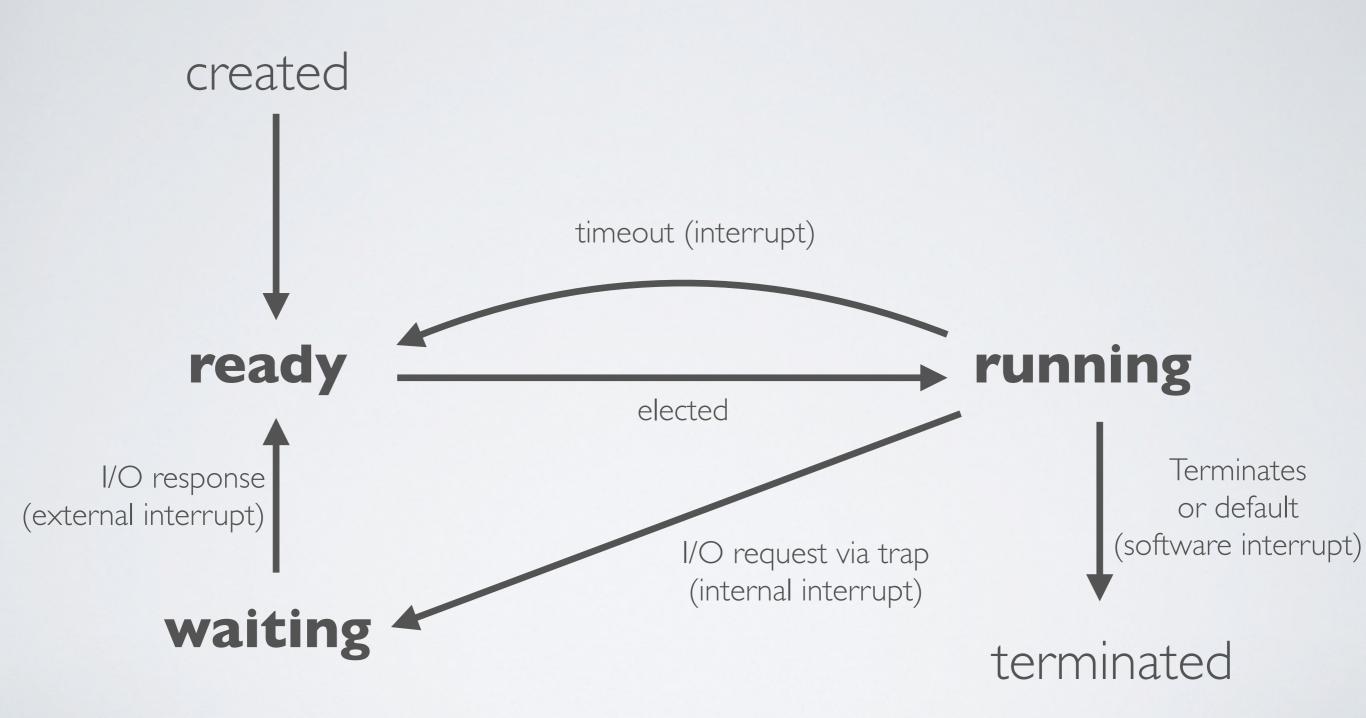
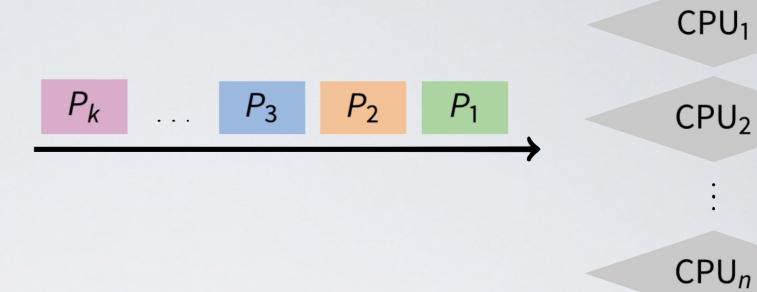
### Scheduling

Thierry Sans

### (recap) The different states of a thread



## The scheduling problem



- n threads ready to run
- k≥ | CPUs
- Scheduling Policy which jobs should we assign to which CPU(s)? and for how long?

#### Non Goals: Starvation

**Starvation** is when a thread is prevented from making progress because some other thread has the resource it requires (could be CPU or a lock)

- → Starvation is usually a side effect of the scheduling algorithm
  - e.g a high priority thread always prevents a low priority thread from running
- → Starvation can be a side effect of synchronization (forthcoming lecture)
  - · e.g constant supply of readers always blocks out writers

### Scheduling Criteria

- **Throughput** # of threads that complete per unit time # *jobs/time* (Higher is better)
- Turnaround time time for each thread to complete
   Tfinish Tstart (Lower is better)
- Response time time from request to first response ()
   i.e. time between waiting to ready transition and ready to running transition
   Tresponse Trequest (Lower is better)
- → Above criteria are affected by secondary criteria
  - CPU utilization %CPU fraction of time CPU doing productive work
  - Waiting time Avg(Twait) time each thread waits in the ready queue

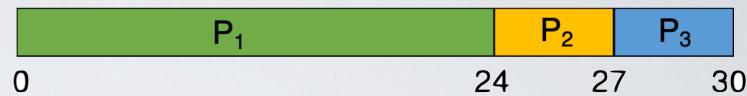
#### How to balance criteria?

- Batch systems (supercomputers)
   strive for job throughput and turnaround time
- Interactive systems (personal computers)
   strive to minimize response time for interactive jobs
  - However, in practice, users prefer predictable response time over faster but highly variable response time
  - Often optimized for an average response time

### Two kinds of scheduling algorithm

- Non-preemptive scheduling (good for batch systems)
   once the CPU has been allocated to a thread, it keeps the
   CPU until it terminates
- Preemptive scheduling (good for interactive systems)
   CPU can be taken from a running thread and allocated to another

### FCFS - First Come First Serve (non-preemptive)



→ Run jobs in order that they arrive (no interrupt)

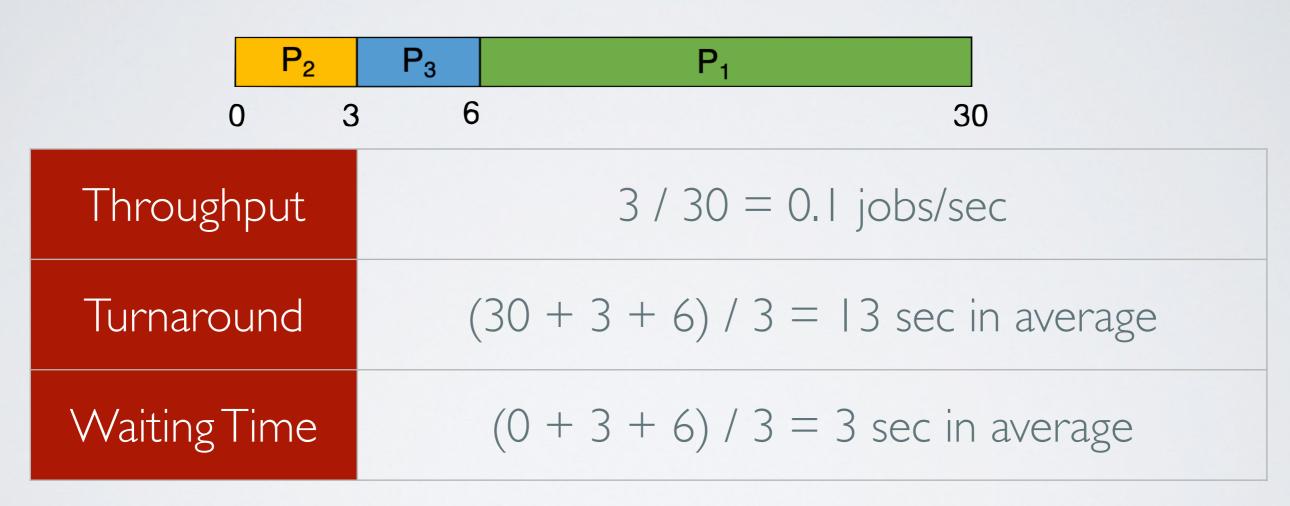
Throughput	3 / 30 = 0.1 jobs/sec	
Turnaround	(24 + 27 + 30) / 3 = 27 sec in average	
WaitingTime	(0 + 24 + 27) / 3 = 17 sec in average	

Problem: convoy effect

all other threads wait for the one big thread to release the CPU

## SJF - Shortest-Job-First (non-preemptive)

→ Choose the thread with the shortest processing time

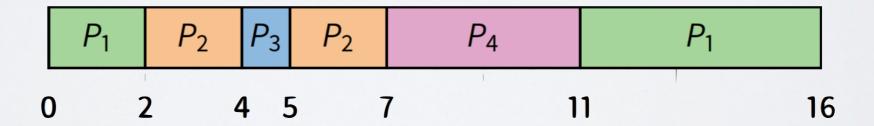


Problem: we need to know processing time in advance

## SRTF - Shortest-Remaining-Time-First (preemptive)

<b>Process</b>	<b>Arrival Time</b>	<b>Burst Time</b>
$P_1$	0	7
$P_2$	2	4
$P_3$	4	1
$P_4$	5	4

→ if a new thread arrives with CPU burst length less than remaining time of current executing thread, preempt current thread



- ✓ Good : optimize waiting time
- Problem: can lead to starvation

# RR - Round Robin (preemptive)

→ Each job is given a time slice called a quantum, preempt job after duration of quantum, move to back of FIFO queue



- ✓ Good: fair allocation of CPU, low waiting time (interactive)
- Problem: no priority between threads

### Time Quantum

- → Context switches are frequent and need to be very fast
- How to pick quantum?
  - Want much larger than context switch cost
  - Majority of bursts should be less than quantum But not so large system reverts to FCFS
- ✓ Typical values: I—I00 ms

### Why having priorities?

- ✓ Optimize job turnaround time for "batch" jobs
- ✓ Minimize response time for "interactive" jobs

## MLQ - Multilevel Queue Scheduling (preemptive)

Associate a priority with each thread and execute highest priority thread first. If same priority, do round-robin.



- Problem I: starvation of low priority thread
- Problem 2: (possibly) starvation of high priority thread
- Problem 3 : how to decide on the priority?

### MLQ - Starvation of high priority thread

- 1. TI (low priority) starts, runs and acquires the lock 1
- 2. T2 (medium priority) starts, preempts the CPU and runs
- 3. T3 (high priority) starts, preempts the CPU, runs but gets blocked while trying to acquire the lock 1
- 4. T2 is elected to run (highest priority thread to be ready to run)
- Problem: starvation of a high priority thread
- √ Solution : priority donation

### MLQ - Priority donation (simple example)

- I. TI (low priority) starts, runs and acquires the lock 1
- 2. T2 (medium priority) starts, preempts the CPU and runs
- 3. T3 (high priority) starts, preempts the CPU, runs but gets blocked while trying to acquire the lock 1
- 4. T3 gives its high priority to TI
- 5. TI (now high priority) runs, releases the lock and returns to low priority immediately after
- 6. T3 (now unblocked) preempts the CPU and runs

### Solutions to other MLQ problems

- → To prevent starvation of low priority thread change the priority over time by either
  - increase priority as a function of waiting time
  - or decrease priority as a function of CPU consumption
- → To decide on the priority
  by observing and keeping track of the thread CPU usage

## MLFQ - Multilevel **Feedback** Queue Scheduling (preemptive)

→ Same as MLQ but change the priority of the process based on observations

Rule I	If $Priority(A) > Priority(B)$ , A runs	
Rule 2	If $Priority(A) = Priority(B)$ , A & B run in round-robin fashion using the time slice (quantum length) of the given queue	
Rule 3	When a job enters the system, it is placed at the highest priority (the topmost queue)	
Rule 4	Once a job uses up its time allotment at a given level (regardless of how many times it has given up the CPU), its priority is reduced (i.e., it moves down one queue)	
Rule 5	After some time period S, move all the jobs in the system to the topmost queue	

✓ Good: Turing-award winner algorithm

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