

```
graph BT; A["smacc_sm_reference  
_library/sm_dance_bot  
/include/sm_dance_bot  
/states/st_navigate_reverse_2.hpp"] <-- B["smacc_sm_reference  
_library/sm_dance_bot  
/include/sm_dance_bot  
/sm_dance_bot.hpp"]; B <-- C["smacc_sm_reference  
_library/sm_dance_bot  
/src/sm_dance_bot/sm_dance  
_bot.cpp"]
```

smacc_sm_reference
_library/sm_dance_bot
/include/sm_dance_bot
/states/st_navigate_reverse_2.hpp

smacc_sm_reference
_library/sm_dance_bot
/include/sm_dance_bot
/sm_dance_bot.hpp

smacc_sm_reference
_library/sm_dance_bot
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_bot.cpp