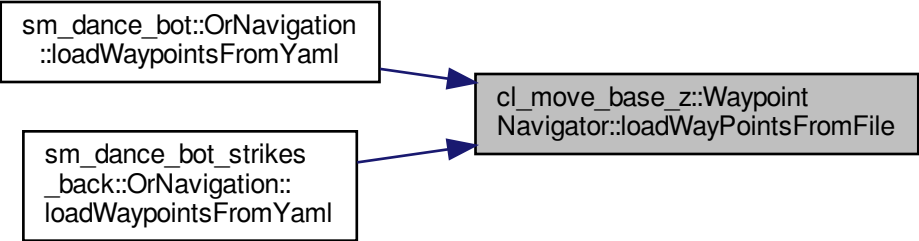


sm_dance_bot::OrNavigation
::loadWaypointsFromYaml

sm_dance_bot_strikes
_back::OrNavigation::
loadWaypointsFromYaml

cl_move_base_z::Waypoint
Navigator::loadWayPointsFromFile



```
graph LR; A["sm_dance_bot::OrNavigation::loadWaypointsFromYaml"] --> C["cl_move_base_z::WaypointNavigator::loadWayPointsFromFile"]; B["sm_dance_bot_strikes_back::OrNavigation::loadWaypointsFromYaml"] --> C;
```

The diagram illustrates a dependency or call relationship. Two source boxes on the left point via blue arrows to a single target box on the right. The top source box contains the text 'sm_dance_bot::OrNavigation::loadWaypointsFromYaml'. The bottom source box contains the text 'sm_dance_bot_strikes_back::OrNavigation::loadWaypointsFromYaml'. The target box, which has a gray background, contains the text 'cl_move_base_z::WaypointNavigator::loadWayPointsFromFile'.