


```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::computeVelocityCommands
```



```
graph LR; A["cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::computeVelocityCommands"] --> B["cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::checkCurrentPoseInGoalRange"]
```

A diagram showing a call sequence between two functions. A blue arrow points from the left box to the right box. The left box has a black border and white background, while the right box has a black border and light gray background.

```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::checkCurrentPoseInGoalRange
```