```
                    ┌─────────────────────────────────┐
                    │       smacc::ISmaccClient       │
                    ├─────────────────────────────────┤
                    │ # components_                   │
                    │ - stateMachine_                 │
                    │ - orthogonal_                   │
                    ├─────────────────────────────────┤
                    │ + ISmaccClient()                │
                    │ + ~ISmaccClient()               │
                    │ + onInitialize()                │
                    │ + getName()                     │
                    │ + getComponent()                │
                    │ + getComponent()                │
                    │ + getType()                     │
                    │ + getStateMachine()             │
                    │ + connectSignal()               │
                    │ + requiresClient()              │
                    │ + getComponents()               │
                    │ + postEvent()                   │
                    │ + postEvent()                   │
                    │ # onOrthogonalAllocation()      │
                    │ # createComponent()             │
                    │ # createNamedComponent()        │
                    │ # getNode()                     │
                    │ # getLogger()                   │
                    │ - initialize()                  │
                    │ - setStateMachine()             │
                    │ - setOrthogonal()               │
                    └─────────────────────────────────┘
```

smacc::client_bases
::SmaccPublisherClient

+ topicName
+ queueSize
+ pub_
- initialized_

+ SmaccPublisherClient()
+ ~SmaccPublisherClient()
+ configure()
+ publish()

cl_ros_publisher::ClRosPublisher

+ ClRosPublisher()
+ ~ClRosPublisher()
+ configure()
+ publish()

sm_dance_bot::cl_string
_publisher::ClStringPublisher

+ topicName_

+ ClStringPublisher()
+ onInitialize()

sm_dance_bot_strikes
_back::cl_string_publisher
::ClStringPublisher

+ topicName_

+ ClStringPublisher()
+ onInitialize()