smacc::ISmaccComponent # stateMachine # owner + ISmaccComponent() + ~ISmaccComponent() + getName() # onInitialize() # postEvent() # postEvent() # onOrthogonalAllocation() # requiresComponent() # requiresClient() # createSiblingComponent() # createSiblingNamedComponent() # aetNode() # aetLoaaer() initialize() setStateMachine() cl move base z::PlannerSwitcher - desired global planner - desired local planner - set planners mode flag

```
    planner selector pub

    controller selector pub

- goal checker selector pub
```

- + setBackwardPlanner() + setUndoPathBackwardPlanner() + setForwardPlanner() + setPureSpinningPlanner()
 - + onInitialize() + setDefaultPlanners()
 - updatePlanners()

+ PlannerSwitcher()