A_DSA Mid 2 Pseudocodes

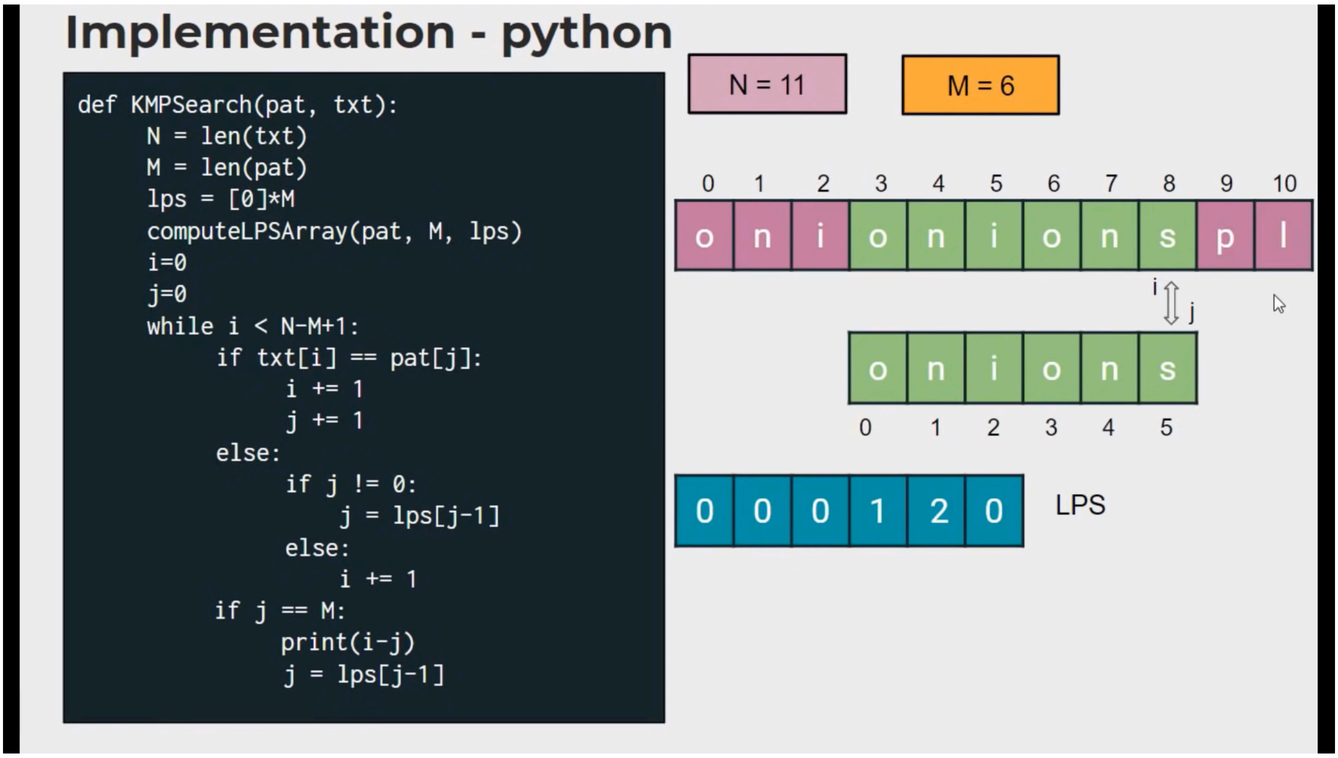
Naive Approach to Pattern Matching

```
void search(char* pat, char* txt)
{
    int M = strlen(pat);
    int N = strlen(txt);

    /* A loop to slide pat[] one by one */
    for (int i = 0; i <= N - M; i++) {
        int j;

        /* For current index i, check for pattern match */
        for (j = 0; j < M; j++)
            if (txt[i + j] != pat[j])
                break;

        if (j == M) // if pat[0...M-1] = txt[i, i+1, ...i+M-1]
            cout << "Pattern found at index "
                 << i << endl;
    }
}
```

$$TimeComplexity = O(m * (n - m + 1))$$

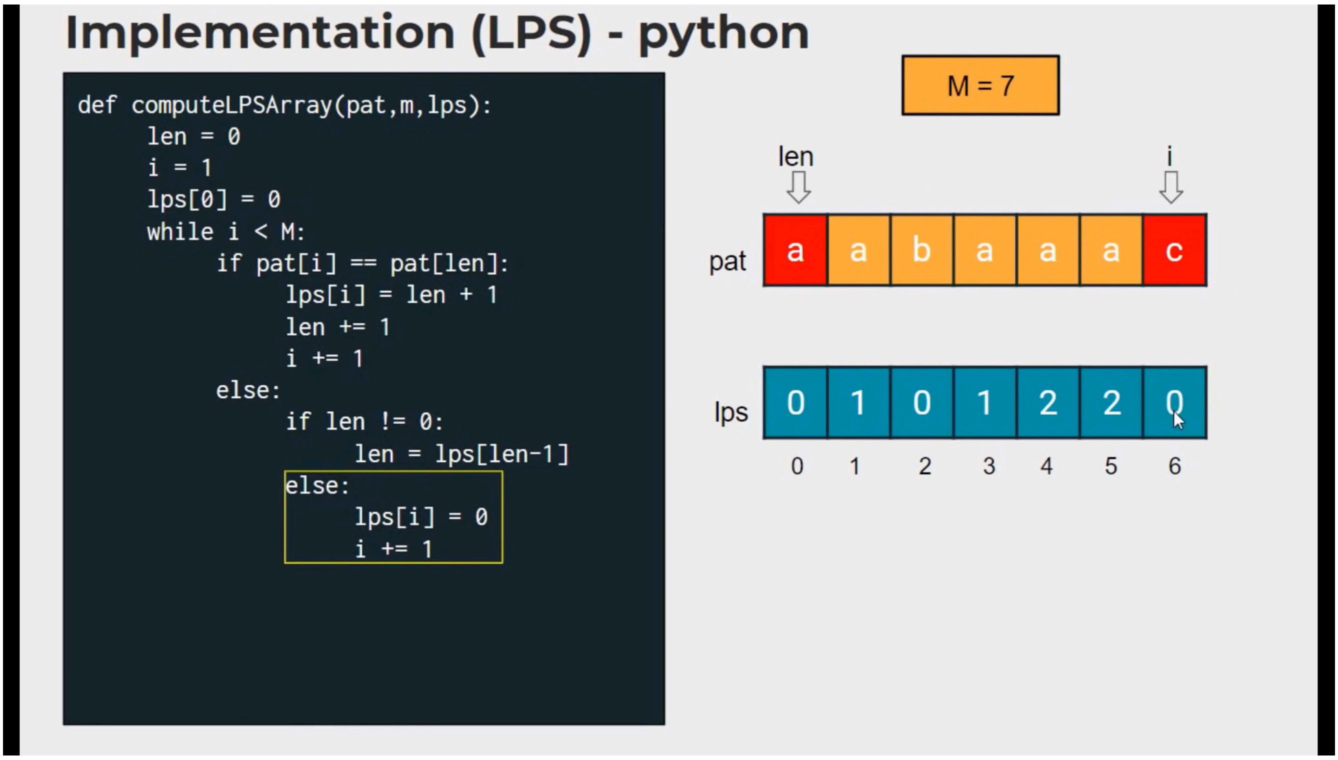
KMP

Search Algo



$$TimeComplexity = O(n)$$

LPS computation Algo



$$TimeCOmplexity = O(m)$$

```
Over all time complexity = O(n+m) => O(n)
```

Pattern Matching Using Automata

Matching Algo

```
FINITE-AUTOMATON-MATCHER(T, δ, m)
n = T.length
q = 0
for i = 1 to n
    q = δ(q, T[i])
    if q == m
        print "Pattern occurs with shift" i − m
```

Transition Function Creator Algo

```
COMPUTE-TRANSITION-FUNCTION(P, Σ)
m = P.length
for q = 0 to m
    for each character a ∈ Σ
        k = min(m + 1, q + 2)
        repeat
            k = k − 1
        until P_k ⊐ P_q a
        δ(q, a) = k
return δ
```

Rabin-Karp Algorithm

```
RABIN-KARP-MATCHER(T, P, d, q)
1  n = T.length
2  m = P.length
3  h = d^(m-1) mod q
4  p = 0
5  t_0 = 0
6  for i = 1 to m                    // preprocessing
7      p = (dp + P[i]) mod q
8      t_0 = (dt_0 + T[i]) mod q
9  for s = 0 to n - m                // matching
10     if p == t_s
11         if P[1..m] == T[s+1..s+m]
12             print "Pattern occurs with shift" s
13     if s < n - m
14         t_{s+1} = (d(t_s - T[s+1]h) + T[s+m+1]) mod q
```

The procedure RABIN-KARP-MATCHER works as follows. All characters are interpreted as radix-d digits. The subscripts on t are provided only for clarity; the program works correctly if all the subscripts are dropped. Line 3 initializes h to the value of the high-order digit position of an m-digit window. Lines 4–8 compute p as the value of $P[1..m] \bmod q$ and t_0 as the value of $T[1..m] \bmod q$. The **for** loop of lines 9–14 iterates through all possible shifts s, maintaining the following invariant:

Whenever line 10 is executed, $t_s = T[s+1..s+m] \bmod q$.

If $p = t_s$ in line 10 (a "hit"), then line 11 checks to see whether $P[1..m] = T[s+1..s+m]$ in order to rule out the possibility of a spurious hit. Line 12 prints out any valid shifts that are found. If $s < n - m$ (checked in line 13), then the **for** loop will execute at least one more time, and so line 14 first executes to ensure that the loop invariant holds when we get back to line 10. Line 14 computes the value of $t_{s+1} \bmod q$ from the value of $t_s \bmod q$ in constant time using equation (32.2) directly.

RABIN-KARP-MATCHER takes $\Theta(m)$ preprocessing time, and its matching time is $\Theta((n-m+1)m)$ in the worst case, since (like the naive string-matching algo-

`Summary`

Algorithm	Preprocessing time	Matching time
Naive	0	$O((n-m+1)m)$
Rabin-Karp	$\Theta(m)$	$O((n-m+1)m)$
Finite automaton	$O(m\,\lvert\Sigma\rvert)$	$\Theta(n)$
Knuth-Morris-Pratt	$\Theta(m)$	$\Theta(n)$

TRIE

Insertion

Searching Pattern

Compressed Trie

Suffix Trie

Binomial Heap

Fibonacci Heap

Insertion

Creating a new Fibonacci heap

To make an empty Fibonacci heap, the MAKE-FIB-HEAP procedure allocates and returns the Fibonacci heap object H, where $H.n = 0$ and $H.min =$ NIL; there are no trees in H. Because $t(H) = 0$ and $m(H) = 0$, the potential of the empty Fibonacci heap is $\Phi(H) = 0$. The amortized cost of MAKE-FIB-HEAP is thus equal to its $O(1)$ actual cost.

Inserting a node

The following procedure inserts node x into Fibonacci heap H, assuming that the node has already been allocated and that $x.key$ has already been filled in.

```
FIB-HEAP-INSERT(H, x)
x.degree = 0
x.p = NIL
x.child = NIL
x.mark = FALSE
if H.min == NIL
    create a root list for H containing just x
    H.min = x
else insert x into H's root list
    if x.key < H.min.key
        H.min = x
H.n = H.n + 1
```

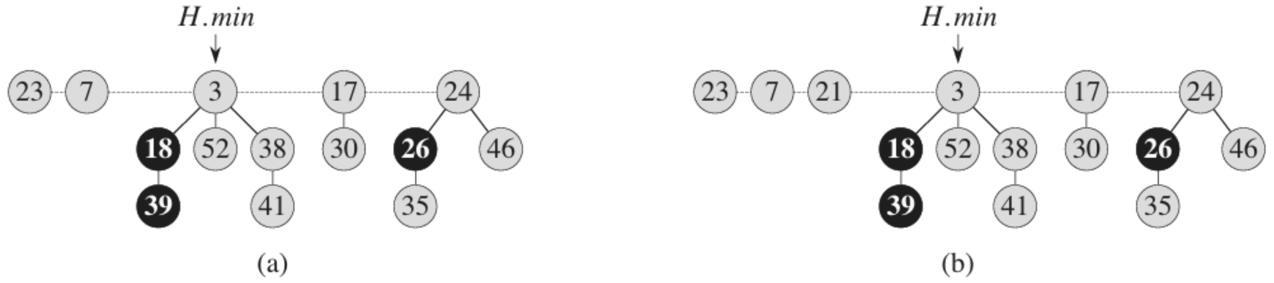


Figure 19.3 Inserting a node into a Fibonacci heap. **(a)** A Fibonacci heap H. **(b)** Fibonacci heap H after inserting the node with key 21. The node becomes its own min-heap-ordered tree and is then added to the root list, becoming the left sibling of the root.

Lines 1–4 initialize some of the structural attributes of node x. Line 5 tests to see whether Fibonacci heap H is empty. If it is, then lines 6–7 make x be the only node in H's root list and set $H.min$ to point to x. Otherwise, lines 8–10 insert x into H's root list and update $H.min$ if necessary. Finally, line 11 increments $H.n$ to reflect the addition of the new node. Figure 19.3 shows a node with key 21 inserted into the Fibonacci heap of Figure 19.2.

To determine the amortized cost of FIB-HEAP-INSERT, let H be the input Fibonacci heap and H' be the resulting Fibonacci heap. Then, $t(H') = t(H) + 1$ and $m(H') = m(H)$, and the increase in potential is

$$((t(H) + 1) + 2m(H)) - (t(H) + 2m(H)) = 1 .$$

Since the actual cost is $O(1)$, the amortized cost is $O(1) + 1 = O(1)$.

Union

```
FIB-HEAP-UNION(H1, H2)
1  H = MAKE-FIB-HEAP()
2  H.min = H1.min
3  concatenate the root list of H2 with the root list of H
4  if (H1.min == NIL) or (H2.min ≠ NIL and H2.min.key < H1.min.key)
5      H.min = H2.min
6  H.n = H1.n + H2.n
7  return H
```

Lines 1–3 concatenate the root lists of H_1 and H_2 into a new root list H. Lines 2, 4, and 5 set the minimum node of H, and line 6 sets $H.n$ to the total number of nodes. Line 7 returns the resulting Fibonacci heap H. As in the FIB-HEAP-INSERT procedure, all roots remain roots.

The change in potential is

$$\begin{aligned}\Phi(H) - (\Phi(H_1) + \Phi(H_2)) \\ &= (t(H) + 2m(H)) - ((t(H_1) + 2m(H_1)) + (t(H_2) + 2m(H_2))) \\ &= 0\,,\end{aligned}$$

because $t(H) = t(H_1) + t(H_2)$ and $m(H) = m(H_1) + m(H_2)$. The amortized cost of FIB-HEAP-UNION is therefore equal to its $O(1)$ actual cost.

Extract Min

```
FIB-HEAP-EXTRACT-MIN(H)
z = H.min
if z ≠ NIL
    for each child x of z
        add x to the root list of H
        x.p = NIL
    remove z from the root list of H
    if z == z.right
        H.min = NIL
    else H.min = z.right
        CONSOLIDATE(H)
    H.n = H.n − 1
return z
```

CONSOLIDATE

```
CONSOLIDATE(H)
let A[0 .. D(H.n)] be a new array
for i = 0 to D(H.n)
    A[i] = NIL
for each node w in the root list of H
    x = w
    d = x.degree
    while A[d] ≠ NIL
        y = A[d]          // another node with the same degree as x
        if x.key > y.key
            exchange x with y
        FIB-HEAP-LINK(H, y, x)
        A[d] = NIL
        d = d + 1
    A[d] = x
H.min = NIL
for i = 0 to D(H.n)
    if A[i] ≠ NIL
        if H.min == NIL
            create a root list for H containing just A[i]
            H.min = A[i]
        else insert A[i] into H's root list
            if A[i].key < H.min.key
                H.min = A[i]
```

```
FIB-HEAP-LINK(H, y, x)
remove y from the root list of H
make y a child of x, incrementing x.degree
y.mark = FALSE
```

Complexity

The potential before extracting the minimum node is $t(H) + 2m(H)$, and the potential afterward is at most $(D(n) + 1) + 2m(H)$, since at most $D(n) + 1$ roots remain and no nodes become marked during the operation. The amortized cost is thus at most

$$\begin{aligned}
O(D(n) + t(H)) &+ ((D(n) + 1) + 2m(H)) - (t(H) + 2m(H)) \\
&= O(D(n)) + O(t(H)) - t(H) \\
&= O(D(n)) ,
\end{aligned}$$

since we can scale up the units of potential to dominate the constant hidden in $O(t(H))$. Intuitively, the cost of performing each link is paid for by the reduction in potential due to the link's reducing the number of roots by one. We shall see in Section 19.4 that $D(n) = O(\lg n)$, so that the amortized cost of extracting the minimum node is $O(\lg n)$.

Decrease-Key

Decreasing a key

In the following pseudocode for the operation FIB-HEAP-DECREASE-KEY, we assume as before that removing a node from a linked list does not change any of the structural attributes in the removed node.

```
FIB-HEAP-DECREASE-KEY(H, x, k)
if k > x.key
    error "new key is greater than current key"
x.key = k
y = x.p
if y ≠ NIL and x.key < y.key
    CUT(H, x, y)
    CASCADING-CUT(H, y)
if x.key < H.min.key
    H.min = x
```

```
CUT(H, x, y)
remove x from the child list of y, decrementing y.degree
add x to the root list of H
x.p = NIL
x.mark = FALSE
```

```
CASCADING-CUT(H, y)
z = y.p
if z ≠ NIL
    if y.mark == FALSE
        y.mark = TRUE
    else CUT(H, y, z)
        CASCADING-CUT(H, z)
```

Complexity

FIB-HEAP-DECREASE-KEY creates a new tree rooted at node x and clears x's mark bit (which may have already been FALSE). Each call of CASCADING-CUT, except for the last one, cuts a marked node and clears the mark bit. Afterward, the Fibonacci heap contains $t(H)+c$ trees (the original $t(H)$ trees, $c-1$ trees produced by cascading cuts, and the tree rooted at x) and at most $m(H)-c+2$ marked nodes ($c-1$ were unmarked by cascading cuts and the last call of CASCADING-CUT may have marked a node). The change in potential is therefore at most

$$((t(H)+c)+2(m(H)-c+2))-(t(H)+2m(H)) = 4-c\ .$$

Thus, the amortized cost of FIB-HEAP-DECREASE-KEY is at most

$$O(c)+4-c = O(1)\ ,$$

Delete Node

Deleting a node

The following pseudocode deletes a node from an n-node Fibonacci heap in $O(D(n))$ amortized time. We assume that there is no key value of $-\infty$ currently in the Fibonacci heap.

```
FIB-HEAP-DELETE(H, x)
  FIB-HEAP-DECREASE-KEY(H, x, -∞)
  FIB-HEAP-EXTRACT-MIN(H)
```

FIB-HEAP-DELETE makes x become the minimum node in the Fibonacci heap by giving it a uniquely small key of $-\infty$. The FIB-HEAP-EXTRACT-MIN procedure then removes node x from the Fibonacci heap. The amortized time of FIB-HEAP-DELETE is the sum of the $O(1)$ amortized time of FIB-HEAP-DECREASE-KEY and the $O(D(n))$ amortized time of FIB-HEAP-EXTRACT-MIN. Since we shall see in Section 19.4 that $D(n) = O(\lg n)$, the amortized time of FIB-HEAP-DELETE is $O(\lg n)$.