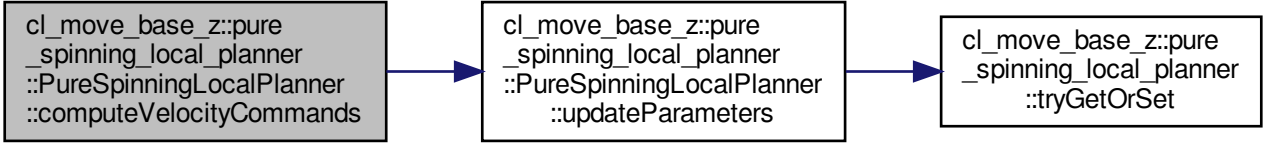


cl_move_base_z::pure
_spinning_local_planner
::PureSpinningLocalPlanner
::computeVelocityCommands



```
graph LR; A["cl_move_base_z::pure  
_spinning_local_planner  
::PureSpinningLocalPlanner  
::computeVelocityCommands"] --> B["cl_move_base_z::pure  
_spinning_local_planner  
::PureSpinningLocalPlanner  
::updateParameters"]; B --> C["cl_move_base_z::pure  
_spinning_local_planner  
::tryGetOrSet"]
```

The diagram consists of three rectangular boxes connected by blue arrows pointing from left to right. The first box on the left has a light gray background and contains the text 'cl_move_base_z::pure', '_spinning_local_planner', '::PureSpinningLocalPlanner', and '::computeVelocityCommands'. The middle box has a white background and contains 'cl_move_base_z::pure', '_spinning_local_planner', '::PureSpinningLocalPlanner', and '::updateParameters'. The third box on the right also has a white background and contains 'cl_move_base_z::pure', '_spinning_local_planner', and '::tryGetOrSet'.

cl_move_base_z::pure
_spinning_local_planner
::PureSpinningLocalPlanner
::updateParameters

cl_move_base_z::pure
_spinning_local_planner
::tryGetOrSet