

KALINGA INSTITUTE OF INDUSTRIAL TECHNOLOGY (KIIT)

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LABORATORY RECORD - AUTUMN 2020

MICROWAVE ENGINEERING LAB (EC 3015)

DEBAGNIK KAR

ROLL NO: 1804373 Section: ETC-06

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Experiment Number	01
Date of Experiment	12/08/2020
Date of Submission	16/08/2020
Name of the student	Debagnik Kar
Roll Number	1804373
Section	ETC – 06

Aim of The Experiment: -

To design a quarter wave transformer for matching a 50 Ω microstrip line with a load of 173 Ω

Equipment / Software Required:-

CST Studio Suite 2019 (Student Edition)

Theory:

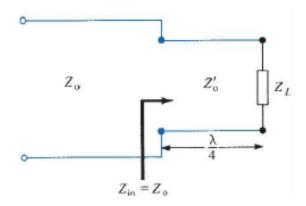


Fig 1.1: Load matching using a quarter wave transformer

When $Z_0 \neq Z_L$, the load is said to be mismatched and a reflected wave exist. So, we use quarter wave transformer for impedance matching.

when
$$l = \frac{\lambda}{4}$$
,

$$Z_{in} = Z_0 \left[\frac{Z_L + \frac{jZ_0 \tan \pi}{2}}{Z_0 + \frac{jZ_L \tan \pi}{2}} \right] = \frac{Z_0^2}{Z_L}$$

A mismatched load can be properly matched to a line (with characteristic impedance Z_0) by inserting prior to the transmission line $\lambda/4$ long (with characteristic impedance Z_0) as depicted in Fig.1.

From (1), Z_0 is selected such that ($Z_{in}=Z_0$)

Therefore,

$$Z_0^{\dagger} = \sqrt{Z_0 Z_L} \tag{2}$$

Note: When microstrip line is used, then guided wavelength must be used, i.e.,

$$\lambda_g = \frac{\lambda_0}{\sqrt{\varepsilon_{eff}}}$$

where, λ_g = guided wavelength.

When $Z_0 \neq Z_L$, the load is said to be mismatched and a reflected wave exist. So, we use quarter wave transformer for impedance matching.

when
$$l=\frac{\lambda}{4}$$
,

$$Z_{in} = Z_0 \left[\frac{Z_L + \frac{jZ_0 \tan \pi}{2}}{Z_0 + \frac{jZ_L \tan \pi}{2}} \right] = \frac{Z_0^2}{Z_L}$$

(1)

A mismatched load can be properly matched to a line (with characteristic impedance Z_0) by inserting prior to the transmission line $\lambda/4$ long (with characteristic impedance Z_0) as depicted in Fig.1.

From (1), Z_0 is selected such that ($Z_{in}=Z_0$)

Therefore,

$$Z_0' = \sqrt{(Z_0 Z_L)}$$

 $Z_0 = 50$

 $Z_{L} = 173$

$$Z_0' = \sqrt{(50 \times 173)}$$

$$Z_0' = 93.01 \,\Omega$$
 (2)

Note: When microstrip line is used, then guided wavelength must be used ,i.e.,

$$\lambda_g = \frac{\lambda_0}{\sqrt{\varepsilon_{eff}}} \tag{3}$$

where, λ_g = guided wavelength.

Substrate: FR4 (Lossless) ($\varepsilon_r = 4.3$)

Width of the substrate is 50 mm and the length are 100 mm

h = 1.6 mm

t = 0.2 mm

W = 2.93 mm (determined using Analysis and synthesis of transmission lines)

 $\varepsilon_{eff} = 3.204$

 $Z_0' = 93.01 \Omega \text{ length} = 17 \text{ mm}$

Therefore, width of the quarter wave line is 0.87mm

Design:

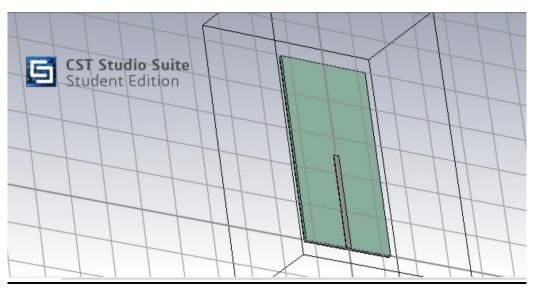


Fig 1.2: Design of microstrip line terminated with the desired load.

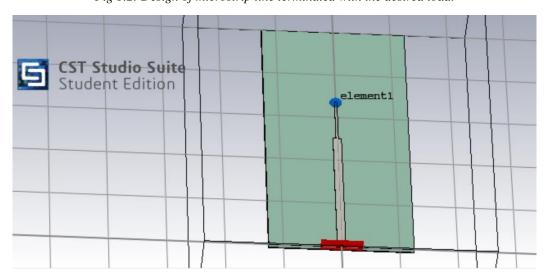


Fig 1.3: Design of microstrip line terminated with quarter wave line and desired load

Output/Graph:-

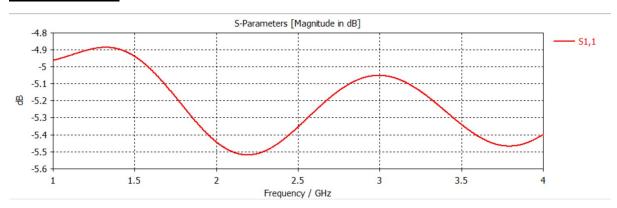


Fig 1.4: Result of the design of the microstrip line

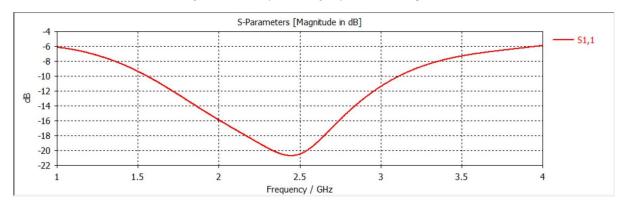


Fig 1.5: Result of the design of the microstrip line terminated by quarter wave line.

Observation of the experiment:

- For fig 4, No resonance is observed around 2.4 GHz which implies impedance mismatch.
- For fig 5, an impedance is achieved at 2.4 GHz by using a quarter wave transformer.

Conclusion:-

The designing of a quarter wave transformer for matching a 50 Ω microstrip line with a load of 173 Ω is successfully achieved.

Experiment Number	02
Date of Experiment	19/08/2020
Date of Submission	24/08/2020
Name of the student	Debagnik Kar
Roll Number	1804373
Section	ETC - 06

Aim of The Experiment:-

To design a wire dipole antenna operating at 373 MHz and to find the directive gain and half power beam width from the radiation pattern.

Software Required:-

CST Studio Suite 2019 (Student Edition)

Theory

The length of the Dipole Antenna is given by the formula:

$$L = \frac{\lambda}{2} = \frac{c}{2f}$$

f = 373 MHz

The length of the dipole is 0.402 m = 402 mm

For the 402 mm length, we have got, 0.373 GHz which is far from our desired result, so we can't consider it as our result.

We know, the input impedance = $(73 \pm 40j)$

To cancel the complex part, we have to use a shorter length.

I am taking 360 mm to get a value which is nearly equal to the desired result 0.373 GHz

Design:-

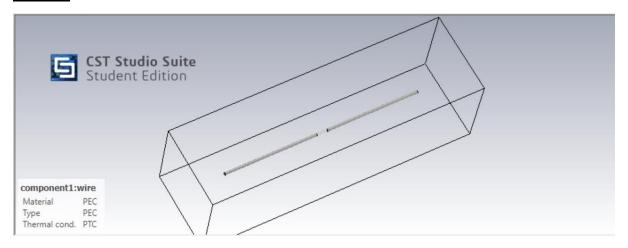


Fig 2.1: Design of wire dipole antenna

Observation:-

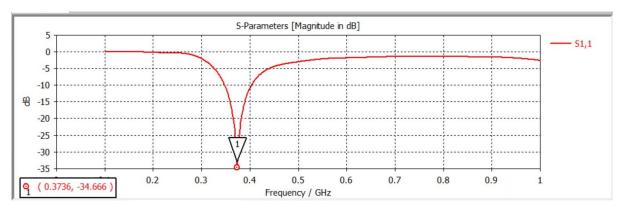


Fig 2.2: S11 Characteristics

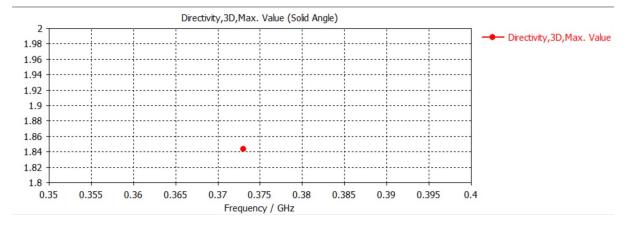


Fig 2.3: Directive Gain

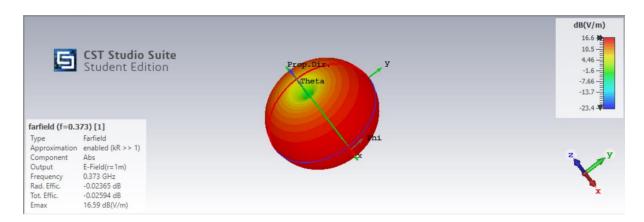


Fig 2.4: Radiation Pattern in X-Z and X-Y plane

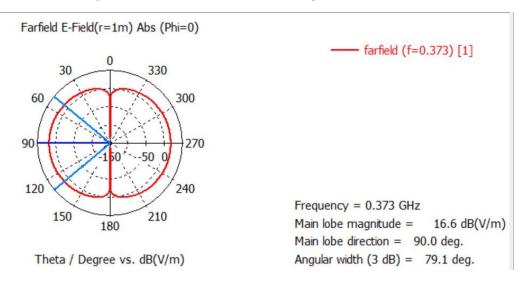


Fig 2.5: Plane radiation pattern and half powered beam width

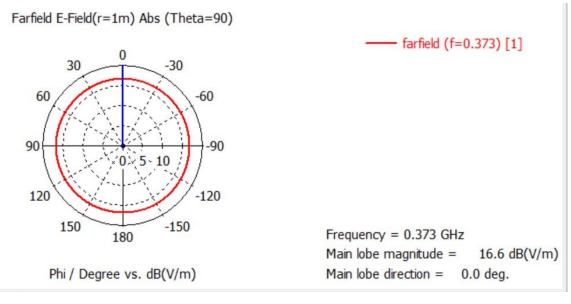


Fig 2.6: H-plane omni-directional Radiation Pattern

Inference of the experiment:

From this experiment, we learnt how to design a wire dipole antenna using CST Studio Suite. We also got to learn about the concept of radiation pattern after performing the experiment

Conclusion:-

A successful design of a wire dipole antenna operating at 373 MHz is successfully simulated on a virtual platform.

Experiment Number	03
Date of Experiment	26/08/2020
Date of Submission	30/08/2020
Name of the student	Debagnik Kar
Roll Number	1804373
Section	ETC - 06

Aim of The Experiment:-

To design Yagi-Uda Array antenna and to find the directivity and Half power beam width form the radiation patterns.

Software Required:-

CST Studio Suite 2019 (Student Edition)

Theory

The Yagi antenna consists of a single 'feed' or 'driven' element, typically a dipole or a folded dipole antenna. This is the only member of the above structure that is actually excited (a source voltage or current applied). The rest of the elements are parasitic - they reflect or help to transmit the energy in a particular direction. The length of the feed element is given as F. The feed antenna is almost always the second from the end. This feed antenna is often altered in size to make it resonant in the presence of the parasitic elements (typically, 0.45-0.48 wavelengths long for a dipole antenna).

The element to the left of the feed element is the reflector. The length of this element is given as R and the distance between the feed and the reflector is SR. The reflector element is typically slightly longer than the feed element. There is typically only one reflector; adding more reflectors improves performance very slightly. This element is important in determining the front-to-back ratio of the antenna.

Calculations:

Operating Frequency: 0.73GHz

Therefore wavelength, $\lambda = \frac{Speed\ of\ light\ (c)}{Given\ frequency(f)} = 410.1\ meters$

Length of feeder: $0.47 \lambda = 192.75 \text{ m}$

Length of reflector: $0.5 \lambda = 205.05 \text{ m}$

Length of director: $0.406 \lambda = 166.50 \text{ m}$

Spacing between the feeder and reflector: $0.25 \lambda = 102.53 \text{ m}$

Spacing between feeder and director: $0.34 \lambda = 139.43 \text{ m}$

But the calculated values may not give the desired results so I took the following values instead which is very close to the calculated values but will also give me the desired result.

Length of feeder: 167.5 m

Length of reflector: 179.5 m

Length of director: 141 m

Spacing between the feeder and reflector: 143.34 m

Spacing between feeder and director: 108.52 m

Design:-

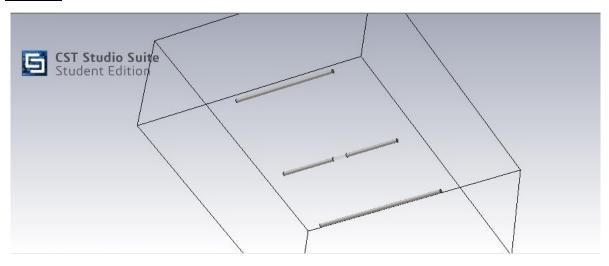


Fig 3.1: Design of the antenna

Observation:-

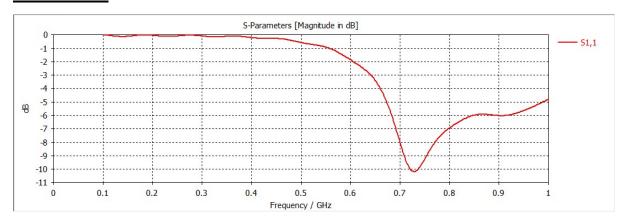


Fig 3.2: S11 Characteristics

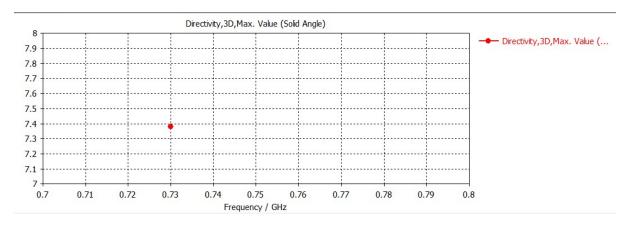


Fig 3.3: Directivity gain

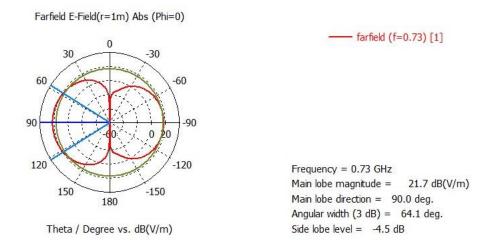


Fig 3.4: Plane radiation pattern and half powered beam width

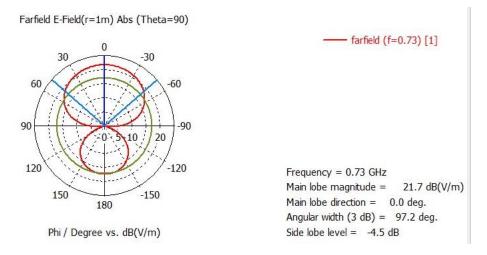


Fig 3.5: H-plane omni-directional Radiation Pattern.

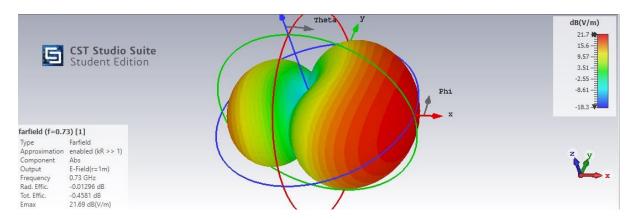


Fig 3.5: Radiation Pattern in X-Z and X-Y plane

Discussion or Inference of the experiment

From this experiment I came to know about the working of Yagi-Uda Antenna and the radiation pattern of it

Conclusion:-

Design of Yagi-Uda Array antenna is executed successfully at 0.73MHz frequency on a virtual platform and the directivity and Half power beam width form the radiation patterns is attached with the lab record.

Experiment Number	04
Date of Experiment	02/09/2020
Date of Submission	03/09/2020
Name of the student	Debagnik Kar
Roll Number	1804373
Section	ETC - 06

Aim of The Experiment :-

Design of a pyramidal Horn Antenna and study its radiation characteristics.

Software Required:-

CST Studio 2019 (Student Suite)

Theory

Design equations

$$\tan \frac{\theta}{2} = \frac{a}{2L}$$

$$L = \frac{a^2}{8\delta}$$

$$\theta = 2 \cdot \arctan\left(\frac{a}{2L}\right) = 2\cos\left(\frac{L}{L+\delta}\right)$$

where, θ = flare angle (θ_E for E plane, θ_H for H plane).

a= aperture (a_E for E plane, a_H for H plane)

L=horn length

 δ = path length difference

Here We are designing a pyramidal horn antenna operating at 5.5GHz ie λ = 0.054m = 54mm. Take δ = 0.17 λ = 0.0092 and L = 160mm

Form $L = \frac{a^2}{8\delta}$ we get, a = 108.5 mm for both E and H plane.

Design:-

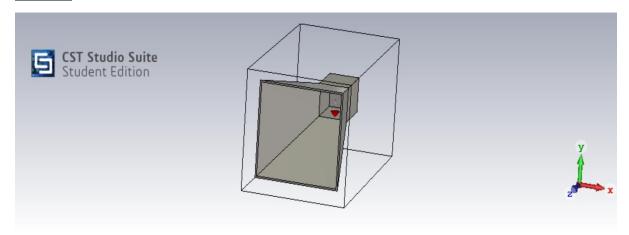


Fig 4.1: 3D model of the design

Observation:-

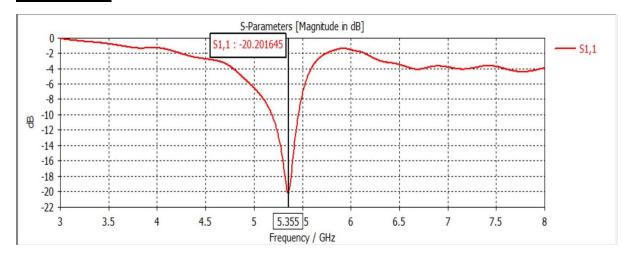
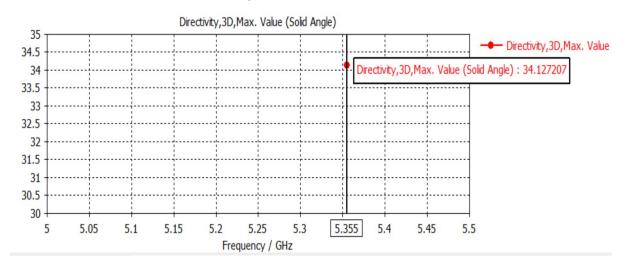


Fig 4.2: S11 Characteristics



4.3: Directivity Gain

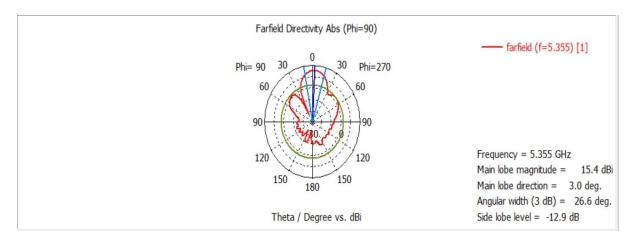


Fig 4.4: Polar Plot

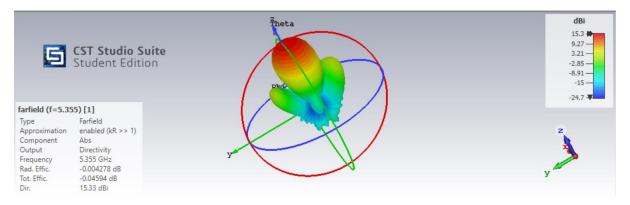


Fig 4.5: Radiation Pattern in X-Z and X-Y plane

Discussion or Inference of the experiment

From this experiment I learnt about the working principle of a horn antenna and the radiation pattern of it.

Conclusion:-

Design of horn Array antenna is executed successfully at 5.5 GHz frequency on a virtual platform and the directivity and Half power beam width form the radiation patterns is attached with the lab record.

Experiment Number	05
Date of Experiment	09/09/2020
Date of Submission	10/09/2020
Name of the student	Debagnik Kar
Roll Number	1804373
Section	ETC-06

Aim of The Experiment:-

Design a 73-element optimal isotropic antenna array with maximum side lobe level of -20 dB. Also calculate the half power beam width and beam width between 1st nulls.

Software Required:-

MATLAB 2018a

Code:-

```
<<<File: Exp_5_1.m comment: Plot Tchebyscheff polynomials of order 5>>>
```

```
%PS 5.1 Plotting Tchebyscheff Polynomials of orders 5 and 6
% Written By Debagnik Kar 1804373

clc
clear all
close all

x=linspace(-1.5,1.5,1000)

m=input('Enter the value of order(m): ')

for i=1:1000
    if abs(x(i))<=1
        y(i)=cos(m*acos(x(i)))
    else
        y(i)=cosh(m*acosh(x(i)))
    end
end

plot(x,y)</pre>
```

```
grid on
xlabel('Values of x --->')
ylabel('Tm(x)--->')
title('Plotting Tchebyscheff Polynomials')
<<<File: Exp_5_1.m comment: Plot Tchebyscheff polynomials of order 5>>>
%PS 5.1 Plotting Tchebyscheff Polynomials of orders 5 and 6
% Written By Debagnik Kar 1804373
clc
clear all
close all
x=linspace(-1.5, 1.5, 1000)
m=input('Enter the value of order(m): ')
for i=1:1000
    if abs(x(i))<=1
         y(i) = cos(m*acos(x(i)));
    else
         y(i) = \cosh(m*a\cosh(x(i)));
    end
end
plot(x, y)
grid on
xlabel('Values of x --->')
ylabel('Tm(x)--->')
title('Plotting Tchebyscheff Polynomials')
<<<File: Exp_5_2.m Comment: Simulating an optimal isotropic antenna array and calculation
of HPBW>>>
%PS5 2 Simulating an optimal isotropic antenna array and
calculation of HPBW
%Written by Debagnik Kar 1804373
clc
clear all
close all
```

```
N = 20
                         %number of isotropic antenna elements
SLL=-20
                         %Desired Side lobe level
b=1/(10^{(SLL/20)})
order=N-1
                         %Order of Tchebyscheff polynomial
xo=cosh(acosh(b)/order)
k = linspace(0, 0, order)
dk = linspace(0, 0, order)
xk = linspace(0, 0, order)
sk = linspace(0, 0, order)
for index=1:order
    k(index)=index
    dk(index) = (2*index-1)*pi/(2*order)
    xk(index) = cos(dk(index))
    sk(index) = 2*acos(xk(index)/xo)
end
f=3*(10^9)
lo=3*(10^8)/f
beta=2*pi/lo
d=0.5*10
%Calculation of Array Factor
ang=linspace(0,pi,361);
AF=linspace(0,0,361);
AF2 = linspace(0, 0, 361);
for index=1:361
    ag=ang(index);
    AF(index)=1;
    si=beta*d*cos(aq);
    for jj=1:order
        AF(index) = AF(index) * (exp(si*1i) - exp(sk(jj)*1i))
    end
    AF2 (index) = abs (AF (index))
AF2(1:361) = AF2(1:361) / max(AF2, 'g')
plot(ang*180/pi,20*log10(AF2))
grid on
xlabel('Elevation angle (degrees)')
ylabel('Array Factor (dB)')
title('Simulating the antenna array')
%Calculating HPBW
HPBW=0
for index=182:361
    if AF2(index) > 0.707
        HPBW=2*(ang(index)-pi/2)*180/pi;
    end
end
```

Output/Graph:-

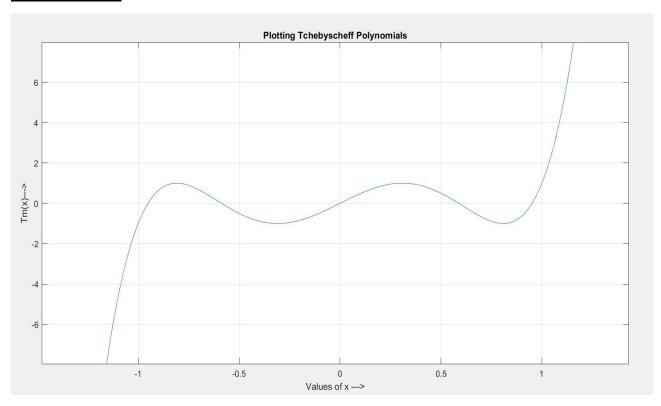


Fig 5.1: Plotting Tchebyscheff Polynomials in order 5

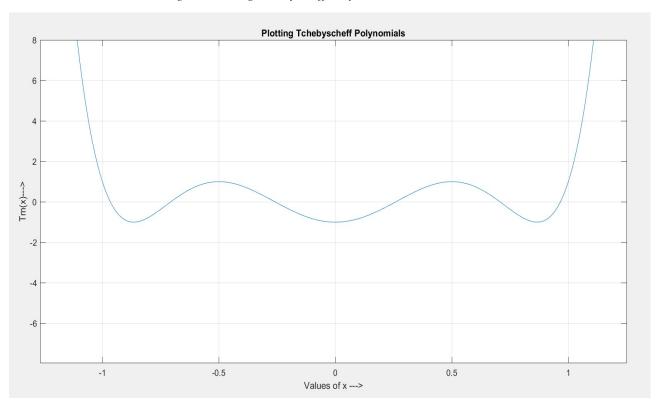


Fig 5.2: Plotting Tchebyscheff Polynomial in order 6

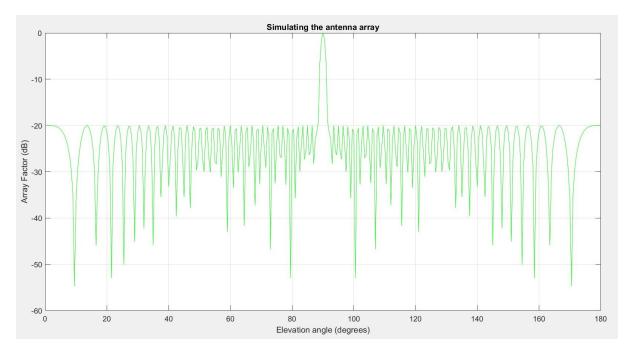


Fig 5.3: Simulation of Array Antenna

Observation:

Maximum SLL (dB)	-20
HPBW (Degrees)	1.075
BWFN (Degrees)	3.5

Conclusion:-

After successfully simulating the 73-element optimal isotropic antenna array we are able to observe the Tchebyshev polynomial plots for different orders and radiation pattern. We also found out the HPBW and BWFN was found out to be 1.0750 & 3.5000 respectively.

Experiment Number	06
Date of Experiment	Design of a rectangular waveguide for cut-off frequency of 6.373GHz in the dominant mode
Date of Submission	07/10/2020
Name of the student	Debagnik Kar
Roll Number	1804373
Section	ETC-06

Aim of The Experiment:

Design of a rectangular waveguide for cut-off frequency of 6.373GHz in the dominant mode

Software Required:-

CST Studio 2019 Student Edition

Theory:

In radio-frequency engineering and communications engineering, waveguide is a hollow metal pipe used to carry radio waves. This type of waveguide is used as a transmission line mostly at microwave frequencies, for such purposes as connecting microwave transmitters and receivers to their antennas, in equipment such as microwave ovens, radar sets, satellite communications, and microwave radio links.

The electromagnetic waves in a (metal-pipe) waveguide may be imagined as travelling down the guide in a zig-zag path, being repeatedly reflected between opposite walls of the guide. For the particular case of rectangular waveguide, it is possible to base an exact analysis on this view. Propagation in a dielectric waveguide may be viewed in the same way, with the waves confined to the dielectric by total internal reflection at its surface. Some structures, such as non-radiative dielectric waveguides and the Goubau line, use both metal walls and dielectric surfaces to confine the wave.

Depending on the frequency, waveguides can be constructed from either conductive or dielectric materials. Generally, the lower the frequency to be passed the larger the waveguide is. For example, the natural waveguide the earth forms given by the dimensions between the conductive ionosphere and the ground as well as the circumference at the median altitude of the Earth is resonant at 7.83 Hz. This is known as Schumann resonance. On the other hand, waveguides used in extremely high frequency (EHF) communications can be less than a millimetres in width.

Design Problem: Design a WR90 waveguide having cut-off frequency of 6373 MHz

Solution:-

$$f_c = \frac{Speed\ of\ light\ (c)}{2 \times a}$$

where 'a' is the width of the waveguide and 9a = 4b and b is the height of the wave guide while we take 1.27mm of wall thickness

From the above equations we got,

a=23.56mm

b=10.45mm

Design:-

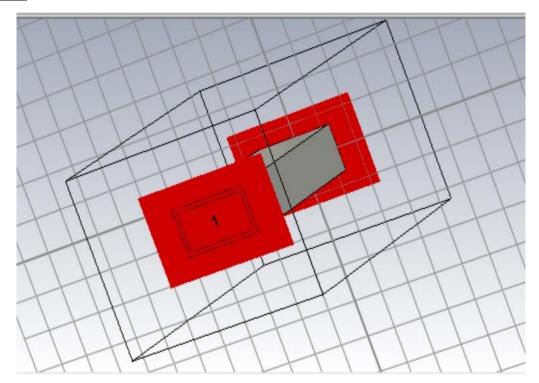


Fig 6.1: Design of the waveguide.

Output/Graph:-

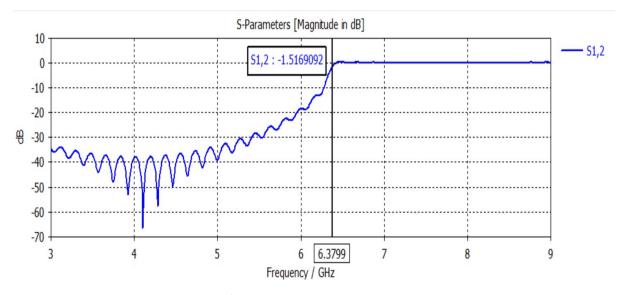


Fig 6.2: S1,2 parameter of the simulation

Inference:-

From this experiment I learnt about the working principle and importance of a waveguide in microwave communication engineering.

Conclusion:-

From the result of the simulation, the resonating frequency of the designed waveguide is 6.3799GHz which is very close to the required result. Hence we can conclude that the experiment is performed successfully

Experiment Number	
Date of Experiment	
Date of Submission	
Name of the student	
Roll Number	
Section	

Aim of The Experiment :-

Equipment / Software Required:-

The Equipment and Software required are as follows:

Theory

Brief Theory of the experiment in your own words

Code:-

Detail Code

Output/Graph:-

Graph with proper heading

Discussion or Inference of the experiment

A paragraph discussion or inference of what you learned in your own words

Conclusion:-

Detail Conclusion