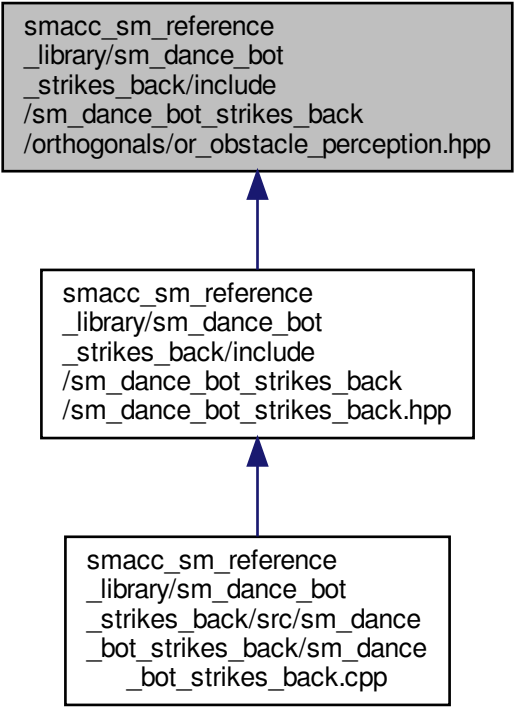


smacc\_sm\_reference  
\_library/sm\_dance\_bot  
\_strikes\_back/include  
/sm\_dance\_bot\_strikes\_back  
/orthogonals/or\_obstacle\_perception.hpp



```
graph BT; A["smacc_sm_reference  
_library/sm_dance_bot  
_strikes_back/src/sm_dance_bot_strikes_back/sm_dance_bot_strikes_back.cpp"] --> B["smacc_sm_reference  
_library/sm_dance_bot_strikes_back/include  
/sm_dance_bot_strikes_back  
/sm_dance_bot_strikes_back.hpp"]; B --> C["smacc_sm_reference  
_library/sm_dance_bot_strikes_back/include  
/sm_dance_bot_strikes_back  
/orthogonals/or_obstacle_perception.hpp"]
```

smacc\_sm\_reference  
\_library/sm\_dance\_bot  
\_strikes\_back/include  
/sm\_dance\_bot\_strikes\_back  
/sm\_dance\_bot\_strikes\_back.hpp

smacc\_sm\_reference  
\_library/sm\_dance\_bot  
\_strikes\_back/src/sm\_dance  
\_bot\_strikes\_back/sm\_dance  
\_bot\_strikes\_back.cpp