CSCI446/946 Big Data Analytics

Week 11 Advanced Analytical Theory and Methods: Time Series Analysis

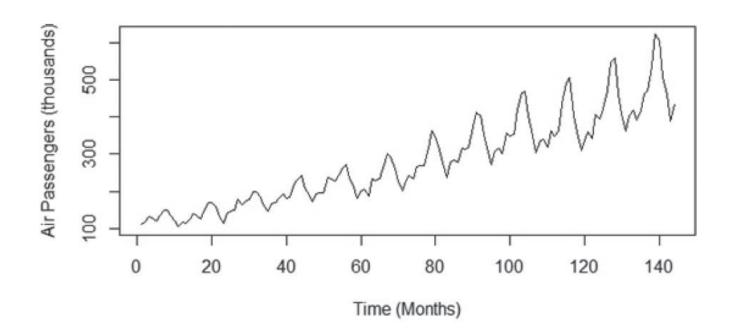
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Advanced Analytical Theory and Methods: Time Series Analysis

- Overview of Time Series Analysis
- Box-Jenkins Methodology
- Autoregressive (AR) Models
- Moving Average (MA) Models
- Building and evaluating ARIMA models
- Additional Models

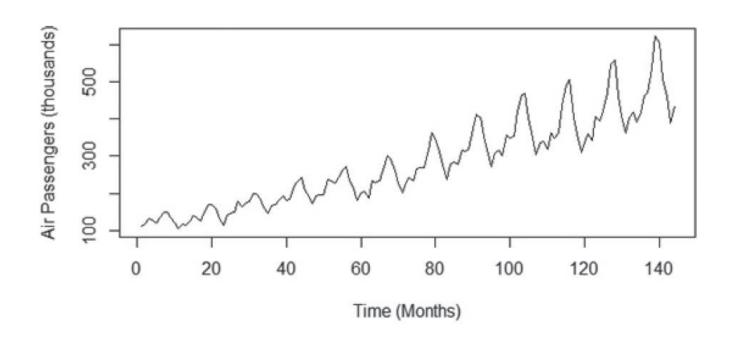
Advanced Analytical Theory and Methods: Time Series Analysis

- Time series
 - An ordered sequence of equally spaced values over time



Advanced Analytical Theory and Methods: Time Series Analysis

- Applications in finance, economics, biology, engineering, retail, manufacturing, etc.
- Understand the underlying process that generates the observed data
- Forecast and monitor the future data
- Three examples
 - Retail sales, Spare parts planning
 - Stock trading



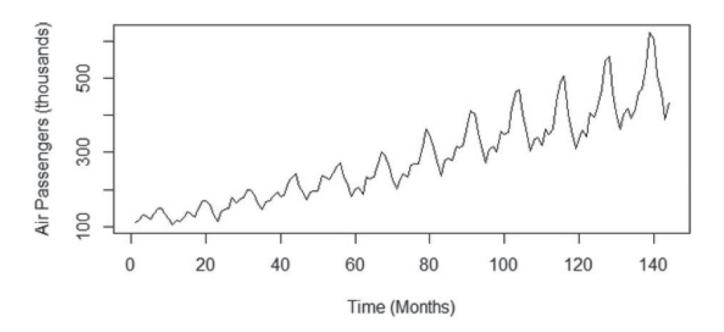
- Identify and model the structure of time series
- Forecast future values in the time series

- Box-Jenkins methodology
 - 1. Condition data and select a model
 - Identify and account for any trends or seasonality in the time series
 - Examine the remaining time series and determine a suitable model
 - 2. Estimate the model parameters
 - 3. Assess the model and return to Step 1, if needed

- A time series can consists of
 - Trend, Seasonality, Cyclic, and Random
- Trend
 - The long-term movement in a time series
 - The values increase or decrease over time
- Seasonality
 - The fixed, periodic fluctuation over time
 - Often related to the calendar

- A time series can consists of
 - Trend, Seasonality, Cyclic, and Random
- Cyclic
 - Periodic, but not fixed fluctuation over time
 - Say, the boom-bust cycles of the economy
- Random
 - What remains after the above three components
 - Noise + underlying structure to be modelled

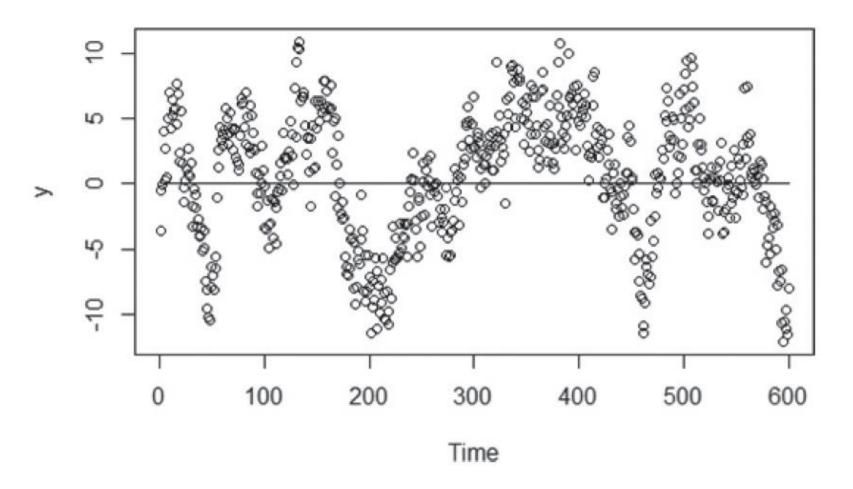
- A time series can consists of
 - Trend, Seasonality, Cyclic, and Random



A plot of the monthly number of international airline passengers over a 12-year period

ARIMA

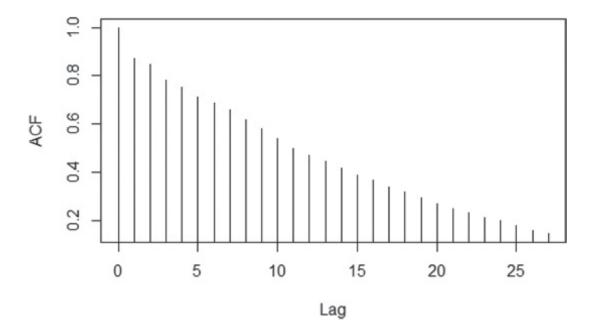
- AutoRegressive Integrated Moving Average
- Shall be applied to stationary time series
- Stationary time series
 - The mean of y_t is a constant over time
 - The variance of y_t is finite (i.e., $cov(y_t, y_t)$)
 - The covariance of y_t and y_{t+h} (i.e., $cov(y_t, y_{t+h})$) depend only on h



Flat looking (No trend); Constant variance (Similar scattering); Constant covariance over time

Autocorrelation function (ACF) ([-1, +1])

$$ACF(h) = \frac{cov(y_t, y_{t+h})}{\sqrt{cov(y_t, y_t)cov(y_{t+h}, y_{t+h})}} = \frac{cov(h)}{cov(0)}$$



- Autoregressive (AR) Models
 - For a stationary time series, AR(p) is expressed as

```
y_{t} = \delta + \phi_{1} y_{t-1} + \phi_{2} y_{t-2} + \ldots + \phi_{p} y_{t-p} + \varepsilon_{t}
where \delta is a constant for a nonzero-centered time series: \phi_{j} is a constant for j = 1, 2, \ldots, p
y_{t-j} \text{ is the value of the time series at time } t - j
\phi_{p} \neq 0
\varepsilon_{t} \sim N(0, \sigma_{\varepsilon}^{2}) \text{ for all } t
```

A point y_t is a linear combination of the prior p values

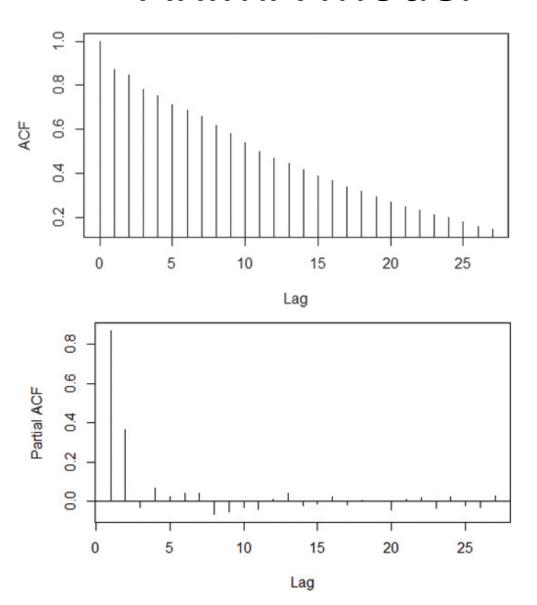
- How to identify the order p in AR(p)?
- Partial autocorrelation function (PACF)
 - "The PACF of an AR(p) process is zero at lag p + 1 and greater"
 - So, let check the PACF of our data and find the lag after which the PACF becomes zero
- Why partial autocorrelation?
 - Even the simple AR(1) model leads to considerable autocorrelation

Partial autocorrelation function (PACF)

$$PACF(h) = corr(y_t - y_t^*, y_{t+h} - y_{t+h}^*) \text{ for } h \ge 2$$

= $corr(y_t, y_{t+1})$ for $h = 1$

where
$$y_t^* = \beta_1 y_{t+1} + \beta_2 y_{t+2} \dots + \beta_{h-1} y_{t+h-1}$$
,
$$y_{t+h}^* = \beta_1 y_{t+h-1} + \beta_2 y_{t+h-2} \dots + \beta_{h-1} y_{t+1}$$
, and the h – 1 values of the βs are based on linear regression



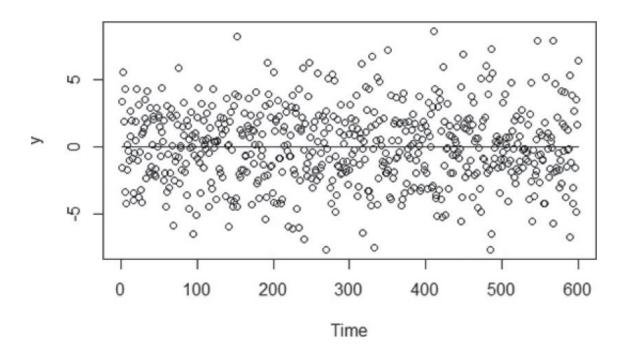
- Moving Average (MA) models
 - For a time series, yt, centred at zero, a MA(q) is expressed as

$$\mathbf{y}_{\mathsf{t}} = \boldsymbol{\varepsilon}_{\mathsf{t}} + \boldsymbol{\varrho}_{\mathsf{1}} \boldsymbol{\varepsilon}_{\mathsf{t-1}} + \ldots + \boldsymbol{\varrho}_{\mathsf{q}} \boldsymbol{\varepsilon}_{\mathsf{t-q}}$$

where θ_k is a constant for k = 1, 2, ..., q $\theta_q \neq 0$ $\varepsilon_t \sim N(0, \sigma_s^2)$ for all t

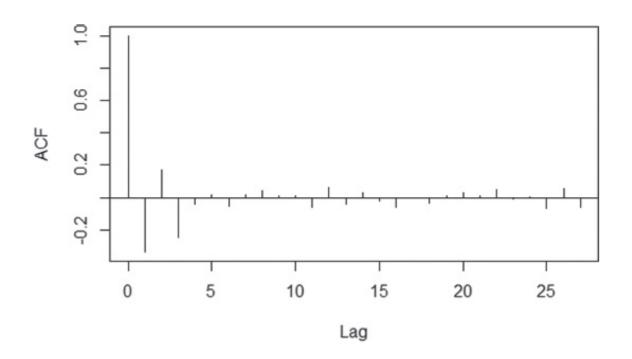
- Moving Average (MA) models
 - A linear regression of yt against current and previous (observed) white noise error terms or random shocks
- Two differences from AR(p) models
 - $-\varepsilon_{t-1}$ are propagated to y_t directly
 - $-\varepsilon_t$ only affects the current and future p values

Finite MA models are always stationary



$$y_t = \varepsilon_t - 0.4 \ \varepsilon_{t-1} + 1.1 \varepsilon_{t-2} - 2.5 \ \varepsilon_{t-3}$$
 where $\varepsilon_t \sim N(0, 1)$

• The ACF of this MA(3) time series



$$y_t = \varepsilon_t - 0.4 \ \varepsilon_{t-1} + 1.1 \varepsilon_{t-2} - 2.5 \ \varepsilon_{t-3}$$
 where $\varepsilon_t \sim N(0, 1)$

^{*} ACF can help to identify q in MA(q)

Why is this case?

$$\begin{split} \mathbf{y}_t &= \boldsymbol{\varepsilon}_t + \boldsymbol{\theta}_1 \boldsymbol{\varepsilon}_{t-1} + \boldsymbol{\theta}_2 \, \boldsymbol{\varepsilon}_{t-2} + \boldsymbol{\theta}_3 \, \boldsymbol{\varepsilon}_{t-3} \\ \mathbf{y}_{t-1} &= & \boldsymbol{\varepsilon}_{t-1} + \boldsymbol{\theta}_1 \, \boldsymbol{\varepsilon}_{t-2} + \boldsymbol{\theta}_2 \, \boldsymbol{\varepsilon}_{t-3} + \boldsymbol{\theta}_3 \, \boldsymbol{\varepsilon}_{t-4} \\ \mathbf{y}_{t-2} &= & \boldsymbol{\varepsilon}_{t-2} + \boldsymbol{\theta}_1 \, \boldsymbol{\varepsilon}_{t-3} + \boldsymbol{\theta}_2 \, \boldsymbol{\varepsilon}_{t-4} + \boldsymbol{\theta}_3 \, \boldsymbol{\varepsilon}_t \\ \mathbf{y}_{t-3} &= & \boldsymbol{\varepsilon}_{t-3} + \boldsymbol{\theta}_1 \boldsymbol{\varepsilon}_{t-4} + \boldsymbol{\theta}_2 \boldsymbol{\varepsilon}_{t-5} + \boldsymbol{\theta}_3 \boldsymbol{\varepsilon} \\ \mathbf{y}_{t-4} &= & \boldsymbol{\varepsilon}_{t-4} + \boldsymbol{\theta}_1 \boldsymbol{\varepsilon}_{t-5} + \boldsymbol{\theta}_2 \, \boldsymbol{\varepsilon}_{t-6} + \boldsymbol{\theta}_3 \end{split}$$

Because yt and yt-4 have no overlapping at all

$$y_t = \varepsilon_t - 0.4 \ \varepsilon_{t-1} + 1.1 \varepsilon_{t-2} - 2.5 \ \varepsilon_{t-3}$$
 where $\varepsilon_t \sim N(0, 1)$

 AR(p) and MA(q) are often combined into one model for time series, resulting in ARMA(p,q).

$$\begin{aligned} \mathbf{y}_t &= \delta + \phi_1 \, \mathbf{y}_{t-1} + \phi_2 \, \mathbf{y}_{t-2} + \ldots + \phi_p \, \mathbf{y}_{t-p} \\ &+ \varepsilon_t + \theta_1 \varepsilon_{t-1} + \ldots + \theta_q \, \varepsilon_{t-q} \end{aligned}$$

where δ is a constant for a nonzero-centered time series

$$\phi_{j}$$
 is a constant for j = 1, 2, ..., p
 $\phi_{p} \neq 0$
 θ_{k} is a constant for k = 1, 2, ..., q
 $\theta_{q} \neq 0$
 $\varepsilon_{t} \sim N(0, \sigma_{\varepsilon}^{2})$ for all t

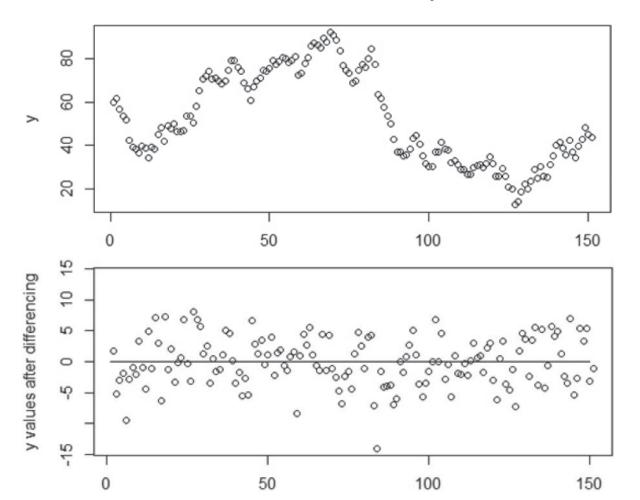
- Transformations to stationary time series
 - Train a linear or higher-order regression model to remove trends
 - Or, compute the difference between successive yvalue, which is known as differencing

$$d_t = y_t - y_{t-1}$$
 for $t = 2, 3, ..., n$

If still not stationary, apply differencing more times

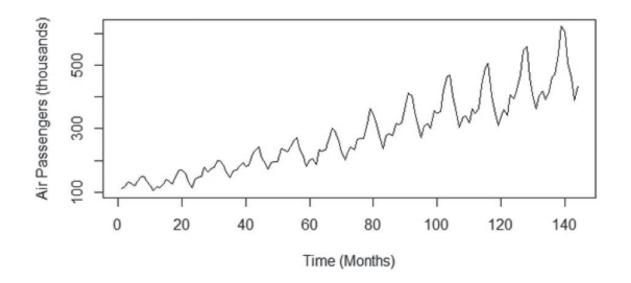
$$d_{t-1} - d_{t-2} = (y_t - y_{t-1}) - (y_{t-1} - y_{t-2})$$
$$= y_t - 2y_{t-1} + y_{t-2}$$

Transformations to stationary time series



- ARIMA model
 - Autoregressive Integrated Moving Average
 - Differencing is included in ARMA model
- ARIMA(p,d,q)
 - ARMA(p,q) mode is applied after applying differencing d times

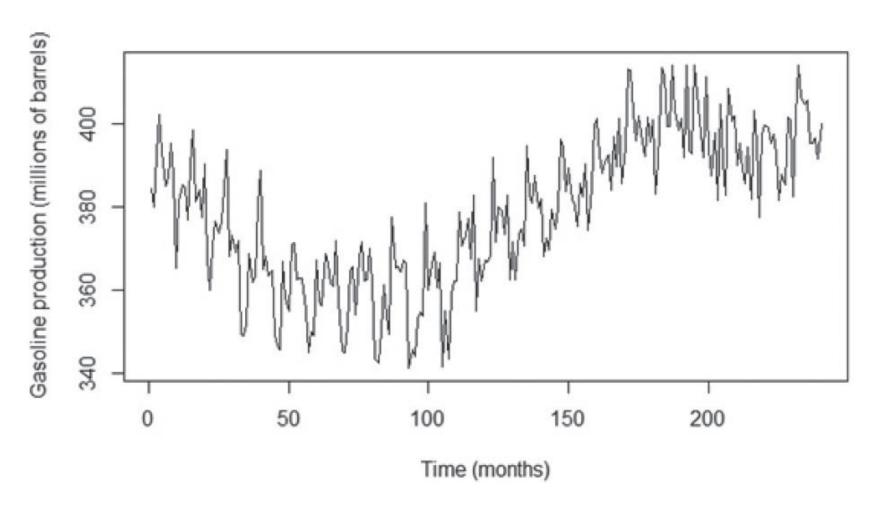
- Seasonal ARIMA model
 - $-ARIMA(p,d,q) \times (P,D,Q)s$
- It is used to account for seasonal patterns
- An alternative to regression analysis



- An example
 - Monthly gasoline production (millions of barrels)
- Need to forecast short-term production

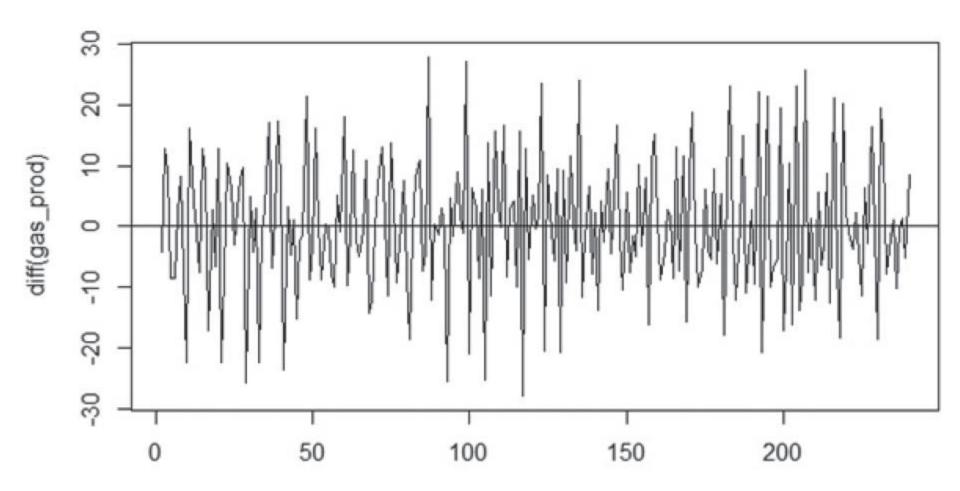


```
library(forecast)
# read in gasoline production time series
# monthly gas production expressed in millions of barrels
qas prod input <- as.data.frame( read.csv("c:/data/qas prod.csv") )</pre>
# create a time series object
gas prod <- ts(gas prod input[,2])</pre>
#examine the time series
plot(gas prod, xlab = "Time (months)",
     ylab = "Gasoline production (millions of barrels)")
```

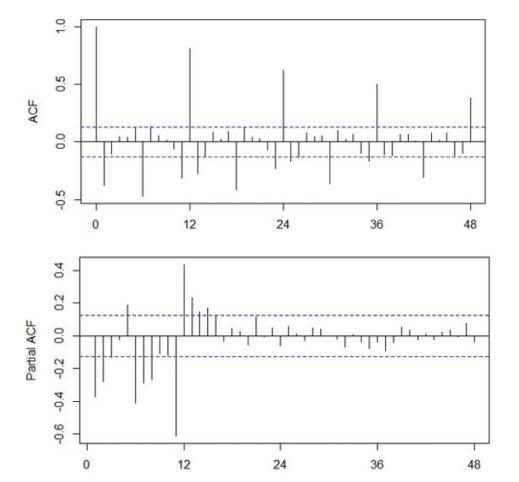


What is your observation on this time series?

```
plot(diff(gas_prod))
abline(a=0, b=0)
```



```
# examine ACF and PACF of differenced series
acf(diff(gas_prod), xaxp = c(0, 48, 4), lag.max=48, main="")
pacf(diff(gas_prod), xaxp = c(0, 48, 4), lag.max=48, main="")
```

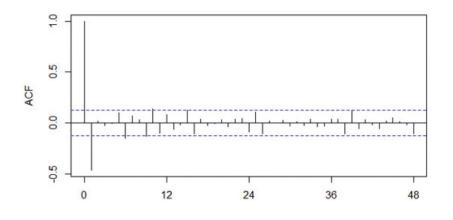


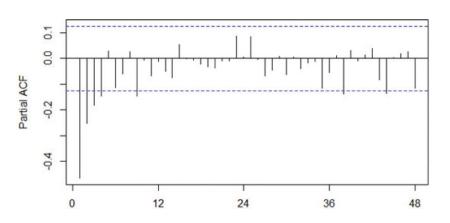
- Differencing + a seasonal AR(1) model
 - $-ARIMA(0,1,0) \times (1,0,0)_{12}$

```
arima 1 <- arima (gas_prod,
                    order=c(0,1,0),
                    seasonal = list(order=c(1,0,0),period=12))
arima 1
Series: qas prod
ARIMA(0,1,0)(1,0,0)[12]
Coefficients:
        sar1
      0.8335
s.e. 0.0324
sigma<sup>2</sup> estimated as 37.29: log likelihood=-778.69
AIC=1561.38 AICc=1561.43 BIC=1568.33
```

 Examine the residuals after fitting ARIMA(0,1,0) x (1,0,0)₁₂

```
# examine ACF and PACF of the (0,1,0)x(1,0,0)12 residuals acf(arima_1$residuals, xaxp = c(0, 48, 4), lag.max=48, main="") pacf(arima_1$residuals, xaxp = c(0, 48, 4), lag.max=48, main="")
```

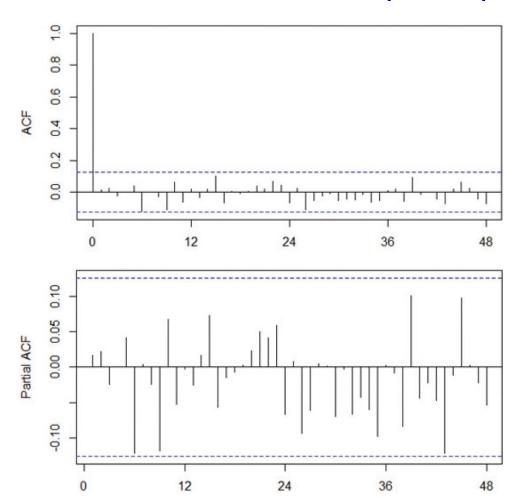




• Fit with a new model ARIMA $(0,1,1) \times (1,0,0)_{12}$

```
arima 2 <- arima (gas prod,
                 order=c(0,1,1),
                 seasonal = list(order=c(1,0,0),period=12))
arima 2
Series: qas prod
ARIMA(0,1,1)(1,0,0)[12]
Coefficients:
         mal sar1
      -0.7065 0.8566
s.e. 0.0526 0.0298
sigma^2 estimated as 25.24: log likelihood=-733.22
AIC=1472.43 AICc=1472.53 BIC=1482.86
```

• Fit with a new model ARIMA(0,1,1) x $(1,0,0)_{12}$



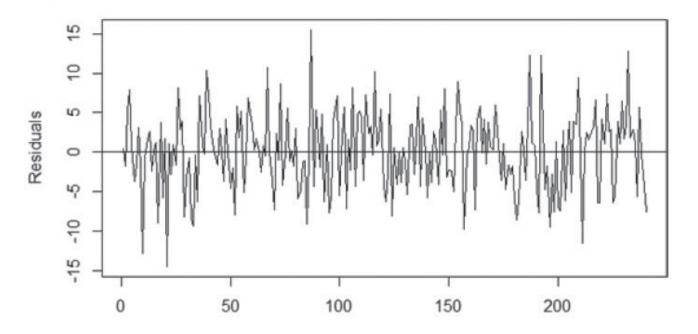
- Comparing fitted time series models
 - Model coefficients are estimated via Maximum Likelihood Estimation (MLE)
 - R provides several measures based on MLE value
 - AIC (Akaike Information Criterion)
 - AICc (AIC corrected)
 - BIC (Bayesian Information Criterion)
 - The preferred model has the smallest AIC, AICc, or BIC value

Comparing fitted time series models

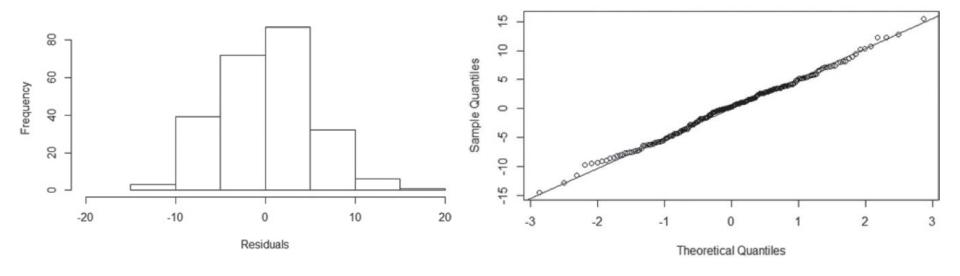
ARIMA Model (p,d,q) × (P,Q,D) _s	AIC	AICc	віс	
$(0,1,0) \times (1,0,0)_{12}$	1561.38	1561.43	1568.33	
$(0,1,1) \times (1,0,0)_{12}$	1472.43	1472.53	1482.86	
(0,1,2) × (1,0,0) ₁₂	1474.25	1474.42	1488.16	
(1,1,0) × (1,0,0) ₁₂	1504.29	1504.39	1514.72	
(1,1,1) × (1,0,0) ₁₂	1474.22	1474.39	1488.12	

Normality and constant variance

```
plot(arima_2$residuals, ylab = "Residuals")
abline(a=0, b=0)
hist(arima_2$residuals, xlab="Residuals", xlim=c(-20,20))
qqnorm(arima_2$residuals, main="")
qqline(arima_2$residuals)
```



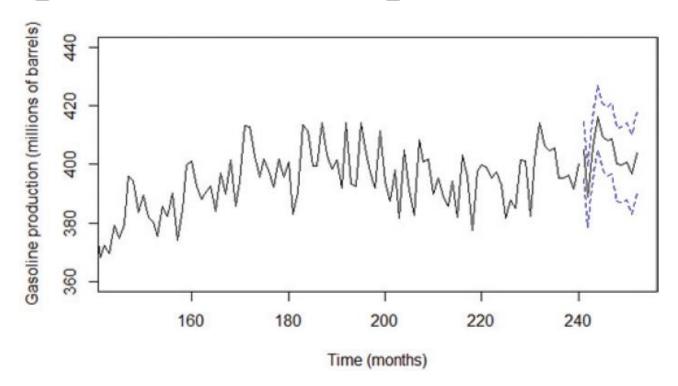
Normality and constant variance



- If not satisfied, need to transform the time series before model fitting
 - Say, apply a logarithm function

- Forecast
 - The next 12 months of gasoline production

```
#predict the next 12 months
arima_2.predict <- predict(arima_2,n.ahead=12)</pre>
```



Reasons to Choose and Cautions

- Time series analysis is based on historical data for the variable of interest
- Forecasting process is simplified with ARIMA
 - What if regression analysis is used instead?
- Disadvantage
 - Not know underlying variables affect the outcome
- Cautions
 - Impact of severe shocks to the system
 - Shall only be used for short-term forecast

Additional Methods

- Autoregressive Moving Average with Exogenous inputs (ARMAX)
- Spectral analysis
- Generalised Autoregressive Conditionally Heteroscedastic (GARCH)
- Kalman filtering
- Multivariate time series analysis (VARIMA)

Summary

- Box-Jenkins methodology
 - Condition, identify, model
 - Stationary time series, ACF, PACF plot
- ARIMA model
 - AR, MA, Differencing
 - $-ARIMA(p,d,q) \times (P,D,Q)s$
- Build ARIMA model in R
- Assess and refine the model

Reference books

- 1. The Analysis of Time Series: An Introduction, Sixth Edition, Chris Chatfield
- 2. Time Series Analysis and Its Applications With R Examples ,Shumway, Robert H., Stoffer, David S.

