smacc::ISmaccComponent

stateMachine_
owner_

+ ISmaccComponent()
+ ~ISmaccComponent()
+ getName()
# onInitialize()
# postEvent()
# postEvent()
# onOrthogonalAllocation()
# requiresComponent()
# requiresClient()
# createSiblingComponent()
# createSiblingNamedComponent()
# getNode()
# getLogger()
- initialize()
- setStateMachine()

cl_move_base_z::Waypoint Navigator

+ waypointsEventDispatcher
+ client_
+ currentWaypoint_
- waypoints_
- succeddedConnection_

+ WaypointNavigator()
+ onInitialize()
+ insertWaypoint()
+ removeWaypoint()
+ loadWayPointsFromFile()
+ setWaypoints()
+ setWaypoints()
+ sendNextGoal()
+ getWaypoints()
+ getCurrentWaypointIndex()
+ onOrthogonalAllocation()
- onGoalReached()