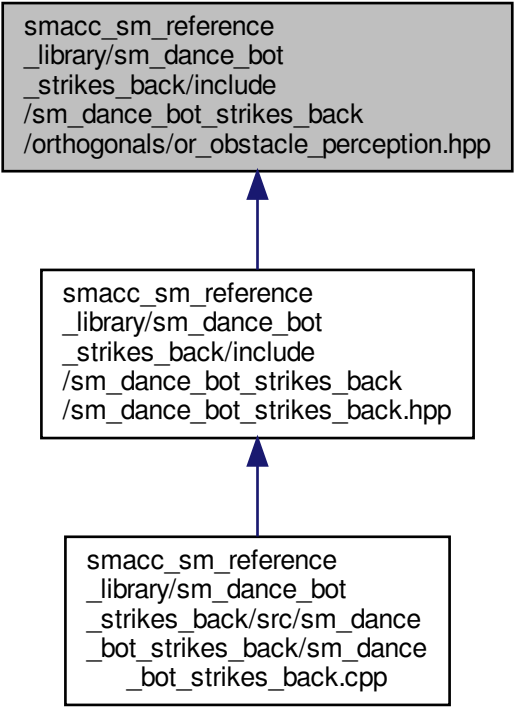


smacc_sm_reference
_library/sm_dance_bot
_strikes_back/include
/sm_dance_bot_strikes_back
/orthogonals/or_obstacle_perception.hpp



```
graph BT; A["smacc_sm_reference_library/sm_dance_bot_strikes_back/src/sm_dance_bot_strikes_back/sm_dance_bot_strikes_back.cpp"] --> B["smacc_sm_reference_library/sm_dance_bot_strikes_back/include/sm_dance_bot_strikes_back/sm_dance_bot_strikes_back.hpp"]; B --> C["smacc_sm_reference_library/sm_dance_bot_strikes_back/include/sm_dance_bot_strikes_back/orthogonals/or_obstacle_perception.hpp"]
```

smacc_sm_reference
_library/sm_dance_bot
_strikes_back/include
/sm_dance_bot_strikes_back
/sm_dance_bot_strikes_back.hpp

smacc_sm_reference
_library/sm_dance_bot
_strikes_back/src/sm_dance
_bot_strikes_back/sm_dance
_bot_strikes_back.cpp