

```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::findInitialCarrotGoal
```



```
graph LR; A["cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::findInitialCarrotGoal"] --> B["cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::computeCurrentEuclideanAndAngularErrors  
ToCarrotGoal"]
```

The diagram illustrates a function call. A grey box on the left contains the code for a backward movement function that calls findInitialCarrotGoal on a BackwardLocalPlanner object. A blue arrow points from this box to a white box on the right, which contains the code for the findInitialCarrotGoal method, showing it calls computeCurrentEuclideanAndAngularErrorsToCarrotGoal on the same BackwardLocalPlanner object.

```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::computeCurrentEuclideanAndAngularErrors  
ToCarrotGoal
```