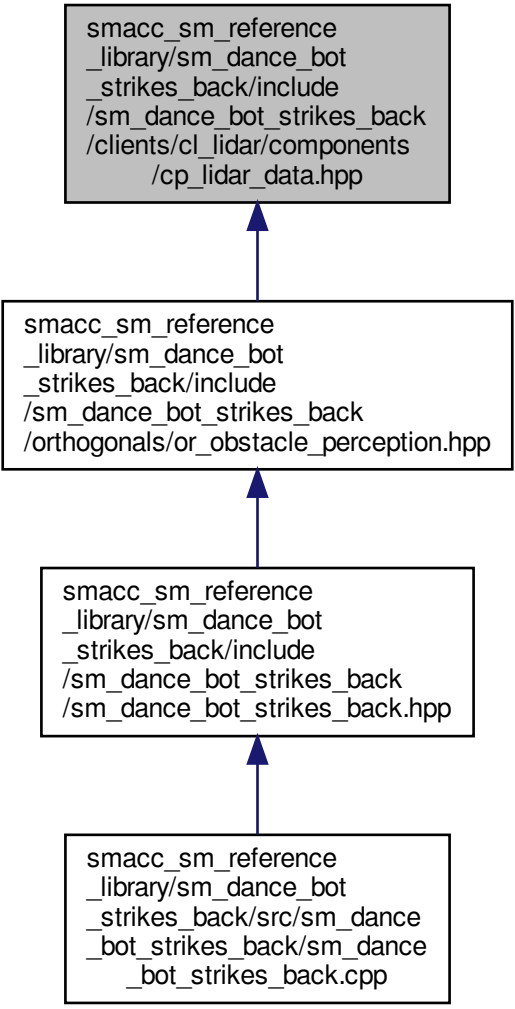
smacc_sm_reference
_library/sm_dance_bot
_strikes_back/include
/sm_dance_bot_strikes_back
/clients/cl_lidar/components
/cp_lidar_data.hpp
smacc_sm_reference
_library/sm_dance_bot
_strikes_back/include
/sm_dance_bot_strikes_back
/orthogonals/or_obstacle_perception.hpp
smacc_sm_reference
_library/sm_dance_bot
_strikes_back/include
/sm_dance_bot_strikes_back
/sm_dance_bot_strikes_back.hpp
smacc_sm_reference
_library/sm_dance_bot
_strikes_back/src/sm_dance
_bot_strikes_back/sm_dance
_bot_strikes_back.cpp