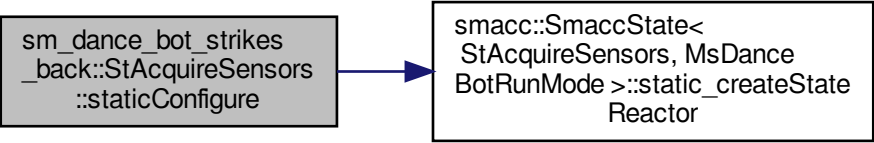


```
sm_dance_bot_strikes  
_back::StAcquireSensors  
::staticConfigure
```



```
graph LR; A["sm_dance_bot_strikes  
_back::StAcquireSensors  
::staticConfigure"] --> B["smacc::SmaccState<  
StAcquireSensors, MsDance  
BotRunMode >::static_createState  
Reactor"]
```

A diagram showing a call from a static method to another static method. On the left, a grey box contains the code `sm_dance_bot_strikes`, `_back::StAcquireSensors`, and `::staticConfigure`. A blue arrow points from this box to a white box on the right. The white box contains the code `smacc::SmaccState<`, `StAcquireSensors, MsDance`, `BotRunMode >::static_createState`, and `Reactor`.

```
smacc::SmaccState<  
StAcquireSensors, MsDance  
BotRunMode >::static_createState  
Reactor
```