

# Artificial Intelligence

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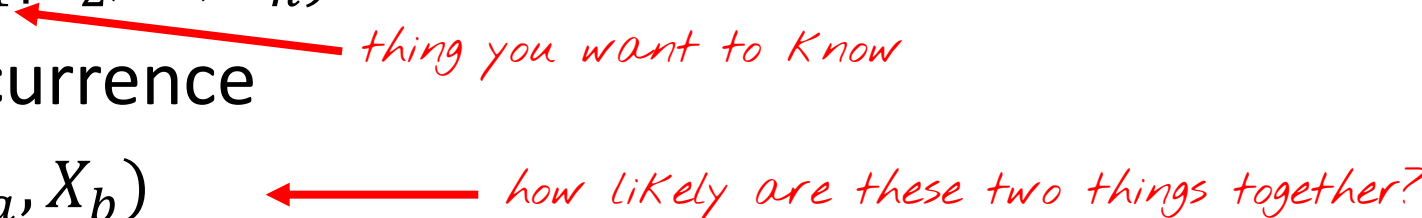

Bayesian Networks

# Recall

- Joint distributions:
  - $P(X_1, \dots, X_n)$
  - Use to infer  $P(X_1)$ ,  $P(X_1, X_s)$ , etc

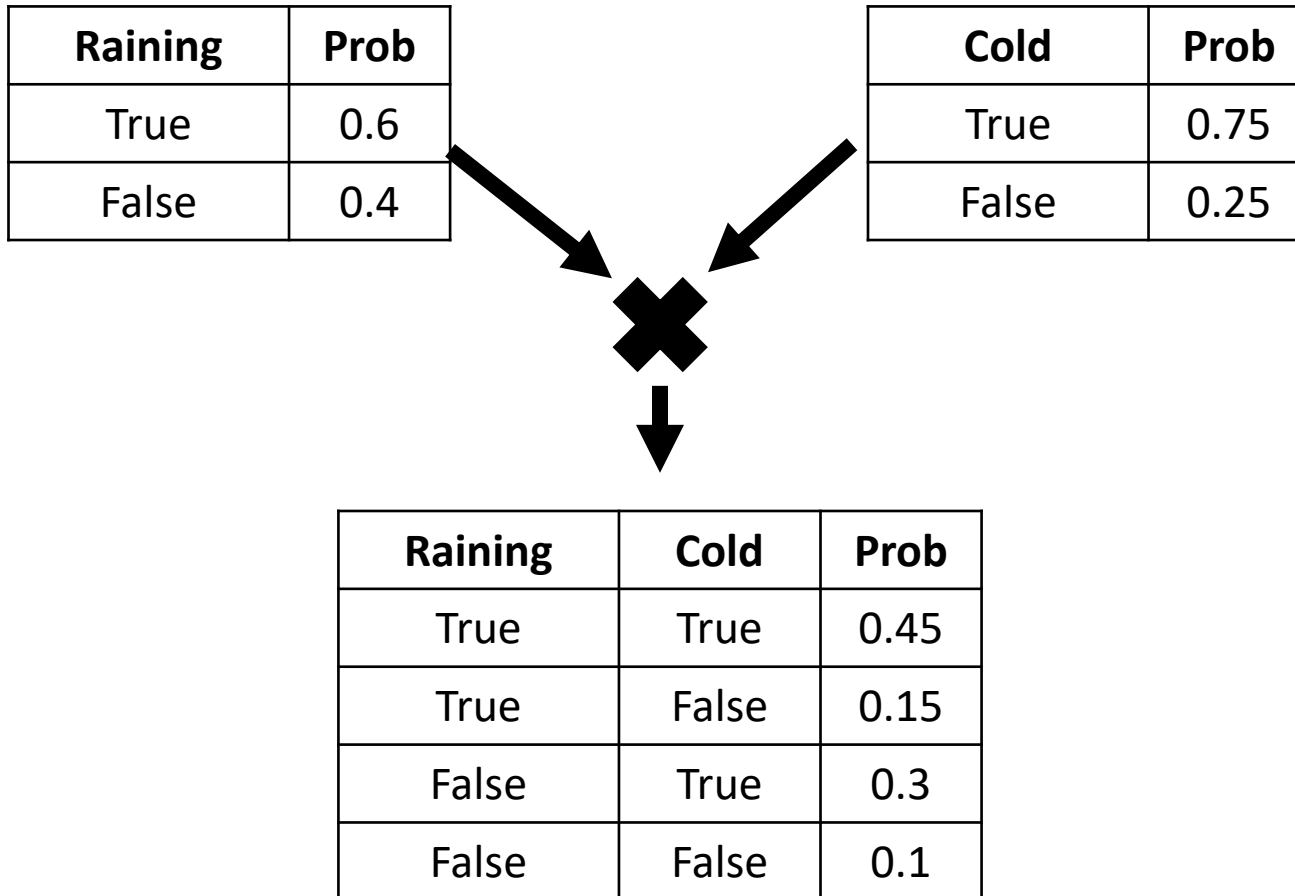
Raining	Cold	Prob
True	True	0.3
True	False	0.1
False	True	0.4
False	False	0.2

# Joint distributions are useful

- All you statistically need to know about  $X_1, \dots, X_n$
- Classification
  - $P(X_1 | X_2, \dots, X_n)$ *things you know*
- Co-occurrence
  - $P(X_a, X_b)$ *thing you want to know*  
*how likely are these two things together?*
- Rare event detection
  - $P(X_1, \dots, X_n)$ *surprising event?*

# Independence

- If independent, can **break JPD into separate tables**



# Conditional independence

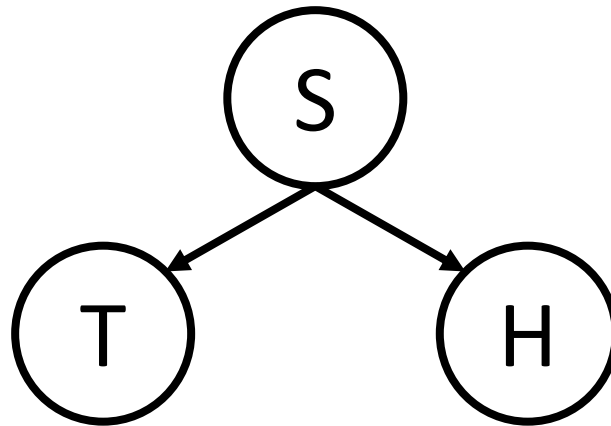
- $A$  and  $B$  are **conditionally independent given  $C$**  if:
  - $P(A|B, C) = P(A|C)$
  - $P(A, B|C) = P(A|C)P(B|C)$
- **If we know  $C$ , we can treat  $A$  and  $B$  as if they were independent**
  - $A$  and  $B$  might not be independent otherwise

# Example

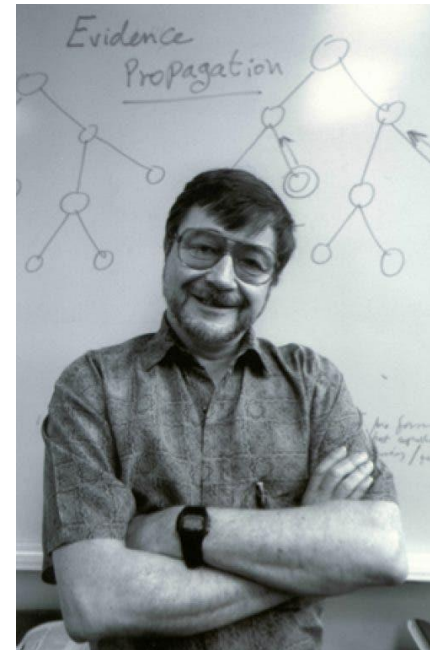
- Consider 3 random variables:
  - Temperature
  - Humidity
  - Season
- Temperature and humidity are not independent
- But they might be given the season
  - Season explains both and they become independent of each other

# Bayes Net

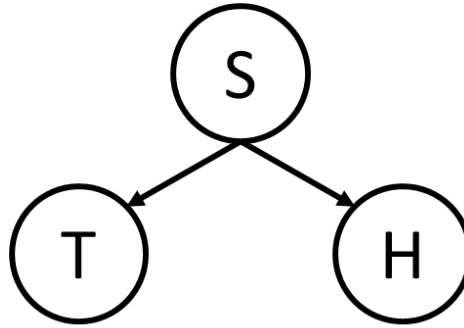
- A particular type of **graphical model**
  - A directed, acyclic graph
  - **Node** for each **RV**



- **Given parents, each RV independent of non-descendants**



# Bayes net



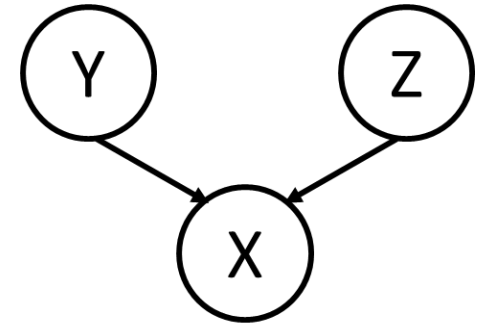
- JPD decomposes

$$P(x_1, \dots, x_n) = \prod_i P(x_i | \text{parents}(x_i))$$

- So for each node, store **conditional probability table (CPT)**:  $P(x_i | \text{parents}(x_i))$



# CPTs



- Conditional probability table
  - Probability distribution over variable **given parents**
  - One distribution per setting of parents

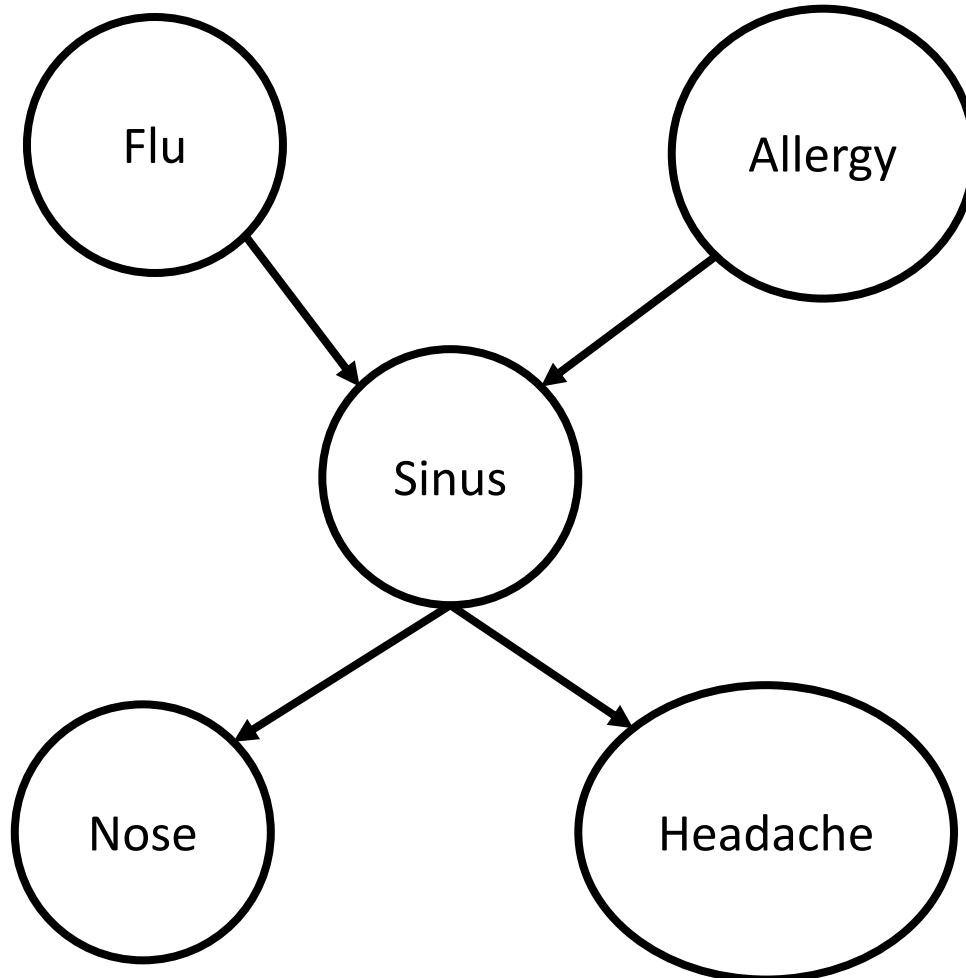
X	Y	Z	P
True	True	True	0.7
False	True	True	0.3
True	True	False	0.2
False	True	False	0.8
True	False	True	0.5
False	False	True	0.5
True	False	False	0.4
False	False	False	0.6

*X = variable of interest  
Y, Z = conditioning variables*

# Example

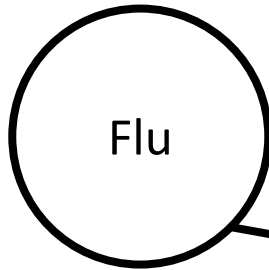
- Suppose we know
  - The flu causes sinus inflammation
  - Allergies cause sinus inflammation
  - Sinus inflammation causes a runny nose
  - Sinus inflammation causes headaches

# Example

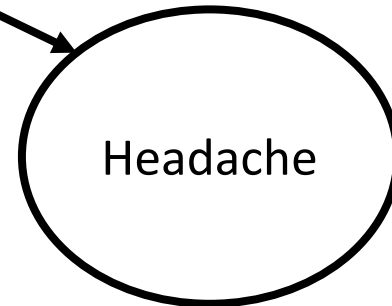
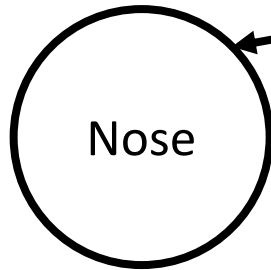
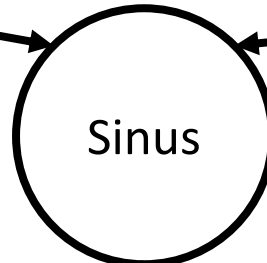


# Example

Flu	P
True	0.6
False	0.4



Allergy	P
True	0.2
False	0.8



Sinus	Flu	Allergy	P
True	True	True	0.9
False	True	True	0.1
True	True	False	0.6
False	True	False	0.4
True	False	True	0.2
False	False	True	0.8
True	False	False	0.4
False	False	False	0.6

Nose	Sinus	P
True	True	0.8
False	True	0.2
True	False	0.3
False	False	0.7

Headache	Sinus	P
True	True	0.6
False	True	0.4
True	False	0.5
False	False	0.5

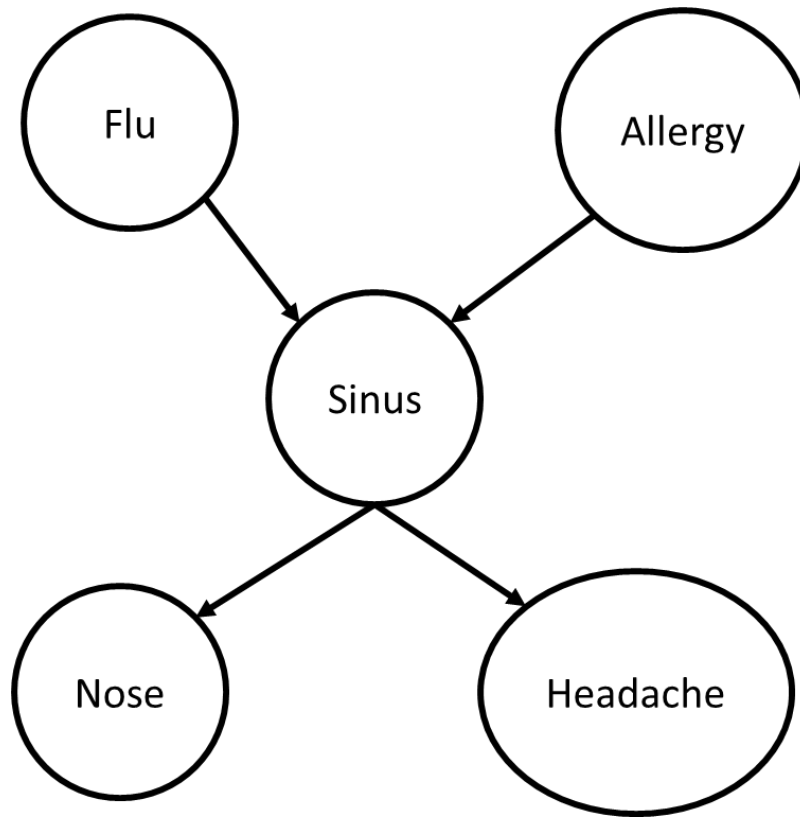
*Joint: 32 (31) entries*

# Uses

- Things you can do with a Bayes net
  - **Inference**: given some variables, posterior?
    - Might be **intractable** (NP-hard)
  - **Learning** (fill in CPTs)
  - **Structure learning** (fill in edges)
- Generally friendly
  - Often **few parents**
  - Inference cost **reasonable**
  - Can include **domain knowledge**

# Inference

- What is  $P(\text{flu} = \text{True} | \text{headache} = \text{True})$ ?



# Inference

$$P(f|h) = \frac{P(f, h)}{P(h)}$$

- Marginalisation:

$$P(a) = \sum_{B=T,F} P(a, B)$$

$$P(a) = \sum_{B=T,F} \sum_{C=T,F} P(a, B, C)$$

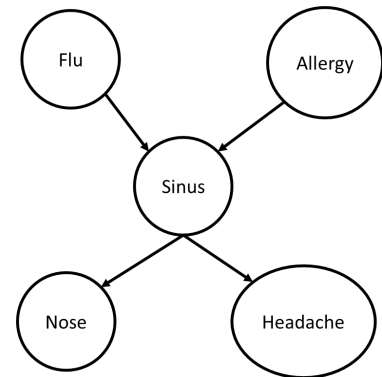
# Inference

$$P(f|h) = \frac{P(f, h)}{P(h)} = \frac{\sum_{SAN} P(f, h, S, A, N)}{\sum_{SANF} P(F, h, S, A, N)}$$

- We know that:

$$P(h) = \sum_{SANF} P(F, h, S, A, N)$$

$$P(h) = \sum_{SANF} P(h|S)P(N|S)P(S|A, F)P(F)P(A)$$





# Variable elimination

$$P(h) = \sum_{SANF} P(h|S)P(N|S)P(S|A, F)P(F)P(A)$$

- We can **eliminate variables** one at a time (distributive law)

$$P(h) = \sum_{SN} P(h|S)P(N|S) \sum_{AF} P(S|A, F)P(F)P(A)$$

$$P(h) = \sum_S P(h|S) \sum_N P(N|S) \sum_{AF} P(S|A, F)P(F)P(A)$$

# Variable elimination

$$P(h) = \sum_S P(h|S) \sum_N P(N|S) \sum_{AF} P(S|A, F) P(F) P(A)$$

$$\begin{aligned} & \text{Sinus true} \\ & 0.6 \times \sum_N P(N|S = \text{True}) \sum_{AF} P(S = \text{True}|A, F) P(F) P(A) \\ & + 0.5 \text{ Sinus false} \\ & \times \sum_N P(N|S = \text{False}) \sum_{AF} P(S = \text{False}|A, F) P(F) P(A) \end{aligned}$$

Headache	Sinus	P
True	True	0.6
False	True	0.4
True	False	0.5
False	False	0.5

# Variable elimination

$$P(h) = \sum_S P(h|S) \sum_N P(N|S) \sum_{AF} P(S|A, F) P(F) P(A)$$

$$\begin{aligned} &0.6 \\ &\times \left[ 0.8 \times \sum_{AF} P(S = \text{True}|A, F) P(F) P(A) + 0.2 \right. \\ &\times \sum_{AF} P(S = \text{True}|A, F) P(F) P(A) \left. \right] + 0.5 \\ &\times \left[ 0.3 \times \sum_{AF} P(S = \text{False}|A, F) P(F) P(A) + 0.7 \right. \\ &\times \sum_{AF} P(S = \text{False}|A, F) P(F) P(A) \left. \right] \end{aligned}$$

Nose	Sinus	P
True	True	0.8
False	True	0.2
True	False	0.3
False	False	0.7

# Variable elimination

- Cons:
  - How to **simplify** (hard in general)?
  - Computational complexity
  - Hard to **parallelise**
- Alternative?
  - **Sampling** approaches!
    - Based on drawing **random numbers**
    - Computationally expensive but **easy to code**
    - Easy to **parallelise**

# Sampling

- From a CPT
- General assumption:
  - Computer can generate (pseudo) random number between 0 and 1
- Generate  $x \in [0, 1]$ 
  - If  $x < 0.6$ , return True
  - else return False

Flu	P
True	0.6
False	0.4

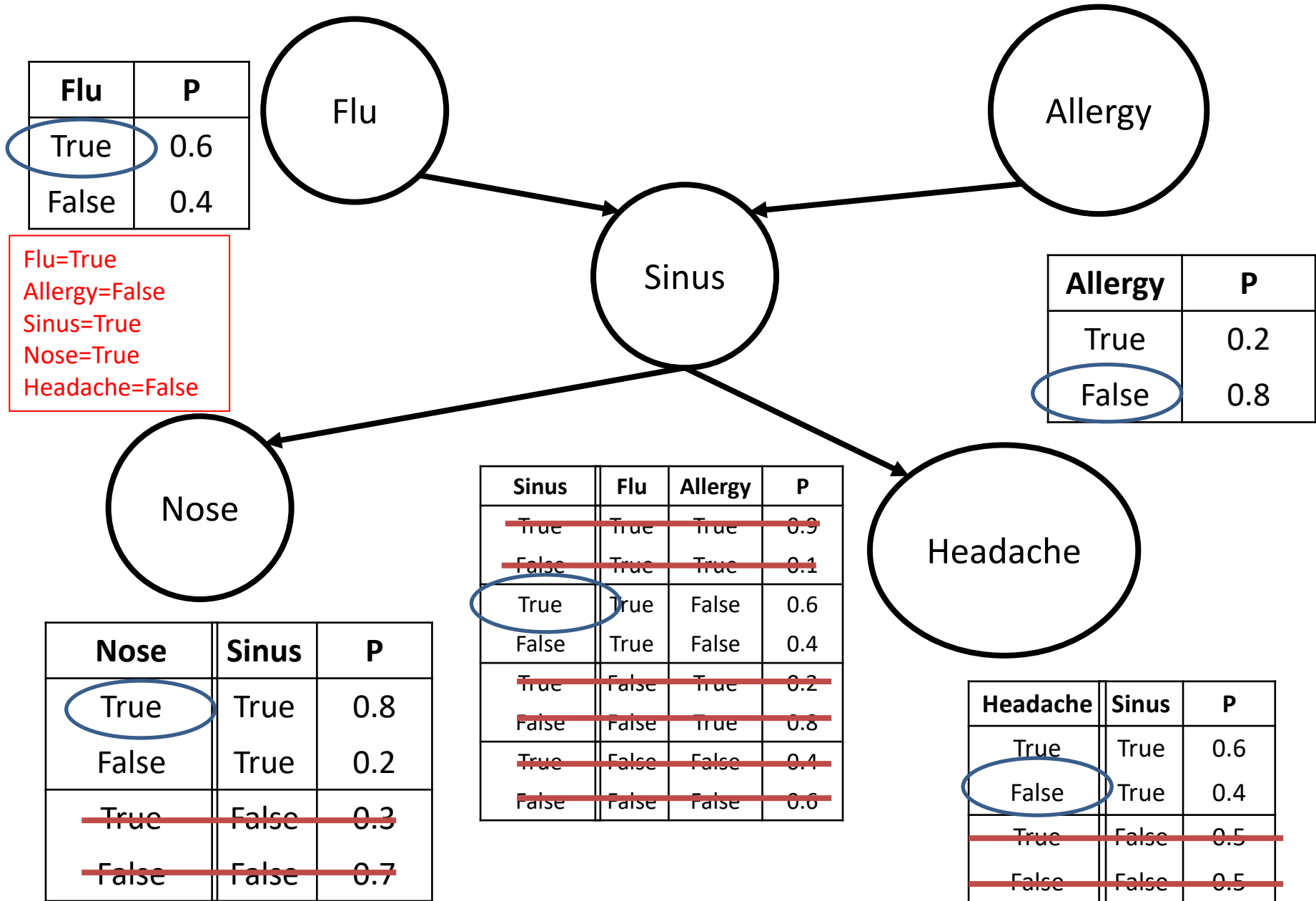
# Generative models

- How do we sample from a Bayes net?
- Bayes net is known as a **generative model**
- Describes generative process for the data
  - Each variable is generated by a distribution
  - Describes the **structure of that generation**
  - Can generate more data
- Natural way to include **domain knowledge via causality**

# Sampling the joint

- Algorithm for generating samples drawn from the joint distribution
- For each node with **no parents**:
  - Draw sample from marginal distribution
  - Condition children on choice (removes edge)
  - Repeat
- Results in artificial dataset
- Probability values?
  - Literally just count!

# Generative models





# Sampling the conditional

- What if we want to know  $P(A|B)$ ?
- We could use previous procedure and just divide data up based on  $B$
- What if we want  $P(A|b)$ ?
  - Could do the same, just use data with  $B = b$
  - Throw away rest of the data
  - Rejection sampling

# Rejection sampling

- Essentially, sample from  $Q$  instead of  $P$  and then keep if sample was likely to come from  $P$
- But lots of **rejecting in high dimensions**:
  - If  $P, Q$  are Gaussian but  $P$  has std dev 1% more
  - Then in 1000 dimensions...
    - Will reject 19999/20000 samples!

# Sampling the conditional

- What if  $b$  is uncommon?
- What if  $b$  involves many variables?
- Importance sampling:
  - Bias the sampling process to get more “hits”
    - New distribution  $Q$
  - Use reweighting trick to unbiased probabilities
    - Multiply by  $P/Q$  to get probability of sample

# Sampling

- Properties of sampling:
  - Slow: convergence  $O(\frac{1}{\sqrt{n}})$ 
    - But independent of dimension!
  - Always works
  - Always applicable
  - Easy to parallelise
  - Computers are getting faster

# Independence

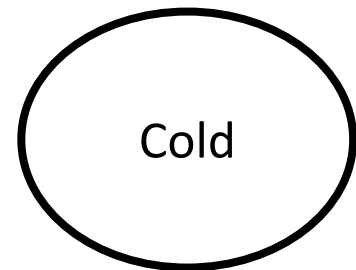
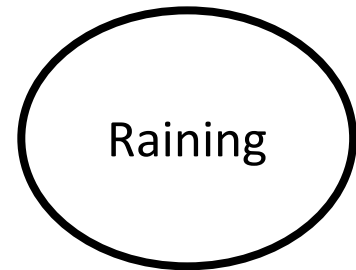
- What does it look like with a Bayes net?

Raining	Prob
True	0.6
False	0.4

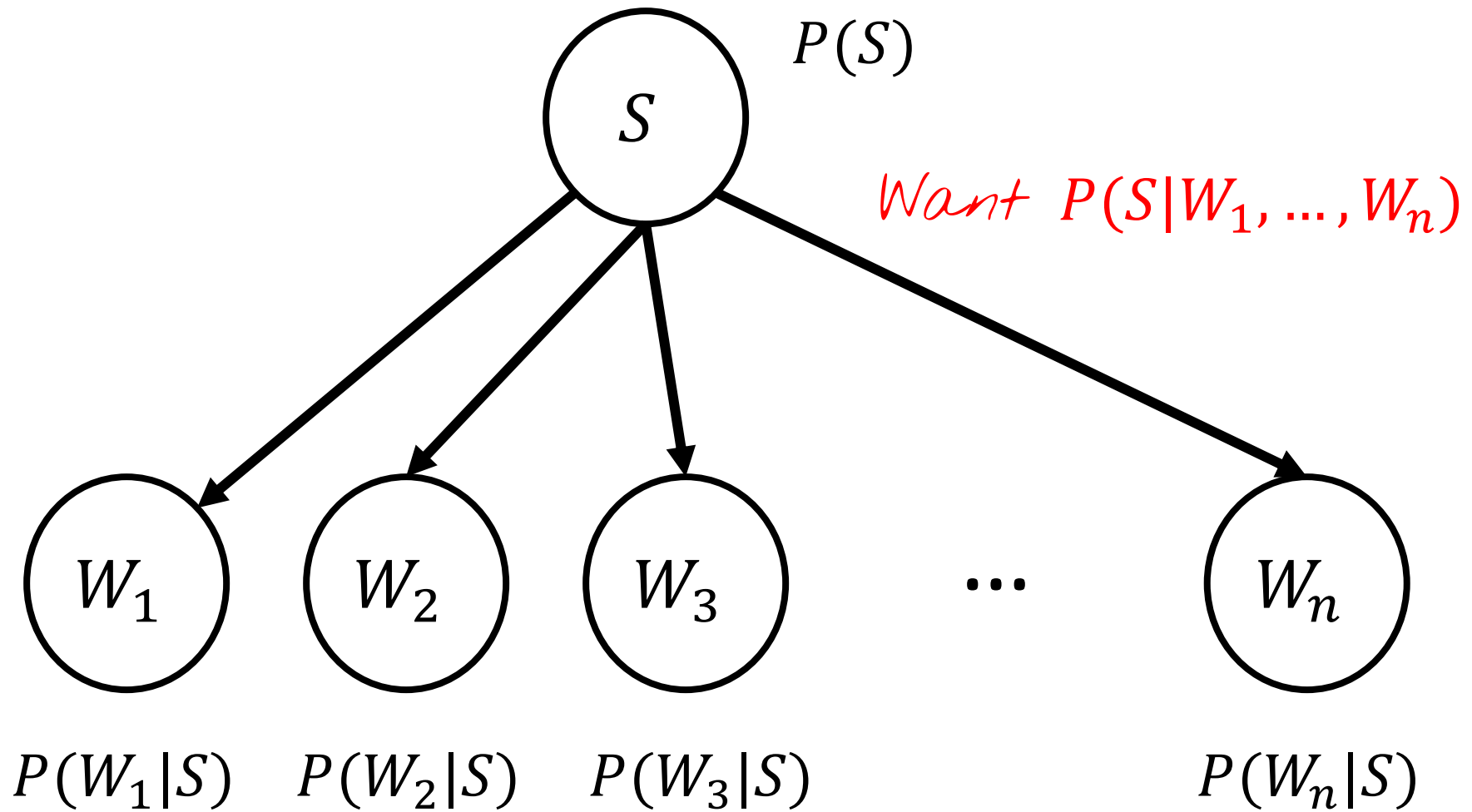
Cold	Prob
True	0.75
False	0.25



Raining	Cold	Prob
True	True	0.45
True	False	0.15
False	True	0.3
False	False	0.1



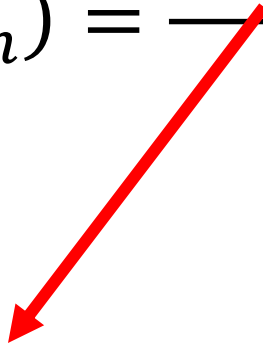
# Naïve Bayes



# Naïve Bayes

*Given*

$$P(S|W_1, \dots, W_n) = \frac{P(W_1, \dots, W_n|S)P(S)}{\cancel{P(W_1, \dots, W_n)}}$$



$$P(W_1, \dots, W_n|S) = \prod_i P(W_i|S)$$

*From Bayes net*



# Bayes nets

- Bayes nets are a **type of representation**
- Multiple inference algorithms; you can choose!
  - AI researchers talk about **models** more than **algorithms**
- Potentially very **compressed but exact**
  - Requires careful construction!

VS

- Approximate representation
  - Hope you're not too wrong!