

cl_move_base_z::CbNavigate
Backwards::onEntry

sm_dance_bot::radial
_motion_states::StiRadialReturn
::onExit

cl_move_base_z::odom
_tracker::OdomTracker
::clearPath

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graph LR; A["cl_move_base_z::CbNavigate Backwards::onEntry"] --> C["cl_move_base_z::odom _tracker::OdomTracker ::clearPath"]; B["sm_dance_bot::radial _motion_states::StiRadialReturn ::onExit"] --> C;
```