

cl\_move\_base\_z::backward  
\_local\_planner::BackwardLocalPlanner  
::divergenceDetectionUpdate



```
graph LR; A["cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::divergenceDetectionUpdate"] --> B["cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::computeCurrentEuclideanAndAngularErrors  
ToCarrotGoal"]
```

cl\_move\_base\_z::backward  
\_local\_planner::BackwardLocalPlanner  
::computeCurrentEuclideanAndAngularErrors  
ToCarrotGoal