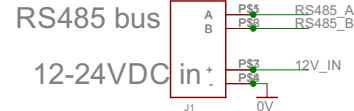
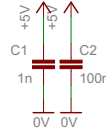
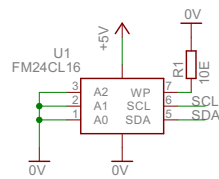
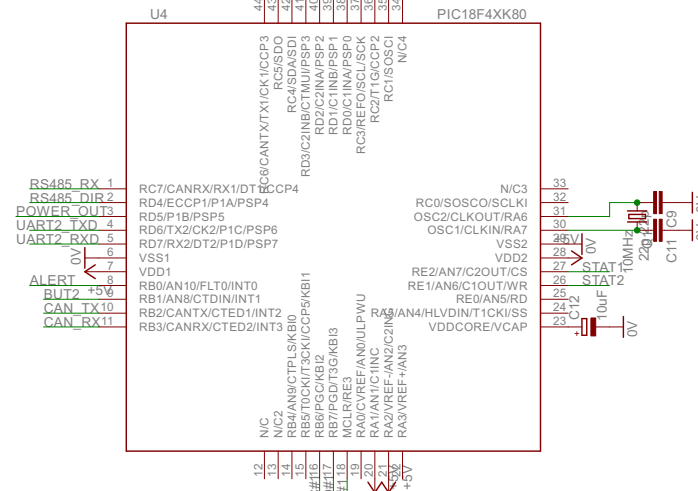
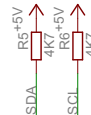


EEPROM

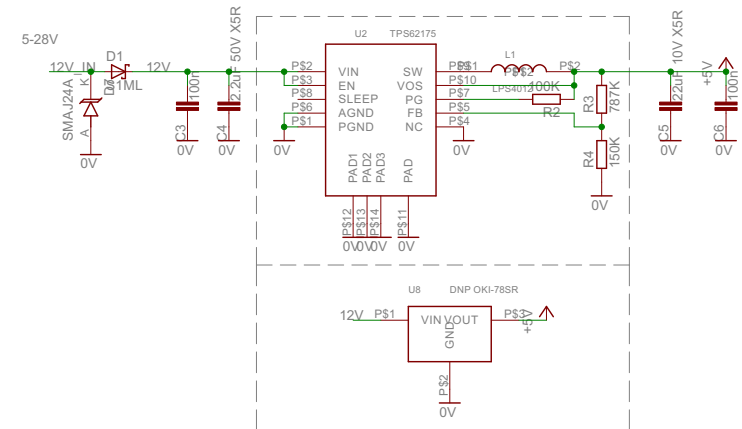


@16MHz & BRGH=1 & 16

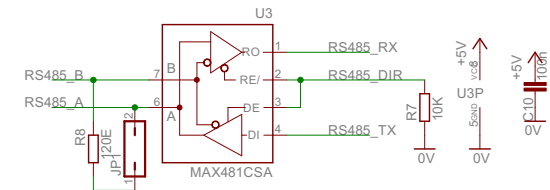
115200bps = 34 = 114286
57600 = 68 = 57971
38400 = 103 = 38462
19200 = 207 = 19231
9600 = 416 = 9592



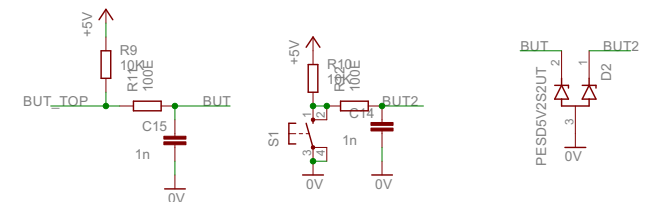
Voltage converters to 5V



RS485 convertor



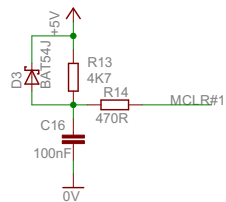
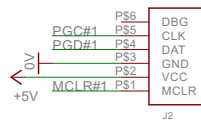
Button



Connector to toppanel PCB

J3G\$1
0V P33G\$2
BUT_TOP P33G\$3
0V P33G\$4
SCL P33G\$5
SDA P33G\$6
STAT2 P33G\$7
STAT1 P33G\$8
+5V P8
PIN

VERSION:
OMHCR_3_1



Project : OpenMotics
Designer : Niko Vinken

TITLE: OMHCR_3_2

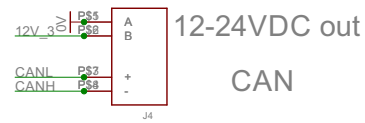
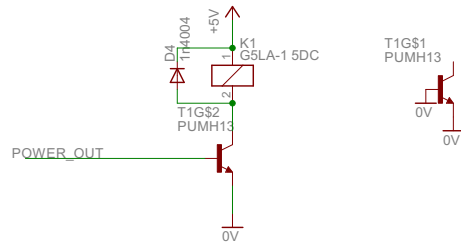
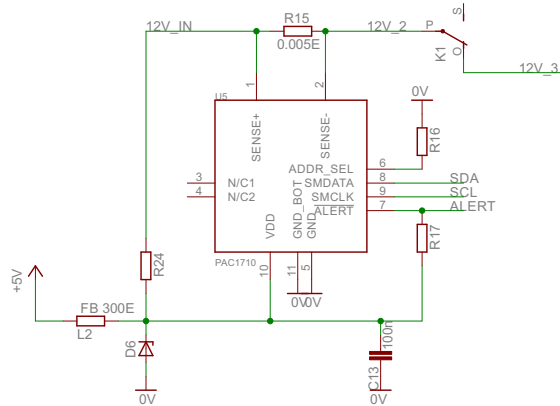
Document Number: Module : CAN control

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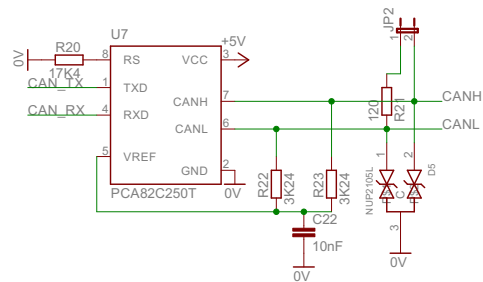
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Sheet: 1/2

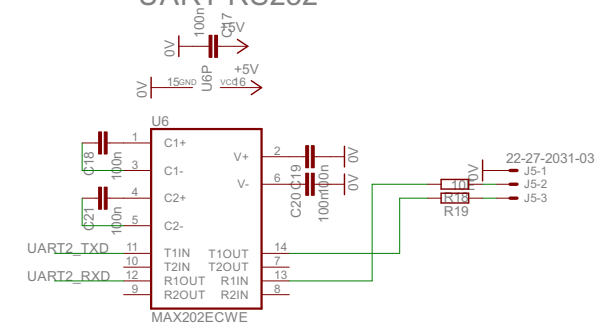
Voltage and current sensing



CAN convertor



UART RS232



Project : OpenMotics
Designer : Niko Vinken

TITLE: OMHCR_3_2

Document Number: Module : CAN control

REV:

Date: 2016-12-05 20:59:25

Sheet: 2/2