

Lecture-2

A review of calculus: Though the basic objects of study in this course are manifolds, these are locally Euclidean, i.e. every point has a neighbourhood \simeq an open ball in \mathbb{R}^n . This allows us to do calculus on such abstract objects, using what are called chart maps and transition maps. We therefore recall first the calculus on \mathbb{R}^n : A function $f: \mathbb{R} \rightarrow \mathbb{R}$ is differentiable at $a \in \mathbb{R}$ if $\lim_{x \rightarrow a} \frac{f(x) - f(a)}{x - a} =: \lambda$ exists; then we define the derivative f' of f at a to be λ , i.e. $f'(a) = \lambda$.

→ The derivative of f at a represents the best linear approximation of f at a .

The above may be rephrased as: $f: \mathbb{R} \rightarrow \mathbb{R}$ is diff at a with derivative $\lambda = f'(a)$ if $\lim_{x \rightarrow a} \frac{f(x) - f(a) - \lambda \cdot (x - a)}{x - a} = 0$.

→

² Since any \mathbb{R} -linear map $\phi: \mathbb{R} \rightarrow \mathbb{R}$ is of the form $\phi(x) = \alpha x$ for some $\alpha \in \mathbb{R}$ fixed, we may think of $\lambda \cdot (x-a)$ above as $\phi(x-a)$ for $\phi: \mathbb{R} \rightarrow \mathbb{R}, x \mapsto \lambda \cdot x$. This leads & motivates us to define

Defⁿ: A map $f: \mathbb{R}^n \rightarrow \mathbb{R}^m$ is differentiable at $a \in \mathbb{R}^n$ if \exists a linear map $\lambda: \mathbb{R}^n \rightarrow \mathbb{R}^m$ such that
$$\lim_{h \rightarrow 0} \frac{\|f(a+h) - f(a) - \lambda(h)\|}{\|h\|} = 0$$

(Note that the norms on numerator & denominator are in \mathbb{R}^m & \mathbb{R}^n resp.).

Exercise 1: Let $f: \mathbb{R}^n \rightarrow \mathbb{R}^m$ be diff at $a \in \mathbb{R}^n$ and $T_i: \mathbb{R}^n \rightarrow \mathbb{R}^m$ be linear maps, $i=1,2$, such that
$$\lim_{h \rightarrow 0} \frac{\|f(a+h) - f(a) - T_i(h)\|}{\|h\|} = 0$$

for $i=1,2$; then $T_1 = T_2$.

2. For sufficiently small $x \in \mathbb{R}^n$ we have

$f(a+x) = f(a) + \lambda(x) + \|x\| \epsilon(x)$, where $\epsilon(x)$ satisfies $\lim_{x \rightarrow 0} \epsilon(x) = 0$.

Notation :- The linear map λ as above, if it exists, is denoted by $Df(a)$ and is called the derivative of f at a .

So $Df(a)$ is a linear transformation
 $: \mathbb{R}^n \rightarrow \mathbb{R}^m$.

Exercise : For any $x \in \mathbb{R}^n$,

$$Df(a)(x) = \lim_{t \rightarrow 0} \frac{1}{t} [f(a+tx) - f(a)].$$

Computing $Df(a)$:- For this, we'll compute

the matrix of $Df(a) \in M_{m \times n}(\mathbb{R})$, where

we write $Df(a) = [C_1 \cdots C_n]$, C_i are the columns of $Df(a)$, and $C_i := Df(a)(e_i)$.

By the above exercise

$$Df(a)(e_j) = \lim_{t \rightarrow 0} \frac{1}{t} [f(a+te_j) - f(a)]$$

→ We can write $f: \mathbb{R}^n \rightarrow \mathbb{R}^m$ in terms of its coordinate functions $f = (f_1, \dots, f_m)^t$,

$f_i: \mathbb{R}^n \rightarrow \mathbb{R}$, $1 \leq i \leq m$; so $f = \sum_{j=1}^m f_j e_j'$,

$e_j' = (0, \dots, 0, \overset{j^{\text{th}}}{1}, 0, \dots, 0)^t$.

Hence we have \leadsto

$$^4 \quad f(a+te_j) - f(a) = \begin{pmatrix} f_1(a+te_j) - f_1(a) \\ \vdots \\ f_i(a+te_j) - f_i(a) \\ \vdots \\ f_m(a+te_j) - f_m(a) \end{pmatrix}$$

and $f_i(a+te_j) - f_i(a)$, for $a = \sum_{k=1}^n a_k e_k$

$$= f_i((a_1, \dots, a_{j-1}, a_j+t, a_{j+1}, \dots, a_n)^t)$$

$$- f_i((a_1, \dots, a_j, \dots, a_n)^t). \text{ Thus, the}$$

i th row of the j th column of $Df(a)$ is

$$\lim_{t \rightarrow 0} \frac{f_i((a+te_j)) - f_i(a)}{t} = (ij)^{\text{th}} \text{ entry of}$$

the matrix of $Df(a)$.

Defⁿ (Partial derivatives): For $\varphi: \mathbb{R}^n \rightarrow \mathbb{R}$

and $a \in \mathbb{R}^n$, the partial derivative of f at $a = (a_1, \dots, a_n)^t$ with respect to x_i (the i th coordinate) is the limit

$$\frac{\partial \varphi}{\partial x_i} \Big|_a = \lim_{t \rightarrow 0} \frac{\varphi((a_1, \dots, a_{i-1}, a_i+t, a_{i+1}, \dots, a_n)) - \varphi((a_1, \dots, a_n))}{t},$$

if it exists. We therefore have



$$Df(a) = (a_{ij}) \text{ where } a_{ij} = \frac{\partial f_i}{\partial x_j} \Big|_a.$$

This matrix is called the Jacobian matrix of f at a .

Examples :- Let $f: \mathbb{R}^n \rightarrow \mathbb{R}$ be a diff. funcⁿ.

The derivative of f at $p \in \mathbb{R}^n$, $Df(p)$ is a $1 \times n$ matrix, i.e. a row vector, called the gradient of f at p .

$$(\nabla f)|_p = \left(\frac{\partial f}{\partial x_1} \Big|_p, \dots, \frac{\partial f}{\partial x_n} \Big|_p \right).$$

The level sets of f are the sets $f^{-1}(c)$, $c \in \mathbb{R}$. For generic c , these give hyper-surfaces in \mathbb{R}^n , i.e. geom. objects having $\dim n-1$, $\subseteq \mathbb{R}^n$. Since f is differentiable, for generic c , these objects are 'differentiable'.

To make sense of this, assume that $p \in S := f^{-1}(c)$ is such that \rightarrow

⁶ $\nabla f|_p \neq 0$. Then $\nabla f|_p$ would constitute a normal at p to the hyper-surface $S \subseteq \mathbb{R}^n$. If $\nabla f|_p \neq 0$, we can define

$$T_p S = \left\{ (b_1, \dots, b_n) \in \mathbb{R}^n \mid \langle \nabla f|_p, (b_1 - a_1, \dots, b_n - a_n) \rangle = 0 \right\}$$

where $p = (a_1, \dots, a_n)$.

$$= \left\{ (b_1, \dots, b_n) \in \mathbb{R}^n \mid \sum_{i=1}^n \frac{\partial f}{\partial x_i} \Big|_p \cdot (b_i - a_i) = 0 \right\},$$

the tangent space to S at p .

Remark:- There are examples (?) of $f: \mathbb{R}^n \rightarrow \mathbb{R}^m$ such that $\frac{\partial f_i}{\partial x_j} \Big|_a$ exist $\forall i, j$, yet f is not continuous at a .

$\rightarrow f: \mathbb{R}^n \rightarrow \mathbb{R}^m$ is diff at $a \Rightarrow f$ is cont. at a .

Thm:- $Df(a)$ exists if all $\partial f_i / \partial x_j$ exist at all points in an open nbd of a and if each $\partial f_i / \partial x_j$ is continuous at a . \square

7 Chain rule :- If $f: U \rightarrow \mathbb{R}^m$ and $g: V \rightarrow \mathbb{R}^l$,
 Where $U \subseteq \mathbb{R}^n$ and $V \subseteq \mathbb{R}^m$ are open and
 $f(U) \subseteq V$; f is diff at $a \in U$, g is diff
 at $f(a) \in V$; then the composite
 $g \circ f: U \rightarrow \mathbb{R}^l$ is diff. at a and its
 derivative at a is given by

$$D(g \circ f)(a) = Dg(f(a)) \circ Df(a)$$

$$\mathbb{R}^n \xrightarrow{Df(a)} \mathbb{R}^m \xrightarrow{Dg(f(a))} \mathbb{R}^l$$

$$Dg(f(a)) \circ Df(a) = D(g \circ f)(a)$$

→ If $L: \mathbb{R}^n \rightarrow \mathbb{R}^m$ is an affine map,
 i.e. $\exists T: \mathbb{R}^n \rightarrow \mathbb{R}^m$ linear & $v \in \mathbb{R}^m$
 with $L(x) = T(x) + v \quad \forall x \in \mathbb{R}^n$; Then
 L is differentiable and $DL(a) = T \quad \forall$
 $a \in \mathbb{R}^n$.

→ $f, g: U \rightarrow \mathbb{R}^m$ be diff at $a \in U \subseteq \mathbb{R}^n$;
 U open;

$\alpha, \beta \in \mathbb{R}$, then $\alpha f + \beta g$ is diff at a .

→ $f, g: U \rightarrow \mathbb{R}$ diff at $a \in U \Rightarrow f \cdot g$ diff at a .

If $f(x) \neq 0 \quad \forall x \in U$, then $x \mapsto f(x)^{-1}$ is
 also diff at a . →

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→ Hence any polynomial function $P: \mathbb{R}^n \rightarrow \mathbb{R}$ is differentiable at all points; a rational function $f: \mathbb{R}^n \rightarrow \mathbb{R}$, $f(x) = \frac{P(x)}{Q(x)}$ where P & Q are polynomials, is differentiable on the open set $U = \mathbb{R}^n - Z(Q)$, $Z(Q) = \{x \in \mathbb{R}^n \mid Q(x) = 0\}$.

Exercise :- 1. Identify $M_n(\mathbb{R})$ with \mathbb{R}^{n^2} . Then

$GL_n(\mathbb{R}) = \{A \in M_n(\mathbb{R}) \mid \det(A) \neq 0\}$ is open. Prove that $i: GL_n(\mathbb{R}) \rightarrow GL_n(\mathbb{R})$ $x \mapsto x^{-1}$ is differentiable at all points in $GL_n(\mathbb{R})$.

2. Consider $f: \mathbb{R}^2 \rightarrow \mathbb{R}; (x, y) \mapsto \begin{cases} \frac{x|y|}{(x^2+y^2)^{3/2}}, & (x, y) \neq (0, 0) \\ 0, & x=y=0. \end{cases}$

show that f is not diff at $(0, 0)$, both partial derivatives exist at $(0, 0)$.

• show that restriction of f to every line passing through $(0, 0)$ is diff.

— — — — — x — — — — — x — — — — — x — — — — — x — — — — —