

# Handling Deadlock for Distributed Systems - II

## Different Approaches



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## Outline



- Introduction to Distributed Deadlock Detection
- Global DDD algorithm
- Centralized DDD algorithm
- Diffusion Computation-based DDD algorithm
- **Mitchell-Merritt Edge Chasing DDD algorithm**

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## Mitchell – Merritt DDD Algorithm



- It is an *edge chasing* algorithm where Control messages are sent over WFG edges to detect cycles
- Each process is represented as  $u/v$  where  $u$  and  $v$  are the public and private labels, respectively.
- Labels are initially identical and unique for each node

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## Mitchell – Merritt DDD Algorithm



- Labels of a process change when it gets blocked on a resource request
- Labels also change when it waits for a process having a larger public label
- A wait-for edge with a specific relation between public and private labels of its source and destination processes indicates presence of a deadlock

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## State Transitions



- Initiate: Set same random value for  $u$ ,  $v$ . Value for each node need to be unique.
- Block: This will be in effect every time a process is blocked.
  - Add a new block edge in the WFG
  - Set both  $u$ ,  $v$  of the blocked process with  $k$ :
    - $k = f(u_1, u_2)$  yields a unique label greater than both  $u_1$  and  $u_2$  – the two public labels for the blocking and blocked processes

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## State Transitions

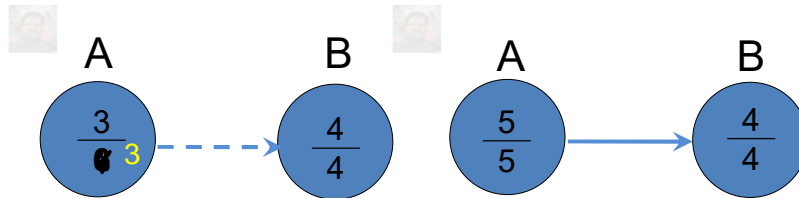


- Transmit: If public label of a blocking process is greater than that of the blocked process in the WFG, then this higher public label propagates in the opposite direction of the edges.
- Detect: If the public and private labels of a blocked process are same, and the value is again same as the public label of the blocking process, a deadlock is detected

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## Mitchell – Merritt DDD Algorithm

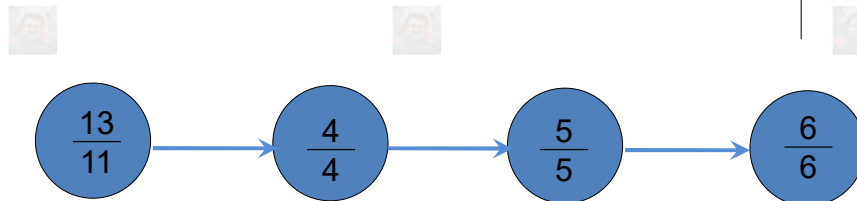


- Block rule
- Assume,  $f(u1, u2) = \text{Maximum}(u1, u2) + 1$

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## Mitchell – Merritt DDD Algorithm

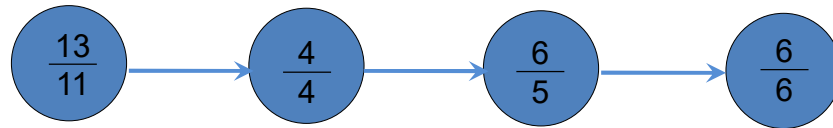


- Transmit rule

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## Mitchell – Merritt DDD Algorithm

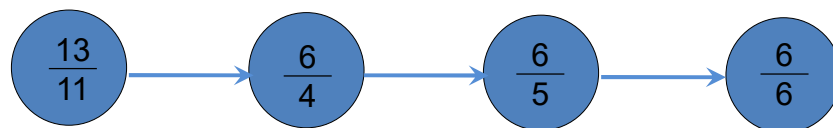


- Transmit rule

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## Mitchell – Merritt DDD Algorithm

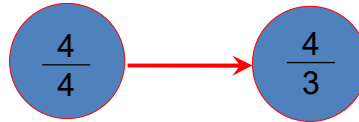


- Transmit rule

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## Mitchell – Merritt DDD Algorithm

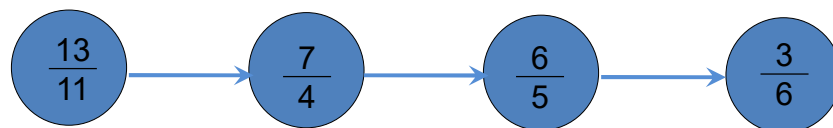


- Detection rule

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## Mitchell – Merritt DDD Algorithm

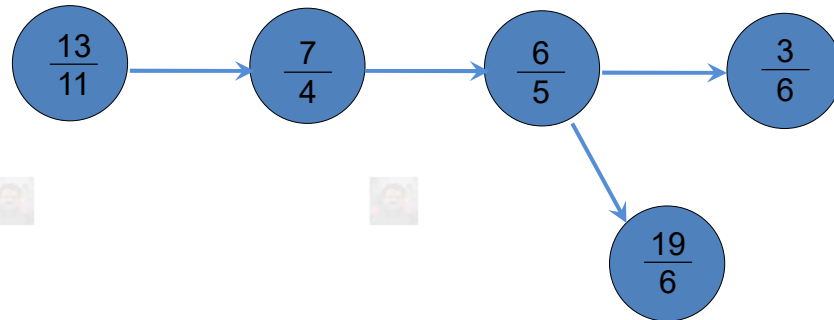


- Scenario 1

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## Mitchell – Merritt DDD Algorithm

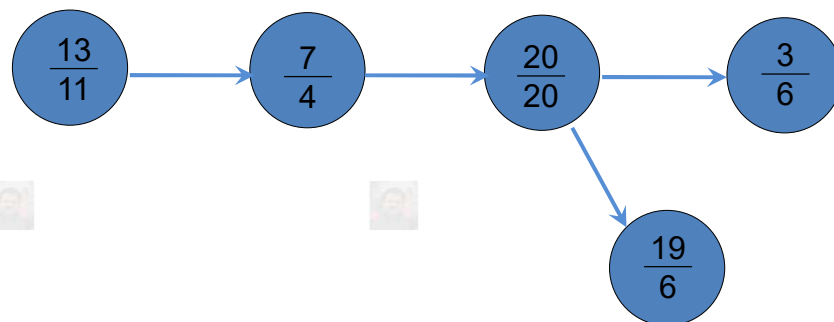


### • Scenario 1

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## Mitchell – Merritt DDD Algorithm

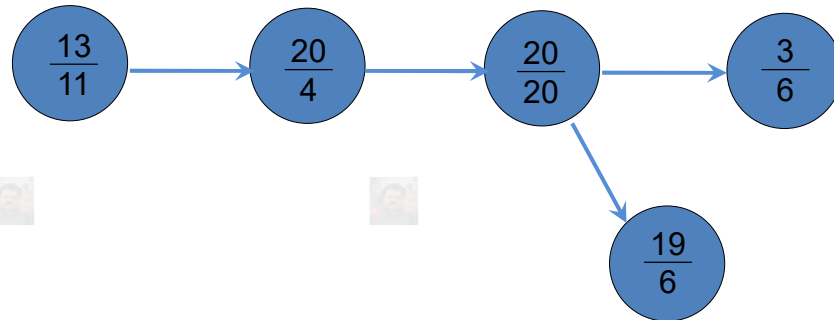


### • Scenario 1

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## Mitchell – Merritt DDD Algorithm

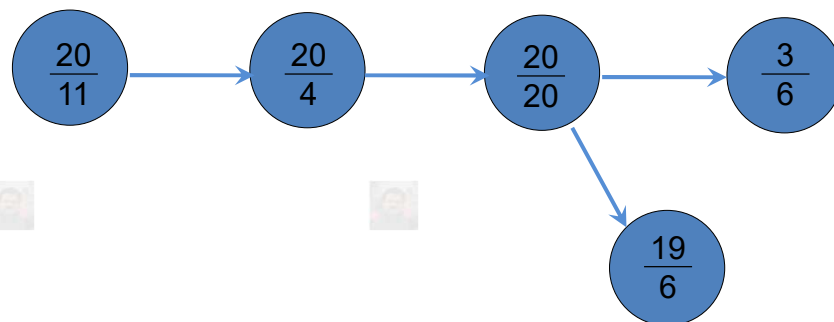


### • Scenario 1

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## Mitchell – Merritt DDD Algorithm



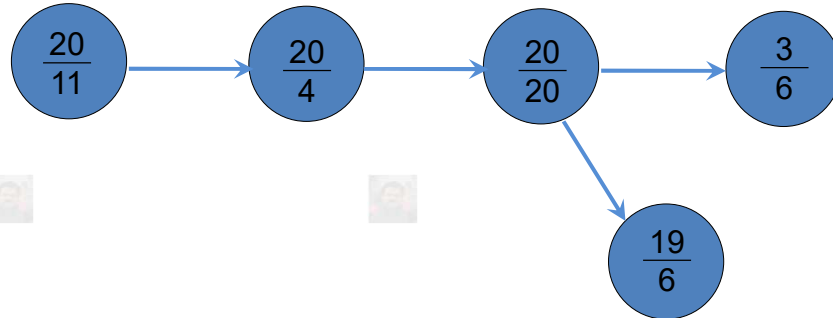
### • Scenario 1

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## Mitchell – Merritt DDD Algorithm

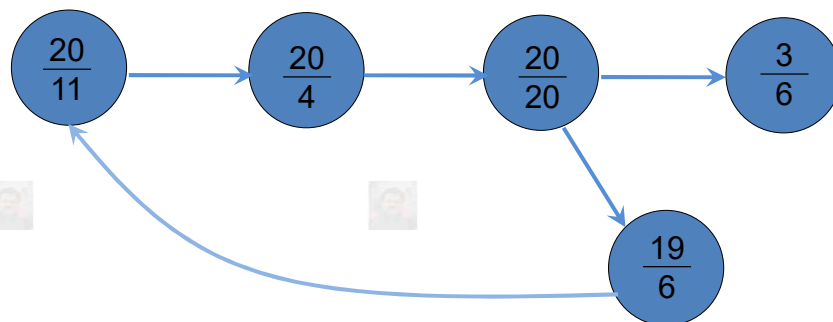


### • Scenario 2

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## Mitchell – Merritt DDD Algorithm

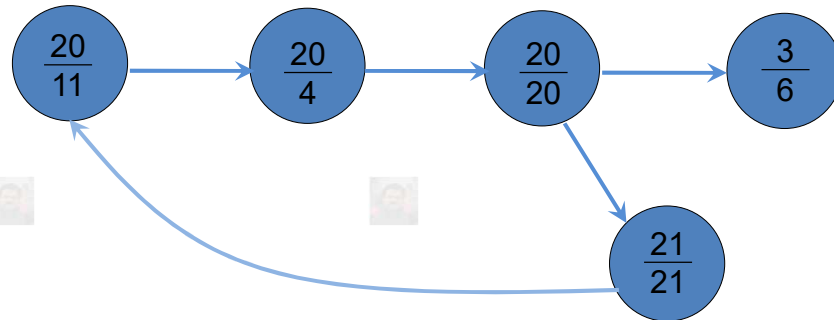


### • Scenario 2

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## Mitchell – Merritt DDD Algorithm

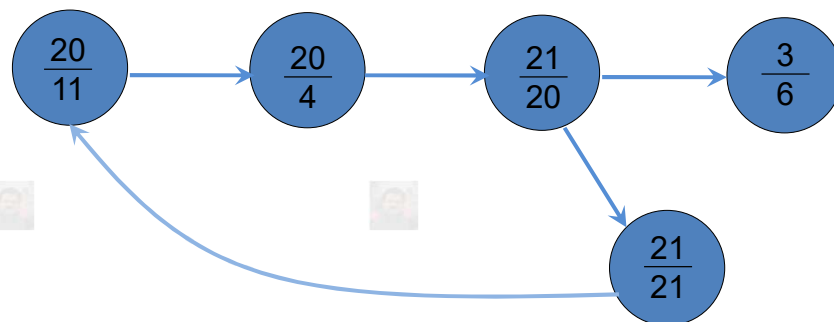


### • Scenario 2

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## Mitchell – Merritt DDD Algorithm

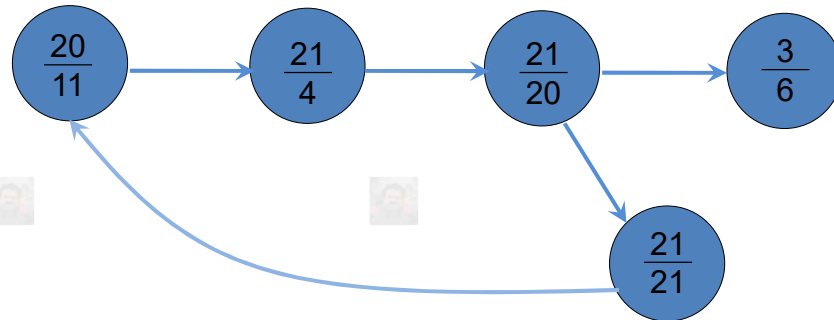


### • Scenario 2

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## Mitchell – Merritt DDD Algorithm

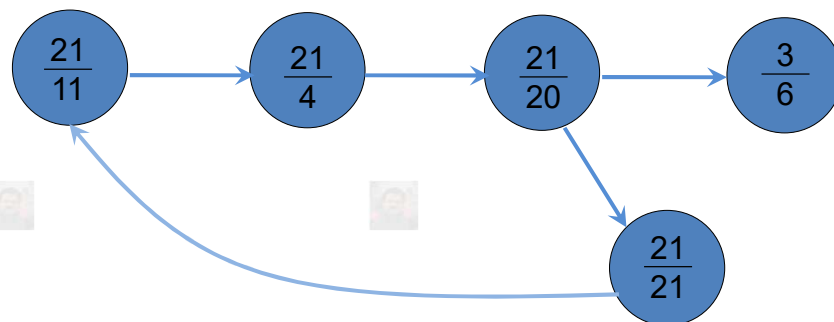


### • Scenario 2

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## Mitchell – Merritt DDD Algorithm

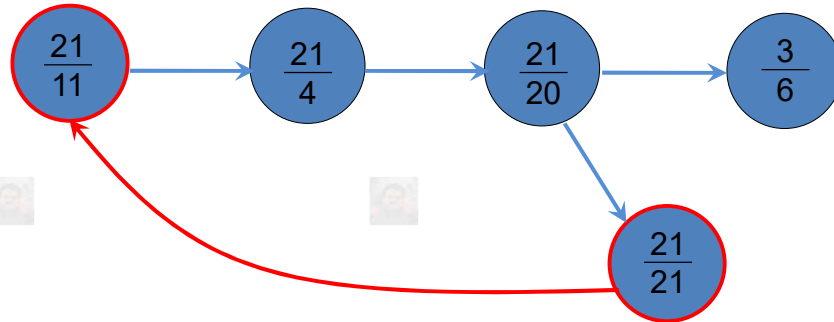


### • Scenario 2

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## Mitchell – Merritt DDD Algorithm

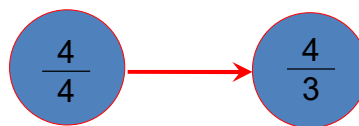


### • Scenario 2

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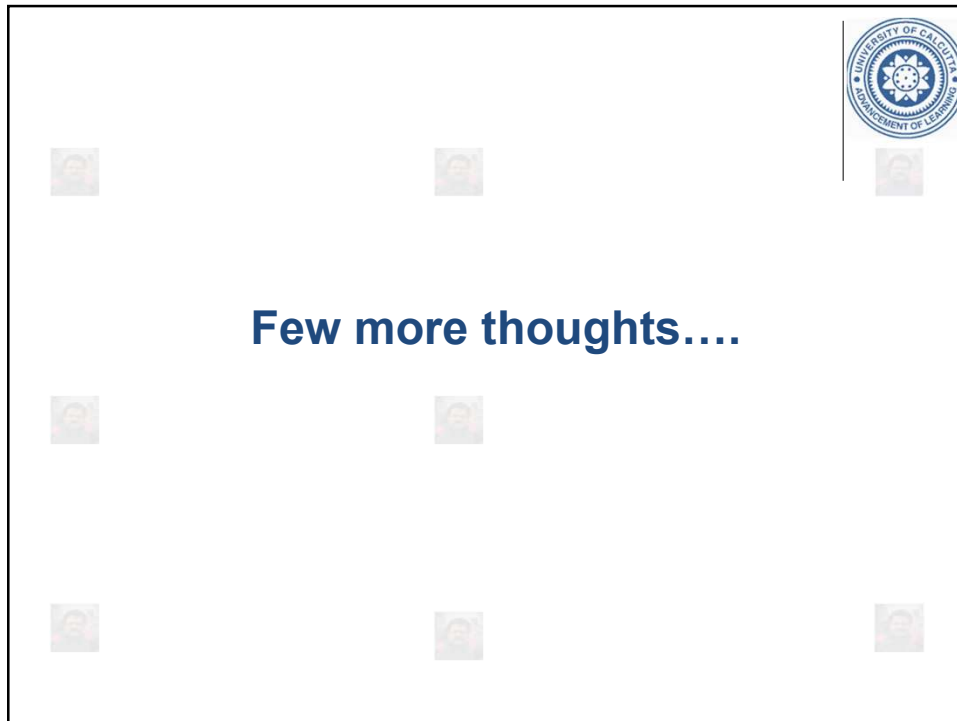
## Mitchell – Merritt DDD Algorithm



### • Detection rule

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## DD Prevention Algorithm

- The basic idea is to ensure that Circular wait does not occur
- Time-stamp creation of a process
  - When process  $P_k$  requests a resource allocated to  $P_m$ , time-stamps of  $P_k$  and  $P_m$  are used to decide whether  $P_k$  can wait for  $P_m$

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## DD Prevention Algorithm



- Two approaches
  - Wait-or-die
    - $P_i$  is allowed to wait if older than  $P_j$ ; otherwise, it is killed
  - Wound-or-wait
    - $P_i$  is allowed to wait if younger than  $P_j$ ; otherwise  $P_j$  is killed
- A killed process retains original timestamp if restarted

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## Path-pushing vs. Edge Chasing




- Path-pushing:
  - Path information is sent to blocking node
    - e.g., partial WFGs sent to blocking nodes for deadlock detection
    - Obermarck's algorithm
- Edge-chasing:
  - Probe messages sent without path information
    - e.g. Mitchell-Merriitt Algorithm

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**Thanks for your kind attention**



**Questions??**

