZE, MPI_FLOAT, source, tag, MPI_COMM_WORLD, &
18
          stat);
19
    MPI_Type_free (&coltype);
20
    MPI Finalize();
21
```

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 - Contiguous Type
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 - Struct Type



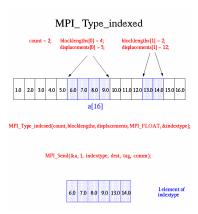
Indexed Type

Indexed: The indexed datatype provides for varying strides between elements.

- Input parameters
 - count: number of blocks also number of entries in indices and blocklens
 - blocklens: number of elements in each block (array of nonnegative integers)
 - indices: displacement of each block in multiples of oldtype (array of integers)
 - oldtype: old datatype

Indexed Type Contd.

- Output parameters
 - newtype: new datatype





Indexed Type Contd.

Indexed type generalizes the vector type; instead of a constant stride, blocks can be of varying length and displacements.



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Struct Type

Struct: The most general constructor allows for the creation of types representing general C/C++ structs/classes.

 We can use MPI_Type_create_struct to build a derived datatype that consists of individual elements that have different basic types:

```
int MPI_Type_create_struct(
  int count, //number of elements in the datatype
  int array_of_blocklengths[], //length of each element
  MPI_Aint array_of_displacements[], //displacements in bytes
  MPI_Datatype array_of_types[],
  MPI_Datatype* new_type_p)
```



Struct Type cont.

- count: number of blocks, also number of entries in arrays array_of_types, array_of_displacements and array_of_blocklengths
- array_of_blocklengths: number of elements in each block
- array_of_displacements: byte displacement of each block
- array_of_types: type of elements in each block
- Output Parameters: newtype: new datatype



Struct Type Cont.

To find the displacements, we can use the function

```
MPI_Get_address:
    int MPI_Get_address(
        void* location_p,
        MPI_Aint* address_p);
```

- It returns the address of the memory location referenced by location_p.
- MPI_Aint is an integer type that is big enough to store an address on the system.



Example 6 (Moving particles between processes)

In N-body problems, the force between particles become less with growing distance. At great enough distance, the influence of a particle on others is negligible. A number of algorithms for N-body simulation take advantage of this fact. These algorithms organize the particles in groups based on their locations using tree structures such quad-tree. One important step in the implementation of these algorithms is that of transferring particles from one process to another as they move. Here, we only discuss a way in which movement of particles can be done in MPI.

Assume a particle is defined by

```
typedef struct {
    int x,y,z;
    double mass;
}Particle;
```



 To send a particle from one process to another, or broadcast the particle, it makes sense in MPI to create a datatype instead of sending the elements in the struct individually.

Example 6 cont.

```
Particle my particle;
MPI Datatype particletype;
Build mpi type (&my particle.x, &my particle.y, &
   my_particle.z, &my_particle.mass, &particletype);
/*process 0 does some computation with my_particle */
/*process 0 performs a broadcast*/
MPI_Bcast(&my_particle, 1, particletype, 0,
   MPI_COMM_WORLD);
MPI_Type_free (&particletype);
```

Struct Type Contd.

Example 6 cont.

```
void Build_mpi_type( int* x_p, int* y_p, int* z_p, double
     * mass p, MPI_Datatype* particletype_p) {
    int array of blocklengths [4] = \{1, 1, 1, 1\};
    MPI_Datatype array_of_types[4] = {MPI_INT, MPI_INT,
       MPI INT, MPI DOUBLE );
    MPI_Aint array_of_displacements[4] = {0};
    MPI_Get_address(x_p, &array_of_displacements[0]);
5
    MPI_Get_address(y_p, &array_of_displacements[1]);
    MPI_Get_address(z_p, &array_of_displacements[2]);
    MPI_Get_address(mass_p, &array_of_displacements[3]);
    for(int i=3; i<=0; i++)
9
      array of displacements[i] -= array of displacements
          [01:
    MPI_Type_create_struct(4, array_of_blocklengths,
           array of displacements, array of types,
12
           particletype p);
13
    MPI_Type_commit(particletype_p);
14
    /* Build_mpi_type */
15
```

Summary





References

Useful references:

- Trobec et al., Introduction to Parallel Computing: From Algorithms to Programming on State-of-the-Art Platforms
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