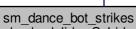
## smacc::ISmaccComponent

# stateMachine\_ # owner

- + ISmaccComponent()
- + ~ISmaccComponent() + qetName()
- # onInitialize()
- # postEvent() # postEvent()
- # onOrthogonalAllocation()
- # requiresComponent()
  # requiresClient()
- # createSiblingComponent()
  # createSiblingNamedComponent()
- # getNode()
- # getLogger()
   initialize()
  - setStateMachine()



\_back::cl\_lidar::CpLidarSensorData

- + lastMessage\_
- + forwardObstacleDistance + SECURITY DISTANCE
- + onInitialize()
- + MessageCallbackStoreDistance ToWall()