

CSCI803 Assignment

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November 19, 2020

1 Problem 1

```
1 # Set N
2 N = 8
3 ld = [0] * 30
4 rd = [0] * 30
5 cl = [0] * 30
6
7 def printSolution(board):
8     for i in range(N):
9         for j in range(N):
10             print(board[i][j], end = " ")
11         print()
12
13 def solveNQUtil(board, col):
14
15     if (col >= N):
16         return True
17
18     for i in range(N):
19
20         if ((ld[i - col + N - 1] != 1 and
21             rd[i + col] != 1) and cl[i] != 1):
22
23             board[i][col] = 1
24             ld[i - col + N - 1] = rd[i + col] = cl[i] = 1
25
26             if (solveNQUtil(board, col + 1)):
27                 return True
28
29             board[i][col] = 0 # BACKTRACK
30             ld[i - col + N - 1] = rd[i + col] = cl[i] = 0
31
32     return False
33
34 def solveNQueue():
35     board = [[0, 0, 0, 0, 0, 0, 0, 0],
```

```

36         [0, 0, 0, 0, 0, 0, 0, 0],
37         [0, 0, 0, 0, 0, 0, 0, 0],
38         [0, 0, 0, 0, 0, 0, 0, 0],
39         [0, 0, 0, 0, 0, 0, 0, 0],
40         [0, 0, 0, 0, 0, 0, 0, 0],
41         [0, 0, 0, 0, 0, 0, 0, 0],
42         [0, 0, 0, 0, 0, 0, 0, 0],
43     ]
44     if (solveNQUtil(board, 0) == False):
45         print("Solution does not exist")
46         return False
47     printSolution(board)
48     return True
49
50 solveNQueue()

```

▲ ~/Desktop/Lab7 py3 task1.py

```

1 0 0 0 0 0 0 0
0 0 0 0 0 0 1 0
0 0 0 0 1 0 0 0
0 0 0 0 0 0 0 1
0 1 0 0 0 0 0 0
0 0 0 1 0 0 0 0
0 0 0 0 0 1 0 0
0 0 1 0 0 0 0 0

```

2 Problem 2

```

1  #include <iostream>
2  #include "stdc++.h"
3
4  using namespace std;
5  #define N 4
6
7  struct Node {
8      Node *parent;
9      int pathCost;
10     int cost;
11     int machineID;

```

```

12     int taskID;
13     bool assigned[N];
14 };
15
16 struct comp {
17     bool operator()(const Node *lhs,
18                     const Node *rhs) const {
19         return lhs->cost > rhs->cost;
20     }
21 };
22
23 Node *newNode(int x, int y, bool assigned[],
24              Node *parent) {
25     Node *node = new Node;
26
27     for (int j = 0; j < N; j++)
28         node->assigned[j] = assigned[j];
29     node->assigned[y] = true;
30
31     node->parent = parent;
32     node->machineID = x;
33     node->taskID = y;
34
35     return node;
36 }
37
38 int calculateCost(int costMatrix[N][N], int x,
39                  int y, bool assigned[]) {
40     int cost = 0;
41
42     bool available[N] = {true};
43
44     for (int i = x + 1; i < N; i++) {
45         int min = INT_MAX, minIndex = -1;
46
47         for (int j = 0; j < N; j++) {
48             if (!assigned[j] && available[j] &&
49                 costMatrix[i][j] < min) {
50                 minIndex = j;
51
52                 min = costMatrix[i][j];
53             }
54         }
55
56         cost += min;
57
58         available[minIndex] = false;
59     }
60
61     return cost;
62 }

```

```

63
64 void printAssignments(Node *min) {
65     if (min->parent == NULL)
66         return;
67
68     printAssignments(min->parent);
69     cout << "Assign_Machine_" << char(min->machineID + '1')
70         << "_to_Task_" << min->taskID << endl;
71 }
72
73
74 // Finds minimum cost using Branch and Bound
75 int findMinCost(int costMatrix[N][N]) {
76     priority_queue<Node *, std::vector<Node *>, comp> prq;
77
78     bool assigned[N] = {false};
79     Node *root = newNode(-1, -1, assigned, NULL);
80     root->pathCost = root->cost = 0;
81     root->machineID = -1;
82
83     prq.push(root);
84
85     while (!prq.empty()) {
86         Node *min = prq.top();
87
88         prq.pop();
89
90         int i = min->machineID + 1;
91
92         if (i == N) {
93             printAssignments(min);
94             return min->cost;
95         }
96
97         for (int j = 0; j < N; j++) {
98             if (!min->assigned[j]) {
99                 Node *child = newNode(i, j, min->assigned, min);
100
101                 child->pathCost = min->pathCost + costMatrix[i][j];
102
103                 child->cost = child->pathCost +
104                     calculateCost(costMatrix, i, j, child
105                                 ->assigned);
106
107                 prq.push(child);
108             }
109         }
110     }
111
112 int main() {

```

```

113     int costMatrix[N][N] =
114         {
115             {13, 4, 7, 6},
116             {1, 11, 5, 4},
117             {6, 7, 2, 8},
118             {1, 3, 5, 9}
119         };
120
121
122     cout << findMinCost(costMatrix)
123         << " is optimal min cost!";
124     return 0;
125 }

```

```

/Users/december/Desktop/task2/cmake-build-debug/untitled
Assign Machine 1 to Task 1
Assign Machine 2 to Task 3
Assign Machine 3 to Task 2
Assign Machine 4 to Task 0
11 is optimal min cost!
Process finished with exit code 0

```